

# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors



**marathon**<sup>®</sup>  
Motors

## Features

- Meets or exceeds NEMA Premium efficiencies
- Inverter duty
- Suitable for use with ALS (across-the-line starting) or IGBT (AC drive)
- 10:1 variable torque and constant torque on VFD with 1.0 service factor
- 1.15 service factor on sinewave; 1.0 service factor on IGBT power
- Class F insulation
- Continuous duty at 40° C ambient
- Rolled steel construction with C-face rigid base mounting
- F3 conduit box location
- Utilizes ball bearings
- Electrically reversible
- UL Recognized, CSA Certified, and CE Mark
- Three-year warranty (through Marathon Electric)

## Applications

- Typical uses include gear reducers, pumps, machine tools, and other direct-coupled equipment installed in damp, dusty, or dirty environments where long life and ultra-high efficiency is desired.

### Motor Shipping Schedule \*

Same or one day *	Up to 7 days	Up to 10 days
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Color indicates shipping lead time in business days. Check stock status online.  
\* Certain heavy and oversized items can be shipped only via LTL.  
Check our website for current shipping method constraints by part number.

### 208–230/460V Motor Specifications

Part Number*	Price	HP	Base RPM	Volts	Enclosure	NEMA Frame	Model No.	FL Amps	Weight (lb)*
<a href="#">E2000</a>		1	3600	208–230 / 460	TEFC	56C	056T34F5940	3.0–2.8 / 1.4	28
<a href="#">E2001A</a>			1800			143TC	143TTFR16053	3.3–3.3 / 1.65	48
<a href="#">E2002</a>			1200			145TC	145TTFR6078	3.8–3.8 / 1.9	42
<a href="#">E2003</a>		1-1/2	3600			143TC	143TTFR5582	4.4–4.0 / 2.0	39
<a href="#">E2004A</a>			1800			145TC	145TTFR16331	4.7–4.6 / 2.3	50
<a href="#">E2005 †</a>			1200			182TC	182TTFW6076	5.6–5.2 / 2.6	77
<a href="#">E2007A</a>		2	1800			145TC	145TTFR16329	6.2–6.0 / 3.0	65
<a href="#">E2008 †</a>			1200			184TC	184TTFW6076	7.35–6.4 / 3.2	94
<a href="#">E2009 †</a>			3			3600	182TC	182TTFW6001	8.4–7.8 / 3.9
<a href="#">E2010 †</a>		1800				182TTFW6026		8.4–7.8 / 3.9	87
<a href="#">E2011A</a>		1200				213TC	213TTFWD6076	9.2–8.8 / 4.4	117

\* Refer to the Motor Shipping Schedule table for shipping information.

Certain heavy and oversized items can be shipped only via LTL. Check our web site for current shipping method constraints by part number.

† These specifications are for the Marathon motor currently being sold. Marathon manufactured a previous version of this Part Number (that had a different model #), and that version had some different specifications. For detailed information on the previous motor, please refer to the "Previous Marathon Model Numbers" table on the next page, or click on the previous motor's specification at [www.AutomationDirect.com/Retired-Products](http://www.AutomationDirect.com/Retired-Products).

Notes: Please review the AutomationDirect Terms & Conditions for warranty and service on this product.

Warranty service can be arranged through numerous Marathon Electric service centers.

See list of service centers on our Web site at [www.automationdirect.com](http://www.automationdirect.com).

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# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors

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## 208–230/460V Motor Specifications

Part Number*	Price	HP	Base RPM	Volts	Enclosure	NEMA Frame	Model No.	F.L. Amps	Weight (lb)*
<b>E2012</b> †		5	3600	208-230 / 460	TEFC	184TC	184TTFW6001	12 / 6	86
<b>E2013</b> †			1800				184TTFW6026	12.6 / 6.3	87
<b>E2014A</b>			1200			215TC	215TTFWD6076	14.8-17 / 7	150
<b>E2015A</b>		7-1/2	3600	208-230 / 460		213TC	213TTFWD6001	19.7-18.6 / 9.3	103
<b>E2016B</b>			1800				213TTFWD16039	20.8-19.6 / 9.8	124
<b>E2018A</b>		10	3600	230 / 460		215TC	215TTFWD6001	23.6 / 11.8	133
<b>E2019B</b>			1800	208-230 / 460	215TTFWD16047		14-26.4 / 13.2	170	

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# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors

## Performance Data

Performance Data (460 Volt)															
Part Number	HP	NEMA Design	F.L. RPM	Min RPM	Current (Amps)			Torque (lb-ft)			Max CHP RPM*	Max Safe RPM	F.L. Effic. (%)	F.L. Power Factor	Rotor Inertia (lb-ft <sup>2</sup> )
					No Load	Full Load	Locked Rotor	Full Load	Locked Rotor	Break-down					
<a href="#">E2000</a>	1	B	3490	349	0.7	1.4	10	1.5	3.6	5.1	5235	7200	80	84	0.04
<a href="#">E2001A</a>		A	1765	177	1.2	1.7	17	3.0	13.7	16.8	1765	4000	85.5	68	0.12
<a href="#">E2002</a>	1-1/2	B	1170	117	1.3	1.9	10	4.5	13.5	15.8	1755	5400	82.5	60	0.14
<a href="#">E2003</a>			3490	349	1.0	2.0	21	2.3	8.5	11.2	5235	7200	84.0	82	0.06
<a href="#">E2004A</a>			1755	176	1.5	2.3	24	4.5	21.2	26	1755	4000	86.5	71	0.14
<a href="#">E2005 †</a>			1175	118	1.3	2.6	17	6.8	13.4	24.4	1762.5	5400	87.5	71.5	0.38
<a href="#">E2007A</a>			1760	176	1.9	3.0	30.5	6.0	24.5	33.2	1760	4000	86.5	71	0.14
<a href="#">E2008 †</a>	2	B	1170	117	1.9	3.2	20.5	9.0	16.8	30.2	1755	4000	88.5	67	0.162
<a href="#">E2009 †</a>	3		3510	351	1.8	3.9	33	4.5	11.0	18.2	5265	7200	86.5	83	0.23
<a href="#">E2010 †</a>			1760	176	1.9	3.9	33.5	8.9	22.5	36	2640	4000	89.5	80.5	0.38
<a href="#">E2011</a>	5		1170	117	2.5	4.4	32	13.5	34	47.5	1755	4200	89.5	70	0.80
<a href="#">E2012 †</a>			3495	350	1.7	6.0	46	7.5	16	26	5243	5400	88.5	89.5	0.30
<a href="#">E2013 †</a>			1760	176	2.4	6.3	49	15.0	30.1	50.2	2640	4000	89.5	83	0.49
<a href="#">E2014A</a>	7-1/2		1170	117	3.7	7.0	46	22.5	45.6	68.2	1755	4000	89.5	75	1.00
<a href="#">E2015</a>			3540	354	3.0	8.9	64	11.1	24	38	5310	5400	90.2	87	0.55
<a href="#">E2016A</a>			1765	177	4.7	9.7	63.5	22.0	52	72	1765	4000	91.7	80	0.85
<a href="#">E2016B</a>	10		1765	177	4.9	9.8	67.5	22.3	52.9	75	1765	4000	91.7	78.3	0.85
<a href="#">E2018</a>			3535	354	3.5	11.8	80	14.9	30	46	5302.5	5400	91.7	87	0.65
<a href="#">R2018A</a>			3525	353	4.4	11.8	79.5	14.9	27.7	47.1	4000	4000	90.2	87.9	0.55
<a href="#">E2019B</a>			1760	176	7.2	13.2	81	29.9	76	90	1760	4000	91.7	77.5	1.1

\* Maximum Constant HP RPM is for direct coupled loads.

† These specifications are for the Marathon motor currently being sold. Marathon manufactured a previous version of this Part Number (that had a different model #), and that version had some different specifications. For detailed information on the previous motor, please refer to the "Previous Marathon Model Numbers" table below, or click on the previous motor's specification at [www.AutomationDirect.com/Retired-Products](http://www.AutomationDirect.com/Retired-Products).

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## Previous Marathon Model Numbers

Previous Marathon Model Numbers				
Part Number	HP	Previous Model #	Current Model #	Date of Change-over
<a href="#"><u>E2001</u></a>	1	143TTFR5642	n/a	09/2014
<a href="#"><u>E2004</u></a>	1-1/2	145TTFR6033	n/a	09/2014
<a href="#"><u>E2005</u></a>	1-1/2	182TTFR6076	182TTFW6076	09/2011
<a href="#"><u>E2007</u></a>	2	145TTFR6035	n/a	09/2014
<a href="#"><u>E2008</u></a>	2	184TTFR6076	184TTFW6076AA	09/2011
<a href="#"><u>E2009</u></a>	3	182TTFR6001	182TTFW6001AA	09/2011
<a href="#"><u>E2010</u></a>	3	182TTFW6026	182TTFW6026AA	09/2011
<a href="#"><u>E2012</u></a>	5	184TTFW6001	184TTFW6001AA	09/2011
<a href="#"><u>E2013</u></a>	5	184TTFW6026	184TTFW6026AA	09/2011
<a href="#"><u>E2016</u></a>	7-1/2	213TTFW6026	n/a	09/2014
<a href="#"><u>E2019</u></a>	10	215TTFW6026	n/a	09/2014

Visit [www.AutomationDirect.com/Retired-Products](http://www.AutomationDirect.com/Retired-Products) for detailed specifications of previous models.  
(The model # appears on the motor nameplate.)

# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors

## Dimensions (units = inches)

See our website: [www.AutomationDirect.com](http://www.AutomationDirect.com) for complete engineering drawings.

Figure 1 - Frame 56C – Part #: **E2000**

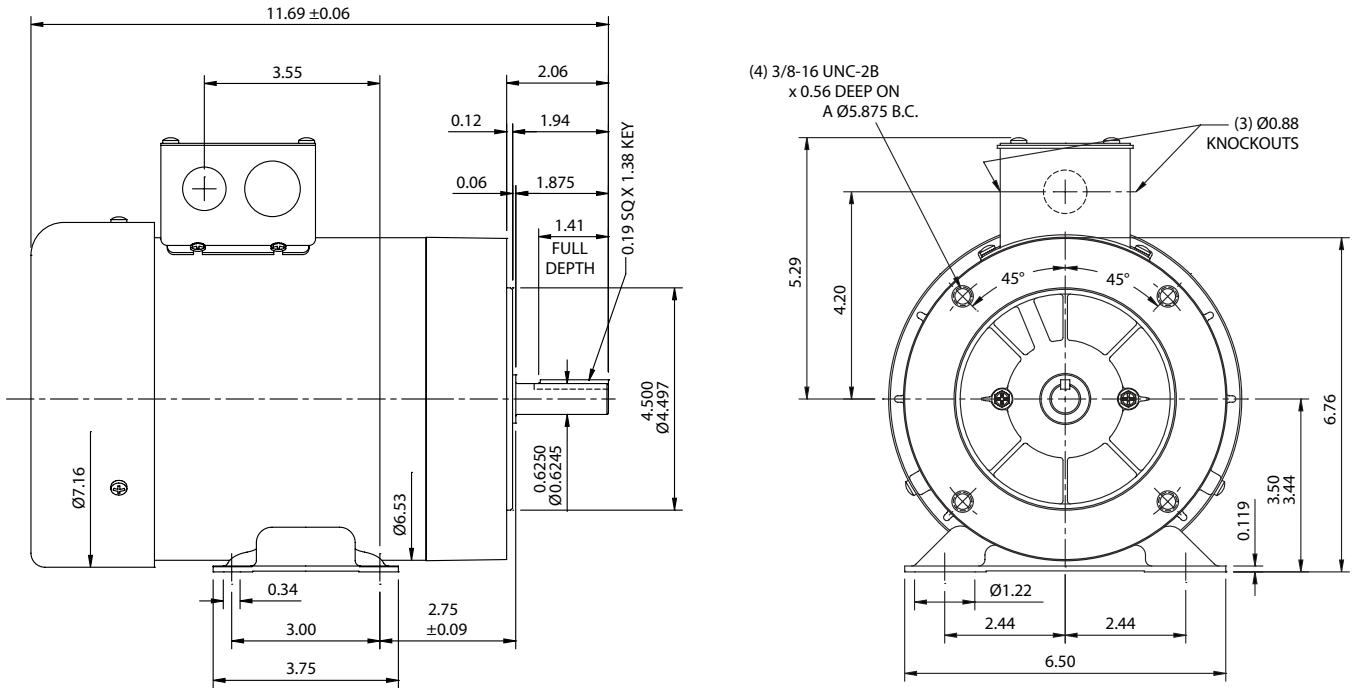
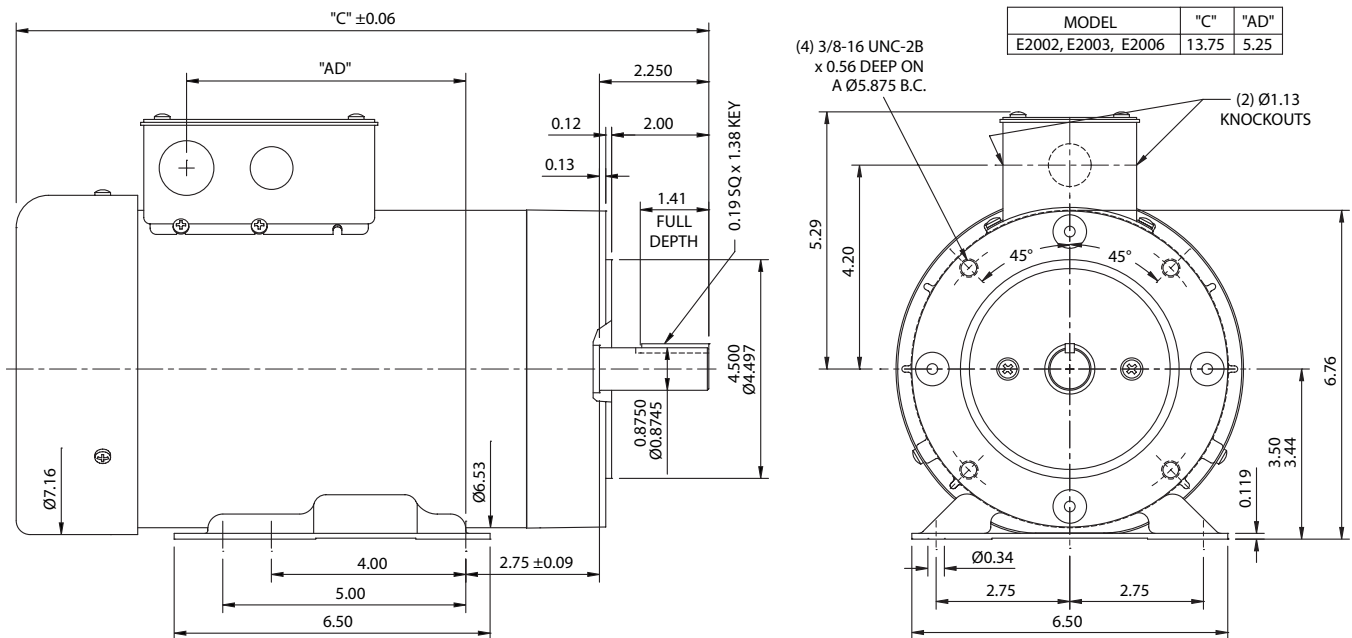


Figure 2 - Frame 143/5TC – Part #: **E2002, E2003**



# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors

## Dimensions (units = inches)

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Figure 3 - Frame 143/5TC - Part #: **E2001A, E2004A, E2007A**

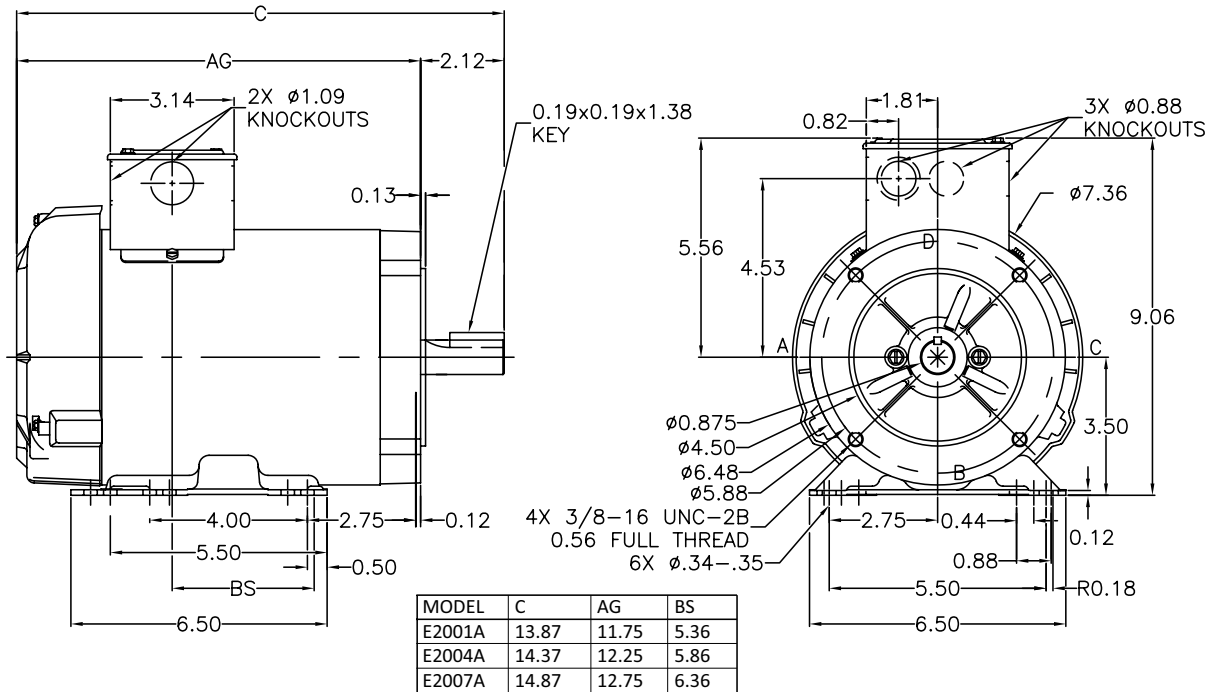
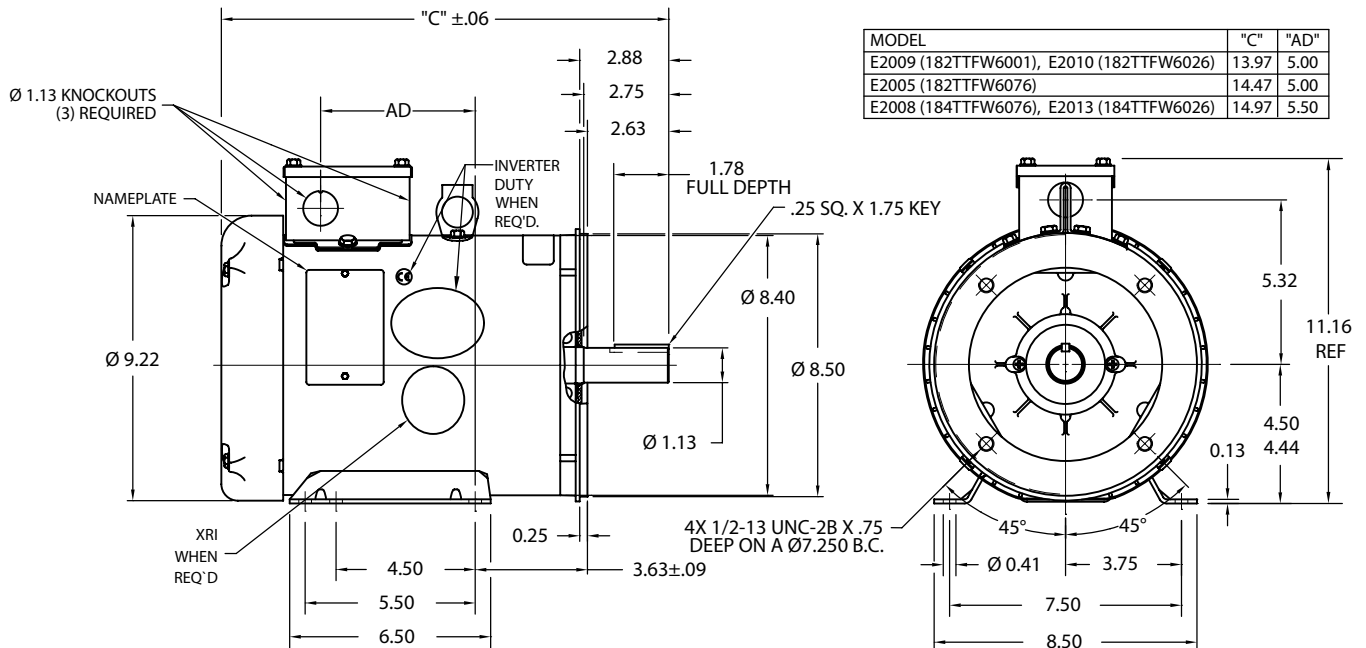


Figure 4 - Frame 182/4TC - Part #: **E2005, E2008, E2009, E2010, E2013**

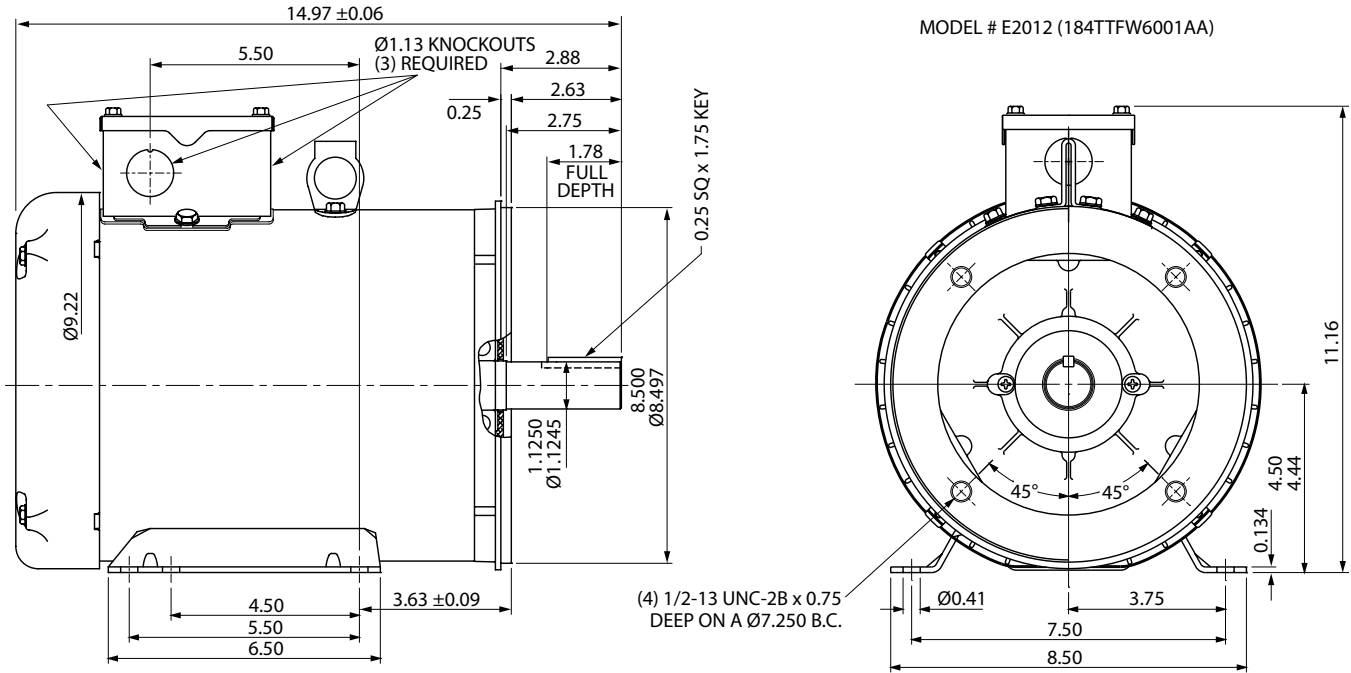


# NEMA Premium® Efficiency XRI® Series Inverter Duty Motors

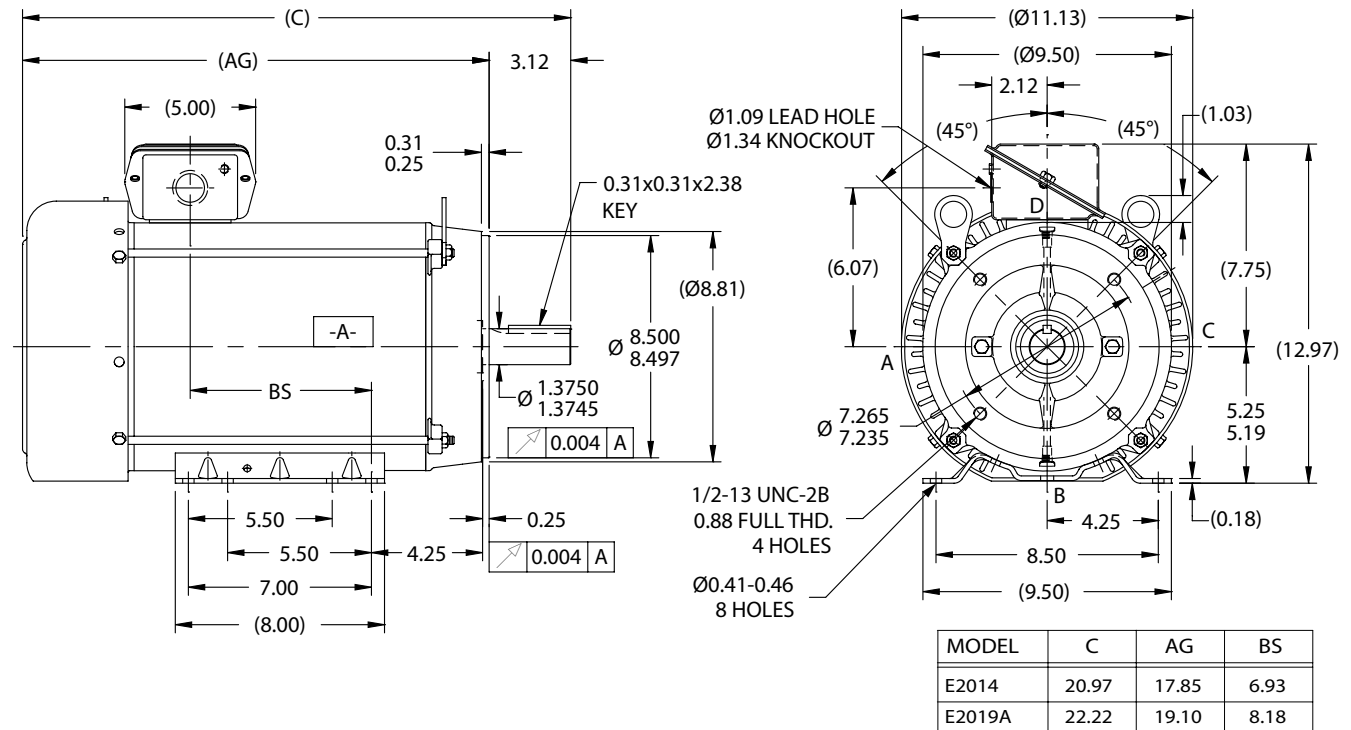
## Dimensions (units = inches)

See our website: [www.AutomationDirect.com](http://www.AutomationDirect.com) for complete engineering drawings.

**Figure 5 - Frame 184TC – Part #: E2012**



**Figure 6 - Frame 213/5TC – Part #: E2011, E2015, E2016A, E2018**



# STABLE™ Motor Slide Bases

## Mounting Slide Bases for 56 to 449T NEMA Motors Features

- Allows adjustment of motor mounting position
- Slide direction is perpendicular to motor shaft
- Double adjusting screws for frames 182T-449T
- Manufactured to precise dimensional standards
- Dimensionally interchangeable with existing major makes
- Heavy-duty steel construction
- Painted with oven-baked primer for better adhesion of customer's paint
- All "D" bolts (motor mounting bolts) are fixed to the exact motor foot pattern
- All "D" bolts are welded into position to prevent spinning and dropping from slots
- Nuts and washers are provided for securing the motor to the slide base



### STABLE Motor Slide Bases for 3-Phase Motors

Part Number	Price	Fits Frame Type	Product Wt. (lb)	Fits Motor						
				IronHorse	Marathon					Blue Chip XRI 230/460V ---- Blue Chip XRI 575V
					micro -MAX ---- Max+	Black Max 230/460V ---- Black Max 575V	Blue Max	XRI GP & NEMA Premium	Powerwash SXT & Jet Pump	
<b><u>MTA-BASE-W56 *</u></b>		56*	2.8	MTPM-P3x-1x18 MTPM-P5x-1x18 MTPM-P7x-1x18 MTPM-0xx-1x18 MTPM-1xx-1x18 MTR(2)(P)-xxx-xxxxx*	<a href="#">Y500</a> <a href="#">Y502</a> <a href="#">Y360</a> <a href="#">Y362</a> <a href="#">Y364</a> <a href="#">Y280</a> <a href="#">Y281</a> <a href="#">Y282</a>	<a href="#">Y592(-A772)</a> <a href="#">Y534(-A772)</a> <a href="#">Y535(-A772)</a> <a href="#">Y555(-A772)</a> <a href="#">Y556(-A772)</a>	-	<a href="#">E2000</a> <a href="#">D390</a> <a href="#">G580</a> <a href="#">K703</a> <a href="#">D391</a> <a href="#">G581</a> <a href="#">K705</a> <a href="#">D392</a> <a href="#">G582</a> <a href="#">K707</a> <a href="#">D393A</a> <a href="#">K708A</a> <a href="#">G583A</a> <a href="#">K709A</a> <a href="#">D394A</a> <a href="#">K721A</a> <a href="#">G584A</a> <a href="#">K722A</a> <a href="#">D395A</a> <a href="#">G585A</a> <a href="#">K724A</a> <a href="#">D396A</a> <a href="#">K725A</a>	<a href="#">N410</a> <a href="#">J066A</a>	-
<b><u>MTA-BASE-W143T</u></b>		143T/TC	4.6	<a href="#">MTC2-001-3BD18(C)</a> <a href="#">MTC2-1P5-3BD36</a>	-	<a href="#">Y536(-A772)</a>	-	<a href="#">E2001A</a> <a href="#">E2003</a>		-
<b><u>MTA-BASE-W145T</u></b>		145T/TC	5.1	<a href="#">MTC2-001-3BD12</a> <a href="#">MTC2-1P5-3BD18(C)</a> <a href="#">MTC2-002-3BD18(C)</a> <a href="#">MTC2-002-3BD36</a>	<a href="#">Y366</a> <a href="#">Y368</a> <a href="#">Y284</a> <a href="#">Y285</a>	<a href="#">Y537(-A772)</a> <a href="#">Y538(-A772)</a> <a href="#">Y551(-A772)</a> <a href="#">Y557(-A772)</a>	-	<a href="#">E2002</a> <a href="#">E2004A</a> <a href="#">E2007A</a>		-
<b><u>MTA-BASE-W182T</u></b>		182T/TC	9.2	<a href="#">MTC2-1P5-3BD12</a> <a href="#">MTC2-003-3BD18(C)</a> <a href="#">MTC2-003-3BD36</a> <a href="#">MTF-002-1C18-182</a>	<a href="#">Y1999</a> <a href="#">Y286A</a>	<a href="#">Y541A(-A772)</a> <a href="#">Y558A(-A772)</a>	-	<a href="#">E2005</a> <a href="#">E2009</a> <a href="#">E2010</a>	<a href="#">G590A</a> <a href="#">C382B</a> <a href="#">C383B</a>	-

\* IronHorse MTR2 56HC motors have double-punched bases to fit on slide base [MTA-BASE-W56](#).

\*\* Motors [MTC-250-3D18](#) and [MTC-300-3D18](#) are obsolete, and no longer available.

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# STABLE™ Motor Slide Bases

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STABLE Motor Slide Bases for 3-Phase Motors										
Part Number	Price	Fits Frame Type	Product Wt. (lb)	Fits Motor						
				IronHorse	Marathon					Blue Chip XRI 230/460V ---- Blue Chip XRI 575V
					micro-MAX ---- Max +	Black Max 230/460V ---- Black Max 575V	Blue Max	XRI GP & NEMA Premium	Powerwash SXT & Jet Pump	
<a href="#">MTA-BASE-W184T</a>		184T/TC	10	<a href="#">MTCP2-002-3BD12</a> <a href="#">MTCP2-005-3BD18(C)</a> <a href="#">MTCP2-005-3BD36</a> <a href="#">MTF-00x-1C18</a>	<a href="#">Y1372</a> <a href="#">Y287A</a>	<a href="#">Y540(-A772)</a> <a href="#">Y543A(-A772)</a> <a href="#">Y559A(-A772)</a>	-	<a href="#">E2008</a> <a href="#">E2012</a> <a href="#">E2013</a>	<a href="#">C387B</a>	-
<a href="#">MTA-BASE-W213T</a>		213T/TC	13	<a href="#">MTCP2-003-3BD12</a> <a href="#">MTCP2-7P5-3BD18(C)</a> <a href="#">MTCP2-7P5-3BD36</a>	<a href="#">Y994</a>	<a href="#">Y542(-A772)</a> <a href="#">Y545(-A772)</a> <a href="#">Y560(-A772)</a>	-	<a href="#">E2011</a> <a href="#">E2015</a> <a href="#">E2016A</a>	<a href="#">C389B</a> <a href="#">C390B</a> <a href="#">C391B</a> <a href="#">E2011A</a> <a href="#">E2015A</a> <a href="#">E2016B</a>	-
<a href="#">MTA-BASE-W215T</a>		215T/TC	15	<a href="#">MTCP2-005-3BD12</a> <a href="#">MTCP2-010-3BD18(C)</a> <a href="#">MTCP2-010-3BD36</a>	<a href="#">Y996</a>	<a href="#">Y544(-A772)</a> <a href="#">Y547(-A772)</a> <a href="#">Y561(-A772)</a>	-	<a href="#">E2018</a>	<a href="#">C392B</a> <a href="#">E2014A</a> <a href="#">E2018A</a> <a href="#">E2019B</a>	-
<a href="#">MTA-BASE-W254T</a>		254T/TC	18	<a href="#">MTCP2-7P5-3BD12</a> <a href="#">MTCP2-015-3BD18(C)</a> <a href="#">MTCP2-015-3BD36</a>	-	<a href="#">Y546(-A772)</a> <a href="#">Y549(-A772)</a> <a href="#">Y562(-A772)</a>	-	-	-	<a href="#">E307</a>
<a href="#">MTA-BASE-W256T</a>		256T/TC	19	<a href="#">MTCP2-010-3BD12</a> <a href="#">MTCP2-020-3BD18(C)</a> <a href="#">MTCP2-20-3BD36</a>	-	<a href="#">Y548(-A772)</a> <a href="#">Y552(-A772)</a> <a href="#">Y563(-A772)</a>	-	-	-	<a href="#">E308</a>
<a href="#">MTA-BASE-W284T</a>		284T/TC	20	<a href="#">MTCP2-015-3BD12</a> <a href="#">MTCP2-025-3BD18(C)</a>	-	<a href="#">Y553(-A772)</a>	-	-	-	<a href="#">E207</a> <a href="#">E309</a>
<a href="#">MTA-BASE-W286T</a>		286T/TC	21	<a href="#">MTCP2-20-3BD12</a> <a href="#">MTCP2-030-3BD18(C)</a>	-	<a href="#">Y393(-A772)</a>	-	-	-	<a href="#">E208</a> <a href="#">E310</a>
<a href="#">MTA-BASE-W324T</a>		324T/TC	30	<a href="#">MTCP2-040-3BD18(C)</a>	-	-	<a href="#">Y571(-A774)</a> <a href="#">Y513(-A775)</a>	-	-	<a href="#">E209</a> <a href="#">E311</a>
<a href="#">MTA-BASE-W326T</a>		326T/TC	31	<a href="#">MTCP2-050-3BD18(C)</a>	-	-	<a href="#">Y572(-A774)</a> <a href="#">Y514(-A775)</a>	-	-	<a href="#">E210</a>
<a href="#">MTA-BASE-W364T</a>		364T/TC	43	<a href="#">MTCP2-060-3BD18(C)</a>	-	-	<a href="#">Y573(-A774)</a> <a href="#">Y515(-A775)</a>	-	-	<a href="#">E313</a>
<a href="#">MTA-BASE-W365T</a>		365T/TC	43	<a href="#">MTCP2-075-3BD18(C)</a>	-	-	<a href="#">Y574(-A774)</a> <a href="#">Y516(-A775)</a>	-	-	<a href="#">E212</a> <a href="#">E315</a>
<a href="#">MTA-BASE-W404T</a>		404T/TC	58	-	-	-	-	-	-	-
<a href="#">MTA-BASE-W405T</a>		405T/TC	60	<a href="#">MTCP2-100-3BD18(C)</a>	-	-	<a href="#">Y575(-A774)</a> <a href="#">Y517(-A775)</a>	-	-	<a href="#">E314</a>
<a href="#">MTA-BASE-W444T</a>		444T	63	<a href="#">MTCP2-125-3BD18</a>	-	-	-	-	-	-
<a href="#">MTA-BASE-W445T</a>		445T	65	<a href="#">MTCP2-150-3BD18</a>	-	-	-	-	-	-
<a href="#">MTA-BASE-W447T</a>		447T	89	<a href="#">MTCP2-200-3BD18</a>	-	-	-	-	-	-
<a href="#">MTA-BASE-W449T</a>		449T	94	<a href="#">MTCP2-250-3D18</a> <a href="#">MTCP2-300-3D18</a>	-	-	-	-	-	-

\* IronHorse MTR2 56HC motors have double-punched bases to fit on slide base [MTA-BASE-W56](#).

# AutomationDirect AC Motors Selection Overview

## General-purpose or inverter-duty motor?

### How to choose a general purpose motor vs. an inverter-duty motor

General purpose motors have been around for many years. They are the workhorse of almost every industry. An inverter-duty motor is a much newer concept that was necessary as general purpose motors began to be driven by VFDs (inverters or AC drives). An inverter duty motor can withstand the higher voltage spikes produced by all VFDs (amplified at longer cable lengths) and can run at very slow speeds without overheating. This performance comes at a cost: inverter-duty motors can be much more expensive than general purpose motors. Guidelines for choosing an IronHorse general purpose motor vs. an inverter-duty motor are given below. If your application falls within the guidelines below, there is no need to apply an inverter-duty motor.

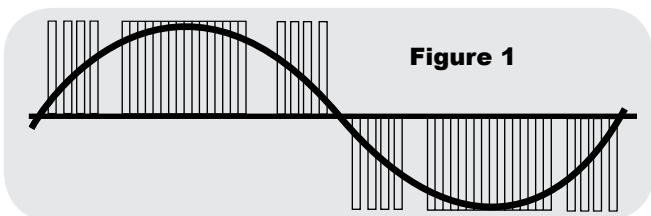
**NOTE:** Marathon inverter-duty motors have limitations as well. Please see the Marathon section for more details.

**Background:** For many years, AC motors were driven by across-the-line contactors and starters. The electricity sent to the motor was a very clean sine wave at 60Hz. Noise and voltage peaks were relatively small. However, there were drawbacks: they only ran electrically at one speed (speed reduction was usually handled by gearboxes or some other, usually inefficient, mechanical means) and they had an inrush of electrical current (when the motor was first turned on) that was usually 5 to 6 times the normal current that the motor would consume. The speed reduction apparatus was expensive and bulky, and the inrush would wreak havoc with power systems and loading (imagine an air conditioning system in an old house - when the compressor would kick on, the lights would dim; now imagine the same circumstances with a motor the size of a small car).

**Note: The following discussion applies only to 3-phase motors. Enter the VFDs (variable frequency drives):**

Drives were introduced to allow the speed of these motors to be changed while running and to lessen the inrush current when the drive first starts up. To do this, the drive takes the incoming 60Hz AC power and rectifies it to a DC voltage (every drive has a DC bus that is around 1.414 (sqrt of 2) \* incoming AC Line Voltage).

This DC voltage is then "chopped" by power transistors at very high frequencies to simulate a sine wave that is sent to the motor [see Figure 1]. By converting the incoming power to DC and then reconverting it to AC, the drive can vary its output voltage and output frequency, thus varying the speed of a motor. Everything sounds great, right? We get to control the frequency and voltage going out to the motor, thus controlling its speed.



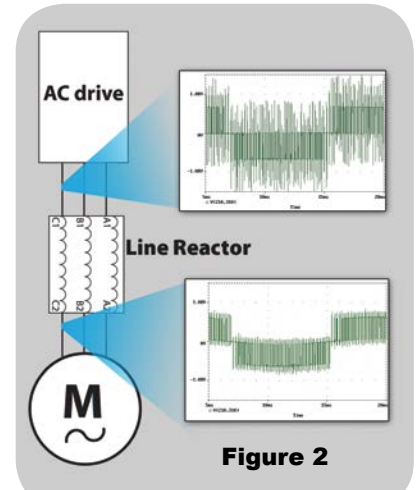
**Figure 1**

**Some things to watch out for:** A VFD-driven general purpose motor can overheat if it is run too slowly. (Motors can get hot if they're run slower than their rated speed.) Since most general purpose motors cool themselves with shaft-mounted fans, if the motor overheats, bearing and insulation life will be reduced. Therefore there are minimum speed requirements for all motors.

The voltage "chopping" that occurs in the drive actually sends high-voltage spikes (at the DC bus level) down the wire to the motor. If the system contains long cabling, there are actually instances where a reflected wave occurs at the motor. The reflected wave can effectively double the voltage on the wire. This can lead to premature failure of the motor insulation. Long cable lengths between the motor and drive increase the harmful effects of the reflected wave, as do high chopping frequencies (listed in drive manuals as carrier frequencies).

Line reactors, 1:1 transformers placed at the output of the drive, can help reduce the voltage spikes going from the drive to the motor. Line reactors are used in many instances when the motor is located far from the drive [see Figure 2].

In summary, general purpose motors can be run with drives in many applications; however inverter-duty motors are designed to handle much lower speeds without overheating and they are capable of withstanding higher voltage spikes without their insulation failing. With the increased performance comes an increase in cost. This additional cost can be worth it if you need greater performance.



**Figure 2**

The considerations for applying IronHorse motors are given below.

### Heat considerations

	IronHorse speed ratio	For an 1800 RPM motor, minimum IronHorse speed is:
Variable Torque applications (fans, centrifugal pumps, etc.)	5:1 (EPAct motors)	1800/5 = 360RPM
	10:1 (PE motors)	1800/5 = 180RPM
Constant Torque Applications (conveyors, extruders, etc.)	2:1 (EPAct motors)	1800/2 = 900RPM
	4:1 (PE motors)	1800/4 = 450RPM

### Voltage Spike considerations

	Max cable distance from drive to IronHorse motor	Max cable distance with a 3% line reactor between drive and IronHorse motor
For use with 230V and 460V VFDs*	125 ft	250 ft

\* Up to 6kHz carrier frequency