DURAPULSE GS3 AC Drives – Introduction

| | GS3 AC Drives | | | | | | | | | | | | | | | |
|---|---------------|------|-----|-----|-----|-----|-----|----|----|------|----|----|----|----|----|-----|
| Maria Barra | | | 2 | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 75 | 100 |
| Motor Rating | | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 |
| 230V Single-Phase Input / 230V Three-Phase Output | | ~ | ~ | ~ | | | | | | | | | | | | |
| 230V Three-Phase Input / Output | | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | | | |
| 460V Three-Phase Input / Output | | | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | ~ | / | V |

Overview

The DURAPULSE series of AC drives offers all of the features of our GS2 series of drives including dynamic braking, PID, removable keypad and RS-485 Modbus communication. The DURAPULSE AC drive also offers sensorless vector control with the option of encoder feedback for enhanced speed control. The standard smart keypad (or Human Interface Module) is designed with defaults for the North American customer and allows you to configure the drive, set the speed, start and stop the drive, and monitor critical parameters for your application. In addition, this keypad has internal memory that allows four complete programs to be stored and transferred to any DURAPULSE drive. The DURAPULSE series offers three analog inputs, eleven digital inputs, and one SPDT relay output.



Features

- Simple Volts/Hertz control
- · Sensorless vector control with autotune
- Sensorless vector control with optional encoder feedback card, for better speed control
- · Sinusoidal pulse width modulation (PWM)
- Variable carrier frequency, depending on model
- IGBT technology
- Starting torque: 125% @ 0.5 Hz/150% @ 1Hz
- 150% rated current for one minute
- · Electronic overload protection
- Stall prevention
- Adjustable accel and decel ramps with linear and S-curve settings
- Automatic torque and slip compensation
- Internal dynamic braking circuit for models under 20 hp; optional baking units available for models 20 hp and above
- DC braking
- · Five skip frequencies
- Trip history
- Programmable jog speed
- Integral PID control
- Removable smart keypad with parameter upload/download
- Keypad with memory to store up to four programs of any *DURAPULSE* drive
- Eleven programmable digital inputs
- Three programmable analog inputs
- Three digital and one SPDT relay programmable outputs
- One programmable analog output
- One digital frequency output
- RS-485 Modbus communications
- Ethernet communication optional
- Two-year warranty
- UL/cUL/CE listed

Accessories

- AC line reactors
- EMI filters
- · RF filter
- · Braking resistors
- Braking units (for models 20 hp and above)
- Fuse kits and replacement fuses
- · Replacement cooling fans
- Remote panel adapter
- · Replacement keypad
- Keypad cables in 1, 3, and 5-meter lengths
- · Ethernet interface
- Four and eight-port RS-485 multi-drop termination boards
- GSoft drive configuration software
- GS3-FB feedback card
- GS-485HD15-CBL *ZIP*Link RS485 communication cable for connection to the DL06 and D2-260 15-pin ports
- USB-485M USB to RS-485 PC adapter (see "Communications Products" chapter for detailed information)
- Detailed descriptions and specifications for GS accessories are available in the "GS/DURAPULSE Accessories" section.

Typical Applications

- • Conveyors
- • Fans
- • Pumps
- • Compressors
- • HVAC
- • Material handling
- Mixing
- • Shop tools
- • Extruding
- • Grinding

DURAPULSE GS3 AC Drives Specifications

| | | | | | | 230\ | / Class | S | | | | | | |
|------------------------|-------------------------------|----------|---|---------------------|----------------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|--------------|--------------|--------------|
| Model Na | ате | | <u>GS3-</u> 21P0 | <u>GS3-</u> 22P0 | <u>GS3-</u> <u>23P0</u> | <u>GS3-</u> 25P0 | <u>GS3-</u> 27P5 | <u>GS3-</u> 2010 | <u>GS3-</u> 2015 | <u>GS3-</u> 2020 | <u>GS3-</u> 2025 | GS3- 2030 | GS3- 2040 | GS3- 2050 |
| Price | | | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> |
| | HP | | 1.0 | 2.0 | 3.0 | 5.0 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 |
| 0 4 4 | Max Motor Output | kW | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 |
| Output Rating | | | 5 | 7 | 11 | 17 | 25 | 33 | 49 | 65 | 75 | 90 | 120 | 145 |
| nanny | Max Output Voltage | | Three-phase 200 to 240V (proportional to input voltage) | | | | | | | | | | | |
| | Rated Frequency | | 0.1 to 400 Hz | | | | | | | | | | | |
| | Rated Voltage/Frequency | | Single/Three-phase Three-phase | | | | | | | | | | | |
| * Input | nateu voitaye/i requeitty | | 200/208/220/230/240 VAC, 50/60Hz | | | | | | | | | | | |
| Rating | Rated Input Current (A) | | 11.9 / 5.7 | 15.3 / 7.6 | 22 / 15.5 | 20.6 | 26 | 34 | 50 | 60 | 75 | 90 | 110 | 142 |
| Voltage/l | Frequency Tolerance | | | | | | Vo | oltage: ± 1 | 0% Frequ | ency: ± 5% | | | | |
| Watt Loss @ 100% I (W) | | 60 | 82 | 130 | 194 | 301 | 380 | 660 | 750 | 920 | 1300 | 1340 | 1430 | |
| Weight (lb [kg]) | | | 4.5 [2.034] | 4.5 [2.034] | 9.4 [4.24] | 9.4 [4.24] | 13.3 [6.031] | 13.3 [6.031] | 14.3 [6.487] | 26.5 [12] | 26.5 [12] | 26.5 [12] | 77.2 [35] | 77.2 [35] |
| * All 3-nha | se power sources must be symm | netrical | | | | | | | | | | | | |

^{*} All 3-phase power sources must be symmetrical.

Do not connect any DURAPULSE drives to grounded, center-tapped delta transformers (which are typically used for lighting circuits).

| | | | | | | 460 | V Cla | ss – T | hree-P | hase | | | | | | |
|--------------------|--------------------------------|----------------------------|---|----------------------------|----------------------------|----------------------------|----------------------------|---------------------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|
| Model N | lame | <u>GS3-</u> <u>41P0</u> | <u>GS3-</u> <u>42P0</u> | <u>GS3-</u> <u>43P0</u> | <u>GS3-</u> <u>45P0</u> | <u>GS3-</u> <u>47P5</u> | <u>GS3-</u> <u>4010</u> | <u>GS3-</u> 4015 | <u>GS3-</u> <u>4020</u> | <u>GS3-</u> <u>4025</u> | <u>GS3-</u> <u>4030</u> | <u>GS3-</u> <u>4040</u> | <u>GS3-</u> <u>4050</u> | <u>GS3-</u> <u>4060</u> | <u>GS3-</u> <u>4075</u> | <u>GS3-</u> <u>4100</u> |
| Price | | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> | <> |
| | Maximum HP Motor | 1 | 2 | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 75 | 100 |
| | Output kW | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 |
| Output | Rated Output Current (A) | 2.7 | 4.2 | 5.5 | 8.5 | 13 | 18 | 24 | 32 | 38 | 45 | 60 | 73 | 91 | 110 | 150 |
| Rating | Maximum Output Voltage | | Three-phase 380 to 480V (proportional to input voltage) | | | | | | | | | | | | | |
| | Rated Frequency | | 0.1 to 400 Hz | | | | | | | | | | | | | |
| *Input | Rated Voltage/ Frequency | | | | | | | 380/400/4 | Three-pl 15/440/460 | nase, /480VAC, 5 | 0/60Hz | | | | | |
| Rating | Rated Input Current (A) | 3.2 | 4.3 | 5.9 | 11.2 | 14 | 19 | 25 | 32 | 39 | 49 | 60 | 63 | 90 | 130 | 160 |
| Toleran | | | | | | | | Voltage | : ± 10% Fr | equency: ± | : 5% | | | | | |
| Watt Lo. 100% I | | 70 | 102 | 132 | 176 | 250 | 345 | 445 | 620 | 788 | 1290 | 1420 | 1680 | 2020 | 2910 | 3840 |
| Weight | (lb [kg]) | 3.9 [1.759] | 4.4 [1.994] | 4.1 [1.857] | 9.4 [4.24] | 13.2 [6.002] | 13.5 [6.106] | 14.4 [6.525] | 26.5 [12] | 26.5 [12] | 26.5 [12] | 77.2 [35] | 77.2 [35] | 77.2 [35] | 116.8 [53] | 116.8 [53] |
| * All 3-nl | nase power source | e must ha | vmmetrical | | | | | | | | | | | | | |

^{*} All 3-phase power sources must be symmetrical.

Do not connect any DURAPULSE drives to grounded, center-tapped delta transformers (which are typically used for lighting circuits).

DURAPULSE GS3 AC Drives General Specifications

| | | | General Specifications | | | |
|--------------------------------------|--------------------------------|--------------------------------------|---|--|--|--|
| | | | General Specifications | | | |
| | | | Control Characteristics Pulse Width Modulation, Carrier frequency adjustable from 1–15 kHz depending on the model. | | | |
| Control System | 1 | | This system determines the control methods of the AC drive. 00: V/Hz open loop control 01: V/Hz closed loop control 02: Sensorless Vector 03: Sensorless Vector with external feedback | | | |
| Rated Output F | requency | | 0.1 to 400.0 Hz | | | |
| Output Frequen | | 1 | 0.1 Hz | | | |
| Overload Capa | | | 150% of rated current for 1 minute | | | |
| Torque Charact | | | Includes auto-torque boost, auto-slip compensation, starting torque 125% @ 0.5 Hz / 150% @ 1.0 Hz | | | |
| Braking Torque | | | 20% without braking resistor, 125% with optional braking resistor (braking circuit built-in only for units under 20 hp) | | | |
| DC Braking | | | Operation frequency 60–0 Hz, 0–100% rated current, Start time 0.0–5.0 seconds, Stop time 0.0–25.0 seconds | | | |
| Acceleration/D | Acceleration/Deceleration Time | | 0.1 to 600 seconds (linear or non-linear acceleration/deceleration), second acceleration/deceleration available | | | |
| Voltage/Frequency Pattern | | | Settings available for Constant Torque - low & high starting torque, Variable Torque - low & high starting torque, and user configured | | | |
| Stall Prevention Level | | | 20 to 200% of rated current | | | |
| | | | Operation Specifications | | | |
| Keypad | | | Setting by <up> or <down> buttons</down></up> | | | |
| | Frequency Setting | External Signal | Potentiometer - 3 to 5 k Ω , 0 to 10 VDC (input impedance 10 k Ω), -10 to +10 VDC, 4 to 20 mA (input impedance 250 Ω), 0 to 20 mA; Multi-Speed Inputs 1 to 4, RS-232C/RS-485 communication interface | | | |
| | | Keypad | Setting by <run>, <stop>, <jog> , <fwd>, <rev> buttons</rev></fwd></jog></stop></run> | | | |
| Inputs | Operation Setting | External Signal | Forward/Stop, Reverse/Stop (run/stop, fwd/rev), 3-wire control, Serial Communication RS-232C & RS-485 (Modbus RTU) | | | |
| | Input Terminals | Digital Sink/Source Selectable | 11 user-programmable: FWD/STOP, REV/STOP, RUN/STOP, REV/FWD, RUN momentary (N.O.), STOP momentary (N.C.), External Fault (N.O./N.C.), External Reset, Multi-Speed Bit (1-4), Manual Keyboard Control, Jog, External Base Block (N.O./N.C.), Second Accel/Decel Time, Speed Hold, Increase Speed, Decrease Speed, Reset Speed to Zero, PID Disable (N.O.), PID Disable (N.O.), Input Disable | | | |
| | Analog | | 3 user-configurable, 0 to 10V (input impedance 10 k Ω), 0 to 20 mA, 4 to 20 mA (input impedance 250 Ω), 10 bit resolution -10V to +10V, 10 bit resolution | | | |
| Outputs | Output | Digital 3 transistors 1 relay | 4 user-programmable: Inverter Running, Inverter Fault, At Speed, Zero Speed, Above Desired Frequency, Below Desired Frequency, At Maximum Speed, Over Torque Detected, Above Desired Current, Below Desired Current, PID Deviation Alarm, Heatsink Overheat Warning (OH), Soft Braking Signal, Above desired Frequency 2, Below desired Frequency 2, Encoder Loss | | | |
| ou.pu.o | Terminals | Digital Square Wave | One digital square wave output representing drive frequency | | | |
| | | Analog | 1 user-programmable, 0 to 10V, 8 bit resolution frequency, current, process variable PV | | | |
| Operating Fund | tions | | Automatic voltage regulation, voltage/frequency characteristics selection, non-linear acceleration/deceleration, upper and lower frequency limiters, 15-stage speed operation, adjustable carrier frequency (1 to 15 kHz), PID control, 5 skip frequencies, analog gain & bias adjustment, jog, electronic thermal relay, automatic torque boost, trip history, software protection | | | |
| Protective Fund | etions | | Electronic Thermal, Overload Relay, Auto Restart after Fault, Momentary Power Loss, Reverse Operation Inhibit, Auto Voltage Regulation, Over-Voltage Stall Prevention, Auto Adjustable Accel/Decel, Over-Torque Detection Mode, Over-Torque Detection Level, Over-Torque Detection Time, Over-Current Stall Prevention during Acceleration, Over-Current Stall Prevention during Operation | | | |
| | Operator De | evices | 9-key, 2 line x 16 character LCD display, 5 status LEDs | | | |
| Operator | Programmii | ng | Parameter values for setup and review, fault codes | | | |
| Interface | Status Disp | | Output Frequency, Motor Speed, Scaled Frequency, Output Current, Motor Load, Output Voltage, DC Bus Voltage, PID Setpoint, PID Feedback, Frequency Setpoint | | | |
| | Key Function | | RUN, STOP/RESET, FWD/REV, PROGRAM, DISPLAY, <up>, <down>, ENTER</down></up> | | | |
| Enclosure Rating Ambient Temperature | | | Protected Chassis, IP20 | | | |
| | | | -10°C to 40°C (14°F to 104°F) | | | |
| Environment | Storage Ten | | -20°C to 60°C (-4°F to 140°F) – during short term transportation period | | | |
| | Ambient Hu | midity | 20 to 90% RH (non-condensing) | | | |
| | Vibration | | 9.8 m/s ² (1G) less than 10 Hz; 5.9 m/s ² (0.6G) 10 to 60 Hz | | | |
| | Installation | Location | Altitude 1000m or lower above sea level, keep from corrosive gas, liquid and dust | | | |
| Options | | | Noise filter, input AC reactor, output AC reactor, cable for remote operator, programming software, dynamic braking resistor, dynamic braking unit; RF filter; remote panel adapter; Ethernet interface; four and eight port RS-485 multidrop termination boards, replacement keypads, fuse kits and replacement fuses | | | |

DURAPULSE GS3 AC Drives Specifications – Installation

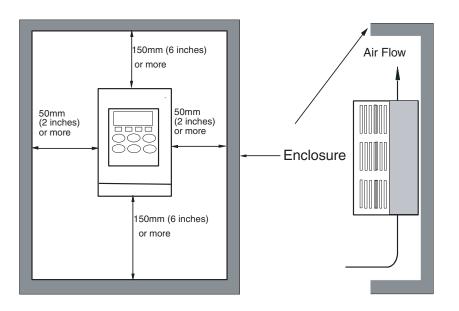
Understanding the installation requirements for your *DURAPULSE* AC drive will help to ensure that it operates within its environmental and electrical limits.

Note: Never use only this catalog for installation instructions or operation of equipment; refer to the user manual, GS3-M.

| Environmental Specifications | | | | | | | |
|--|---|--|--|--|--|--|--|
| Protective Structure ¹ | IP20 | | | | | | |
| Ambient Operating Temperature ² | -10 to 40°C (14°F to 104°F) | | | | | | |
| Storage Temperature ³ | -20 to 60°C (-4°F to 140°F) | | | | | | |
| Humidity | To 90% (no condensation) | | | | | | |
| Vibration ⁴ | 9.8 m/s² (1g), less than 10 Hz 5.9 m/s² (0.6g),10 to 60 Hz | | | | | | |
| Location | Altitude 1,000 m or less, indoors (no corrosive gases, liquids or dust) | | | | | | |

- 1: Protective structure is based upon EN60529
- 2: The ambient temperature must be in the range of
- -10° to 40° C. If the range will be up to 50° C, you will need to set the carrier frequency to 2.1 kHz or less and derate the output current to 80% or less.
- 3: The storage temperature refers to the short-term temperature during transport.
- 4: Conforms to the test method specified in JIS CO911 (1984)

| Watt-loss C | hart |
|-----------------|--------------|
| GS3 Drive Model | At full load |
| <u>GS3-21P0</u> | 60 |
| GS3-22P0 | 82 |
| <u>GS3-23P0</u> | 130 |
| <u>GS3-25P0</u> | 194 |
| <u>GS3-27P5</u> | 301 |
| <u>GS3-2010</u> | 380 |
| <u>GS3-2015</u> | 660 |
| <u>GS3-2020</u> | 750 |
| <u>GS3-2025</u> | 920 |
| <u>GS3-2030</u> | 1300 |
| <u>GS3-2040</u> | 1340 |
| <u>GS3-2050</u> | 1430 |
| <u>GS3-41P0</u> | 70 |
| <u>GS3-42P0</u> | 102 |
| <u>GS3-43P0</u> | 132 |
| <u>GS3-45P0</u> | 176 |
| <u>GS3-47P5</u> | 250 |
| <u>GS3-4010</u> | 345 |
| <u>GS3-4015</u> | 445 |
| <u>GS3-4020</u> | 620 |
| <u>GS3-4025</u> | 788 |
| <u>GS3-4030</u> | 1290 |
| <u>GS3-4040</u> | 1420 |
| <u>GS3-4050</u> | 1680 |
| <u>GS3-4060</u> | 2020 |
| <u>GS3-4075</u> | 2910 |
| <u>GS3-4100</u> | 3840 |



Minimum Clearances and Air Flow



WARNING: AC DRIVES GENERATE A LARGE AMOUNT OF HEAT WHICH MAY DAMAGE THE AC DRIVE. AUXILIARY COOLING METHODS ARE TYPICALLY REQUIRED IN ORDER NOT TO EXCEED MAXIMUM AMBIENT TEMPERATURES.



WARNING: MAXIMUM AMBIENT TEMPERATURES MUST NOT EXCEED 50°C (122°F), OR 40°C (104°F) FOR MODELS 7.5 HP (5.5 KW) AND HIGHER!

DURAPULSE GS3 AC Drives Specifications —

Terminals

| Maii | Main Circuit Terminals | | | | | | | |
|------------------|---|--|--|--|--|--|--|--|
| Terminal | Description | | | | | | | |
| L1, L2, L3 | Input Power | | | | | | | |
| T1, T2, T3 | AC Drive Output | | | | | | | |
| B1, B2 | Braking Resistor Connection (Under 20HP) | | | | | | | |
| +2, – (negative) | External Dynamic Brake Unit (20HP & Over) | | | | | | | |
| ÷ | Ground | | | | | | | |



GS3-4030 shown

| | Co | ontrol Circuit Terminals |
|-----------------|--------------------------------|---|
| Terminal Symbol | Description | Remarks |
| +24V | DC Voltage Source | (+24V, 20mA), used only for AC drive digital inputs wired for source mode operation |
| DI1 | Digital Input 1 | |
| DI2 | Digital Input 2 | |
| DI3 | Digital Input 3 | |
| DI4 | Digital Input 4 | Les (Millers dels cells O cells d'es Mercine bels) |
| DI5 | Digital Input 5 | Input Voltage: Internally Supplied (see Warning below) Sink Mode: Low active, V _{inL} Min = 0V, V _{inL} Max = 15V, |
| DI6 | Digital Input 6 | lin Min = 2.1mA, I _{in} Max = 7.0mA |
| DI7 | Digital Input 7 | lin Min = 2.1mA, I _{in} Max = 7.0mA Source Mode: High active, V _{inH} Min = 8.5V, V _{inH} Max = 24V, I _{in} Min = 2.1mA, I _{in} Max = 7.0mA |
| DI8 | Digital Input 8 | Input response: 12–15 msec Also see "Basic Wiring Diagram" on the next pages. |
| DI9 | Digital Input 9 | Also see basic willing biagram on the next pages. |
| DI10 | Digital Input 10 | |
| DI11 | Digital Input 11 | |
| DCM | Digital Common | |
| +10V | Internal Power Supply | +10VDC (10mA maximum load) |
| AI1 | Analog Input | 0 to +10 V input only |
| AI2 | Analog Input | 0 to 20mA / 4 to 20mA input |
| AI3 | Analog Input | -10 to +10 V input only |
| ACM | Analog Common | |
| R10 | Relay Output 1 Normally Open | Resistor Load: 240VAC - 5A (N.O) / 3A (N.C.) |
| R1C | Relay Output 1 Normally Closed | 24VDC - 5A (N.O.) / 3A (N.C.) Inductive Load: |
| R1 | Relay Output 1 Common | 240VAC - 1.5A (N.O) / 0.5A (N.C) 24VDC - 1.5A (N.O) / 0.5A (N.C) See P 3.01 to P 3.03 |
| D01 | Photocoupled digital output | |
| D02 | Photocoupled digital output | Maximum 48VDC, 50mA |
| D03 | Photocoupled digital output | INIAAIIIUIII 40 VDO, SUIIIA |
| DOC | Digital Output Common | |
| AO | Analog Output | 0 to +10 V 2mA Output |
| F0 | Digital Frequency Output | Square wave pulse train output |



WARNING: DO NOT CONNECT EXTERNAL VOLTAGE SOURCES TO THE DIGITAL INPUTS. PERMANENT DAMAGE MAY RESULT.



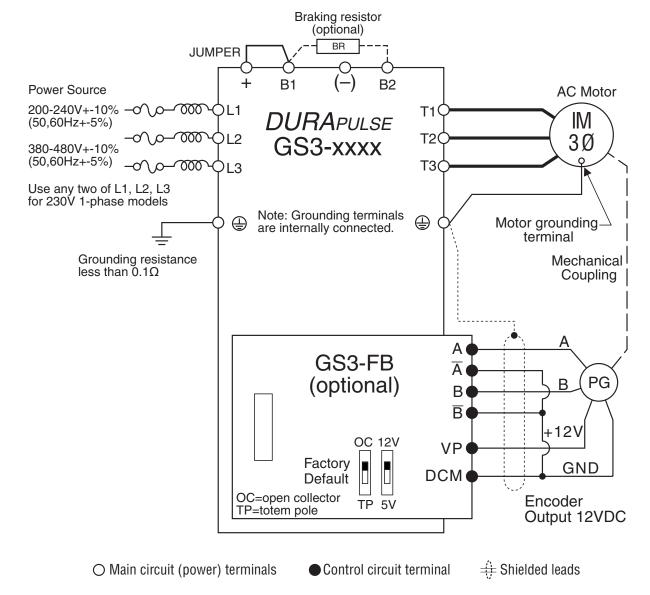
NOTE: USE TWISTED-SHIELDED, TWISTED-PAIR OR SHIELDED-LEAD WIRES FOR THE CONTROL SIGNAL WIRING. IT IS RECOMMENDED TO RUN ALL SIGNAL WIRING IN A SEPARATE STEEL CONDUIT. THE SHIELD WIRE SHOULD ONLY BE CONNECTED AT THE AC DRIVE. DO NOT CONNECT SHIELD WIRE ON BOTH ENDS.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram - drives under 20 hp

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-M for additional specific wiring information.)

Note: Please refer to the following pages for explanations and information regarding feedback cards (pg.tGSX-101), line reactors (pg.tGSX-103), braking components (pg.tGSX-1), EMI filters (pg.tGSX-134), RF filters (pg.tGSX-143), and fuses (pg.tGSX-144).



W,

Warning: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/**DURA**PULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

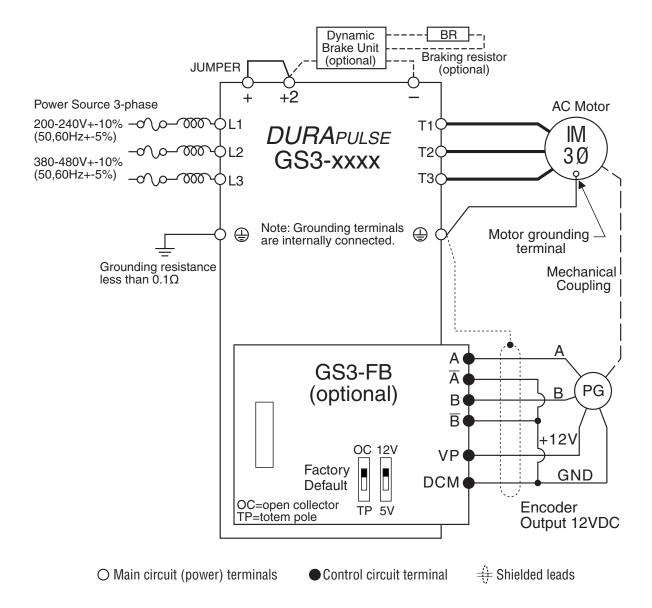
TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram – 20 to 30 hp (230 VAC) & 20 to 60 hp (460 VAC)

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-M for additional specific wiring information.)

Note: Pleaserefer to the following pages for explanations and information regarding feedback cards (pg.tGSX-101), line reactors (pg.tGSX-103), braking components (pg.tGSX-1), EMI filters (pg.tGSX-134), RF filters (pg.tGSX-143), and fuses (pg.tGSX-144).



DAMAGE MAY RESULT.

Warning: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT

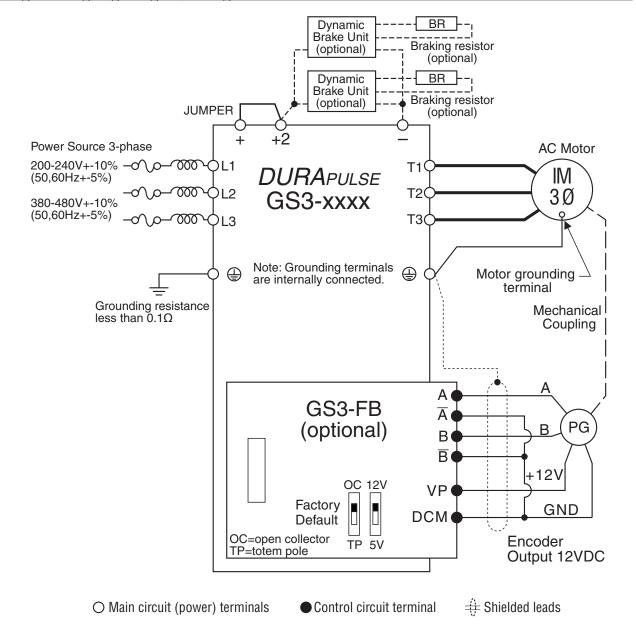
TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

DURAPULSE GS3 AC Drives – Basic Wiring Diagram

Power Wiring Diagram - 40 to 50 hp (230 VAC) & 75 to 100 hp (460 VAC)

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS3-UMP for additional specific wiring information.)

Note: Please refer to the following catalog pages in the Drives section of our catalog for explanations and information regarding feedback cards (X), line reactors (X), braking units (X) and resistors (X), EMI (X) and RF (X) filters, and fuses (X).



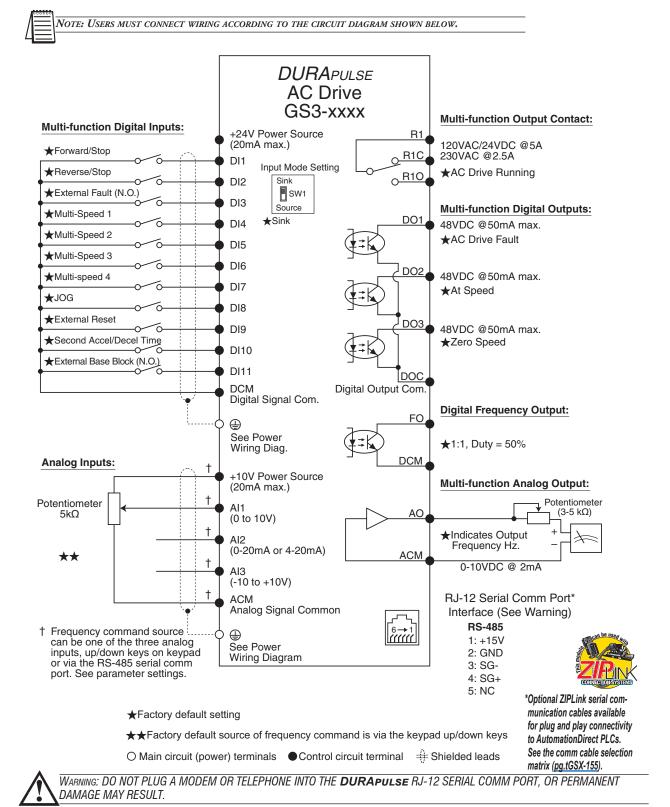
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Warning: DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS3/**DURA**PULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

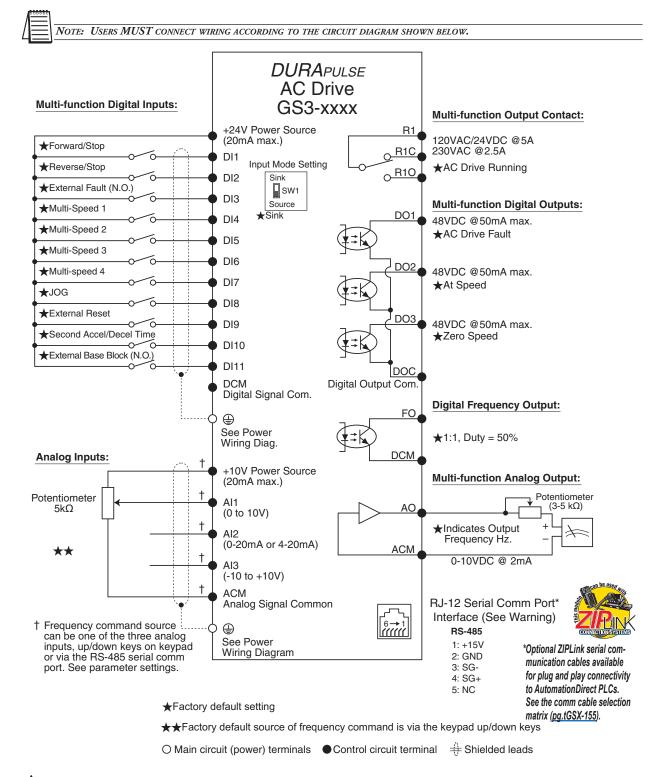
DURAPULSE GS3 AC Drives – Control Wiring Diagram – DI Connection to Sinking Outputs

Control Wiring Diagram - Digital Input Connections to Sinking Output Devices



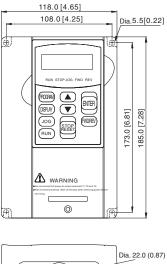
DURAPULSE GS3 AC Drives – Control Wiring Diagram – DI Connections to Sourcing Outputs

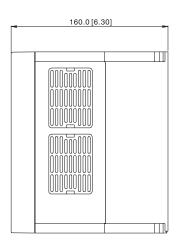
Control Wiring Diagram - Digital Input Connections to Sourcing Output Devices

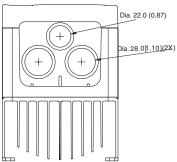


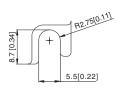
WARNING: DO NOT PLUG A MODEM OR TELEPHONE INTO THE DURAPULSE RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT.

GS3-21P0, GS3-22P0, GS3-41P0, GS3-42P0

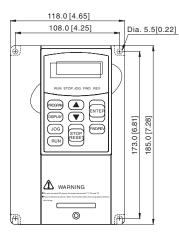


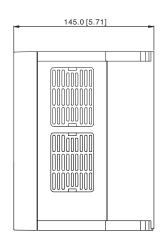


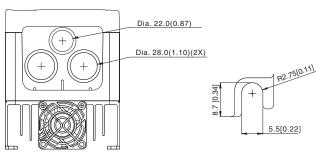




GS3-43P0

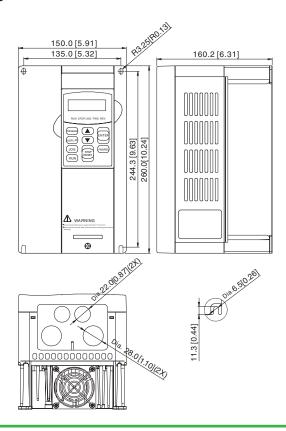




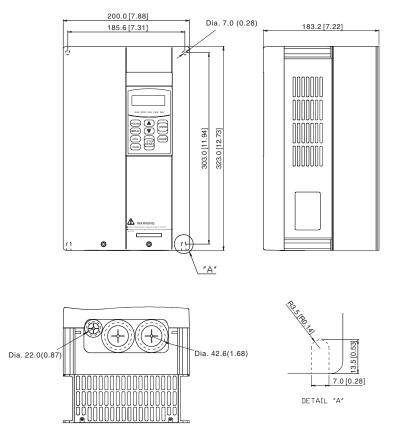


unit: mm(in)

GS3-23P0, GS3-25P0, GS3-45P0

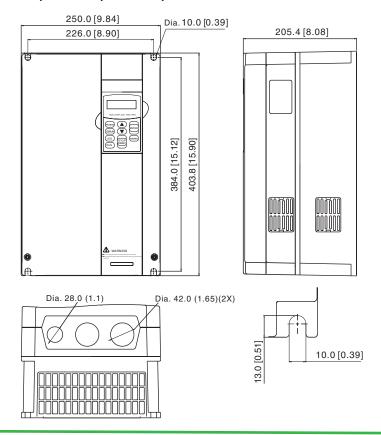


GS3-27P5, GS3-2010, GS3-2015, GS3-47P5, GS3-4010, GS3-4015

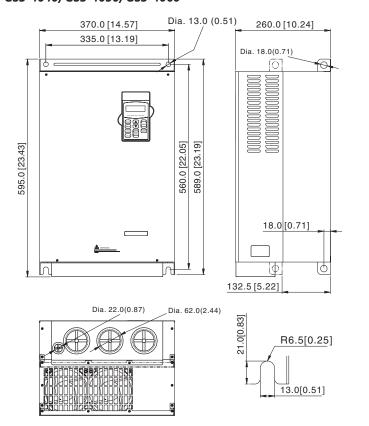


unit: mm(in)

GS3-2020, GS3-2025, GS3-2030, GS3-4020, GS3-4025, GS3-4030

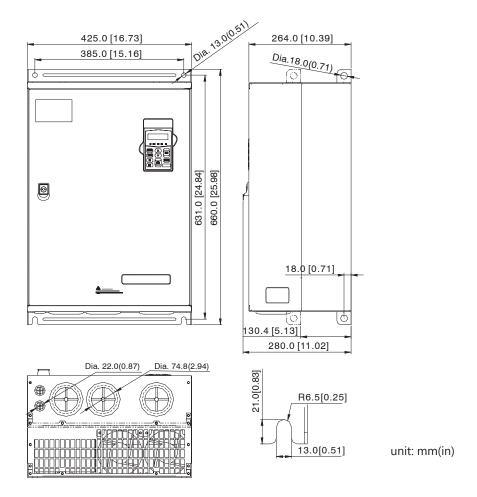


GS3-2040, GS3-2050, GS3-4040, GS3-4050, GS3-4060



unit: mm(in)

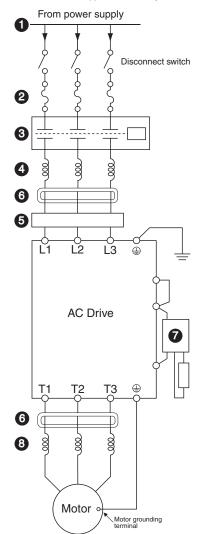
GS3-4075, GS3-4100



AC Drives Optional Accessories – Overview

Drive Accessories

(not all accessories are applicable for every drive model)



Power Supply

Please follow the specific power supply requirements as detailed in the specific drive manual.

2 Fuses

Input fuses protect the AC drive from excessive input current due to line surges, short circuits, and ground faults. They are recommended for all installations and may be required for UL-listed installations.

3 Contactor (Optional)

Do not use a contactor or disconnect switch for run/stop control of the AC drive and motor. This will reduce the operating life cycle of the AC drive. Cycling a power circuit switching device while the AC drive is in run mode should be done only in emergency situations.

4 Input Line Reactor (Optional)

See the Line Reactors section at www.automationdirect.com for more information.

Input line reactors protect the AC drive from transient overvoltage conditions, typically caused by utility capacitor switching. The input line reactor also reduces the harmonics associated with AC drives. Input line reactors are recommended for all installations.

5 EMI filter (Optional)

See the EMI Filters section at www.automationdirect.com for more information.

Input EMI filters reduce electromagnetic interference or noise on the input side of the AC drive. They are required for CE compliance and recommended for installations prone to or sensitive to electromagnetic interference.

6 RF filter (Optional)

RF filters reduce the radio frequency interference or noise on the input or output side of the inverter.

7 Braking Unit and/or Braking Resistor (Optional)

Dynamic braking allows the AC drive to produce additional braking (stopping) torque. AC drives can typically produce between 15% & 20% braking torque without the addition of any external components. The addition of optional braking may be required for applications that require rapid deceleration or high inertia loads.

8 Output Load Reactor or Voltage Time (dV/dT) Filter (Optional)

Output line reactors protect the motor insulation against AC drive short circuits and IGBT reflective wave damage, and also "smooth" the motor current waveform, allowing the motor to run cooler. They are **recommended for operating "noninverter-duty" motors and when the length of wiring between the AC drive and motor is less than 100 feet.**

Voltage Time filters provide enhanced protection for motors with distances up to 1,000 feet.

Voltage Time filters provide even more protection against wave reflection and reduce common mode noise. They are recommended when the length of wiring between the AC drive and motor is from 100 feet up to 1,000 feet.

See www.automationdirect.com for specific product offerings.

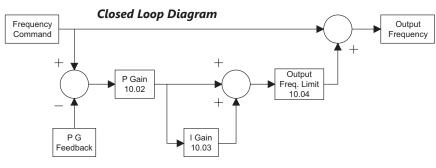
GS3 *DURA*PULSE Accessories – Feedback Card

| Feedback Card for DURApulse AC Drives | | | | | | | | |
|---------------------------------------|----------------|---------------------|--|--|--|--|--|--|
| Part Number | Price | Drive Model | | | | | | |
| GS3-FB | | | | | | | | |
| The GS3-FB feedback c AC drives. | ard is for use | only with DURAPULSE | | | | | | |

Description

The GS3-FB card is used to add another layer of precision control to the already precise control algorithm utilized in the DURAPULSE drive series. This added control is activated by selecting control modes V/Hz closed loop control or sensorless vector with external feedback. The feedback mechanism uses pulses generated by an external encoder or pulse generator. Unlike other feedback types, the GS3-FB accommodates the four most common encoder signal types: output voltage, open collector, line driver, and complimentary.

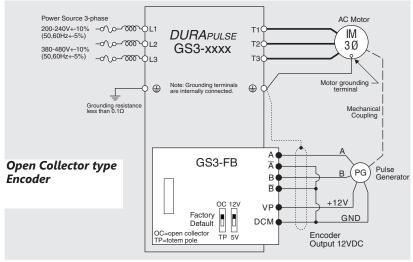




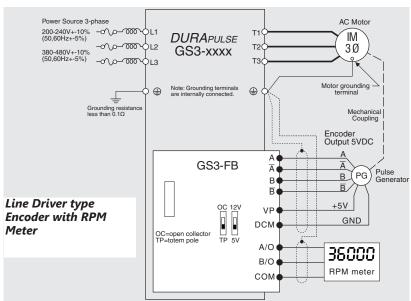
| Т | as of Francisco | SW1 and SW2 | switches |
|----------------|-----------------|----------------|----------------|
| Тур | es of Encoders | 5V | 12V |
| Output Voltage | VCC O/P | OC12V TP 5V | OC12V TP 5V |
| Open collector | VCC O/P | OC12V TP 5V | OC12V TP 5V |
| Line driver | - Q Q | OC12V TP 5V | OC12V TP 5V |
| Complimentary | VCC O/P | OC12V TP 5V | OC12V TP 5V |

GS3 *DURA* **PULSE Accessories** – **Feedback Card**

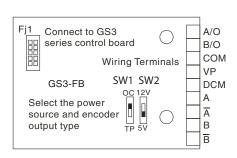
Wiring Diagrams

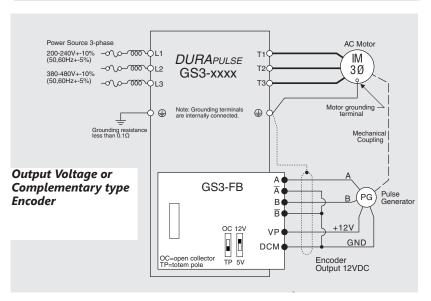


| Terminal Symbols | Description |
|----------------------|---|
| VP | Power source of GS3-FB (SW1 can be switched to 12V or 5V) Output Voltage: (+12VDC ±5% 200mA) or (+5VDC ±2% 400mA) |
| DCM | Power source (VP) and input signal (A, B) common |
| A, NOT A B, NOT B | Input signal from Encoder. Input type is selected by SW2; Maximum 500kp/ sec |
| A/0, B/0 | GS3-FB output signal for use with RPM Meter. (Open Collector) Maximum DC24V 100mA |
| сом | GS3-FB output signal (A/O, B/O) common |



Control Terminals Block Designations







Wiring Solutions

Wiring Solutions using the **ZIP**Link Wiring System

ZIPLinks eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the ZIPLink System ranging from PLC I/O-to-ZIPLink Connector Modules that are ready for field

termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of *ZIP*Link modules are provided with *ZIP*Link cables. See the following solutions to help determine the best *ZIP*Link system for your application.

Solution 1: DirectLOGIC, CLICK and Productivity I/O Modules to ZIPLink Connector Modules

When looking for quick and easy I/O-to-field termination, a ZIPLink connector module used in conjunction with a prewired ZIPLink cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.

Using the PLC I/O Modules to *ZIP*Link Connector Modules selector tables located in this section,

- 1. Locate your I/O module/PLC.
- 2. Select a **ZIP**Link Module.
- 3. Select a corresponding **ZIP**Link Cable.



Solution 2: DirectLOGIC, CLICK and Productivity I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the ZIPLink Pigtail Cables. ZIPLink Pigtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

- 1. Locate your PLC I/O module.
- Select a ZIPLink Pigtail Cable that is compatible with your 3rd party device.



Solution 3: GS Series and DURAPULSE Drives Communication Cables

Need to communicate via Modbus RTU to a drive or a network of drives?

ZIPLink cables are available in a wide range of configurations for connecting to PLCs and SureServo, SureStep, Stellar Soft Starter and AC drives. Add a ZIPLink communications module to quickly and easily set up a multi-device network.

Using the Drives Communication selector tables located in this section,

- 1. Locate your Drive and type of communications.
- 2. Select a **ZIP**Link cable and other associated hardware.





Wiring Solutions

Solution 4: Serial Communications Cables

ZIPLink offers communications cables for use with *Direct*LOGIC, CLICK, and Productivity CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25-pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the Serial Communications Cables selector table located in this section,

• 1. Locate your connector type 2. Select a cable.



Solution 5: Specialty ZIPLink Modules

For additional application solutions, *ZIP*Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and SureServo 50-pin I/O interface connection.

Using the ZIPLink Specialty Modules selector table located in this section,

- 1. Locate the type of application.
- 2. Select a ZIPLink module.



Solution 6: ZIPLink Connector Modules to 3rd Party Devices

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible *ZIP*Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the Universal Connector Modules and Pigtail Cables table located in this section,

- 1. Select module type.
- 2. Select the number of pins.
- 3. Select cable.





Motor Controller Communication

| AC Dri | ve / Controller | Co | ommunications | S | 7 | IPLink Cable | | |
|---------------|-----------------|---------------------|---------------------------------|-------------------|------------------------------|---------------------|------------------------------|--|
| Controller | Comm Port Type | Network/Protocol | Connects to | Comm Port Type | Cable (2 meter length) | Cable Connectors | Other Hard- ware Required | |
| | | | BRX MPUs | RS-485, 3-Pin | | RJ12 to pigtail | | |
| | | | P1 CPUs | | | | | |
| | | | P2 CPUs | RS-485 | ZL-RJ12-CBL-2P | | | |
| | | | P3 CPUs | | ZL-NJ 12-ODL-21 | | | |
| | | | P2-SCM P3-SCM | RS-485, 4-Pin | | | | |
| GS1 | RJ12 | RS-485 Modbus RTU | DL06 PLCs | Port 2 (HD15) | GS-485HD15- | RJ12 to HD15 | N/A | |
| | | | D2-260, D2-262 CPU | FOIL 2 (LID 13) | CBL-2 | NJ 12 (OTID 13 | | |
| | | | GS-EDRV100 | RJ12 | GS-EDRV-CBL-2 | | | |
| | | | ZL-CDM-RJ12Xxx * | RJ12 | GS-485RJ12- CBL-2 | RJ12 to RJ12 | | |
| | | | FA-ISOCON | 5-pin connector | GS-ISOCON- CBL-2 | RJ12 to 5-pin plug | | |
| | | | BRX MPUs | RS-232/485, 3-Pin | | | | |
| | | | P1 CPUs | | | | | |
| | | | P2 CPUs | RS-485 | ZL-RJ12-CBL-2P | RJ12 to pigtail | | |
| | | | P3 CPUs | | | | N/A | |
| | | | P2-SCM | Ports 1, 2 & 3 | | | IN/A | |
| | | RS-232 Modbus RTU | P3-SCM | Ports 1 to 4 | | | | |
| | | 110-202 Wodbus 1110 | CLICK PLCs | Port 2 (RJ12) | | | | |
| | | | DL05 PLCs | 1 0112 (11012) | | | | |
| | | | DL06 PLCs | | GS-RJ12-CBL-2 | RJ12 to RJ12 | | |
| | | | D2-250-1 CPU | Port 2 (HD15) | | 11012 1011012 | FA-15HD | |
| | | | D2-260, D2-262 CPU | | | | | |
| 200 | D 140 | | D4-450, D4-454 CPU | Port 3 (25-pin) | | | FA-CABKIT | |
| iS2 | RJ12 | | BRX MPUs | RS-232/485, 3-Pin | _ | | | |
| | | | | P1 CPUs | | | | |
| | | | P2 CPUs | RS-485 | ZL-RJ12-CBL-2P | RJ12 to pigtail | | |
| | | | P3 CPUs | | _ | | - N//A | |
| | | | P2-SCM P3-SCM | RS-485, 4-Pin | | | | |
| | | RS-485 Modbus RTU | DL06 PLCs D2-260, D2-262 CPU | Port 2 (HD15) | GS-485HD15- CBL-2 | RJ12 to HD15 | N/A | |
| | | | GS-EDRV100 | RJ12 | GS-EDRV-CBL-2 | | | |
| | | | ZL-CDM-RJ12Xxx * | RJ12 | GS-485RJ12- CBL-2 | RJ12 to RJ12 | | |
| | | | FA-ISOCON | 5-pin connector | GS-ISOCON- CBL-2 | RJ12 to 5-pin plug | | |
| | | | BRX MPUs | RS-485, 3-Pin | 4 | | | |
| | | | P1 CPUs | | | | | |
| | | | P2 CPUs | RS-485 | ZL-RJ12-CBL-2P | RJ12 to pigtail | | |
| DuraPulse | | | P3 CPUs | | _ | | | |
| | | | P2-SCM | RS-485, 4-Pin | | | | |
| | RJ12 | RS-485 Modbus RTU | P3-SCM DL06 PLCs | | 00 40511045 | | N/A | |
| GS3) | 1.012 | 1.0 400 Modbas IVIO | D2-260, D2-262 CPU | Port 2 (HD15) | GS-485HD15- CBL-2 | RJ12 to HD15 | 13/13 | |
| | | | GS-EDRV100 | RJ12 | GS-EDRV-CBL-2 | | | |
| | | | | | GS-EDRV-CBL-2 GS-485RJ12- | RJ12 to RJ12 | | |
| | | | ZL-CDM-RJ12Xxx * | RJ12 | CBL-2 | 1.012 (01/012 | | |
| | | | E4 10000; | 5 . 0 . | GS-ISOCON- | D.140.4 5 | 1 | |
| | | | FA-ISOCON | 5-pin Connector | CBL-2 | RJ12 to 5-pin plug | | |

^{*} When using the ZL-CDM-RJ12Xxx ZIPLink Communication Distribution Module, replace the lowercase xx with the number of RJ12 ports, i.e. 4 for four ports or 10 for ten ports. (ex: ZL-CDM-RJ12X4 or ZL-CDM-RJ12X10)