

16 Loop PID CoProcessor

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F4-16PID **retired**



Overview

The F4-16PID is a Proportional Integral Derivative (PID) CoProcessor designed to execute up to 16 PID loops independent of the DL405 CPU. Using the high-speed Intelligent Bus Interface, the F4-16PID reads the process variable and writes the PID output directly into V-memory of the DL405 CPU. Configure the module PID loop using *DirectSOFT* Data View or ladder logic.

Minimal ladder logic is required in the CPU, therefore, the floating point math-intensive PID calculations in the CoProcessor have little effect on the CPU scan time. As a result, the CPU can perform high-speed discrete control while the CoProcessor performs high-speed PID.

Operation

The process variable (PV) comes from an input module, usually an analog input or thermocouple. The user ladder logic copies the input value to the Process Variable location.

The PID module calculates the loop output value and places it at the Output location. The user can write this value to an analog output channel, use it as a time proportion for a discrete output, or send it to the setpoint or another loop for cascading loops.

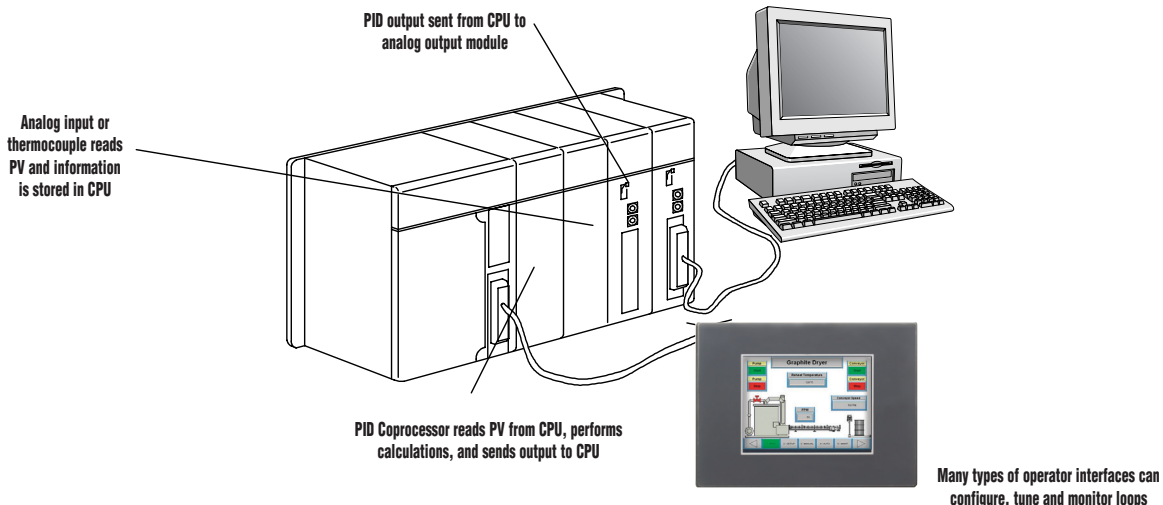
All loop information is read from and written to a user specified block of V-memory. Each loop that is enabled requires 32 V-memory locations. Since all loop parameters are stored in V-memory, any device capable of reading and writing DL405 V-memory can be used to configure, tune, and monitor loops.

The information included in each loop's block of V-memory includes:

- Bit Mapped Mode Word
- Process Variable (PV)
- Setpoint (SP)
- Bias
- Output
- Bit Mapped Alarm word
- Sample Rate (.1 to 999.9 sec. or min.)
- Gain
- Reset
- Rate
- PV Low Low Alarm
- PV Low Alarm
- PV High Alarm
- PV High High Alarm
- PV Yellow Deviation Limit
- PV Orange Deviation Limit
- Alarm Deadband
- Error Deadband Below SP
- Error Deadband Above SP
- Derivative Gain Limiting Coefficient
- Setpoint Low Limit
- Setpoint High Limit
- Maximum Output Clamp
- Minimum Output Clamp

Some variations of PID control are done with supporting ladder logic. Examples that are included in the PID manual are:

- Auto/Manual Mode Control
- Setpoint Ramp and Soak
- Alarm Word Decoding
- Time Proportioning Control Loops
- Cascading Loops
- Positioning Actuator Control Loops



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Specifications and Key Features	
Module Type	CoProcessor, Intelligent
Number of Loops	16 maximum
Modules per CPU	Six maximum, any slot in CPU base
PID Algorithm	Position or Velocity form of the PID equation. Optionally specify direct or reverse acting, square root of the error and error squared control.
Sample Rate	Specify the time interval between PV samples, 0.1 to 999.9 in units of seconds or minutes
Auto/Manual	A control relay, CR, which when energized places the corresponding loop into automatic mode. PV alarm monitoring continues when loops are in manual mode.
Square Root PV	Specify a square root of the PV for a flow control application.
Limit SP	Specify a high and low limit for allowable setpoint changes.
Gain	Specify proportional gain of 0.00 to 99.99.
Reset	Specify reset time of 0.1 to 999.9 minutes, seconds, milliseconds, or microseconds
Bumpless Transfer I	Bias and setpoint are initialized automatically when the module is switched from manual to automatic. This provides for a bumpless transfer.
Bumpless Transfer II	Bias is set equal to the Output when the module is switched from manual to automatic. This allows switching in and out of automatic mode without having to re-enter the setpoint.
Limit Output	Optionally specify maximum and minimum output values
Step Bias	Provides proportional bias adjustment for large setpoint changes. This may stabilize the loop faster and reduce the chance of the output going out of range. Step bias should be used in conjunction with the normal adjusted bias operation.
Anti-windup	If the position form of the PID equation is specified, the reset action is stopped when the PID output reaches 0 or 100%. Select adjusted bias or freeze bias operation.
Rate	Specify the derivative time, 0 to 999.9 in units of minutes or seconds.
Rate Limiting	Specify a derivative gain limiting coefficient to filter the PV used in calculating the derivative term (99.99 to 00.01).
Error Deadband	Specify an incremental value above and below the setpoint in which no change in output is made.
Error Squared	Squaring the error minimizes the effect a small error has on the Loop output, however; both Error Squared and Error Deadband control may be enabled
20% offset of PV	Specify a 20% offset of the PV to input a 4-20mA transmitter using a 0-20mA analog input module range.
Internal Power Consumption	160mA at +5VDC, (supplied by base power supply)
Operating Environment	0°C to 60°C (32°F to 140°F) 5% to 95% humidity (non-condensing)
Alarm Specifications	
Deadband	Specify 0.1% to 5% alarm deadband on all alarms except Rate of Change.
PV Alarm Points	A Y output or CR may be activated based on four PV alarm points.
PV Deviation	A Y output or CR may be activated based on four PV alarm points. Specify an alarm for PV deviation above or below the setpoint (Yellow Deviation) and an alarm for greater PV deviation from the setpoint (Orange Deviation).
Rate of Change	A Y output or CR may be activated when the PV changes faster than a specified rate of change limit.
Broken Transmitter	Monitor the PV for a broken transmitter.

Check the Power Budget

Verify your power budget requirements

Your I/O configuration choice can be affected by the power requirements of the I/O modules you choose. When determining the types and quantity of I/O modules you will be using, it is important to remember there is a limited amount of power available from the power supply.

The chart on the opposite page indicates the power supplied and used by each DL405 device. The adjacent chart shows an example of how to calculate the power used by your particular system. These two charts should make it easy for you to determine if the devices you have chosen fit within the power budget of your system configuration.

If the I/O you have chosen exceeds the maximum power available from the power supply, you can resolve the problem by shifting some of the modules to an expansion base or remote I/O base (if you are using remote I/O).

Warning: It is extremely important to calculate the power budget correctly. If you exceed the power budget, the system may operate in an unpredictable manner which may result in a risk of personal injury or equipment damage.

Use ZIPLinks to reduce power requirements

If your application requires a lot of relay outputs, consider using the ZipLink AC or DC relay output modules. These modules can switch high current (10A) loads without putting a load on your base power budget. Refer to Wiring System for DL405 PLCs later in this section for more information.

This logo is placed next to I/O modules that are supported by the ZIPLink connection systems.

See the I/O module specifications at the end of this section.



Calculating your power usage

The following example shows how to calculate the power budget for the DL405 system. The example is constructed around a single 8-slot base using the devices shown. It is recommended you construct a similar table for each base in your system.

A				
	Base Number 0	Device Type	5 VDC (mA)	External 24 VDC Power (mA)
B	CURRENT SUPPLIED			
	CPU/Expansion Unit /Remote Slave	D4-440 CPU	3700	400
C	CURRENT REQUIRED			
	SLOT 0	D4-16ND2	+150	+0
	SLOT 1	D4-16ND2	+150	+0
	SLOT 2	F4-04DA	+120	+100
	SLOT 3	D4-08ND3S	+100	+0
	SLOT 4	D4-08ND3S	+100	+0
	SLOT 5	D4-16TD2	+100	+0
	SLOT 6	D4-16TD2	+100	+0
	SLOT 7	D4-16TR	+1000	+0
D	OTHER			
	BASE	D4-08B-1	+80	+0
	Handheld Programmer	D4-HPP-1	+320	+0
E	Maximum Current Required		2820	100
F	Remaining Current Available		3700-2820=880	400-100=300
	1. Using a chart similar to the one above, fill in column 2. 2. Using the tables on the opposite page, enter the current supplied and used by each device (columns 3 and 4). Pay special attention to the current supplied by the CPU, Expansion Unit, and Remote Slave since they differ. Devices which fall into the "Other" category (Row D) are devices such as the Base and the Handheld programmer, which also have power requirements, but do not plug directly into the base. 3. Add the current used by the system devices (columns 3 and 4) starting with Slot 0 and put the total in the row labeled "maximum current required" (Row E). 4. Subtract the row labeled "Maximum current required" (Row E), from the row labeled "Current Supplied" (Row B). Place the difference in the row labeled "Remaining Current Available" (Row F). 5. If "Maximum Current Required" is greater than "Current Supplied" in either column 3 or 4, the power budget will be exceeded. It will be unsafe to use this configuration and you will need to restructure your I/O configuration. Note the auxiliary 24 VDC power supply does not need to supply all the external power. If you need more than the 400mA supplied, you can add an external 24VDC power supply. This will help keep you within your power budget for external power.			

DL405 CPU power supply specifications and power requirements

Specification	AC Powered Units	24 VDC Powered Units	125 VDC Powered Units
Part Numbers	D4-454, D4-450, D4-440, D4-EX (expansion base unit), D4-RS (remote slave unit)	D4-454DC-1, D4-440DC-1, (expansion base unit), D4-EXDC, D4-RSDC (remote slave unit)	D4-450DC-2
Voltage Withstand (dielectric)	1 minute @ 1,500 VAC between primary, secondary, field ground, and run relay		
Insulation Resistance	> 10MΩ at 500VDC		
Input Voltage Range	85-132 VAC (110 range) 170-264 VAC (220 range)	20-28 VDC (24 VDC) with less than 10% ripple	90-146 VDC (125 VDC) with less than 10% ripple
Maximum Inrush Current	20 A	20 A	20 A
Maximum Power	50 VA	38 W	30 W

Power Requirements

Power Supplied					
<i>CPUs/Remote Units/ Expansion Units</i>	<i>5 VDC Current Supplied in mA</i>	<i>24V Aux Power Supplied in mA</i>	<i>CPUs/Remote Units/ Expansion Units</i>	<i>5V Current Supplied in mA</i>	<i>24V Aux Power Supplied in mA</i>
D4-440 CPU	3700	400	D4-EX	4000	400
D4-440DC-1 CPU	3700	NONE	D4-EXDC	4000	NONE
D4-450 CPU	3700	400	D4-RS	3700	400
D4-454 CPU	3100	400	D4-RSDC	3700	NONE
D4-450DC-2 CPU	3100	NONE	H4-EBC	3470	400
D4-454DC-1	3100	NONE	H4-EBC-F	3300	400
Power Consumed					
<i>Power-consuming Device</i>	<i>5V Current Consumed</i>	<i>External 24VDC Current Required</i>	<i>Power-consuming Device</i>	<i>5V Current Consumed</i>	<i>External 24VDC Current Required</i>
<i>I/O Bases</i>			<i>Analog Modules (continued)</i>		
D4-04B-1	80	NONE	F4-16AD-1	75	100
D4-06B-1	80	NONE	F4-16AD-2	75	100
D4-08B-1	80	NONE	F4-04DA-1	70	75+20per circuit
			F4-04DA-2	90	90
			F4-04DAS-1	60	60 per circuit
			F4-04DAS-2	60	60 per circuit
			F4-08DA-1	90	100+20 per circuit
			F4-08DA-2	80	150
			F4-16DA-1	90	100+20 per circuit
			F4-16DA-2	80	25 max.
			F4-08RTD	80	NONE
			F4-08THM-n	120	50
			F4-08THM	110	60
<i>DC Input Modules</i>			<i>Remote I/O</i>		
D4-08ND3S	100	NONE	H4-ERM100	320(300)	NONE
D4-16ND2	150	NONE	H4-ERM-F	450	NONE
D4-16ND2F	150	NONE	D4-RM	300	NONE
D4-32ND3-1	150	NONE			
D4-64ND2	300 max.	NONE			
<i>AC Input Modules</i>			<i>Communications and Networking</i>		
D4-08NA	100	NONE	H4-ECOM100	300	NONE
D4-16NA	150	NONE	D4-DCM	500	NONE
			F4-MAS-MB	235	NONE
			FA-UNICON	NONE	65
<i>AC/DC Input Modules</i>			<i>CoProcessors</i>		
D4-16NE3	150	NONE	F4-CP128-1	305	NONE
F4-08NE3S	90	NONE	F4-CP128-T	350	NONE
<i>DC Output Modules</i>			<i>Specialty Modules</i>		
F4-08TD1S	295	NONE	H4-CTRIO	400	NONE
D4-16TD1	200	125	D4-INT	100	NONE
D4-16TD2	400	NONE	F4-16PID	160	NONE
D4-32TD1	250	140	F4-8MPI	225	170
D4-32TD1-1	250	140 (15V)	D4-16SIM	150	NONE
D4-32TD2	350	120 (4A max including loads)	F4-4LTC	280	75
D4-64TD1	800	NONE			
<i>AC Output Modules</i>			<i>Programming</i>		
D4-08TA	250	NONE	D4-HPP-1 (Handheld Prog.)	320	NONE
D4-16TA	450	NONE			
<i>Relay Output Modules</i>			<i>Operator Interface</i>		
D4-08TR	550	NONE	DV-1000	150	NONE
F4-08TRS-1	575	NONE			
F4-08TRS-2	575	NONE	C-more Micro-Graphic	210	NONE
D4-16TR	1000	NONE			
<i>Analog Modules</i>					
F4-04AD	150	100			
F4-04ADS	370	120			
F4-08AD	75	90			