DURAPULSE GS3 AC Drives – Introduction

GS3 AC Drives																
Motor Poting	HP	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100
Motor Rating		0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
230V Single-Phase Input / 230V Three-Phase Output		✓	√	√												
230V Three-Phase Input / Output		✓	√	√	√	√	✓	✓	✓	✓	√	✓	✓			
460V Three-Phase Input / Output		✓	√	√	√	√	✓	√	✓	√	√	√	√	✓	√	√

Overview

The DURAPULSE series of AC drives offers all of the features of our GS2 series of drives including dynamic braking, PID, removable keypad and RS-485 Modbus communication. The DURAPULSE AC drive also offers sensorless vector control with the option of encoder feedback for enhanced speed control. The standard smart keypad (or Human Interface Module) is designed with defaults for the North American customer and allows you to configure the drive, set the speed, start and stop the drive, and monitor critical parameters for your application. In addition, this keypad has internal memory that allows four complete programs to be stored and transferred to any DURAPULSE drive. The DURAPULSE series offers three analog inputs, eleven digital inputs, and one SPDT relay output.



Features

- Simple Volts/Hertz control
- · Sensorless vector control with autotune
- Sensorless vector control with optional encoder feedback card, for better speed control
- Sinusoidal pulse width modulation (PWM)
- Variable carrier frequency, depending on model
- IGBT technology
- Starting torque: 125% @ 0.5 Hz/150% @ 1Hz
- 150% rated current for one minute
- · Electronic overload protection
- Stall prevention
- Adjustable accel and decel ramps with linear and S-curve settings
- Automatic torque and slip compensation
- Internal dynamic braking circuit for models under 20 hp; optional baking units available for models 20 hp and above
- DC braking
- · Five skip frequencies
- · Trip history
- Programmable jog speed
- Integral PID control
- Removable smart keypad with parameter upload/download
- Keypad with memory to store up to four programs of any *DURAPULSE* drive
- Eleven programmable digital inputs
- Three programmable analog inputs
- Three digital and one SPDT relay programmable outputs
- One programmable analog output
- One digital frequency output
- RS-485 Modbus communications
- Ethernet communication optional
- Two-year warranty
- UL/cUL/CE listed

Accessories

- AC line reactors
- EMI filters
- · RF filter
- Braking resistors
- Braking units (for models 20 hp and above)
- Fuse kits and replacement fuses
- · Replacement cooling fans
- Remote panel adapter
- · Replacement keypad
- Keypad cables in 1, 3, and 5-meter lengths
- · Ethernet interface
- Four and eight-port RS-485 multi-drop termination boards
- GSoft drive configuration software
- GS3-FB feedback card
- GS-485HD15-CBL ZIPLink RS485 communication cable for connection to the DL06 and D2-260 15-pin ports
- USB-485M USB to RS-485 PC adapter (see "Communications Products" chapter for detailed information)
- Detailed descriptions and specifications for GS accessories are available in the "GS/DURAPULSE Accessories" section.

Typical Applications

- Conveyors
- Fans
- Pumps
- Compressors
- HVAC
- Material handling
- Mixing
- · Shop tools
- Extruding
- Grinding

DURAPULSE GS3 AC Drives Specifications

						230\	/ Class	3						
Model Na	ame		<u>GS3-</u> 21P0	GS3- 22P0	<u>GS3-</u> 23P0	GS3- 25P0	<u>GS3-</u> 27P5	<u>GS3-</u> 2010	<u>GS3-</u> 2015	<u>GS3-</u> 2020	<u>GS3-</u> 2025	<u>GS3-</u> 2030	<u>GS3-</u> 2040	<u>GS3-</u> 2050
Price			<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>
	HI HI		1.0	2.0	3.0	5.0	7.5	10	15	20	25	30	40	50
0.4.4	Max Motor Output	kW	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37
Output Rating	Rated Output Current (A)		5	7	11	17	25	33	49	65	75	90	120	145
	Max Output Voltage		Three-phase 200 to 240V (proportional to input voltage)											
	Rated Frequency		0.1 to 400 Hz											
	Rated Voltage/Frequency		Single/Three-phase Three-phase											
* Input	nateu voltaye/Frequency		200/208/220/230/240 VAC, 50/60Hz											
Rating	Rated Input Current (A)		11.9 / 5.7	15.3 / 7.6	22 / 15.5	20.6	26	34	50	60	75	90	110	142
Voltage/l	Frequency Tolerance		Voltage: ± 10% Frequency: ± 5%											
Watt Loss @ 100% I (W)		60	82	130	194	301	380	660	750	920	1300	1340	1430	
Weight (lb [kg])			4.5 [2.034]	4.5 [2.034]	9.4 [4.24]	9.4 [4.24]	13.3 [6.031]	13.3 [6.031]	14.3 [6.487]	26.5 [12]	26.5 [12]	26.5 [12]	77.2 [35]	77.2 [35]
* All 3-pha	se power sources must be symn	netrical.												

Do not connect any DURAPULSE drives to grounded, center-tapped delta transformers (which are typically used for lighting circuits).

						4	60V CI	ass –	Three-	Phase						
Model I	Vame		GS3- 42P0	<u>GS3-</u> <u>43P0</u>	<u>GS3-</u> <u>45P0</u>	<u>GS3-</u> <u>47P5</u>	<u>GS3-</u> <u>4010</u>	<u>GS3-</u> 4015	<u>GS3-</u> <u>4020</u>	<u>GS3-</u> <u>4025</u>	<u>GS3-</u> <u>4030</u>	<u>GS3-</u> <u>4040</u>	<u>GS3-</u> <u>4050</u>	<u>GS3-</u> <u>4060</u>	<u>GS3-</u> <u>4075</u>	<u>GS3-</u> <u>4100</u>
Price			<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>	<>
	Maximun Motor	n HP	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100
	Output	kW	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
Output	Rated Ou Current (•	4.2	5.5	8.5	13	18	24	32	38	45	60	73	91	110	150
Rating	Maximun Output Voltage	n		Three-phase 380 to 480V (proportional to input voltage)												
	Rated Frequent	ey .		0.1 to 400 Hz												
*Input	Rated Voltage/ Frequent	;y		Three-phase, 380/400/415/440/460/480VAC, 50/60Hz												
Rating	Rated In		4.3	5.9	11.2	14	19	25	32	39	49	60	63	90	130	160
Toleran	Frequenc ce	y						Volta	ge: ± 10%	Frequency:	± 5%					
Watt Lo	ss @		102	132	176	250	345	445	620	788	1290	1420	1680	2020	2910	3840
Weight	(lb [kg])		4.4 [1.994]	4.1 [1.857]	9.4 [4.24]	13.2 [6.002]	13.5 [6.106]	14.4 [6.525]	26.5 [12]	26.5 [12]	26.5 [12]	77.2 [35]	77.2 [35]	77.2 [35]	116.8 [53]	116.8 [53]
* ΔII 3-nI	hase nower	SOURCES	must be svi	mmetrical												

All 3-phase power sources must be symmetrical.

Do not connect any DURAPULSE drives to grounded, center-tapped delta transformers (which are typically used for lighting circuits).

DURAPULSE GS3 AC Drives General Specifications

Control System Rated Output Fre Output Frequency	y Resolution ty		Control Characteristics Pulse Width Modulation, Carrier frequency adjustable from 1–15 kHz depending on the model. This system determines the control methods of the AC drive. 00: V/Hz open loop control 01: V/Hz closed loop control 02: Sensorless Vector 03: Sensorless Vector with external feedback				
Rated Output Fre	y Resolution ty		Pulse Width Modulation, Carrier frequency adjustable from 1–15 kHz depending on the model. This system determines the control methods of the AC drive. 00: V/Hz open loop control 01: V/Hz closed loop control 02: Sensorless Vector				
Rated Output Fre	y Resolution ty		This system determines the control methods of the AC drive. 00: V/Hz open loop control 01: V/Hz closed loop control 02: Sensorless Vector				
· · · · · · · · · · · · · · · · · · ·	y Resolution ty						
· · · · · · · · · · · · · · · · · · ·	y Resolution ty		0.1 to 400.0 Hz				
Output Frequency Resolution			0.1 Hz				
Overload Capacity			150% of rated current for 1 minute				
Torque Character			Includes auto-torque boost, auto-slip compensation, starting torque 125% @ 0.5 Hz / 150% @ 1.0 Hz				
Braking Torque	Braking Torque		0% without braking resistor, 125% with optional braking resistor (braking circuit built-in only for units under 20 hp)				
DC Braking			Operation frequency 60–0 Hz, 0–100% rated current, Start time 0.0–5.0 seconds, Stop time 0.0–25.0 seconds				
Acceleration/Dec	eleration Ti	ime	0.1 to 600 seconds (linear or non-linear acceleration/deceleration), second acceleration/deceleration available				
Voltage/Frequent	cy Pattern		Settings available for Constant Torque - low & high starting torque, Variable Torque - low & high starting torque, and user configured				
Stall Prevention	Level		20 to 200% of rated current				
			Operation Specifications				
Keypad			Setting by <up> or <down> buttons</down></up>				
	Frequency Setting	External Signal	Potentiometer - 3 to 5 k Ω , 0 to 10 VDC (input impedance 10 k Ω), -10 to +10 VDC, 4 to 20 mA (input impedance 250 Ω), 0 to 20 mA; Multi-Speed Inputs 1 to 4, RS-232C/RS-485 communication interface				
		Keypad	Setting by <run>, <stop>, <jog> , <fwd>, <rev> buttons</rev></fwd></jog></stop></run>				
	Operation		Forward/Stop, Reverse/Stop (run/stop, fwd/rev), 3-wire control, Serial Communication RS-232C & RS-485 (Modbus				
Inputs	Setting	External Signal	RTU) 11 user-programmable: FWD/STOP, REV/STOP, RUN/STOP, REV/FWD, RUN momentary (N.O.), STOP momentary				
	Input Terminals	Digital Sink/Source Selectable	(N.C.), External Fault (N.O./N.C.), External Reset, Multi-Speed Bit (1-4), Manual Keyboard Control, Jog, External Base Block (N.O./N.C.), Second Accel/Decel Time, Speed Hold, Increase Speed, Decrease Speed, Reset Speed to Zero, PID Disable (N.O.), PID Disable (N.C.), Input Disable				
		Analog	3 user-configurable, 0 to 10V (input impedance 10 k Ω), 0 to 20 mA, 4 to 20 mA (input impedance 250 Ω), 10 bit resolution -10V to +10V, 10 bit resolution				
IIIIIIIII	Output	Digital 3 transistors 1 relay	4 user-programmable: Inverter Running, Inverter Fault, At Speed, Zero Speed, Above Desired Frequency, Below Desired Frequency, At Maximum Speed, Over Torque Detected, Above Desired Current, Below Desired Current, PID Deviation Alarm, Heatsink Overheat Warning (OH), Soft Braking Signal, Above desired Frequency 2, Below desired Frequency 2, Encoder Loss				
Carpato	Terminals	Digital Square Wave	One digital square wave output representing drive frequency				
		Analog	1 user-programmable, 0 to 10V, 8 bit resolution frequency, current, process variable PV				
Operating Function	ons		Automatic voltage regulation, voltage/frequency characteristics selection, non-linear acceleration/deceleration, upper and lower frequency limiters, 15-stage speed operation, adjustable carrier frequency (1 to 15 kHz), PID control, 5 skip frequencies, analog gain & bias adjustment, jog, electronic thermal relay, automatic torque boost, trip history, software protection				
Protective Functi	ons		Electronic Thermal, Over-load Relay, Auto Restart after Fault, Momentary Power Loss, Reverse Operation Inhibit, Auto Voltage Regulation, Over-Voltage Stall Prevention, Auto Adjustable Accel/Decel, Over-Torque Detection Mode, Over-Torque Detection Level, Over-Torque Detection Time, Over-Current Stall Prevention during Acceleration, Over-Current Stall Prevention during Operation				
	Operator De	evices	9-key, 2 line x 16 character LCD display, 5 status LEDs				
Operator	Programmin	ng	Parameter values for setup and review, fault codes				
	Status Displ	lay	Output Frequency, Motor Speed, Scaled Frequency, Output Current, Motor Load, Output Voltage, DC Bus Voltage, PID Setpoint, PID Feedback, Frequency Setpoint				
	Key Function		RUN, STOP/RESET, FWD/REV, PROGRAM, DISPLAY, <up>, <down>, ENTER</down></up>				
_	Enclosure R		Protected Chassis, IP20				
-	Ambient Ten		-10°C to 40°C (14°F to 104°F)				
Fnvironment -	Storage Ten		-20°C to 60°C (-4°F to 140°F) – during short term transportation period				
	Ambient Hui	midity	20 to 90% RH (non-condensing)				
-	Vibration		9.8 m/s ² (1G) less than 10 Hz; 5.9 m/s ² (0.6G) 10 to 60 Hz				
	Installation	Location	Altitude 1000m or lower above sea level, keep from corrosive gas, liquid and dust				
Options			Noise filter, input AC reactor, output AC reactor, cable for remote operator, programming software, dynamic braking resistor, dynamic braking unit; RF filter; remote panel adapter; Ethernet interface; four and eight port RS-485 multidrop termination boards, replacement keypads, fuse kits and replacement fuses				

DURAPULSE GS3 AC Drives Specifications – Installation

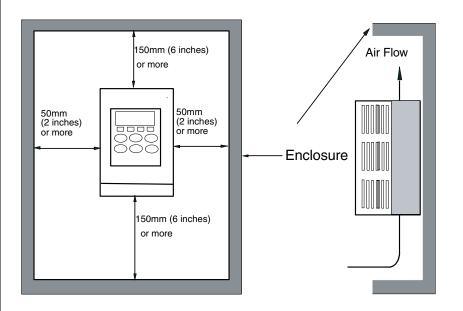
Understanding the installation requirements for your *DURAPULSE* AC drive will help to ensure that it operates within its environmental and electrical limits.

Note: Never use only this catalog for installation instructions or operation of equipment; refer to the user manual, GS3-M.

Environmental Specifications							
Protective Structure ¹	IP20						
Ambient Operating Temperature ²	-10 to 40°C (14°F to 104°F)						
Storage Temperature ³	-20 to 60°C (-4°F to 140°F)						
Humidity	To 90% (no condensation)						
Vibration ⁴	9.8 m/s² (1g), less than 10 Hz 5.9 m/s² (0.6g),10 to 60 Hz						
Location	Altitude 1,000 m or less, indoors (no corrosive gases, liquids or dust)						

- 1: Protective structure is based upon EN60529
- 2: The ambient temperature must be in the range of
- -10° to 40° C. If the range will be up to 50° C, you will need to set the carrier frequency to 2.1 kHz or less and derate the output current to 80% or less.
- 3: The storage temperature refers to the short-term temperature during transport.
- 4: Conforms to the test method specified in JIS CO911 (1984)

Watt-loss C	hart
GS3 Drive Model	At full load
<u>GS3-21P0</u>	60
GS3-22P0	82
<u>GS3-23P0</u>	130
GS3-25P0	194
<u>GS3-27P5</u>	301
<u>GS3-2010</u>	380
GS3-2015	660
<u>GS3-2020</u>	750
GS3-2025	920
<u>GS3-2030</u>	1300
<u>GS3-2040</u>	1340
<u>GS3-2050</u>	1430
<u>GS3-42P0</u>	102
<u>GS3-43P0</u>	132
<u>GS3-45P0</u>	176
<u>GS3-47P5</u>	250
<u>GS3-4010</u>	345
<u>GS3-4015</u>	445
<u>GS3-4020</u>	620
<u>GS3-4025</u>	788
<u>GS3-4030</u>	1290
<u>GS3-4040</u>	1420
<u>GS3-4050</u>	1680
<u>GS3-4060</u>	2020
<u>GS3-4075</u>	2910
<u>GS3-4100</u>	3840



Minimum Clearances and Air Flow



WARNING: AC DRIVES GENERATE A LARGE AMOUNT OF HEAT WHICH MAY DAMAGE THE AC DRIVE. AUXILIARY COOLING METHODS ARE TYPICALLY REQUIRED IN ORDER NOT TO EXCEED MAXIMUM AMBIENT TEMPERATURES.



WARNING: MAXIMUM AMBIENT TEMPERATURES MUST NOT EXCEED 50°C (122°F), OR 40°C (104°F) FOR MODELS 7.5 HP (5.5 KW) AND HIGHER!

DURAPULSE GS3 AC Drives Specifications —

Terminals

Maii	Main Circuit Terminals							
Terminal	Description							
L1, L2, L3	Input Power							
T1, T2, T3	AC Drive Output							
B1, B2	Braking Resistor Connection (Under 20HP)							
+2, – (negative)	External Dynamic Brake Unit (20HP & Over)							
÷	Ground							



GS3-4030 shown

	Co	ntrol Circuit Terminals
Terminal Symbol	Description	Remarks
+24V	DC Voltage Source	(+24V, 20mA), used only for AC drive digital inputs wired for source mode operation
DI1	Digital Input 1	
DI2	Digital Input 2	
DI3	Digital Input 3	
DI4	Digital Input 4	Lead Malliana delegandi O collind (con Marcine balan)
DI5	Digital Input 5	Input Voltage: Internally Supplied (see Warning below) Sink Mode: Low active, V _{inL} Min = 0V, V _{inL} Max = 15V,
D16	Digital Input 6	Iin Min = 2.1mA, $ $ $ $ Max = 7.0mA
DI7	Digital Input 7	Source Mode: High active, V _{inH} Min = 8.5V, V _{inH} Max = 24V, I _{in} Min = 2.1mA, I _{in} Max = 7.0mA
DI8	Digital Input 8	Input response: 12–15 msec Also see "Basic Wiring Diagram" on the next pages.
DI9	Digital Input 9	Also see basic willing Diagram on the next pages.
DI10	Digital Input 10	
DI11	Digital Input 11	
DCM	Digital Common	
+10V	Internal Power Supply	+10VDC (10mA maximum load)
AI1	Analog Input	0 to +10 V input only
AI2	Analog Input	0 to 20mA / 4 to 20mA input
AI3	Analog Input	-10 to +10 V input only
ACM	Analog Common	
R10	Relay Output 1 Normally Open	Resistor Load: 240VAC - 5A (N.O) / 3A (N.C.)
R1C	Relay Output 1 Normally Closed	24VDC - 5A (N.O.) / 3A (N.C.) Inductive Load:
R1	Relay Output 1 Common	240VAC - 1.5A (N.O) / 0.5A (N.C) 24VDC - 1.5A (N.O) / 0.5A (N.C) See P 3.01 to P 3.03
D01	Photocoupled digital output	
D02	Photocoupled digital output	Maximum 48VDC, 50mA
D03	Photocoupled digital output	maximum 40700, Julia
DOC	Digital Output Common	
AO	Analog Output	0 to +10 V 2mA Output
F0	Digital Frequency Output	Square wave pulse train output



WARNING: DO NOT CONNECT EXTERNAL VOLTAGE SOURCES TO THE DIGITAL INPUTS. PERMANENT DAMAGE MAY RESULT.



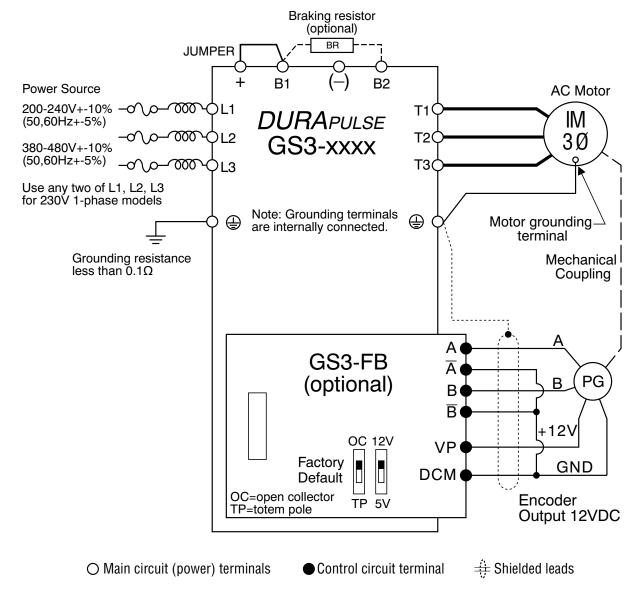
Note: Use twisted-shielded, twisted-pair or shielded-lead wires for the control signal wiring. It is recommended to run all signal wiring in a separate steel conduit. The shield wire should only be connected at the AC drive. Do not connect shield wire on both ends.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram – drives under 20 hp

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-M for additional specific wiring information.)

Note: Please refer to the following pages for explanations and information regarding feedback cards (pg.tGSX-116), line reactors (pg.tGSX-118), braking components (pg.tGSX-17), EMI filters (pg.tGSX-150), RF filters (pg.tGSX-159), and fuses (pg.tGSX-160).



 \triangle

WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

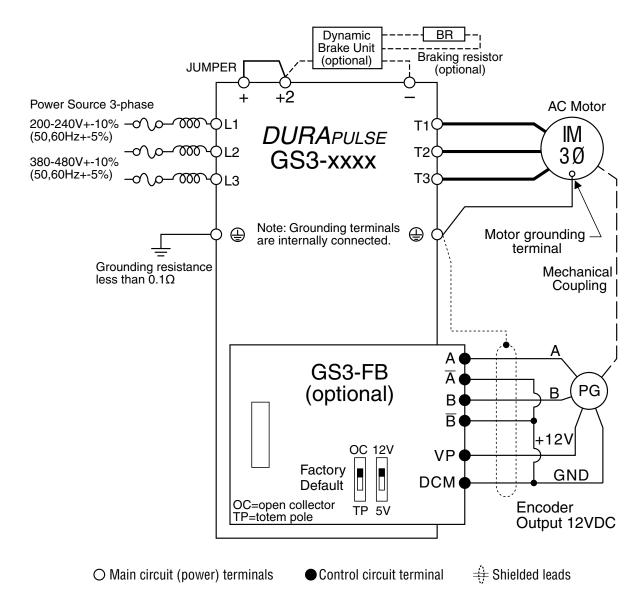
TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram - 20 to 30 hp (230 VAC) & 20 to 60 hp (460 VAC)

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-M for additional specific wiring information.)

Note: Pleaserefertothefollowingpagesforexplanations and information regarding feedbackcards (pg.tGSX-116), linereactors (pg.tGSX-118), braking components (pg.tGSX-17), EMI filters (pg.tGSX-150), RF filters (pg.tGSX-159), and fuses (pg.tGSX-160).



WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

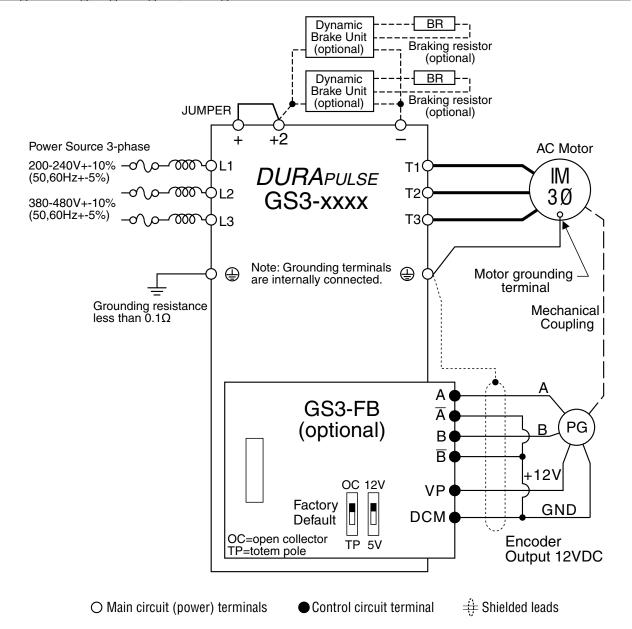
TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram - 40 to 50 hp (230 VAC) & 75 to 100 hp (460 VAC)

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-UMP for additional specific wiring information.)

Note: Please refer to the following catalog pages in the Drives section of our catalog for explanations and information regarding feedback cards (X), line reactors (X), braking units (X) and resistors (X), EMI (X) and RF (X) filters, and fuses (X).



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WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

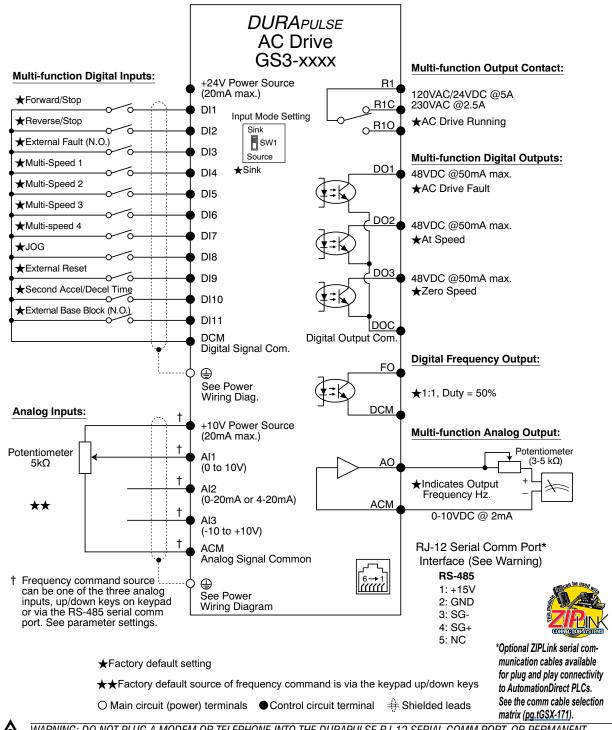
TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

DURAPULSE GS3 AC Drives – Control Wiring Diagram – DI Connection to Sinking Outputs

Control Wiring Diagram - Digital Input Connections to Sinking Output Devices



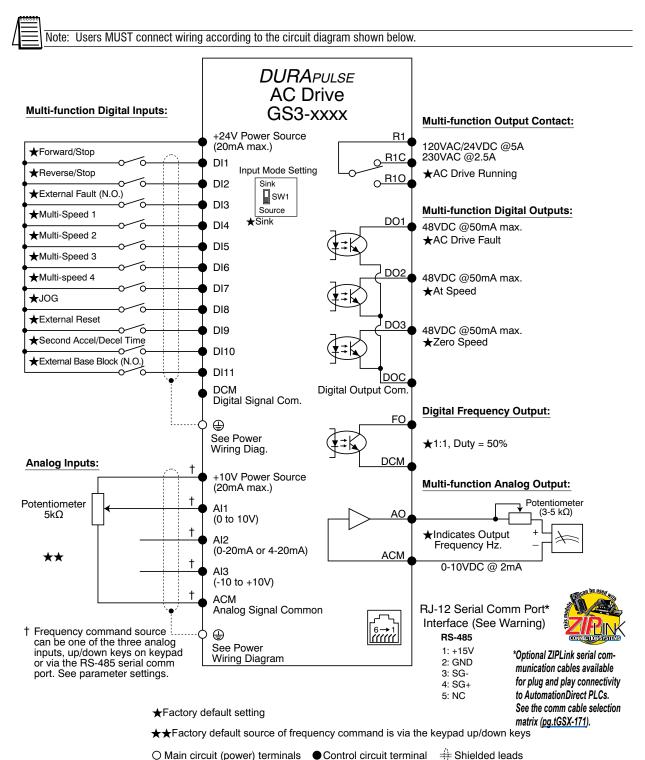
Note: Users must connect wiring according to the circuit diagram shown below.



WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

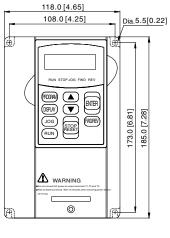
DURAPULSE GS3 AC Drives – Control Wiring Diagram – DI Connections to Sourcing Outputs

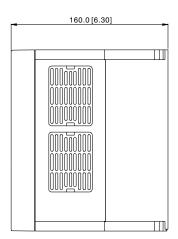
Control Wiring Diagram - Digital Input Connections to Sourcing Output Devices

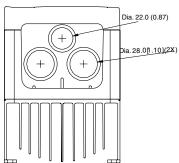


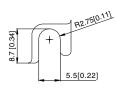
WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

GS3-21P0, GS3-22P0, GS3-42P0

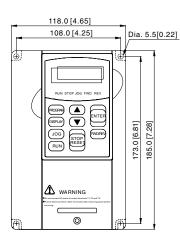


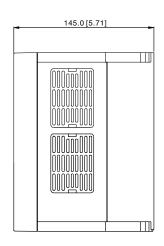


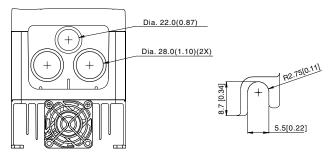




GS3-43P0

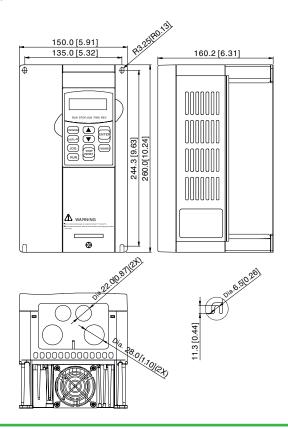




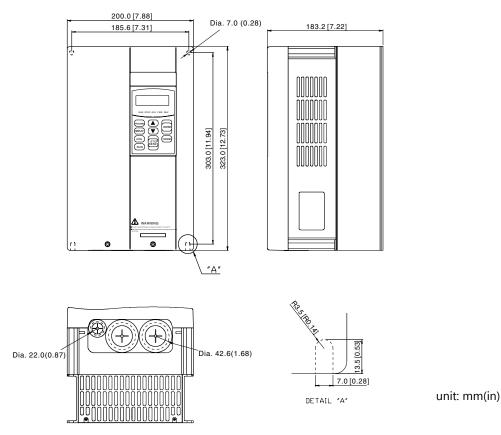


unit: mm(in)

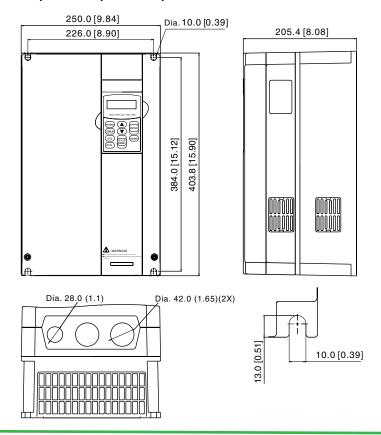
GS3-23P0, GS3-25P0, GS3-45P0



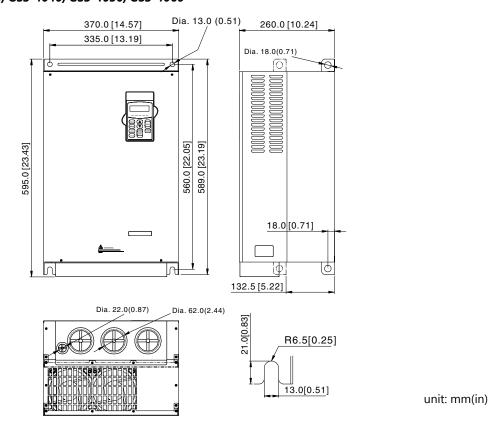
GS3-27P5, GS3-2010, GS3-2015, GS3-47P5, GS3-4010, GS3-4015



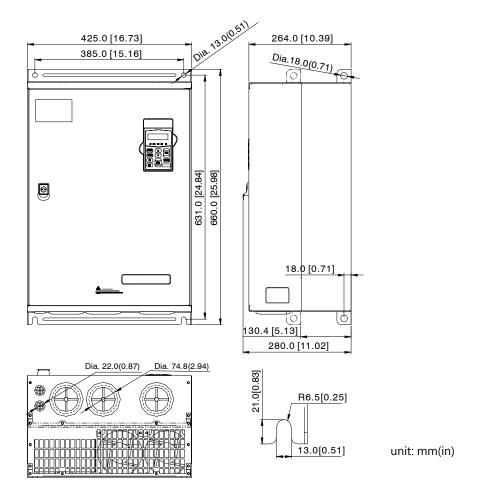
GS3-2020, GS3-2025, GS3-2030, GS3-4020, GS3-4025, GS3-4030



GS3-2040, GS3-2050, GS3-4040, GS3-4050, GS3-4060



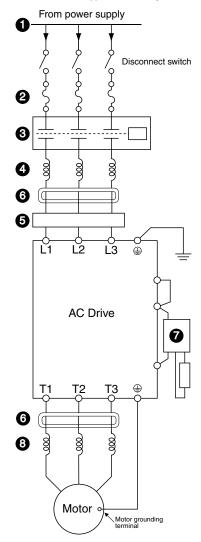
GS3-4075, GS3-4100



AC Drives Optional Accessories – Overview

Drive Accessories

(not all accessories are applicable for every drive model)



1 Power Supply

Please follow the specific power supply requirements as detailed in the specific drive manual

2 Fuses

Input fuses protect the AC drive from excessive input current due to line surges, short circuits, and ground faults. They are recommended for all installations and may be required for UL-listed installations.

3 Contactor (Optional)

Do not use a contactor or disconnect switch for run/stop control of the AC drive and motor. This will reduce the operating life cycle of the AC drive. Cycling a power circuit switching device while the AC drive is in run mode should be done only in emergency situations.

4 Input Line Reactor (Optional)

See the Line Reactors section at $\underline{www.automation direct.com}$ for more information.

Input line reactors protect the AC drive from transient overvoltage conditions, typically caused by utility capacitor switching. The input line reactor also reduces the harmonics associated with AC drives. Input line reactors are recommended for all installations.

5 EMI filter (Optional)

See the EMI Filters section at www.automationdirect.com for more information.

Input EMI filters reduce electromagnetic interference or noise on the input side of the AC drive. They are required for CE compliance and recommended for installations prone to or sensitive to electromagnetic interference.

6 RF filter (Optional)

RF filters reduce the radio frequency interference or noise on the input or output side of the inverter.

7 Braking Unit and/or Braking Resistor (Optional)

Dynamic braking allows the AC drive to produce additional braking (stopping) torque. AC drives can typically produce between 15% & 20% braking torque without the addition of any external components. The addition of optional braking may be required for applications that require rapid deceleration or high inertia loads.

3 Output Load Reactor or Voltage Time (dV/dT) Filter (Optional)

Output line reactors protect the motor insulation against AC drive short circuits and IGBT reflective wave damage, and also "smooth" the motor current waveform, allowing the motor to run cooler. They are recommended for operating "noninverter-duty" motors and when the length of wiring between the AC drive and motor is less than 100 feet.

Voltage Time filters provide enhanced protection for motors with distances up to 1,000 feet.

Voltage Time filters provide even more protection against wave reflection and reduce common mode noise. They are recommended when the length of wiring between the AC drive and motor is from 100 feet up to 1,000 feet.

See www.automationdirect.com for specific product offerings.

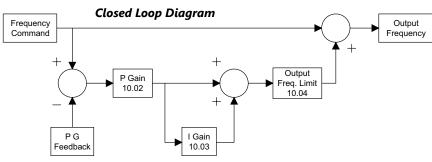
GS3 DURAPULSE Accessories – Feedback Card

Feedback Card for <i>DURA</i> pulse AC Drives								
Part Number	Price	Drive Model						
GS3-FB	<>	GS3-xxxx						
The GS3-FB feedback c AC drives.	ard is for use	only with DURAPULSE						

Description

The GS3-FB card is used to add another layer of precision control to the already precise control algorithm utilized in the DURAPULSE drive series. This added control is activated by selecting control modes V/Hz closed loop control or sensorless vector with external feedback. The feedback mechanism uses pulses generated by an external encoder or pulse generator. Unlike other feedback types, the GS3-FB accommodates the four most common encoder signal types: output voltage, open collector, line driver, and complimentary.

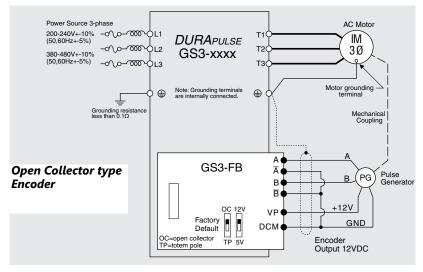




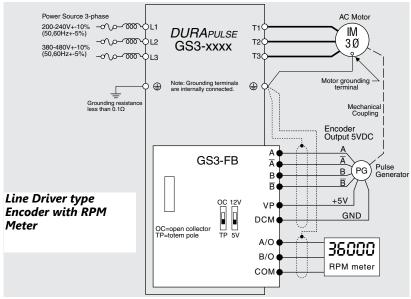
Turo	as of Engadors	SW1 and SW2	switches
Тур	es of Encoders	5V	12V
Output Voltage	VCC O/P	OC12V III TP 5V	OC12V TP 5V
Open collector	VCC O/P	OC12V TP 5V	OC12V TP 5V
Line driver	- Q - Q	OC12V TP 5V	OC12V TP 5V
Complimentary	VCC O/P	OC12V TP 5V	OC12V TP 5V

GS3 DURAPULSE Accessories – Feedback Card

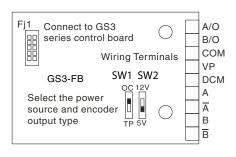
Wiring Diagrams

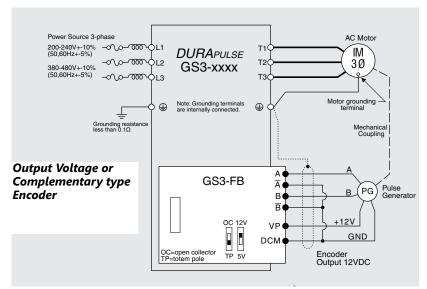


Terminal Symbols	Description
VP	Power source of GS3-FB (SW1 can be switched to 12V or 5V) Output Voltage: (+12VDC ±5% 200mA) or (+5VDC ±2% 400mA)
DCM	Power source (VP) and input signal (A, B) common
A, NOT A B, NOT B	Input signal from Encoder. Input type is selected by SW2; Maximum 500kp/ sec
A/0, B/0	GS3-FB output signal for use with RPM Meter. (Open Collector) Maximum DC24V 100mA
сом	GS3-FB output signal (A/O, B/O) common



Control Terminals Block Designations







Wiring Solutions

Wiring Solutions using the **ZIP**Link Wiring System

ZIPLinks eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the ZIPLink System ranging from PLC I/O-to-ZIPLink Connector Modules that are ready for field

termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of *ZIP*Link modules are provided with *ZIP*Link cables. See the following solutions to help determine the best *ZIP*Link system for your application.

Solution 1: DirectLOGIC, CLICK and Productivity I/O Modules to ZIPLink Connector Modules

When looking for quick and easy I/O-to-field termination, a **ZIP**Link connector module used in conjunction with a prewired **ZIP**Link cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.

Using the PLC I/O Modules to *ZIP*Link Connector Modules selector tables located in this section,

- 1. Locate your I/O module/PLC.
- 2. Select a **ZIP**Link Module.
- 3. Select a corresponding **ZIP**Link Cable.



Solution 2: DirectLOGIC, CLICK and Productivity I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the *ZIP*Link Pigtail Cables. *ZIP*Link Pigtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

- 1. Locate your PLC I/O module.
- Select a ZIPLink Pigtail Cable that is compatible with your 3rd party device.



Solution 3: GS Series and DURAPULSE Drives Communication Cables

Need to communicate via Modbus RTU to a drive or a network of drives?

ZIPLink cables are available in a wide range of configurations for connecting to PLCs and *Sure*Servo, *Sure*Step, Stellar Soft Starter and AC drives. Add a **ZIP**Link communications module to quickly and easily set up a multi-device network.

Using the **Drives Communication** selector tables located in this section,

- 1. Locate your Drive and type of communications.
- 2. Select a **ZIP**Link cable and other associated hardware.



Wiring Solutions

Solution 4: Serial Communications Cables

ZIPLink offers communications cables for use with **Direct**LOGIC, CLICK, and Productivity CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25-pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the **Serial Communications Cables** selector table located in this section,

1. Locate your connector type
 2. Select a cable.



Solution 5: Specialty ZIPLink Modules

For additional application solutions, *ZIP*Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and SureServo 50-pin I/O interface connection.

Using the **ZIPLink Specialty Modules** selector table located in this section,

- 1. Locate the type of application.
- 2. Select a ZIPLink module.



Solution 6: ZIPLink Connector Modules to 3rd Party Devices

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible *ZIP*Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the Universal Connector Modules and Pigtail Cables table located in this section,

- 1. Select module type.
- 2. Select the number of pins.
- 3. Select cable.





PINE Motor Controller Communication

AC Dri	ve / Controller	Co	ommunications	S	2	IPLink Cable		
Controller	Comm Port Type	Network/Protocol	Connects to	Comm Port Type	Cable (2 meter length)	Cable Connectors	Other Hard- ware Required	
			BRX MPUs	RS-485, 3-Pin				
			P1 CPUs			RJ12 to pigtail		
			P2 CPUs	RS-485	ZL-RJ12-CBL-2P			
			P3 CPUs			Tto 12 to pigtan		
			P2-SCM P3-SCM	RS-485, 4-Pin				
GS1	RJ12	RS-485 Modbus RTU	DL06 PLCs	Port 2 (HD15)	GS-485HD15-	RJ12 to HD15	N/A	
			D2-260, D2-262 CPU	` ′	CBL-2	NOTE TO TID TO		
			GS-EDRV100	RJ12	GS-EDRV-CBL-2			
			ZL-CDM-RJ12Xxx *	RJ12	GS-485RJ12- CBL-2	RJ12 to RJ12		
			FA-ISOCON	5-pin connector	GS-ISOCON- CBL-2	RJ12 to 5-pin plug	1	
			BRX MPUs	RS-232/485, 3-Pin				
			P1 CPUs					
			P2 CPUs		ZL-RJ12-CBL-2P	RJ12 to pigtail		
			P3 CPUs				N/A	
		RS-232 Modbus RTU	P2-SCM	Ports 1, 2 & 3			IN/A	
			P3-SCM	Ports 1 to 4				
			CLICK PLCs	Port 2 (RJ12)				
			DL05 PLCs	1 0112 (11012)				
			DL06 PLCs		GS-RJ12-CBL-2	RJ12 to RJ12		
			D2-250-1 CPU	Port 2 (HD15)	00.1012.022.2		FA-15HD	
			D2-260, D2-262 CPU	D (0.05 1)	_		EL CARICE	
GS2	RJ12		D4-450, D4-454 CPU	Port 3 (25-pin)			FA-CABKIT	
102	11012		BRX MPUs RS-232/485		-			
			P2 CPUs	RS-485	ZL-RJ12-CBL-2P	RJ12 to pigtail		
		RS-485 Modbus RTU	P3 CPUs	KS-400				
			P2-SCM		-			
			P3-SCM	RS-485, 4-Pin			NI/A	
			DL06 PLCs D2-260, D2-262 CPU	Port 2 (HD15)	GS-485HD15- CBL-2	RJ12 to HD15	N/A	
			GS-EDRV100	RJ12	GS-EDRV-CBL-2			
			ZL-CDM-RJ12Xxx *	RJ12	GS-485RJ12- CBL-2	RJ12 to RJ12		
			FA-ISOCON	5-pin connector	GS-ISOCON- CBL-2	RJ12 to 5-pin plug		
			BRX MPUs	RS-485, 3-Pin	_			
			P1 CPUs	_				
			P2 CPUs	RS-485	ZL-RJ12-CBL-2P	RJ12 to pigtail		
DuraPulse			P3 CPUs			,, J		
			P2-SCM	RS-485, 4-Pin				
	RJ12	RS-485 Modbus RTU	P3-SCM DL06 PLCs		00 40511545		N/A	
(GS3)	1.012	NO-TOO IVIOUDUS INTO	D2-260, D2-262 CPU	Port 2 (HD15)	GS-485HD15- CBL-2	RJ12 to HD15	13/73	
			GS-EDRV100	RJ12	GS-EDRV-CBL-2		-	
					GS-485RJ12-	RJ12 to RJ12		
			ZL-CDM-RJ12Xxx *	RJ12	CBL-2	1.012 101.012		
			EN ICOCONI	F ain Construction	GS-ISOCON-	D 140 to 5 12 12		
	1		FA-ISOCON	5-pin Connector	CBL-2	RJ12 to 5-pin plug		

^{*} When using the ZL-CDM-RJ12Xxx ZIPLink Communication Distribution Module, replace the lowercase xx with the number of RJ12 ports, i.e. 4 for four ports or 10 for ten ports. (ex: ZL-CDM-RJ12X4 or ZL-CDM-RJ12X10)