Sure/v-2

AC Servo Systems

Drive features

- Power:
- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW
- Fully digital with up to 3.1 kHz bandwidth velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the SureServo2 Pro PCbased software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- · Communications include:
- Serial Modbus (native/built-in)
- Optional Modbus TCP card
- Optional Ethernet/IP card (this card can use implicit and explicit messaging. SureServo2 Pro software can generate an EDS file to transfer custom data between PLC and drive)
- · Command options include:
- ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
- Powerful built-in motion controller for position control using 99 preset positions (enter these during development, or send them through the communications options above during runtime)
- Internal sequencing for position/speed

commands, registration (capture/compare), electronic camming, homing (10 different options), Jumps, and arithmetic statements.

- The 3.1 kHz bandwidth allows for high-level automatic tuning. Several modes of tuning are available including Auto Tune that can estimate the load inertia and fine-tune the system when all the loads are attached.
- Optically isolated digital inputs (10) and outputs (6), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution).
- Other Features:
- Secondary/Auxiliary encoder feedback (for true closed loop control)
- Registration ability
- Analog positioning
- Safe Torque Off (STO) included so no need for large, bulky contactors to disconnect power from the drive in E-stop situations
- Absolute Encoder operation (with optional encoder battery backup)
- Electronic camming (you can define the cam with SureServo2 Pro software or you can import an Excel spreadsheet)
- Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.

Motor features

- · Low inertia models:
- 100W, 200W, 400W, 750W, 1kW, 1.5 kW, and 2kW
- Speeds up to 6,000 rpm
- · Medium inertia models:
- 1kW, 1.5 kW, 2kW, and 3kW
- Speeds up to 3,000 rpm
- · High inertia models:
 - 3kW, 4.5 kW, 5.5 kW, 7.5 kW, 11kW, and 15kW
- Speeds up to 3,000 rpm
- Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style couplings
- Integrated encoder with 16,777,216 encoder pulses/revolution plus marker pulse (once per revolution)
- Optional 24 VDC spring-set holding brakes (xxxxB series motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for brake motors 230V systems 5.5kW and larger or 460V systems 11kW and larger)
- Motor cables available in standard or flexrated lengths of 3, 5, 10, and 20m
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 20-pin spring clamp terminal block (limited I/O) that mounts directly to the drive

SureServo2 tuning technology

The SureServo2 drive closes the loop on current, velocity, and position (depending on control mode selection). The 3.1 kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and five (5) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can easily tune systems with as much as 60:1 inertia mismatch.

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- One Touch Auto Tuning—the drive tunes the motor without any motion (static motor/ system analysis)
- Normal Auto Tuning—the drive tunes the load while an external controller or the drive's internal indexer provides point-to-point moves
- Assisted Tuning–3 modes where the drive tunes the motor while moving. The user can adjust responsiveness while the drive is analyzing the system
- Manual Tuning–20+ parameters are available to give power users the ultimate flexibility to tune their systems.

SureServo2 Built-in motion controller

While the SureServo2 drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to 99 index moves can be pre-defined and stored in the drive and then selected and executed using digital inputs (inputs as events or inputs used as a multiplexer) or communication (serial Modbus, Modbus TCP, or Ethernet/IP). The index profiles can also be changed while in-process with digital events or via comms. The internal motion can consist of incremental or absolute moves, and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial/Ethernet communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful motion controller inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

SureServo2 Optional Holding Brake

Each SureServo2 motor rating can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

SureGear® Precision Gearboxes for Servo motors

Inertia balancing issue in your design?

The SureGear
PGA series
easily mates
to SureServo2
motors. Everything
you need to mount your
SureServo2 motor is included!

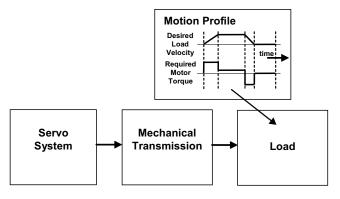
- Four gear ratios available (5, 10, 15, 25:1)
- Mounting hardware included for attaching to SureServo2 motors
- Industry-standard mounting dimensions
- Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty

AC Servo Systems

How to select and apply SureServo2 systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo2 system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement. SureServo2 Pro has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.

AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from www. automationdirect.com on the store page for your drive.



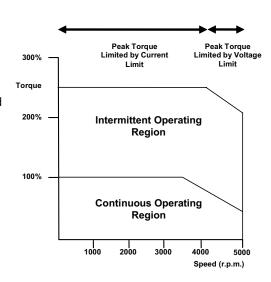
1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system.

In general, applications that need high response or bandwidth will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo2 systems may be tuned manually, fully Automatically, or via a hybrid mode where the software tunes the system with input for system responsiveness from the user.

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have a SureServo2 system, these values are easily captured and recorded with the Scope feature built into SureServo2 Pro. If you are designing the system, use VisualSizer to define the system and calculate expected inertia and required power.



AC Servo Systems

Application tip - coupling considerations

The SureServo2 motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider the stiffness, torque rating, and inertia. Higher stiffness

(lb-in/radian) is needed for better response but there is a tradeoff between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo2 **peak** torque requirement of your application.

Available Couplings

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo2 systems can go up to 6,000 rpm for the low inertia motors and up to 3,000 rpm for the medium inertia motors.

Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo

system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

SureServo2 motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.

For more information, refer to the website listed below.

Mechanical Transmission: <u>Timing Belts and Pulleys</u>
Precision Gearboxes

Ordering guide instructions

The following four pages are your ordering guide for SureServo2 systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

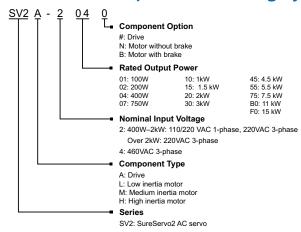
Each system needs:

- Motor
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either CN1 cable + RTB breakout board, or an LTB20 breakout board that mounts on the drive)
- For brakemotors 4.5 kW and below, the brake wiring is included in the power cable. For brakemotors 5.5 kw and above, a separate brake cable is required.

A wide variety of optional accessories are also available, such as Ethernet cards, RS485 splitters/terminators, toroids, etc.

You can also use the SureServo2 selector tool on the AutomationDirect.com website to help you configure your system.

SureServo2 series drives and motors part numbering system



Here is what you will need to order a complete servo system:













NOTE: Unit can be programmed via keypad. Optional programming software (free download) and optional programming cable available.



NOTE: If you need a gear box for your configuration, you can do it easily online: http://www.sureservo.com/gearbox/selector



www.automationdirect.com



Torque to SureServo2 System Quick Reference

	230V Sy	stem Torque	
System Rated Torque (N∙m)	System Maximum Torque (N·m)	Suggested Servo Motor	Required Servo Drive
0.32	1.12	SV2L-201N or SV2L-201B	<u>SV2A-2040</u>
0.64	2.24	SV2L-202N or SV2L-202B	SV2A-2040
1.27	3.96	SV2L-204N or SV2L-204B	SV2A-2040
2.39	7.86	SV2L-207N or SV2L-207B	SV2A-2075
3.18	8.12	SV2L-210N or SV2L-210B	SV2A-2150
4.77	14.32	SV2M-210N or SV2M-210B	SV2A-2150
7.16	14.88	SV2M-215N or SV2M-215B	SV2A-2150
9.55	24.54	SV2M-220N or SV2M-220B	SV2A-2200
17.55	48.29	SV2M-230N or SV2M-230B	SV2A-2300
28.65	71.62	SV2H-245N or SV2H-245B	SV2A-2550
35.01	87.53	SV2H-255N or SV2H-255B	SV2A-2550
47.74	119.36	SV2H-275N or SV2H-275B	SV2A-2750
70	175	SV2H-2B0N or SV2H-2B0B	SV2A-2F00
95.4	224.0	SV2H-2F0N or SV2H-2F0B	<u>SV2A-2F00</u>

	460V System Torque							
System Rated Torque (N·m)	System Maximum Torque (N·m)	Suggested Servo Motor	Required Servo Drive					
1.27	4.45	SV2L-404N or SV2L-404B	<u>SV2A-4040</u>					
2.24	7.58	SV2L-407N or SV2L-407B	<u>SV2A-4075</u>					
3.18	9.54	SV2L-410N or SV2L-410B	<u>SV2A-4150</u>					
4.77	14.32	<u>SV2M-410N</u> or <u>SV2M-410B</u>	<u>SV2A-4150</u>					
7.16	18.1	SV2L-415N or SV2L-415B	<u>SV2A-4150</u>					
9.55	28.65	SV2L-420N or SV2L-420B	<u>SV2A-4200</u>					
19.1	49.38	SV2H-430N or SV2H-430B	<u>SV2A-4300</u>					
28.65	64.61	<u>SV2H-445N</u> or <u>SV2H-445B</u>	<u>SV2A-4550</u>					
35.01	73.48	SV2H-455N or SV2H-455B	SV2A-4550					
47.74	93.71	<u>SV2H-475N</u> or <u>SV2H-475B</u>	<u>SV2A-4750</u>					
70	175	SV2H-4B0N or SV2H-4B0B	<u>SV2A-4F00</u>					
95.4	224.0	SV2H-4F0N or SV2H-4F0B	SV2A-4F00					



SureServo2 AC servo drive, motor, and cable combinations

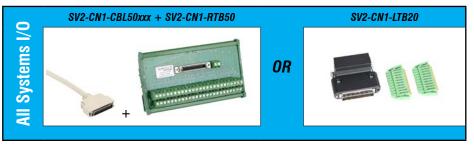
	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		1,12 (350%)	SV2L-201N		SV2C-PA18-xxNN	SV2C-E122-xxNN
Ш	120V	(E+A) Intermittent Region	0V2E-2011V	SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
Syste	1200	0.32 (100%) Continuous Region	SV2L-201B	<u> 3VZA-2040</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
Inertia		1,600 3,000 4,200 Speed (r/min)	<u>3v2L-201D</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
100W Low Inertia System		(350%)	SV2L 201N		SV2C-PA18-xxNN	SV2C-E122-xxNN
100N	2201/	[上 (188%)] (188%)] (188%)	<u>SV2L-201N</u>	CV2A 2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
	230V	(188%) 0.32 (100%) 0.16 (50%) Continuous Region 3,000 4,800 6,000 Speed (r/min)	SV2L-201B	SV2A-2040	SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
		Intermittent Region Continuous Region	SV2L-202N	SV2A-2040	SV2C-PA18-xxNN	SV2C-E122-xxNN
u	120V				SV2C-PA18-xxFN	SV2C-E122-xxFN
200W Low Inertia System	1200				SV2C-PB18-xxNB	SV2C-E122-xxNN
ertia		1,400 3,000 3,700 Speed (r/min)	<u>SV2L-202B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
Low In		2.24 (350%) 1.90	CVOL 202N		SV2C-PA18-xxNN	SV2C-E122-xxNN
MOO	2201/	الهجار (جورور) الهجار (جورور) الهجار (جورور) الهجار (جورورور) الهجار (جورورورورورورورورورورورورورورورورورورور	<u>SV2L-202N</u>	- <u>SV2A-2040</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	230V	30V	SV2L-202B		SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
Noto	"vv" in the cable	nart numbers represents cable length: SV2C-xx	vv-10vv is a 10m cable	•		

SV2C-xxxx-xxNB is a non-flex, brake motor cable

Note: "xx" in the cable part numbers represents cable length. Clark The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFN is a flex-rated, brake motor cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

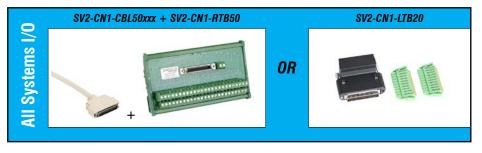
	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			3.96 (312%)	<u>SV2L-204N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N·m)	Intermittent Region		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
		1 (100 ⁶	Continuous Region	SV2L-204B	<u></u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,000 2,700 3,600 Speed (r/min)	<u>3V2L-204b</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
400W Low Inertia System	230V	3 (312 3 (274	3.96 2%) 4.48 4%)	SV2L-204N SV2A-2040 SV2L-204B	SV2A-2040	SV2C-PA18-xxNN	SV2C-E122-xxNN
Inertia		Torque (N·m)	Intermittent Region			SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low		1 (100	1.27 (100%) 0.65 (50%)		SV2C-PB18-xxNB	SV2C-E122-xxNN	
400		(50	3,000 4,400 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
			4.45	SV2L-404N	- SV2A-4040	SV2C-PA18-xxNN	SV2C-E122-xxNN
	460V	Torque (N·m)	3.45 72%) Intermittent Region	3V2L-404IV		SV2C-PA18-xxFN	SV2C-E122-xxFN
	4000	(10	1.27 00%) 0.65 50%) Continuous Region			SV2C-PB18-xxNB	SV2C-E122-xxNN
	(()) in the cold	3,000 3,900 6,000 Speed (r/min)	SV2L-404B		SV2C-PB18-xxFB	SV2C-E122-xxFN	

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



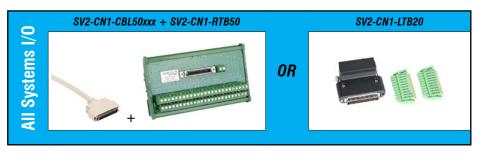
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(3299	7.86 (329%)	<u>SV2L-207N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N·m)	Intermittent Region	<u> </u>	SV2A-2075	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200	2.3 (1009	Continuous Region	SV2L-207B	3V2A-2013	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,300 2,550 3,200 Speed (r/min)	3V2L-2U/D		SV2C-PB18-xxFB	SV2C-E122-xxFN
System		(329	5.63	CV2L 207N	SV2A-2075	SV2C-PA18-xxNN	SV2C-E122-xxNN
750W Low Inertia System	230V	Torque (N·m)	Intermittent Region	<u>SV2L-207N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low	2300	Torq	Continuous Region	SV2L-207B		SV2C-PB18-xxNB	SV2C-E122-xxNN
750		1.1 (50	195 0%) 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
		(338	58 9%) 48	CVOL 407N		SV2C-PA18-xxNN	SV2C-E122-xxNN
	4001	Torque (N·m)	Intermittent Region	SV2L-407N	0)/04 4075	SV2C-PA18-xxFN	SV2C-E122-xxFN
	460V	2 (100	95	SV2L-407B	SV2A-4075	SV2C-PB18-xxNB	SV2C-E122-xxNN
		(53	3,200 4,350 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
Note	"vv" in the cable	nort num	bers represents cable length: SV2C-xx	ovy 10vy io o 10m oobl	•		

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

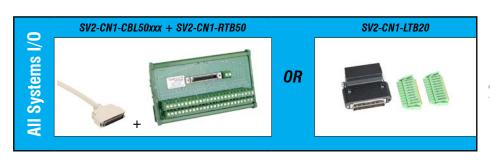
Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
	(E	8.12 (255%)	<u>SV2L-210N</u>		SV2C-PC16-xxNN	SV2C-E222-xxNN
1201/	Torque (N·r	Intermittent Region		SV2A 2150	SV2C-PC16-xxFN	SV2C-E222-xxFN
1200		Continuous Region	SV2L-210B	<u>3VZA-213U</u>	SV2C-PC16-xxNB	SV2C-E222-xxNN
		1,800 2,800 3,500 Speed (r/min)	<u> </u>		SV2C-PC16-xxFB	SV2C-E222-xxFN
		8.12 (255%)	0)/01 0401		SV2C-PC16-xxNN	SV2C-E222-xxNN
230V	ue (N·m)	Intermittent Region	372E-21014	SV2A-2150	SV2C-PC16-xxFN	SV2C-E222-xxFN
	Torq	3.18 (100%) Continuous Region	<u>SV2L-210B</u>		SV2C-PC16-xxNB	SV2C-E222-xxNN
		1.91 3,000 3,300 5,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN
		9.54 (300%)		SV2A-4150	SV2C-PC16-xxNN	SV2C-E222-xxNN
4007	que (N·m)	Intermittent Region	SV2L-410IN		SV2C-PC16-xxFN	SV2C-E222-xxFN
46UV	P	3.18 (100%) 1.91 (60%) Continuous Region 3,000 5,000 Speed (r/min)	SV2L-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
					SV2C-PC16-xxFB	SV2C-E222-xxFN
	120V 230V 460V	120V 230V 120V 120V 120V 120V 120V 120V 120V 12	230V 2460V 255% Continuous Region Continuous Region Continuous Region Continuous Region Speed (r/min) Continuous Region Continuous Region Speed (r/min) Continuous Region Speed (r/min)	120V Sv2L-210N Sv2L-210N	120V	120V

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector **Online**



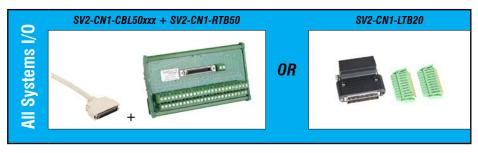
SureServo2 AC servo drive, motor, and cable combinations, continued

		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
	(:	14.32 (300%)	SV2M-210N		SV2C-PC12-xxNN	SV2C-E222-xxNN
120V	orque (N·m)	Intermittent Begins		SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
1200	-	4.77 (100%) Continuous Region	SV/2M-210B	<u> </u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
		700 1,550 2,000 Speed (r/min)	<u> 342IVI-210D</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
	14,3. (300%	14,32 (300%)	SV2M-210N	SV2A-2150	SV2C-PC12-xxNN	SV2C-E222-xxNN
2201/	orque (N·m)	Intermittent Region			SV2C-PC12-xxFN	SV2C-E222-xxFN
230V	(100	1.77 1.77 1.79%) Continuous Region	SV2M-210B		SV2C-PC12-xxNB	SV2C-E222-xxNN
		3,20 2,000 3,000 Speed (r/min)			SV2C-PC12-xxFB	SV2C-E222-xxFN
	Torque (N·m)	14.32 (300%)	SV2M-410N	SV2A-4150	SV2C-PC16-xxNN	SV2C-E222-xxNN
4607		Intermittent Region			SV2C-PC16-xxFN	SV2C-E222-xxFN
400V		4.77 (100%) 3.20 (67%) Continuous Region	SV2M-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
		2,000 3,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN
	230V 460V	230V 230V Land (M-M)	230V 14,32	120V 1	120V	120V 120V

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			14.88 (208%)	<u>SV2M-215N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
m _i	120V	Torque (N·m)	7.16 (100%)		SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
1.5 kW Medium Inertia System	1200	F (Continuous Region	SV2M-215B	<u> </u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
m Inert			1,000 1,400 1,800 Speed (r/min)	<u> </u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
Mediu		Torque (N·m)	14.88 (208%)	SV2M-215N	SV2A-2150	SV2C-PC12-xxNN	SV2C-E222-xxNN
1.5 kW	2221		Intermittent Region			SV2C-PC12-xxFN	SV2C-E222-xxFN
	230V		7.16 (100%) Continuous Region	<u>SV2M-215B</u>		SV2C-PC12-xxNB	SV2C-E222-xxNN
			4.60 2.000 2.400 3,000 Speed (r/min)			SV2C-PC12-xxFB	SV2C-E222-xxFN
ystem		18.1 (253%)			SV2C-PC16-xxNN	SV2C-E222-xxNN	
nertia S	460V	Torque (N·m)	(E 支) Intermittent Region	SV2L-415N	CV/2A 44E0	SV2C-PC16-xxFN	SV2C-E222-xxFN
1.5 kW Low Inertia System	40 0V	Torq	7.16 (100%) 4.77 (67%) Continuous Region		SV2A-4150	SV2C-PC16-xxNB	SV2C-E222-xxNN
			2,000 3,000 Speed (r/min)	SV2L-415B		SV2C-PC16-xxFB	SV2C-E222-xxFN

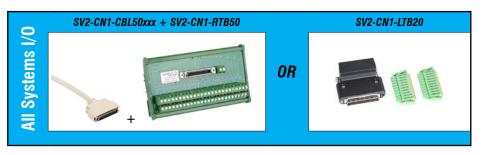
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable. The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



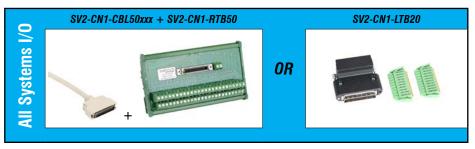
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		24.54 (257%)	SV2M-220N		SV2C-PD12-xxNN	SV2C-E222-xxNN
m.	120V	Intermittent Region	OVZIWIZZON	SV2A-2200	SV2C-PD12-xxFN	SV2C-E222-xxFN
2.0 kW Medium Inertia System	1200	9.55 (100%) Continuous Region	SV2M-220B	<u> </u>	SV2C-PD12-xxNB	SV2C-E222-xxNN
m Inerti		800 1,500 1,950 Speed (r/min)	OVZIWI-ZZOD		SV2C-PD12-xxFB	SV2C-E222-xxFN
Mediu		24.54 (257%)	SV2M-220N	SV2A-2200	SV2C-PD12-xxNN	SV2C-E222-xxNN
2.0 kW	230V	Intermittent Region 9,55 (100%)	<u> </u>		SV2C-PD12-xxFN	SV2C-E222-xxFN
		9,55 (100%) Continuous Region	<u>SV2M-220B</u>		SV2C-PD12-xxNB	SV2C-E222-xxNN
		6.40 2,000 2,200 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		28.65 (300%)	SV2L-420N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Intermittent Region	SVZL-4ZUN	SV2A-4200	SV2C-PC16-xxFN	SV2C-E222-xxFN
2.0 kW Low Inertia System	400V	9.55 (100%) (67%) Continuous Region Speed (r/min) Speed (r/min)	01/01/4005	SV2A-4200	SV2C-PC16-xxNB	SV2C-E222-xxNN
2.0 KM			SVZL-420B		SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable
SV2C-xxxx-xxNN is a flex-rated, non-brake cable
SV2C-xxxx-xxNB is a non-flex, brake motor cable
SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

n	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
a Systen		48.29 (275%)	CVOM OZONI		SV2C-PD12-xxNN	SV2C-E222-xxNN
3.0 kW Medium Inertia System	230V	Intermittent Region 17.55 (100%)	<u>SV2M-230N</u>	SV2A-2300	SV2C-PD12-xxFN	SV2C-E222-xxFN
N Mediu	2300	17.55 (100%) 10.00 (57%) 9.55 (54%) Continuous Region	<u>SV2M-230B</u>		SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 KI		1,700 1,800 3,000 Speed (r/min)	<u>SV2M-230B</u>		SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		49.38 (259%) (EL.) Intermittent Region	SV2H-430N	SV2A-4300	SV2C-PD12-xxNN	SV2C-E222-xxNN
nertia S	460V				SV2C-PD12-xxFN	SV2C-E222-xxFN
3.0 kW High Inertia System	4000	9.00 (47%) Continuous Region	SV2H-430B		SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 KI		1,500 1,800 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN

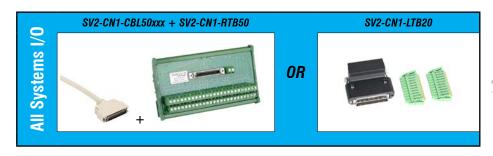
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		71.62 (250%)	SV2H-245N		SV2C-PD08-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	<u> </u>		SV2C-PD08-xxFN	SV2C-E222-xxFN
System	2007	28.65 (100%) 14.33 (50%) Continuous Region	SV2H-245B	<u>SV2A-2550</u>	SV2C-PD08-xxNB	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN
4.5 kW High Inertia System		64.61 (226%)	SV2H-445N		SV2C-PD08-xxNN	SV2C-E222-xxNN
4.5	460V	Intermittent Region		SV2A-4550	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	14.33 (50%) Continuous Region	SV2H-445B	3V2A-4330	SV2C-PD08-xxNB	SV2C-E222-xxNN
		1,500 1,700 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN

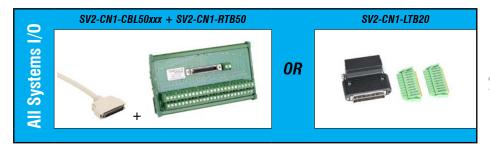
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





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SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		87.53 (250%)	SV2H-255N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region 35.01 (100%)	<u> </u>	SV2A-2550	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2300	35.01 (100%) 17.51 (50%) Continuous Region	C//2H 2EED		SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	SV2H-255B		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
5.5 kW High Inertia System		73.48 (210%)	SV2H-455N		SV2C-PD08-xxNN	SV2C-E222-xxNN
5.5	460V	Intermittent Region	3V211-433IV	SV2A-4550	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	19.1 (55%) 17.51 (50%) Continuous Region	SV2H-455B	SV2A-4550	SV2C-PD08-xxNN	SV2C-E222-xxNN
		1,500 1,900 3,000 Speed (r/min)			SV2C-PD08-xxFN	SV2C-E222-xxFN

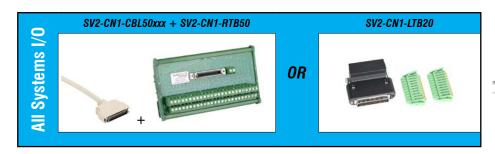
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





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SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(119.36 (250%)	0,401,0771		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Torque (N·m)	Intermittent Region	<u>SV2H-275N</u>	<u>SV2A-2750</u>	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	230V	Tor	47.74 (100%) 23.87 (50%) Continuous Region	SV2H-275B		SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia			1,500 3,000 Speed (r/min)	<u> </u>		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
7.5 kW High Inertia System			93.71	0)/01/4751	- SV2A-4750	SV2C-PD08-xxNN	SV2C-E222-xxNN
7.5	460V	Torque (N·m)	Intermittent Region 47.74 100%	SV2H-475N		SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000		20.0 2%) Continuous Region		3V2N-4730	SV2C-PD08-xxNN	SV2C-E222-xxNN
			1,500 2,000 3,000 Speed (r/min)	SV2H-475B		SV2C-PD08-xxFN	SV2C-E222-xxFN

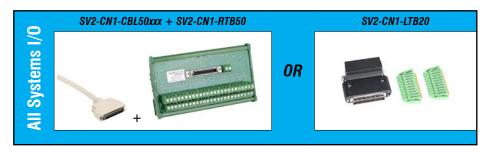
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



SureServo2 AC servo drive, motor, and cable combinations, continued

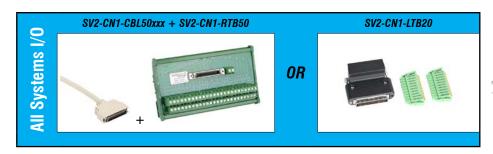
	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(2	175.0 250%)		<u>SV2H-2B0N</u>		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Torque (N·m)		Intermittent Region	SVZH-ZDUN	0101.050	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	230V	Torqu	70.0 100%) 52.5 (75%)	Continuous Region	SV2H-2B0B	<u>SV2A-2F00</u>	SV2C-PF06-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
11.0 kW High Inertia System				1,500 2,000 Speed (r/min)	372,12505		SV2C-PF06-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN
kW High		(2	175.0 250%)		SV2H-4B0N	SV2A-4F00	SV2C-PF08-xxNN	SV2C-E222-xxNN
11.0	460V	Torque (N·m)	70.0	Intermittent Region	SVZH-4DUN		SV2C-PF08-xxFN	SV2C-E222-xxFN
	400V	. (1	70.0 100%) 52.5 (75%)	Continuous Region	SV2H-4B0B	3V2A-41 00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
				1,500 2,000 Speed (r/min)	37211-4000		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online

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SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		224.0 (235%)	<u>SV2H-2F0N</u>		SV2C-PF04-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	<u> 3v2n-2run</u>	- <u>SV2A-2F00</u>	SV2C-PF04-xxFN	SV2C-E222-xxFN
System	2307	95.4 (100%) 71.6 (75%) Continuous Region	<u>SV2H-2F0B</u>		SV2C-PF04-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
15.0 kW High Inertia System		1,500 2,000 Speed (r/min)			SV2C-PF04-xxFB and SV2C-B120-xxFB	SV2C-E222-xxFN
kW High		224.0 (235%)	SV2H-4F0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
15.0	460V	Intermittent Region	37211-41 014	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	400 V	95.4 (100%) 71.6 (75%) Continuous Region		5V2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
		1,500 2,000 Speed (r/min)	SV2H-4F0B		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

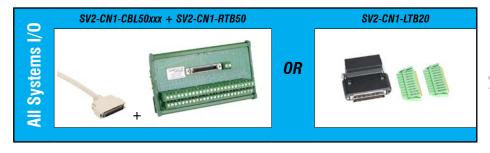
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



Servo drive overview

Charge

LED is lit when DC bus is energized (may take several seconds for power to dissipate after incoming power is removed)

Control Power Terminal

220VAC drives: control power = 120 or 220 VAC single phase.

460VAC drives: control power = 24VDC

Main Power Terminal

- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW

Regenerative Resistor Terminal

- When the internal regenerative resistor is used, the P3 and D terminal are connected together while the P3 and C connection is left open.
- 2. When an external regenerative resistor is used, it is connected across the P3 and C terminals while the P3 and D connection is left open. See the user manual for recommended resistance and power requirements for each system.

Motor Output Terminal

The servo motor power cable is connected to U, V and W. Use our factory made and tested cables available in 3, 5, 10, or 20 meter lengths for easy and trouble free connection.

LED Display

The LED display has 5 full digits and is used to indicate servo status and alarms

Safe Torque Off (STO) Connector Port

erminal ower to U,

Ground Terminals



High Density DB15 Connector

CN5: Auxiliary/Secondary Encoder input. Used for applications requiring Full Closed Loop, Linear Measurement, etc.

Keypad

Five Function keys:

- MODE: Press to change mode
- SHIFT: Press to change parameter group or move cursor left
- UP: Press to increase values
- DOWN: Press to decrease values
- SET: Press to enter value

USB Connector

Used to connect a PC for configuration with SureServo2 Pro software

Serial Communication Interface

RJ45 connectors for RS485 Modbus communication between drives and controllers. Modbus RTU/ ASCII protocol. Use our factorymade cables for easy connection to the PC or the host controller.

I/O Interface

50-pin connector for interfacing the host controller and other types of I/O signals.

- CBL50 + RTB50 = Cable and remote DIN-rail mount module. All I/O pins available.
- LTB20 = Mounted and wired directly at CN1. Most commonly used pins available.
- Command inputs:
 Pulse and Direction
 Encoder Follower
 Analog Velocity/Torque
- (10) Digital Inputs
- (6) Digital Outputs
- (2) Analog Monitors
- Encoder Output (scalable)

A+, A-, B+, B-, Z+, Z-

Encoder Interface

Connector for interfacing the servo motor encoder.

Use our factory-made and tested cables available in 3, 5, 10, or 20 meter lengths for easy and trouble free connection.

SureServo2 systems run "out-of-the-box"... but may be reconfigured for many applications!

The SureServo2 drives are fully digital and include over 400 programmable parameters. For convenience, the parameters are grouped into five categories:

- 1. Monitor parameters
- 2. Basic parameters
- 3. Extended parameters
- 4. Communication parameters
- 5. Diagnostic and analog parameters
- 6. Motion control parameters
- 7. PATH definition parameters

All parameters have commonly used default values which allow you to operate the SureServo2 system "out-of-the-box". However, the programmability and large variety of parameters make the SureServo2 systems suitable for a very broad range of applications, including almost all types of general purpose industrial machinery such as assembly, test, packaging, machine tool, and robotics.

The SureServo2 Pro configuration software has Parameter Wizards to quickly and easily guide you through the most common setup routines.



230V Servo drive specifications

		SureS	ervo2 230	OV Drive S	Specificat	ions				
	Model	SV2A-2040	SV2A-2075	SV2A-2150	SV2A-2200	SV2A-2300	SV2A-2550	SV2A-2750	SV2A-2F00	
	Price	\$421.00	\$525.00	\$560.00	\$658.00	\$726.00	\$920.00	\$1,075.00	\$1,405.00	
	Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
	Power Rating	400W	750W	1.5 kW	2kW	3kW	5.5 kW	7.5 kW	15kW	
	Input Voltage	Singl	Single-phase 100–120 VAC, -15% to +10% Single-phase 200–230 VAC, -15% to +10% Three-phase 200–230 VAC, -15% to +10%				e-phase 200–23	0 VAC, -15% to -	+10%	
	Input Current 200–230 VAC 3-phase [Amps] rms	2.76	5.09	8.09	11.36	14.52	27.06	37.33	69.95	
	Input Current 100–120 VAC 1-phase [Amps] rms	3.98	7.73	12.56	18.03	_	_	-	-	
Power	Input Current 200–230 VAC 1-phase [Amps] rms	4.69	8.71	14.82	20.83	-	-	-	-	
	Continuous Output Current [Amps] rms	2.60	5.10	8.33	13.40	17.92	41.33	49.04	78	
	Max. Instantaneous Output Current [Amps] rms	8.56	15.43	20.16	40.57	55.93	91.44	127.46	162.04	
	Main Circuit Inrush Current [Amps]	1.44	1.40	1.44	4.64	4.42	9.55	28.68	32.0	
	Control Circuit Inrush Current [Amps]	37.0	37.40	39.80	32.40	36.40	32.80	40.0	37.0	
	Cooling Method	Air Conv. Cooling Fan Cooling								
	Encoder Resolution	24-bit (16777216 p/rev)								
	Main Circuit Control				SVPWN	1 control				
	Control Mode					I / Auto	I			
	Regenerative Resistor		Built-in (ext	ernal options als				External (optiona	1)	
	Pulse Type			Pulse + Dire	ction, CCW pulse	e + CW pulse, Al	B Quadrature			
Position Control Mode	Max. Input Pulse Frequency				CCW pulse + C\ 3 Quadrature: sir	ction: 4 Mpps; N pulse: 4 Mpps ngle-phase 4 Mp or: 200 Kpps				
n Co	Command Source				External pulse /	Internal registers	3			
ositio	Smoothing Method				Low-pass and	d P-curve filter				
٩	Torque Limit				Paramete	er settings				
	Feed Forward Compensation				Paramete	er settings				



230V Servo drive specifications (continued)

		Su	reServo2	230V Dr	ive Speci	ications (Continued				
		Model	SV2A-2040	SV2A-2075	SV2A-2150	SV2A-2200	SV2A-2300	SV2A-2550	SV2A-2750	SV2A-2F00	
		Voltage Range	±10VDC								
	Analog	Resolution				15	-bit				
	Command Input	Input Impedance				1M	ΙΩ				
a,		Time Constant		,		25	μs				
Mod		Speed Control Range1				1:6	6000				
ntrol		Command Source			Exteri	nal analog comm	and / Internal re	gisters			
Speed Control Mode		Smoothing Method				Low-pass and	S-curve filter				
Spe		Torque Limit				Parameter settin	gs / Analog inpu	t			
		Bandwidth				Maximum 3.1 kl	Hz (closed-loop)				
			±0.01% at 0% to 100% load fluctuation								
	S	peed Calibration Ratio2	±0.01% at ±10% power fluctuation								
		W-# B	±0.01% at 0°C to 50°C ambient temperature fluctuation								
a Je	Analog	Voltage Range		±10VDC							
Torque Control Mode	Command Input	Input Impedance	1ΜΩ								
ontro	,	Time Constant				25µs					
ne C		Command Source			Exteri	nal analog comm	and / Internal re	gisters			
Torq		Smoothing Method				Low-pa	iss filter				
		Speed Limit				Parameter settin	gs / Analog inpu	t			
		Analog Monitor Output			gnal can be set l	•		,,			
Digital Input/Output		Input	Servo on, Fault reset, Gain switch, Pulse clear, Zero speed clamping, Command input reverse control, Internal position command trigger, Torque limit, Speed limit, Internal position command selection, Motor stop, Speed command selection, Speed / position mode switching, Speed / torque mode switching, Torque / position mode switching, PT / PR command switching, motor override, Forward / reverse limit, Original point, Forward / reverse operation torque limit, Homing activated, E-Cam engage, Forward / reverse JOG input, Event trigger, E-Gear N selection, Pulse input prohibition								
tal In						A, B, Z line					
Digi		Output	Servo ready, Servo on, Zero speed detection, Target speed reached, Target position reached, Torque limiting, Servo alarm, Magnetic brake control, Homing completed, Early warning for overload, Servo warning, Position command overflows, Software limit (reverse direction), Software limit (forward direction), Internal position command completed, Capture procedure completed, Servo procedure completed, Master position area of E-Cam.								

^{1 -} Within the rated load, the speed ratio is: the minimum speed (smooth operation) / rated speed.

^{2 -} Within the rated speed, the speed calibration ratio is: (rotational speed with no load - rotational speed with full load) / rated speed.

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AC Servo Drive Specifications

230V Servo drive specifications (continued)

	Sui	reServo2	230V Dri	ve Specif	ications C	ontinued				
	Model	SV2A-2040	SV2A-2075	SV2A-2150	SV2A-2200	SV2A-2300	SV2A-2550	SV2A-2750	SV2A-2F00	
	Protection Function	STO (Category 3 / SIL 2), Overcurrent, Overvoltage, Undervoltage, Overheat, Regeneration error, Overload, Excessive speed deviation, Excessive position deviation, Encoder error, Adjustment error, Emergency stop, Forward / reverse limit error, Excessive deviation of full-closed loop control, Serial communication error, RST leak phase, Serial communication timeout, Short-circuit protection for terminals U, V, W and CN1, CN2, CN3								
	Communication Interface		R	S-485 / Modbus	RTU / USB / Op	tional EtherNet/l	IP or Modbus TC	;P		
	Weight [kg (lb)]	0.92 (2.03)	1.3 (2.87)	1.3 (2.87)	2.7 (5.95)	2.7 (5.95)	4.9 (10.8)	7.2 (15.9)	13 (29)	
	Installation Site		Indoors (avoid direct sunlight), no corrosive vapor (avoid fumes, flammable gases, and dust)							
	Altitude	Altitude 1000m or lower above sea level								
	Atmospheric Pressure				86kPa -	106kPa				
Environment	Operating Temperature		((If operating temp	0°C to perature is above		poling is required	l)		
nvirc	Storage Temperature				-20°C f	to 65°C				
E	Humidity			U	nder 0 - 90% RH	I (non-condensin	ng)			
	Vibration		(9.80665 m/s2 (1	G) less than 20	Hz, 5.88 m/s2 (0	.6 G) 20 to 50 H	Z		
	IP Rating				IP	20				
	Power System				TN sys	stem3,4				
	Approvals			IEC/EN	61800-5-1, UL 5	08C, TUV (for S	TO), CE			

^{3 -} TN system: the neutral point of the power system connects directly to the ground. The exposed metal components connect to the ground through the protective ground conductor.

^{4 -} Use a single-phase three-wire power system for the single-phase power model.



460V Servo drive specifications

		SureS	ervo2 460	OV Drive S	Specificat	ions				
	Model	SV2A-4040	SV2A-4075	SV2A-4150	SV2A-4200	SV2A-4300	SV2A-4550	SV2A-4750	SV2A-4F00	
	Price	\$506.00	\$534.00	\$732.00	\$713.00	\$803.00	\$920.00	\$1,155.00	\$1,499.00	
	Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
	Power Rating	400W	750W	1.5 kW	2kW	3kW	5.5 kW	7.5 kW	15kW	
	Input Voltage			Т	hree-phase 380	-480 VAC, ±10°	%	1	,	
	Input Current 380–480 VAC 3-phase [Amps] rms	1.49	2.31	4.98	6.29	9.92	16.83	23.06	36.65	
	Continuous Output Current [Amps] rms	1.6	2.91	6.05	6.7	12.6	23.6	28.7	40.5	
Power	Max. Instantaneous Output Current [Amps] rms	5.4	9.7	13.94	21.35	30.46	47.5	57.69	95.3	
	Control Power Input Current	1.17	1.17	1.17	1.35	1.63	1.91	1.91	4.26	
	Main Circuit Inrush Current [Amps]	5.6	5.6	5.6	12.5	12.5	12.5	12.5	12.5	
	Control Circuit Inrush Current [Amps]	5	5	5	4.8	4.8	5.5	5.5	6	
	Control Circuit Voltage	24VDC								
	Cooling Method	Fan cooling								
	Encoder Resolution	24-bit (16777216 p/rev)								
	Main Circuit Control	SVPWM control								
	Control Mode	Manual/Auto								
	Regenerative Resistor	Built-in (ext	Built-in (external options also available) External (optional)							
	Pulse Type			Pulse + Directi	on, CCW pulse -	CW pulse, A ph	nase + B phase			
Position Control Mode	Max. Input Pulse Frequency			A ph	Pulse + Direct CCW pulse + CV ase + B phase: s Open collect	V pulse: 4 Mpps single-phase 4 N	; lpps;			
ontro	Command Source				External pulse /	Internal registers	3			
ion C	Smoothing Method			Low-pa	ss, moving-aver	aging, and S-cur	ve filter			
Posit	E-Gear Ratio					(1/4 < N/M < 262 M: 1–21474836				
	Torque Limit				Paramete	er settings				
	Feed Forward Compensation				Paramete	er settings				



460V Servo drive specifications (continued)

		Su	reServo2	460V Dr	ive Speci	fications (Continued					
		Model	SV2A-4040	SV2A-4075	SV2A-4150	SV2A-4200	SV2A-4300	SV2A-4550	SV2A-4750	SV2A-4F00		
		Voltage Range				±10	VDC			,		
	Analog	Resolution				12	-bit					
	Command Input	Input Impedance	1ΜΩ									
a,		Time Constant		-		25	iµs					
Mode		Speed Control Range1				1:6	6000					
ntrol		Command Source			Exter	nal analog comm	and / Internal re	gisters				
Speed Control Mode		Smoothing Method				Low-pass and	d S-curve filter					
Spee		Torque Limit				Parameter settin	igs / Analog inpu	t				
		Bandwidth				Maximum 3.1 k	Hz (closed-loop)					
					±0	.01% at 0% to 10	00% load fluctua	tion				
	S	peed Calibration Ratio2	±0.01% at ±10% power fluctuation									
			±0.01% at 0°C to 50°C ambient temperature fluctuation									
وي ا	Analog	Voltage Range	±10VDC									
Torque Control Mode	Command Input	Input Impedance	1ΜΩ									
ontro		Time Constant				25	iµs					
ne Co		Command Source			Exter	nal analog comm	and / Internal re	gisters				
Torq		Smoothing Method				Low-pa	ass filter					
		Speed Limit				Parameter settin	igs / Analog inpu	t				
		Analog Monitor Output		Monitor si	gnal can be set	by parameters (v	oltage output rar	nge: ±8V); resolu	ution:10-bit			
Digital Input/Output		Input	Servo on, Fault reset, Gain switch, Pulse clear, Zero speed clamping, Command input reverse control, Internal position command trigger, Torque limit, Speed limit, Internal position command selection, Motor stop, Speed command selection, Speed / position mode switching, Speed / torque mode switching, Torque / position mode switching, PT / PR command switching, Emergency Stop, Forward / reverse limit, Original point, Forward / reverse operation torque limit, Homing activated, E-Cam engage, Forward / reverse JOG input, Event trigger, E-Gear N selection, Pulse input prohibition									
tal In						A, B, Z line	driver output					
Digit		Output	Magnetic brak	A, B, Z line driver output Servo ready, Servo on, Zero speed detection, Target speed reached, Target position reached, Torque limiting, Servo alarm, Magnetic brake control, Homing completed, Early warning for overload, Servo warning, Position command overflows, Software limit (reverse direction), Software limit (forward direction), Internal position command completed, Capture procedure completed, Servo procedure completed, Master position area of E-Cam.								

^{1 -} Within the rated load, the speed ratio is: the minimum speed (smooth operation) / rated speed.

^{2 -} Within the rated speed, the speed calibration ratio is: (rotational speed with no load - rotational speed with full load) / rated speed.



460V Servo drive specifications (continued)

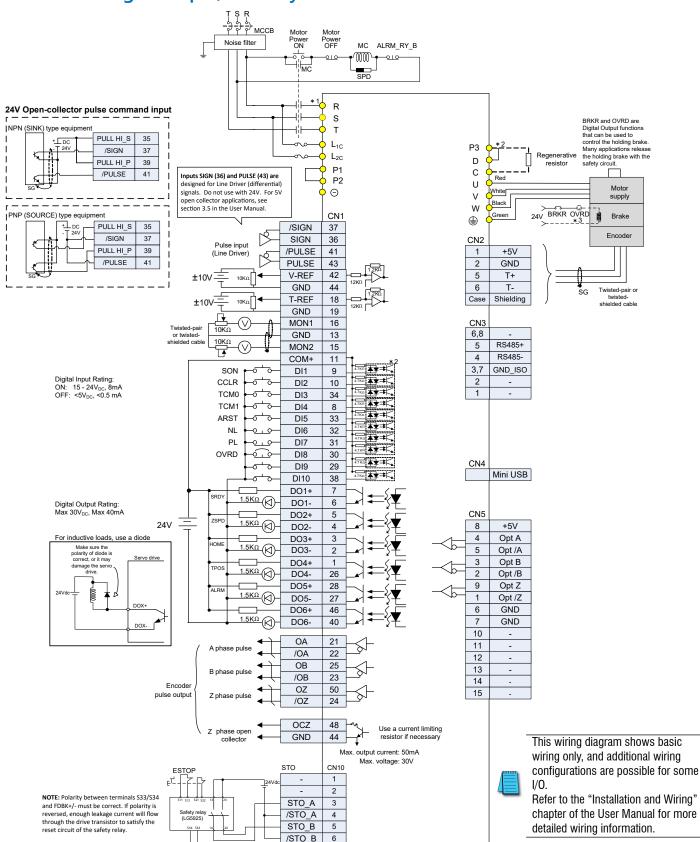
	SureServo2 460V Drive Specifications Continued											
	Model	SV2A-4040	SV2A-4075	SV2A-4150	SV2A-4200	SV2A-4300	SV2A-4550	SV2A-4750	SV2A-4F00			
	Protection Function	Overcurrent, Overvoltage, Undervoltage, Overheat, Regeneration error, Overload, Excessive speed deviation, Excessive position deviation, Encoder error, Adjustment error, Emergency stop, Forward / reverse limit error, Excessive deviation of full-closed loop control, Serial communication error, RST leak phase, Serial communication timeout, Short-circuit protection for terminals U, V, W and CN1, CN2, CN3										
	Communication Interface				RS-48	5 / USB						
	Weight [kg (lb)]	5.96 [13.1]	5.96 [13.1]	5.96 [13.1]	9.71 [21.4]	9.71 [21.4]	12.14 [26.8]	12.14 [26.8]	15.01 [33.1]			
	Installation Site		Indoors (avoid direct sunlight), no corrosive vapor (avoid fumes, flammable gases, and dust)									
	Altitude	1000m or lower above sea level										
	Atmospheric Pressure	86kPa – 106kPa										
Environment	Operating Temperature		(If operating temp	0°C to 55°C [perature is above		ooling is required	l)				
nviro	Storage Temperature				-20°C to 65°C	[-4°F to 149°F]						
E	Humidity				Under 90% RH (non-condensing)					
	Vibration		Ç	9.80665 m/s2 (1	G) less than 20	Hz, 5.88 m/s2 (0	.6 G) 20 to 50 H	Z				
	IP Rating				IP	20						
	Power System				TN sys	stem ^{3,4}						
	Approvals			IEC/EN	61800-5-1, UL 5	08C, TUV (for S	TO), CE					

^{3 -} TN system: the neutral point of the power system connects directly to the ground. The exposed metal components connect to the ground through the protective ground conductor.

^{4 -} Use a single-phase three-wire power system for the single-phase power model.

AC Servo System Wiring

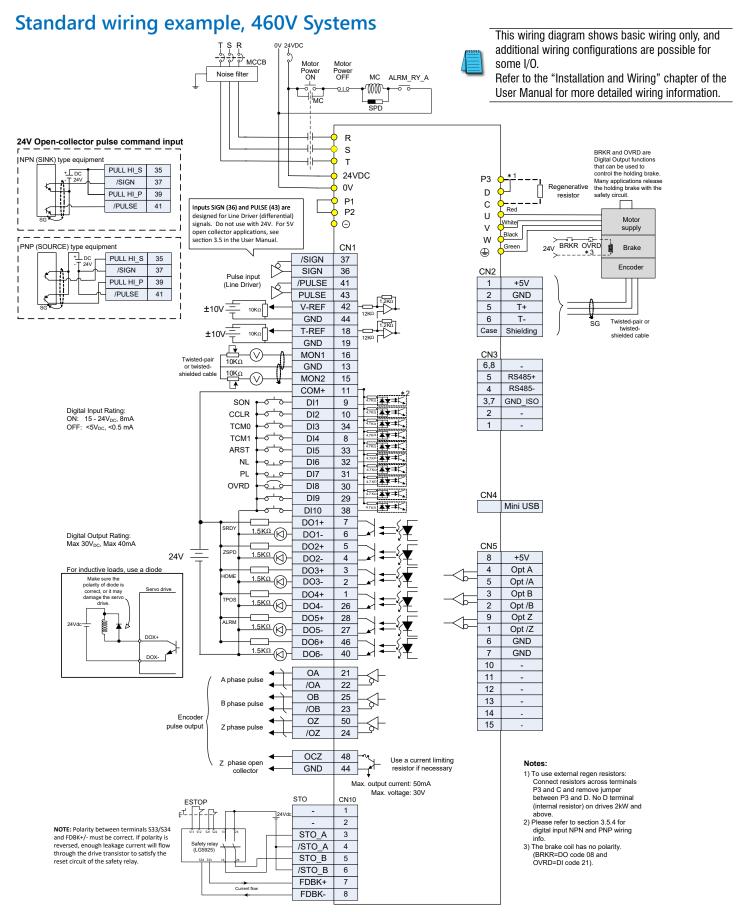
Standard wiring example, 230V Systems



FDBK+

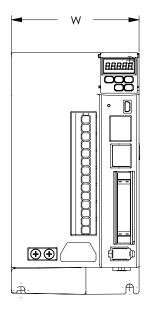
7

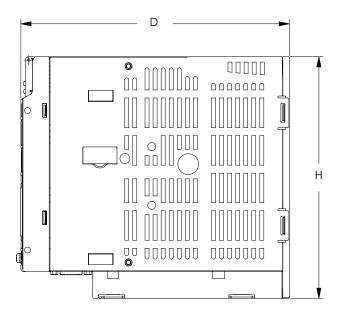
AC Servo System Wiring



AC Servo System Dimensions

Servo drive dimensions





S	ureServo2	Drive Dime	nsions	
Model	Drawing Link	W mm [inches]	D mm [inches]	H mm [inches]
<u>SV2A-2040</u>	<u>PDF</u>	35 [1.38]	170 [6.69]	170 [6.69]
SV2A-2075	<u>PDF</u>	50 [1.97]	180 [7.09]	180 [7.09]
<u>SV2A-2150</u>	<u>PDF</u>	50 [1.97]	180 [7.09]	180 [7.09]
SV2A-2200	<u>PDF</u>	95 [3.74]	200 [7.87]	180 [7.09]
SV2A-2300	PDF	95 [3.74]	200 [7.87]	180 [7.09]
<u>SV2A-2550</u>	<u>PDF</u>	120 [4.72]	206 [8.12]	273 [10.75]
<u>SV2A-2750</u>	PDF	141 [5.56]	226 [8.90]	312 [12.28]
<u>SV2A-2F00</u>	<u>PDF</u>	186 [7.32]	281 [11.08]	390 [15.35]
<u>SV2A-4040</u>	PDF	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4075</u>	<u>PDF</u>	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4150</u>	PDF	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4200</u>	<u>PDF</u>	110 [4.33]	200.8 [7.9]	260 [10.24]
SV2A-4300	<u>PDF</u>	110 [4.33]	200.8 [7.9]	260 [10.24]
<u>SV2A-4550</u>	<u>PDF</u>	110 [4.33]	200.8 [7.9]	260 [10.24]
SV2A-4750	<u>PDF</u>	120 [4.72]	206.3 [8.12]	273 [10.75]
<u>SV2A-4F00</u>	<u>PDF</u>	141 [5.55]	225.5 [8.88]	312 [12.28]



For additional dimensions, see the AutomationDirect website or click on the drawing links.



Requires 2" above and below the drive for air flow. For proper air flow clearance, please see section 2.3.1 of the SureServo2 User Manual.



For cabinet depth, add approximately 100mm (4 inches) for CN1 (I/O) and CN2 (encoder) cable bend radius.