1-800-633-0405 Stellar[®] SR55 Full-Featured Soft Starters

Overview

SR55 full-featured solid-state Soft Starters provide many advantages when used instead of electromechanical contactors to control 3-phase AC induction motors. The SR55 Soft Starters are fully digital, and use thyristors in all three motor phases for controlled reduced voltage motor starting and stopping. SR55's have an Automatic Application Setup that fully configures the starter for a specific application with one entry. SR55's also have a built-in internal bypass and patented iERS (intelligent Energy Recovery System) that reduces energy costs when used on lightly loaded and oversized motors.

Features

- 17-477A @ 200-480VAC
- 24VDC, 110VAC, or 230VAC selectable control voltage
- Internally bypassed during run
- Full three-phase motor control
- Built-in SCR failure protection
- Full motor overload protection
- · Full data logging (fault records, motor current, operational status, etc.)
- · Fully programmable
- · Easily and separately adjustable motor start and stop times
- iERS (intelligent Energy Recovery System) saves energy on lightly-loaded motors
- · Can be connected 'in-the-delta', allowing use of a smaller Soft Starter (no iERS optimizing with in-delta connections)
- · Can be used for motor reversing (with external contactors)
- · Suitable for a wide variety of motor loads
- Touchscreen with easy-to-navigate menu structure and quick automatic application set up
- Can be used with local or remote control
- Integrated Modbus RTU, or optional Modbus TCP or EtherNet/IP communication
- · Optional remote touchscreen available
- Programmable analog I/O, digital inputs, and relay outputs for remote control
- Fault record history of last 10 trips (using the download fault log will give faults and running data for the life of the SR55)
- · IP20, panel mount with optional finger guards for frame sizes 1 and 2 soft starters
- Two-year warranty
- CE, ETL (CSA C22.2 No.14 and UL 508), REACH, RoHS
- Auto Reset Feature available

Advantages

Mechanical Advantages

- Smaller physical size than equivalent SR44 models (even with the built-in bypass contactors)
- Smooth acceleration; reduced mechanical shock and starting stress
- Extend lifespan of mechanical drive-train components
- Fluid couplings and some clutches can be eliminated

Electrical Advantages

- Reduced starting currents and spikes More motors or larger motors can be
- started from lower-capacity power sources
- · Allows motors to be started more frequently

Economic Advantages

- Lower overall costs for new installations
- Bypass relays built in
- · Reduced maintenance and replacement of mechanical drive-train components
- · Reduced starting current lowers demand charges
- iERS (intelligent Energy Recovery System) reduces electrical power costs
- Automatic Application setup feature speeds installation by configuring the SR55 for a specific application with one setting

Optional Accessories

- EtherNet/IP communication module
- Modbus TCP communication module
- · Modbus serial communication splitter
- RJ12 to RJ45 adapter
- Power terminal IP20 finger guards
- Remote touchscreen
- Replacement touchscreen
- Replacement cooling fans

Applications

- General purpose applications where traditional across-the-line starting or wye-delta starting would typically be appropriate
- Applications with oversized or lightly loaded motors (iERS reduces energy usage)
- · Applications requiring lower inrush currents



1-800-633-0405

Stellar® SR55 Full-Featured Soft Starters

SR55 Soft Starter Technical Specifications

SR55 S	eries Fu	ull-Featu	red Soft	Starter	s – 17/	A-96A *			
Modei	SR55-017	SR55-021	SR55-027	SR55-034	SR55-040	SR55-052	SR55-065	SR55-077	SR55-096
Frame Size					1				
Price	\$1,066.00	\$1,114.00	\$1,183.00	\$1,221.00	\$1,317.00	\$1,610.00	\$1,715.00	\$1,917.00	\$1,964.00
* Rated Current le (A)	17	21	27	34	40	52	65	77	96
Rated Operational Voltage				20	0VAC to 480V	AC		-	
* Motor Rating @ 200V (hp)	3	5	7.5	10	10	15	20	20	30
* Motor Rating @ 208V (hp)	5	5	7.5	10	10	15	20	25	30
* Motor Rating @ 230V (hp)	5	5	7.5	10	10	15	20	25	30
* Motor Rating @ 460V (hp)	10	15	20	25	30	40	50	60	75
Trip Class				prog	rammable 10	to 30			
Index Rating [per IEC 60947-4-2]				le: AC	-53a: 3.5–17	90–5			
Impulse Withstand Voltage	4kV								
Insulation Voltage Rating					480V			-	
Short Circuit Current Rating (type 1) (kA)				5				1	0
Control Power Consumption			60W inru	sh to latch inte	ernal bypass r	elays; 4W ste	ady state		
Control Voltage Range			24\	/DC +10%-15	% or 110–23	0VAC +10%-1	5%		
Control Fuse (external)					4A				
Control Inputs	(3)) DI @ 24VDC	, 110VAC, or 2	230VAC; (1) F	TC Thermisto	r; (1) AI @ 0-	-10VDC 10mA	max or 4–20r	nA
Control Outputs	(3) N/O	relay and (1) I	N/C relay @ 3	0VDC 0.5A / 2	30VAC 1A res	istive; (1) AO	@ 0-10VDC	10mA max or	4–20mA
** Start Time Setting Range (s)					1 to 300				
Start Voltage Setting Range (%)					10 to 100				
** Stop Time Setting Range (s)					0 to 300				
Ambient Operating Temperature	-20°C [-4	4°F] to 50°C [122°F] ; above	e 50°C derate	linearly by 4%	of SR55 le pe	er °C to a max	kimum of 60°C	(140°F)
Transportation & Storage Temperature				-20°C to 60°C	C[-4°F to 140°	'F] continuous			
Humidity			max 85% r	ion-condensin	g, not exceed	ing 50% @ 40	°C [104°F]		
Maximum Altitude	1,000m [3,281ft] ; abov	re 1000m dera	te by 1% of S	R55 le per 100	0m (328ft) to a	a maximum alt	itude of 2000m	n (6562ft)
Environmental Rating		Main Circui	it: IP00 (IP20 v		nger guards fo osive gases pe		nly); Control (Circuit: IP20	
Weight (lb [kg])		6.6 [3.0]				7.7	[3.5]		
*** Agency Approvals		CE, CSA	C22.2 No.14	(ETL tested),	ETL 4004274,	REACH, RoH	IS, UL508 (ET	L tested)	

* Refer to Selection Table for deratings by application and overload trip class.

Important: Care must be taken to select the correct SR55 for the application to ensure that the SR55 is not undersized. Refer to Selection Tables

or to online selection tool for deratings by application and overload trip class (https://www.automationdirect.com/selectors/softstarters).

** Start Time and Stop Time define the length of time the soft starter varies the voltage to the motor. While a Variable Frequency Drive (AC Drive) can define motor speed throughout the acceleration and deceleration ramps by varying its output frequency, a soft starter only controls average voltage to the motor and cannot accurately control motor speed. Therefore, motor speed during acceleration and deceleration can vary with load. Example: a conveyor soft starter could have a Start Time of 10s. If the conveyor is empty, the motor may actually reach top speed in 8s. If the conveyor is heavily loaded, the motor may not reach full speed until 10s. For more information, please see the <u>SR55 User Manual</u> - "Appendix B: Soft Starter Application Considerations."

*** To obtain the most current agency approval information, see the Agency Approval Checklist section on the specific part number's web page.

SR55 Soft Starter Technical Specifications

SR55 Seri	es Full-F	eatured	Soft Sta	rters –	124A-47	7A *		
Model	SR55-124	<u>SR55-156</u>	SR55-180	SR55-242	SR55-302	SR55-361	SR55-414	<u>SR55-477</u>
Frame Size		2				3		
Price	\$2,151.00	\$3,039.00	\$3,320.00	\$3,375.00	\$3,618.00	\$4,246.00	\$5,324.00	\$6,087.00
* Rated Current le (A)	124	156	180	242	302	361	414	477
Rated Operational Voltage				200VAC t	o 480VAC			
* Motor Rating @ 200V (hp)	40	50	60	75	100	125	150	150
* Motor Rating @ 208V (hp)	40	50	60	75	100	125	150	150
* Motor Rating @ 230V (hp)	40	60	60	75	100	150	150	150
* Motor Rating @ 460V (hp)	100	125	150	200	250	300	350	400
Trip Class				programma	ble 10 to 30			
Index Rating [per IEC 60947-4-2]	le: A	C-53a: 3.5–17:	90–5		le: A	C-53a: 3.5–17	90–3	
Impulse Withstand Voltage	4kV							
Insulation Voltage Rating				48	0V			
Short Circuit Current Rating (type 1)(kA)		10kA				18kA		
Control Power Consumption		60W inrush to	latch internal by	ypass relays; 4	W steady state)		i; 4W steady ate
Control Voltage Range		24VDC +	-10%-15% or	110-230VAC +	10%-15%		110VAC +	·10%-15%
Control Fuse (external)				4	A			
Control Inputs	(3) DI	@ 24VDC, 110	VAC, or 230VA	C; (1) PTC Th	ermistor; (1) A	0–10VDC	10mA max or 4	–20mA
Control Outputs	(3) N/O rela	y and (1) N/C r	elay @ 30VDC	0.5A / 230VAC	A resistive; ((1) AO @ 0–10	VDC 10mA ma	k or 4–20mA
** Start Time Setting Range (s)				1 to	300			
Start Voltage Setting Range (%)				10 to	o 100			
** Stop Time Setting Range (s)				0 to	300			
Ambient Operating Temperature	-20°C [-4°F]	to 50°C [122°	F] ; above 50°C	c derate linearly	y by 4% of SR5	5 le per °C to a	a maximum of 6	60°C (140°F)
Transportation & Storage Temperature			-20°C	to 60°C [-4°F	to 140°F] conti	nuous		
Humidity		r	nax 85% non-co	ondensing, not	exceeding 50%	@ 40°C [104°	'F]	
Maximum Altitude	1,000m [3,28	31ft] ; above 10	00m derate by	1% of SR55 le	per 100m (328	ft) to a maximu	m altitude of 20	000m (6562ft)
Environmental Rating	Ν	lain Circuit: IP	00 (IP20 with o	otional finger g	uards for sizes	1&2 only); Cor	ntrol Circuit: IP2	.0
Weight (lb [kg])	12.1 [5.5]	14.3	[6.5]		35.3 [16.0]		46.7	[21.2]
*** Agency Approvals	CE, CSA C22	.2 No.14 (ETL	tested), ETL 40	04274, REACH	H, RoHS, UL50	8 (ETL tested)	CE, REA	CH, RoHS

* Refer to Selection Table for deratings by application and overload trip class.

Important: Care must be taken to select the correct SR55 for the application to ensure that the SR55 is not undersized. Refer to Selection Tables

or to online selection tool for deratings by application and overload trip class (https://www.automationdirect.com/selectors/softstarters). ** Start Time and Stop Time define the length of time the soft starter varies the voltage to the motor. While a Variable Frequency Drive (AC Drive) can define motor speed throughout the acceleration and deceleration ramps by varying its output frequency, a soft starter only controls average voltage to the motor and cannot accurately control motor speed. Therefore, motor speed during acceleration and deceleration can vary with load. Example: a conveyor soft starter could have a Start Time of 10s. If the conveyor is empty, the motor may actually reach top speed in 8s. If the conveyor is heavily loaded, the motor may not reach full speed until 10s. For more information, please see the SR55 User Manual - "Appendix B: Soft Starter Application Considerations."

*** To obtain the most current agency approval information, see the Agency Approval Checklist section on the specific part number's web page.

1-800-633-0405

Stellar[®] SR55 Full-Featured Soft Starters

SR55 Energy-Saving iERS Feature

Intelligent Energy Recovery System

iERS is an advanced SR55 feature that can reduce the energy consumed by lightly-loaded (or oversized) motors. iERS matches the power consumption to the load by monitoring and regulating voltage, current, and power factor during the motor starting and running stages. iERS automatically bypasses itself when it is not needed (as the motor approaches full load torque/current), and continues monitoring to re-engage itself as needed (as the required motor torque/current decreases).

In its most basic function, iERS reduces the voltage being fed to the motor when the motor does not need it. While the torque (and therefore current) required by the load stays the same, reducing the voltage to the motor reduces excess magnetizing current inside the motor. For a more detailed explanation of how iERS reduces magnetizing current and saves energy, please see "Chapter 4: Principles of IERS" in the SR55 User Manual.

Many, if not most, AC motor applications are oversized when the motor FLA is compared to actual running current. Oversizing can be due to non-optimal design, but can also occur intentionally: many applications need a larger motor for starting reasons, for available headroom, for future expansion, etc. Other applications may have different motor demands based on loading; think of an "up" escalator. A fully-loaded escalator requires a lot of torque (current), while an empty escalator requires significantly less torque (current) to maintain speed. When the escalator is empty, the motor will not draw as much current as its FLA. When the SR55 senses this reduced torque load, the starter will reduce the voltage to the motor. This reduced voltage results in reduced magnetizing current in the motor (and thereby saves energy). Note that the current required by the load stays the same; only magnetizing current is reduced.



How Much Will iERS Save?

The savings realized by using iERS will vary by application, how heavily the motor is loaded, and the losses internal to the motor. While these factors can be difficult to quantify, the following estimating tools and examples may help predict your potential savings:

Estimating Energy Savings

Basis for estimations:

- 3-phase squirrel cage induction motor, standard type.
- Supply: 380 to 440V, 50Hz.
- Supply voltage > minimum working voltage on motor rating plate.
- · Operation 30% rated nameplate full load.

Energy Sa	Energy Savings Estimations – Table 1												
4-Pole Motor Size kW HP Estimated Savings (% rated kW													
5 7.5	10												
Less than	22.5	30	6.5										
Less than	55	75	3.5										
	110	150	2.5										
More than	110	150	1.5										

Energy Savings Modifying Factors – Table 2									
Motor Poles Motor Slip									
Number of Poles	Add (% kW)	% Slip	Add (% kW)						
2	-0.5	0.5	-0.5						
4	0	2	0						
6	0.5	3.3	0.5						
8	1	5	1						

Examples of estimated savings:

1) 37.5 kW 4-pole motor

From Table 1, use the estimated savings figure for the next higher rating, i.e. 55 kW = 3.5% of full rated kW.

The savings would be approximately $3.5\% \times 37.5 \text{ kW} = 1.3125 \text{ kW}$. Savings % = kW saved / (30% loaded motor kW)

= 1.3125 kW / (30% x 37.5 kW) = 12%.

2) 37.5 kW 2-pole motor

From Table 1, use the estimated savings figure for the next higher rating, i.e. 55 kW = 3.5% of full rated kW. From Table 2, apply the pole-number factor of -0.5 %.

The savings would be approximately (3.5 % - 0.5 %) x 37.5 kW = 1.125 kW.

Savings % = kW saved / (30% loaded motor kW)

= 1.125 kW / (30% x 37.5 kW) = 10%.

Real-world applications:

iERS has been installed in many pump-jack applications (for oil drilling, etc.). The cycle of a pump jack is extreme; for part of the cycle the pump requires near-full torque. In the other part of the cycle, the pump jack is very lightly loaded. In this extreme application, iERS reduced average power consumed by the pump jack (over 30-minute intervals) from 23.99kW down to 19.85kW. This is a 17% reduction in consumed power. Again, this is an extreme example and is not indicative of what a typical application may save.

iERS has been installed on metal grinding equipment. A machine that was retrofitted with an iERS starter had a 75hp motor on a spindle that typically ran at about 20–30% of full load. iERS was able to reduce the energy consumed by this motor by 13–15%.

Stellar® SR55 Full-Featured Soft Starters

SR55 Soft Starter Overcurrent Protection

Customer-supplied external power-circuit isolation devices (contactors, disconnect switches, fusible disconnects, shunt-trip circuit breakers, etc.) and short-circuit protection devices (circuit breakers, fuses, etc.) are required for use with SR55 soft starters.

External Sh	ort-Circ	uit P	rotec	tion F	Requir	ed fo	r SR5	5			
SR55 Model Number (SR55-XXX)			<u>017</u>	<u>021</u>	<u>027</u>	<u>034</u>	<u>040</u>	<u>052</u>	<u>065</u>	<u>077</u>	<u>096</u>
Rated Operational Current	le	(A)	17	21	27	34	40	52	65	77	96
Semiconductor Fuse (class aR) #1	Туре					Bussn Bussn Bussn	n 6,9 URI nann 170 nann 170 nann 170 IBA 20 61	M30xx M31xx M32xx			
	Rating	(A)	100	100	160	160	160	200	200	250	315
Class J High-Speed Current-Limiting Fuse #2	Rating Z1	(A)	30	45	60	70	90	110	125	150	175
Class J Time-Delay Fuse #3	Rating Z2	(A)	30	40	50	60	70	100	125	150	175
UL Listed Inverse Time-Delay Circuit Breaker #3	Rating Z3	(A)	60	60	60	60	60	150	150	250	300
Rated Conditional Short-Circuit Current	lq	(kA)				5				1	0
SR55 Model Number (SR55-XXX)			<u>124</u>	<u>156</u>	<u>180</u>	<u>242</u>	<u>302</u>	<u>361</u>	<u>414</u>	<u>477</u>	-
Rated Operational Current	le	(A)	124	156	180	242	302	361	414	477	
Semiconductor Fuse (class aR) #1	Туре	1	Bussr Bussr Bussr	en 6,9 URI nann 170 nann 170 nann 170 IBA 20 61	M40xx M41xx M42xx	Mersen 6,9 URD 33xx Bussmann 170M60xx Bussmann 170M61xx Bussmann 170M62xx SIBA 20 63xx					
	Rating	(A)	400	550	550	700	800	900	1000	1100	
Class J High-Speed Current-Limiting Fuse #2	Rating Z1		250	350	400	500	600	600	n,	-	
Class J Time-Delay Fuse #3	Rating Z2	(A)	225	300	350	450	500	500	600	600	
UL Listed Inverse Time-Delay Circuit Breaker #3	Rating Z3	(A)	350	450	500	700	800	1000	1000	1000	
Rated Conditional Short-Circuit Current	lq	(kA)		10				18			

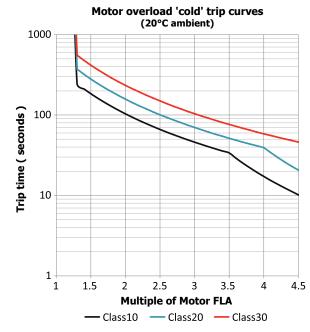
#1 Correctly selected semiconductor fuses can provide additional protection against damage to the SR55 unit (this is sometimes referred to as type 2 coordination). These semiconductor fuses are recommended to provide this increased protection.

#2 Suitable for use in a circuit capable of delivering not more than lq rms Symmetrical Amperes, when protected by Class J high-speed current-limiting 600V-rated fuses with a maximum trip rating of Z1 (IEC Type 1 coordination short-circuit protection).

#3 Suitable for use in a circuit capable of delivering not more than lq rms Symmetrical Amperes, 480 Volts maximum, when protected by Class J time delay fuses with a maximum rating of Z2, or by a circuit breaker with an interrupting rating not less than Z3 rms Symmetrical Amperes, 480 Volts maximum as in table.

SR55 Soft Starter Overload Trip

The SR55 soft starter provides motor overload protection, which can be configured through the touchscreen. Overload trip settings are determined by the Motor Current setting and the Trip Class setting. Trip class choices are class 10, class 20, and class 30. The SR55 soft starters are protected using full I2T motor overload with memory.



SR55 Soft Starter Selection

An Online Product Selection Tool is available on our website: https://www.automationdirect.com/selectors/softstarters

SR55 Soft Starters – O/L Trip Classes 1						
Default	10					
Heavy	20					
Agitator	10					
Compressor - Centrifugal	20					
Compressor - Reciprocating	20					
Compressor - Rotary Screw	20					
Compressor - Rotary Vane	10					
Compressor - Scroll	10					
Ball mill	20					
Centrifuge*	30					
Bow Thruster - Zero Pitch	10					
Bow Thruster - Loaded	20					
Conveyor - Unloaded	10					
Conveyor - Loaded	20					
Crusher	30					
Fan - Low Inertia < 85A	10					
Fan - High Inertia > 85A	30					
Feeder - screw	10					
Grinder	20					
Hammer mill	20					
Lathe machines	10					
Mills - Flour, etc.	20					
Mixer - Unloaded	10					
Mixer - Loaded	20					
Molding Machine	10					
Pelletizers	20					
Plastic and textile machines	10					
Press, flywheel	20					
Pump - Submersible Centrifugal	10					
Pump - Submersible Rotodynamic	10					
Pump - Positive displacement Reciprocating	20					
Pump - Positive displacement Rotary	20					
Pump Jack	20					
Rolling mill	20					
Roots Blower	20					
Saw - Band	10					
Saw - Circular	20					
Screen - Vibrating	20					
Shredder	30					
Transformers, voltage regulators	10					
Tumblers	20					
Wood chipper	30					

SR55 Soft Starter Selection Steps

1 Determine the required trip class based on the motor load and required start time. See examples to the left (refer to the definitions of Class 10, 20, and 30 Trip Curves on page tSST-26).

2 Below, select the row with the correct motor full load amps. Then select the correct SR55 soft starter to the right based on Trip Class (longer start times require a larger starter). Notice that there are different Motor Amps columns for starters wired In-Line (most common) and In-Delta. Select the applicable SR55 part number based on the required Trip Class, motor HP, and connection type.

Derating is necessary if your application requires multiple starts per hour. Refer to page tSST-29, "SR55 Increased Starts per Hour - Derating."

										Table 2 le G.1)				
	Motor Size Soft Starter Size													
In-Line Connection						In-Del	ta Conne	ection *		Арр	Application Trip Class			
		HP	@				HP	@						
I (A)	200V	208V	230V	460V	I (A)	200V	208V	230V	460V	Class 10	Class 20	Class 30		
17	3	5	5	10	29	7.5	7.5	10	20	SR55-017	<u>SR55-021</u>	<u>SR55-02</u>		
21	5	5	5	15	36	10	10	10	25	<u>SR55-021</u>	<u>SR55-027</u>	SR55-034		
27	7.5	7.5	7.5	20	47	10	15	15	30	<u>SR55-027</u>	<u>SR55-034</u>	<u>SR55-04</u>		
34	10	10	10	25	59	15	15	20	40	<u>SR55-034</u>	<u>SR55-040</u>	<u>SR55-05</u>		
40	10	10	10	30	69	20	20	25	50	<u>SR55-040</u>	<u>SR55-052</u>	<u>SR55-06</u>		
52	15	15	15	40	90	25	30	30	60	<u>SR55-052</u>	<u>SR55-065</u>	<u>SR55-07</u>		
65	20	20	20	50	113	30	30	40	75	<u>SR55-065</u>	<u>SR55-077</u>	<u>SR55-09</u>		
77	20	25	25	60	133	40	40	50	100	<u>SR55-077</u>	<u>SR55-096</u>	<u>SR55-12</u>		
96	30	30	30	75	166	50	50	60	125	SR55-096	<u>SR55-124</u>	<u>SR55-15</u>		
124	40	40	40	100	215	60	75	75	150	<u>SR55-124</u>	<u>SR55-156</u>	<u>SR55-18</u>		
156	50	50	60	125	270	75	75	100	200	<u>SR55-156</u>	<u>SR55-180</u>	<u>SR55-24</u>		
180	60	60	60	150	312	100	100	125	250	<u>SR55-180</u>	<u>SR55-242</u>	<u>SR55-30</u>		
242	75	75	75	200	419	150	150	150	300	<u>SR55-242</u>	<u>SR55-302</u>	<u>SR55-36</u>		
302	100	100	100	250	523	150	150	200	450	<u>SR55-302</u>	<u>SR55-361</u>	<u>SR55-41</u>		
361	125	125	150	300	625	200	200	250	500	<u>SR55-361</u>	<u>SR55-414</u>	<u>SR55-47</u>		
414	150	150	150	350	717	250	250	250	500	<u>SR55-414</u>	<u>SR55-477</u>	n/a		
477	150	150	150	400	826	250	300	300	600	SR55-477	n/a	n/a		

* For In-Delta connections, all six motor wires must be available for connection, and it is critical to exactly follow the In-Delta wiring diagram in the SR55 User Manual or Quick-start Guide. Nine-lead motors CANNOT be connected in the delta. The Soft Starter will only sense the Phase Current, which is about 58% of the Line Current.

* For In-Delta connections, a main contactor that is controlled by the Run relay of the SR55 must be used in the incoming power circuit for isolation. Circuit breaker isolation alone is not sufficient.

* iERS energy optimizing feature is not available for In-Delta connections.

* Size centrifuge starter at I(A) = (motor FLA x 2.3). Trip Class 30.

Stellar® SR55 Full-Featured Soft Starters

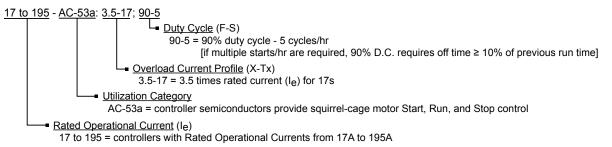
SR55 Index Ratings (per IEC 60947-4-2)

SR55 Index Ratings *								
Model Number Ie (A) Standard Operation AC-53a; X-Tx; F-S								
<u>SR55-017</u> to <u>SR55-180</u>	17 to 195	AC-53a: 3.5-17; 90-5						
SR55-242 to SR55-477	242 to 500	AC-53a: 3.5-17; 90-3						

* Index ratings AC-53a and AC-53b are specified by IEC standard # 60947-4-2.

IEC Index Ratings are comprised of Rated Operational Current (le), Utilization Category, Overload Current Profile (X-Tx), and Duty Cycle (F-S) or OFF-time.

Index Rating Example – Standard Operation (AC-53a Utilization Category per IEC 60947-4-2)



Standard Overload Current Profile and Duty Cycle

The SR55 has been designed for a specific Overload Current Profile and Duty Cycle as shown above in the SR55 Index Ratings.

The Overload Current Profile is expressed by two symbols, X and Tx.

X denotes the overload current as a multiple of le and represents the maximum value of operating current due to starting, operating, or maneuvering under overload conditions.

For example, X = 3.5 means that the maximum overload start current allowed is 3.5 times FLC.

Tx denotes the duration of the controlled overload currents during starting, stopping, operating, or maneuvering.

For example, Tx = 17 means that the maximum allowed overload current is permitted for up to 17 seconds only.

The Duty Cycle is expressed by two symbols, F and S which describe the duty and also set the time that must be allowed for cooling.

F is the ratio of the on-load period to the total period expressed as a percentage.

For example, F=90 means that the soft starter is ON for 90% of the time and then OFF for 10% of the time between each start.

If there are not multiple starts per hour, then the Duty Cycle is continuous.

S is the number of starts or operating cycles per hour.

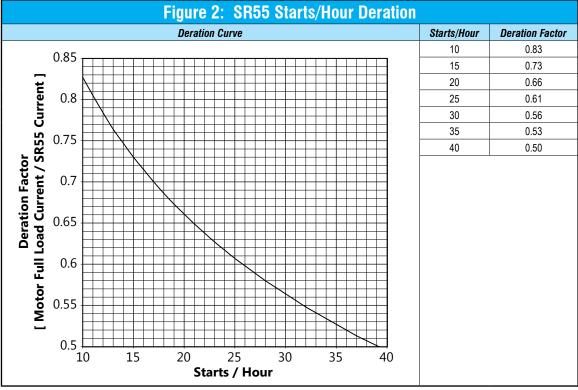
For example, S = 5 means that the soft starter is capable of 5 equally spaced starts per hour.

These characteristics are summarized in Figure 1.

Figure 1: Standard Overload Current											
Profiles and Duty Cycles											
Model	Rated Current (A)	Class 10 O/L Multiple (X)	Class 10 0/L Time (Tx)	Starts / Hour (S)	Duty (F)						
<u>SR55-017</u>	017										
<u>SR55-021</u>	021										
<u>SR55-027</u>	027										
<u>SR55-034</u>	034										
<u>SR55-040</u>	040										
<u>SR55-052</u>	052			5							
<u>SR55-065</u>	065										
<u>SR55-077</u>	077	25	47		000/						
<u>SR55-096</u> SR55-124	096 124	3.5	17		90%						
SR55-124 SR55-156	124										
SR55-150	180										
SR55-242	242										
SR55-302	302										
SR55-361	361			3							
SR55-414	414			-							
SR55-477	477										

SR55 Increased Starts per Hour – Derating

If more than the standard number of starts/hour is required, the SR55 must be derated. To derate for more starts/hour, the motor full load current must be less than the SR55 current. The relationship between the SR55 deration and the starts/hour is given below in Figure 2 and the two examples that follow. This assumes that the SR55 is still operating at the same duty (F) as given in Figure 1.



Deration Factor = (138 - (24·ln(starts/hr))) / 100 [where ln(starts/hr) is the natural log of the # of starts/hour] Example: Deration Factor for 10 starts/hr = (138 - (24·ln(10))) / 100 = 0.83

Exa	mple 1: SR55 Selection and Co	nfiguration						
Step	SR55 Selection							
1	Application	Application Loaded Conveyor						
2	Trip Class	20						
3	Duty	90%						
4	In-Line or In-Delta	In-Line						
5	Ambient Temperature	40°C						
6	Altitude	1000m						
7	Full Motor Load Current	80A						
8	Current Limit	4 x 80A = 320A						
9	Number of Starts/Hour	10						
10	Deration Factor (from Fig.2)	0.83						
11	SR55 (A) = Motor FLC / Deration Factor	96A						
12	Determine SR55 from Sizing Guide	<u>SR55-096</u>						
Step	SR55 Configuration							
1	Select Application	(Auto Setup)						
2	Leave Motor Current 100A (maximum)	(Auto Setup)						
3	Set Start Current Limit to 320A (400% of motor FLC)	(Start Current Limit)						
4	Set Overload Level to 88A (110% of motor FLC)	(Overload Settings)						
Step	SR55 Alternative Configuration							
1	Set Application	(Auto Setup)						
2	Set Motor Current to 80A	(Auto Setup)						
3	Warm Trip Time will be reduced to Trip Class 10 value	(320A for 13s)						

Ex	ample 2: SR55 Selection and Co	onfiguration
Step	SR55 Selection	
1	Application	Agitator
2	Trip Class	10
3	Duty	90%
4	In-Line or In-Delta	In-Line
5	Ambient Temperature	40°C
6	Altitude	1000m
7	Full Motor Load Current	66A
8	Current Limit	3.5 x 66A = 231A
9	Number of Starts/Hour	20
10	Deration Factor (from Fig.2)	0.66
11	SR55 (A) = Motor FLC / Deration Factor	100A
12	Determine SR55 from Sizing Guide	<u>SR55-124</u>
Step	SR55 Configuration	
1	Select Application	(Auto Setup)
2	Leave Motor Current 100A (maximum)	(Auto Setup)
3	Set Start Current Limit to 231A (350% of motor FLC)	(Start Current Limit)
4	Set Overload Level to 72A (110% of motor FLC)	(Overload Settings)
Step	SR55 Alternative Configuration	
1	Set Application	(Auto Setup)
2	Set Motor Current to 66A	(Auto Setup)
3	Set Trip Class to 30	(Overload Settings)
4	Warm Trip Time will be reduced to Trip Class 10 value	(231A for 17s)

See our website: www.AutomationDirect.com for complete engineering drawings.

Stellar[®] SR55 Full-Featured Soft Starters

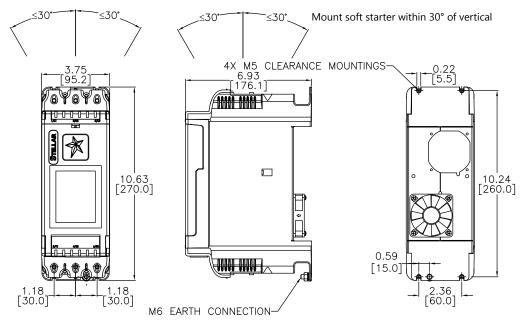
SR55 Soft Starter Dimensions

Dimensions = in [mm]

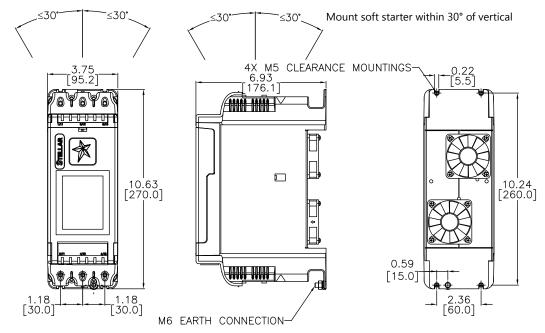


The addition of optional finger guards to size 1 and size 2 SR55 soft starters adds approximately 14mm [0.5in] to the soft starter vertical dimension, but does NOT change the clearance distance.

Frame Size 1: SR55-017 to SR55-027



Frame Size 1: SR55-034 to SR55-096



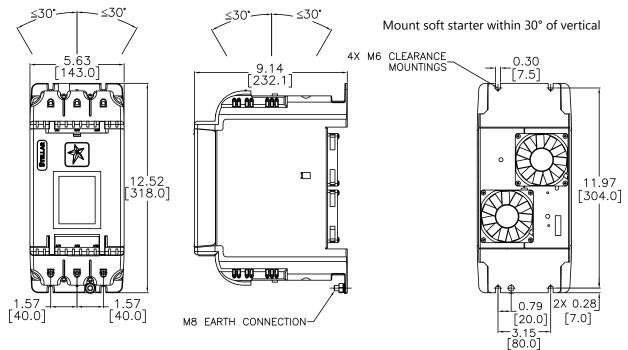
SR55 Soft Starter Dimensions

Dimensions = in [mm]

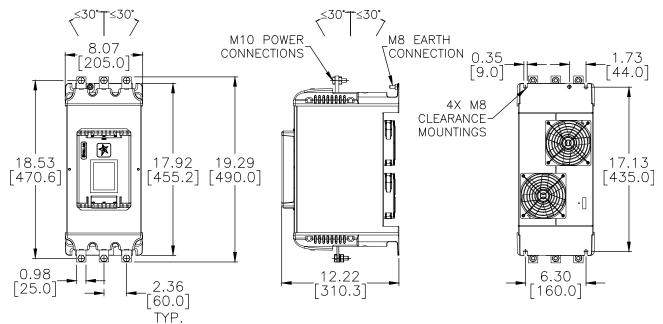
See our website: www.AutomationDirect.com for complete engineering drawings.

The addition of optional finger guards to size 1 and size 2 SR55 soft starters adds approximately 14mm [0.5in] to the soft starter vertical dimension, but does NOT change the clearance distance.

Frame Size 2: SR55-124 to SR55-180



Frame Size 3: <u>SR55-242</u> to <u>SR55-361</u>

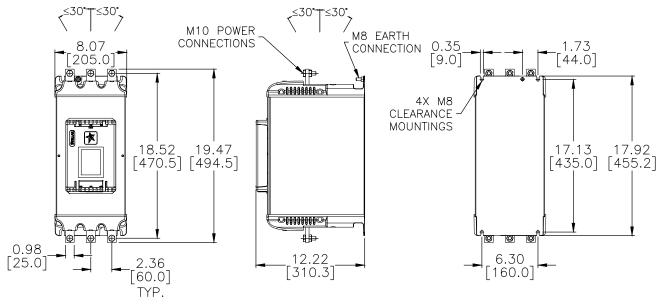


SR55 Soft Starter Dimensions

Dimensions = in [mm]

See our website: www.AutomationDirect.com for complete engineering drawings.

Frame Size 3: <u>SR55-414</u> to <u>SR55-477</u>



Ventilation for Enclosures

SR55 Minimum Clearance Distances * (in [mm])										
SR55 Soft Starter Model Top Bottom Left Right Front										
Size 1: <u>SR55-017</u> to <u>SR55-096</u>	3	[75]		1 [25]						
Size 2: <u>SR55-124</u> to <u>SR55-180</u>	3.9	[100]	1.6 [40]		1 [25]					
Size 3: <u>SR55-242</u> to <u>SR55-477</u>	4.9	[125]	2.4	[60]	1 [25]					

* For heat dissipation, the SR55 must not be mounted any closer to another object than these distances.



The addition of optional finger guards to size 1 and size 2 SR55 soft starters adds approximately 14mm [0.5in] to the soft starter vertical dimension, but does NOT change the clearance distance.

When fitting SR55 into an enclosure, ventilation must be provided if the heat output of the unit is greater than the enclosure will dissipate. Use the formula at right to determine the fan requirement. An allowance has been incorporated into the formula so that the figure for Q is the air delivery in the fan suppliers data.

The power dissipation of the thyristors are at their peak when the SR55 is in energy saving mode (iERS), therefore causing the most heat generated from the starter. Heat dissipated can be approximated with the formula: Watts (SR55) = $1/2 \times (SR55 \text{ current rating}) \times 3$ $Q = (4xWt) / (T_{max} - T_{amb})$

Q = Volume of air (cubic meters per hour - m^3/h)

- Wt = Heat produced by the unit and all other heat sources within the enclosure (Watts)
- T_{max} = Maximum permissible temperature within the enclosure (50°C for a fully rated SR55)
- T_{amb} = Temperature of the air entering the enclosure (°C) (If you prefer to work in CFM, substitute °F for °C. Q is now in CFM)

SR55 Soft Starter Optional Accessories

EtherNet/IP Module

The EtherNet/IP communication module is intended to be installed in the SR55 option slot, and allows the SR55 to be connected to an EtherNet/IP network. The interface offers the following functionality:

- CIP Parameter Object Support
- Supports Explicit and Implicit Messaging

SR55-CM-ENETIP2

- 7 Input Words from the network master to SR55
- 5 Output Words from SR55 to the network master

SR55-CM-ENETIP

- 2 Input Words from the network master to SR55
- 2 Output Words from SR55 to the network master

Modbus TCP Module

Allows an SR55 soft starter to be connected to a Modbus TCP network using TCP/IP protocol.

The communication module supports 4 simultaneous (master) connections and allows access to all user parameters.



Modbus TCP Module: SR55-CM-MODTCP

Finger Guards

For SR55 soft starter power-circuit line and load side terminals; provides IP20 protection for soft starter sizes <u>SR55-180</u> and below (frame sizes 1 and 2).

Remote Touchscreen

Allows remote monitoring, configuration, and control of SR55 soft starters. Since the touchscreen is a master RS-485 device, it can control multiple SR55 soft starters. Includes a 3m Ethernet cable and an <u>SR55-RJ45-RJ12</u> adapter.



Remote Touchscreen: SR55-KPD-REM



Modbus Serial Splitter: SR55-SPLT



Finger Guards:

SR55-FG-1 & SR55-FG-2

RJ45 to RJ12 Adapter: SR55-RJ45-RJ12

USB Flash Drive: USB-FLASH

Modbus Serial Splitter

Includes an <u>SR55-RJ45-RJ12</u> adapter cable. Allows a Modbus network over RS-485 to be constructed as plug-and-play with standard Ethernet cables. Customer must provide cable between RS-485 master and the first splitter. Can only be used with one master at a time on the network, e.g. Remote Touchscreen, PLC, or HMI. Splitter includes (3) female RJ45 ports.

RJ45 to RJ12 Adapter

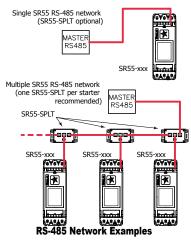
Allows connection of the Remote Touchscreen, Modbus Splitter, or other Modbus master to the RJ12 port on top of the SR55 soft starter.

Adapter has a male RJ12 connector and a female RJ45 connector (allows use of standard Ethernet cables).

USB Flash Drive

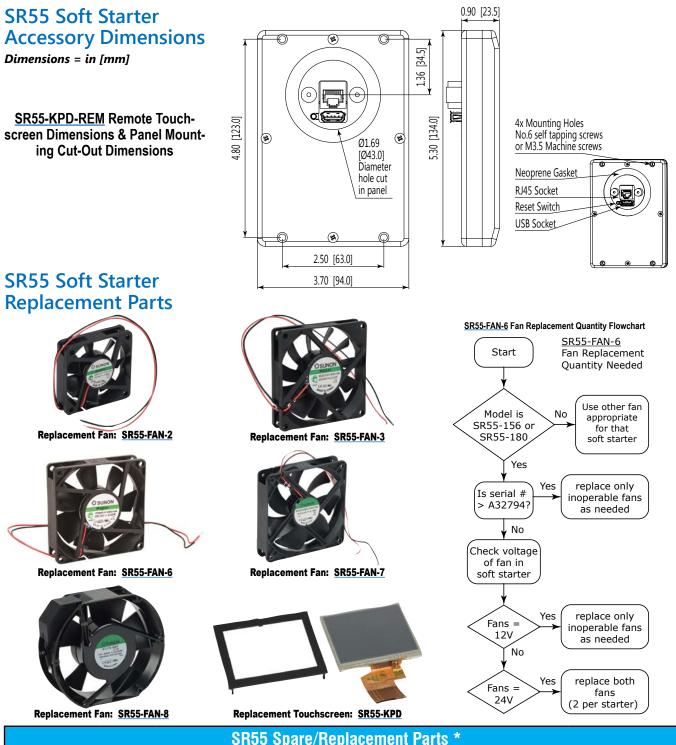
4GB USB Flash drive. Recommended for SR55 firmware updates and data logging.

NOTE: Other flash drives may not work with SR55. <u>USB-</u> FLASH has been successfully tested with SR55.



SR55 Optional Accessories					
Part Number	Price	Description			
<u>SR55-CM-</u> ENETIP2	\$608.00	EtherNet/IP communication module, optional, for Stellar SR55 series soft starters, dual RJ45 communication ports, complete EtherNet/ IP adapter, TCP/IP socket interface, CIP parameter object support, implicit and explicit messaging, transformer isolated Ethernet interface, 10/100 Mbps full duplex.	all		
<u>SR55-CM-</u> ENETIP	Retired	EtherNet/IP communication module, optional, for Stellar SR55 series soft starters, dual RJ45 communication ports, complete EtherNet/ IP adapter, TCP/IP socket interface, CIP parameter object support, implicit and explicit messaging, transformer isolated Ethernet interface, 10/100 Mbps full duplex.			
<u>SR55-CM-</u> MODTCP	\$541.00	Modbus TCP communication module, optional, for Stellar SR55 series soft starters, dual RJ45 communication ports, complete Modbus TCP server, up to 256 bytes of I/O data in each direction, transformer isolated interface, 100 Mbps full duplex, TCP/IP socket interface, supports 4 simultaneous (master) connections.			
<u>SR55-FG-1</u>	\$43.00	Finger guards, replacement, for size 1 Stellar SR55 series soft starter power terminals. Provides IP20 protection rating. Package of 2.			
<u>SR55-FG-2</u>	\$43.00	Finger guards, replacement, for size 2 Stellar SR55 series soft starter power terminals, Provides IP20 protection rating. Package of 2.			
<u>SR55-KPD-</u> <u>REM</u>	\$459.00	Touchscreen, optional remote, for Stellar SR55 series soft starters. Used to remotely monitor, configure, and control SR55 series units without opening enclosures. Rated for NEMA 4/4X enclosures, no external power wiring required. Includes 3m RJ45 cable and <u>SR55-RJ45-RJ12</u> adapter.			
<u>SR55-SPLT</u>	\$183.00	8 Serial Modbus communication splitter, optional, for Stellar SR55 series soft starters. Used for creating a Modbus network with multiple SR55 series soft starters. Uses 3 serial RJ45 connectors for upstream/downstream connectivity and connection to the starter.			
<u>SR55-RJ45-</u> <u>RJ12</u>	\$10.00	RJ45 female to RJ12 male adapter, optional, for Stellar SR55 series soft starters.			
USB-FLASH	\$30.50	USB Flash drive, SanDisk, 4GB (SanDisk P/N SDCZ50-004G-A46).			

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SR55 Spare/Replacement Parts *						
Part Number	Price	Description	For SR55 Models			
<u>SR55-FAN-2</u> **	\$23.00	Cooling fan, replacement, for size 1 Stellar SR55 series soft starters, 60 x 60 x 15 mm	<u>017</u> thru <u>096</u>			
<u>SR55-FAN-3</u> **	\$27.00	Cooling fan, replacement, for size 2 Stellar SR55 series soft starters, 80 x 80 x 15 mm	<u>124</u>			
<u>SR55-FAN-6</u> ***	\$24.00	Cooling fan, replacement, for size 2 Stellar SR55 series soft starters, 80 x 80 x 20 mm	<u>156</u> thru <u>180</u>			
<u>SR55-FAN-7</u> **	\$64.00	Cooling fan, replacement, for size 3 Stellar SR55 series soft starters, 120 x 120 x 25 mm	<u>242</u> thru <u>361</u>			
<u>SR55-FAN-8</u> **	\$167.00	Cooling fan, replacement, for size 3 Stellar SR55 series soft starters, 171 x 151 x 51 mm	<u>414</u> thru <u>477</u>			
<u>SR55-KPD</u>	\$151.00	Touchscreen, replacement, for Stellar SR55 series soft starters	all			

* These items are exact replacements for the comparable part that is originally installed on the applicable SR55.

** These fans include wiring connectors.

*** <u>SR55-FAN-6</u> 12VDC fan kits fit <u>SR55-156</u> and <u>SR55-180</u> soft starters. Some early models of these starters were equipped with 24VDC fans, and two <u>SR55-FAN-6</u> kits are required for those particular models since both 24VDC fans require replacement. The 12VDC fan kits include wiring connectors and a resistor, which is for use only with the 24VDC soft starters. Refer to the Fan Replacement Quantity flowchart above to determine how many fan kits you need.