# Surestep® Stepping System Drives

# SureStep® Microstepping Drives

		Sure Step Series Specifications – Mici	ostepping Drives		
Microstep	ping Drive	STP-DRV-4035	STP-DRV-4850	STP-DRV-80100	
Price		<>	<>	<>	
Drive Type		Microstepping drive with pulse input	Advanced microstepping drive with pulse or analog input, serial communication (serial communication allows indexing capability)		
Output Current		selectable from 0.4 to 3.5 A/phase (maximum output power is 140 W)	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)	
Input Voltage (external p/s required)		12-42 VDC (including ripple voltage)	24-48 VDC (nominal) (range: 18-53 VDC)	24-80 VDC (nominal) (range: 18-88 VDC)	
Configurat	ion Method	dip switches	SureStep Pro software (inclu	ded)	
Amplifier Type		MOSFET, dual H-bridge, bipolar chopper	MOSFET, dual H-bridge, 4-quadrant		
Current Control		3-state PWM 20 kHz	4-state PWM @ 20 kHz		
Protection		n/a	over-voltage, under-voltage, over-temperature, external output faults (phase-to-phase & phase-to-ground), inter-amplifier shorts		
Recommended Input Fusing		Fuse: 4A fast acting; ADC # ACG4 Fuse Holder: ADC # DN-F6L110	Fuse: 4A 3AG delay (ADC #MDL4) Fuse: 6.25A 3AG delay (ADC #MDL6-25) Fuse Holder: ADC #DN-F6L110 Fuse Holder: ADC #DN-F6L110		
Input Circuit		Opto-coupler input with 440Ω resistance (5 to 15 mA input current); Logic Low is input 0.8 VDC or less; Logic High is input 4 VDC or higher.	Opto-coupler input with 5 to	15 mA input current; or less; Logic High is input 4 VDC or higher.	
Land	Step/Pulse	Motor steps on falling edge of pulse and minimum pulse width is 0.5 microseconds (1MHz)	optically isolated, differential, 5V, $330\Omega$ ; min pulse width = 250 ns max pulse frequency = 2MHz		
Input Signals	Direction	Needs to change at least 2 microseconds before a step pulse is sent	adjustable bandwidth digital noise rejection feature  FUNCTIONS: step & direction, CW/CCW step, A/B quadrature, run/stop & direction, jog CW/CCW, CW/CCW limits		
	Enable	Logic 1 will disable current to the motor (current is enabled with no hook-up or logic 0)	optically isolated, 5-12V, $680\Omega$ ; FUNCTIONS: motor enable, alarm reset, speed select (oscillator mode)		
	Analog	n/a	Range: 0–5 VDC; Resolution: 12 bit; FUNCTION: speed control		
Output Sig	ınal	n/a	optically isolated, 24V, 10mA max; FUNCTIONS: fault, motion, tach		
	cation Interface	n/a	RS-232; RJ11 (6P4C) receptacle		
Non-volati Memory S	torage	n/a	Configurations are saved in FLASH memory on-board the DSP.		
	Idle Current Reduction	0% or 50% reduction (idle current setting is active if motor is at rest for 1 second or more)	reduction range of 0-90% of running current after delay selectable in ms		
	Microstep Resolution	400 (200x2), 1,000 (200x5), 2,000 (200x10), or 10,000 (200x50) steps/rev	software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev		
	Modes of Operation	step & direction	step & direction, CW/CCW, A/B quadrature, oscillator, joystick, serial com		
Features	Phase Current Setting	0.4 to 3.5 A/phase with 32 selectable levels	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)	
	Self Test	uses half-step to rotate 1/2 revolution in each direction at 100 steps/second	checks internal & external po	wer supply voltages, diagnoses open motor phases	
	Additional Features	n/a	Anti-resonance (Electronic Damping) Auto setup Microstep emulation Torque ripple smoothing (allows for fine adjustment of phase in the range 0.25 to 1.5 rps) Waveform (command signal) smoothing		
Connector	s	Screw terminal blocks with AWG 18 maximum wire size	Communication: RJ11 (6P4	C); Other: removable screw terminal blocks	
Maximum	Humidity	90% nor	n-condensing		
Storage Te	emperature	-20 to 80 °C	C [-4 to 176 °F]		
Operating	Temperature	0 to 55 °C [32 to 131 °F] recommended; 70 °C [158 °F] maximum	0–55 °C [32–151 °F]; (mount to suitable heat sink)		
Drive Cool	ling Method	natural convection (mount drive to metal surface to dissipate heat)	natural convection (mount to suitable heat sink)		
Mounting		(4) #4 screws to mount on wide side; (2) #4 screws to mount on narrow side	#6 mounting screws (mount to suitable heat sink)		
Dimension	18	3.0 x 4.0 x 1.5 inches [76.2 x 101.6 x 38.1 mm]	3.0 x 3.65 x 1.125 inches [76.2 x 92.7 x 28.6 mm]		
Weight		9.3 oz. [264 g]	8 oz [227g] (approximate)		
Agency Approvals		CE (complies with EN55011A & EN50082-1 (1992)), RoHS	CE, RoHS		

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# Surestep® Stepping System Software

## SureStep® Microstepping Drives

	SureStep® Drives Modes of Operation				
Drive Part #	Step & Direction <sup>(1)</sup>	CW/CCW (1)	A/B Quadrature (1)	Oscillator (Analog Input) (2)	Serial Command (Indexing) (3)
STP-DRV-4035	Y	-	-	-	-
STP-DRV-4850	Y	Υ	Y	Υ	Υ
STP-DRV-80100	Y	Υ	Υ	Υ	Υ

- 1) Pulse Inputs: Refer to the charts at the end of the SureStep section for PLC compatibility.
- 2) Analog Inputs: Use any 0-5V analog output card. Advanced drives (-4850 & -80100) also have a built-in +5VDC for use with potentiometers.
- 3) Serial Commands: use any controller that has ASCII capability.

## SureStep Pro Drive Configuration Software

SureStep Pro configuration software is available as a free download from our website for advanced SureStep drives (STP-DRV-4850 & -80100)

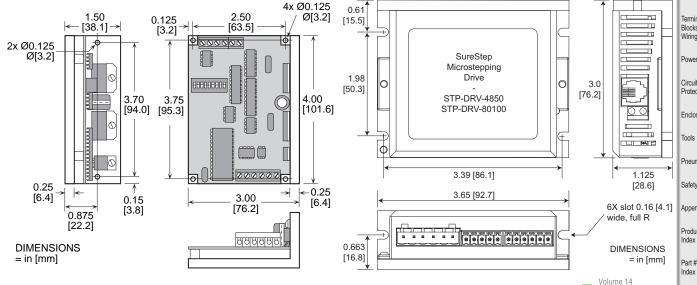
- · Used for easy configuration and setup of the drive, including drive, motion control mode, I/O, motor.
- · Serial command language for motor drive control via serial port; eliminates the need for separate motion controllers or indexers; provides easy interface to other industrial devices such as PCs, PLCs and HMIs.
- Easily use the ASCII output commands from most of our PLCs to enable indexing capability.
- · Help files include technical data, application information, advanced setup, serial command instructions.
- Runs on Windows 98, 2000, ME, NT. Vista, XP.



## Microstepping Drive Dimensions

#### **STP-DRV-4035**

#### STP-DRV-4850 & -80100



Company

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**Drives/Motors/Motion** 

# Surestep® Stepping Systems

## SureStep® System Overview



The SureStep® stepping system series includes:

- Four step motor power supplies
- One DIP-switch configurable microstepping drive
- Two software configurable advanced microstepping drives
- Two motor extension cables
- Twenty step motors (NEMA 17, 23, 34 frame sizes; single shaft & dual shaft)

SureStep Power Supply / Drive Compatibility					
Drive <sup>(1)(2)</sup>	Recommended Power Supply <sup>(1)(2)</sup>				
Model #	STP-PWR-3024	STP-PWR-4805 STP-PWR-4810	STP-PWR-7005		
STP-DRV-4035 (40 VDC max input)	√	<b>V</b>	No		
STP-DRV-4850 (48 VDC max input)	√	<b>V</b>	No		
STP-DRV-80100 (80 VDC max input)	<b>V</b>	<b>V</b>	٧		

Do NOT use a power supply that exceeds the drive's input voltage range. If
using a non-STP linear power supply, ensure that the unloaded voltage does not
float above the drive's maximum input range.

For best performance, use the lowest voltage power supply that supplies the required speed and torque.

SureStep Drive / Motor Compatibility					
Motor <sup>(1)(2</sup>	2)		Reco	mmended Dr	ive <sup>(1)</sup>
Model # <sup>(1)(2)</sup>	Rated Amps	Extension Cable <sup>(2)</sup>	STP-DRV -4035 <sup>(1)</sup> (3.5A max output)	STP-DRV -4850 <sup>(1)</sup> (5.0A max output)	STP-DRV -80100 <sup>(1)</sup> (10.0A max output)
STP-MTR-17040(D)	1.7		√	√	
STP-MTR-17048(D)	2.0		√	√	-
STP-MTR-17060(D)	2.0	STP- EXT- 020	√	√	
STP-MTR-23055(D)	2.8		√	√	
STP-MTR-23079(D)	2.8		√	√	
STP-MTR-34066(D)	2.8		√	√	
STP-MTRH-23079(D)	5.6				√
STP-MTRH-34066(D)	6.3	STP- EXTH-	_	_	√
STP-MTRH-34097(D)	6.3	020			√
STP-MTRH-34127(D)	6.3				√

The combinations above will perform according to the published speed/torque curves.
 However, any STP motor can be used with any STP drive. Using a motor with a current
 rating higher than the drive's output rating will proportionally limit the motor torque.

### Standard stepper drive features

- Max 3.5A, 40V
- DIP switch configurable
- Selectable microstepping: x2, x5, x10, x50 steps/revolution
- · Self test feature
- Idle current reduction

## Advanced stepper drive features

- Max 5A, 48V and max 10A, 80V models available
- Software configurable
- Programmable microsteps
- Internal indexer (via ASCII commands)
- Self test feature
- Idle current reduction
- · Anti-resonance
- Torque ripple smoothing
- · Step, analog, & serial communication inputs
- · Serial communications allow point-to-point positioning

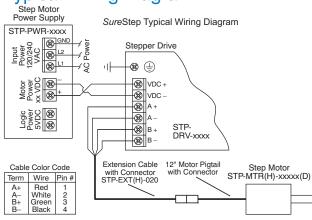
#### Motor features

- High torque, 2-phase, bipolar, 1.8° per step, 4-lead
- Available in single-shaft and dual-shaft models
- (6) NEMA 17 motors
- (6) NEMA 23 motors
- (8) NEMA 34 motors

### Power supply features

- · Linear, unregulated DC power supplies
- 120/240 VAC selectable input
- 32V, 48V, 70V DC output models available
- All models have additional 5VDC, 500 mA regulated logic supply
- Fusing included for both incoming AC and outgoing DC
- 5V supply has electronic overload protection

## Typical Wiring Diagram



MTR motors have connectors compatible with the EXT extension cables. MTRH motors have connectors compatible with the EXTH extension cables.



# Wiring Solutions

## Wiring Solutions using the **ZIP**Link Wiring System

**ZIP**Links eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the ZIPLink System ranging from

PLC I/O-to-ZIPLink Connector Modules that are ready for field termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of **ZIP**Link modules are provided with **ZIP**Link cables. See the following solutions to help determine the best **ZIP**Link system for your application.

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Software

C-more &

other HMI

Soft Starters

Motors &

Steppers/

Motor Controls Proximity

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#### Solution 1: DirectLOGIC, CLICK and Productivity3000 I/O Modules to ZIPLink Connector Modules

When looking for guick and easy I/O-to-field termination, a ZIPLink connector module used in conjunction with a prewired **ZIP**Link cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.

Using the PLC I/O Modules to ZIPLink Connector Modules selector tables located in this section,

- 1. Locate your I/O module/PLC.
- 2. Select a ZIPLink Module.
- 3. Select a corresponding ZIPLink Cable.



#### Solution 2: DirectLOGIC, CLICK and Productivity3000 I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the **ZIP**Link Pigtail Cables. **ZIP**Link Pigtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

- 1. Locate your PLC I/O module.
- 2. Select a ZIPLink Pigtail Cable that is compatible with your 3rd party device.



#### Solution 3: GS Series and DuraPulse Drives **Communication Cables**

Need to communicate via Modbus RTU to a drive or a network of drives?

**ZIP**Link cables are available in a wide range of configurations for connecting to PLCs and SureServo, SureStep, Stellar Soft Starter and AC drives. Add a ZIPLink communications module to quickly and easily set up a multi-device network.

www.automationdirect.com/drives

Using the **Drives Communication** selector tables located in this section,

- 1. Locate your Drive and type of communications.
- 2. Select a ZIPLink cable and other associated hardware.



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# **Wiring Solutions**

#### **Solution 4: Serial Communications Cables**

*ZIP*Link offers communications cables for use with *Direct*LOGIC, CLICK, and Productivity3000 CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25-pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the **Serial Communications Cables** selector table located in this section,

- 1. Locate your connector type
- 2. Select a cable.



#### Solution 5: Specialty ZIPLink Modules

For additional application solutions, *ZIP*Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and *SureServo* 50-pin I/O interface connection.

Using the *ZIPLink* Specialty Modules selector table located in this section,

- 1. Locate the type of application.
- 2. Select a ZIPLink module.



# Solution 6: *ZIP*Link Connector Modules to 3rd Party Devices

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible *ZIP*Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the Universal Connector Modules and Pigtail Cables table located in this section,

- 1. Select module type.
- 2. Select the number of pins.
- 3. Select cable.



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# **Motor Controller Communication**

Other Hardwald Required  15  - 2  in plug
2 -
2 -
-
-
in plug –  –  –
-
_
2 <b>FA-15HD</b>
FA-CABKIT
-
15 –
-
_
2
in plug –
-
15
_
2
in plug –
15
SR44-RS485**
2
_
_
o RJ12 <b>FA-15HD</b>
FA-CABKIT
_
o HD15
o RJ12 🕒
o RJ45 —
_
RJ12 –
_
_
1 1 1

<sup>\*</sup> When using the ZL-CDM-RJ12Xxx ZIPLink Communication Distribution Module, replace the lowercase xx with the number of RJ12 ports, i.e.4 for four ports or10 for ten ports. (ex: ZL-CDM-RJ12X4 or ZL-CDM-RJ12X10)

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Comm.

Terminal Blocks & Wiring Power

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<sup>\*\*</sup> The SR44-RS485 Communications Adapter must be installed for RS-485 communications with the Stellar soft starters.