

### SureStep® Integrated Motors System

#### General integrated motor/drive features

- DC power supply required (12-48 VDC or 12-70 VDC)
- Pulse/Direction or CW Pulse/CCW Pulse
- · Digital input filtering
- "E" models include an encoder
- Three optically isolated digital inputs, 5 to 24 volts
- Step input signal smoothing (microstep emulation), performs high resolution stepping by synthesizing coarse steps into fine microsteps
- Dynamic smoothing, software-configurable filtering for use in removing spectral components from command sequence, reduces jerk, limiting excitation of system resonance
- Anti-resonance (electronic damping): raises the system-damping ratio to eliminate midrange instability and allow stable operation throughout the speed range of the motor
- Idle current reduction range of 0-90% of running current after a delay selectable in milliseconds (Standard models = 50/90%, DIP switch selectable)
- Configurable hardware digital noise filter, software noise filter
- Non-volatile storage, configurations are saved in FLASH memory on-board the DSP
- Dynamic current control, software configurable for running current, accel current, idle current, to make motion smoother and the motor run cooler



Standard NEMA 17 and 23 motor/drives

#### Standard integrated motor/drive features

#### (STP-MTRD-x)

- "E" models have an externally wireable encoder which can provide feedback to an external controller
- Configurable via DIP switches
- Available torque from 68 to 210 oz-in

#### Advanced integrated motor/drive features

#### (STP-MTRD-xR)

- Step and Direction, CW/CCW, and AB Quadrature/Encoder following
- Velocity (Oscillator) and position mode
- Control via streaming SCL commands
- RS-485 ASCII (2- or 4-wire) communications
- On "E" models, the internal encoder provides improved position and speed control
- Four "Variable I/O" points, 5 to 24 volts (NEMA 24 models)
- Analog input for speed and position, 0 to 5 VDC
- Configurable via SureMotion Pro software
- Available torque from 54 to 340 oz-in

SureStep Series Part Numbers Standard Integrated Motor/Drives								
Integrated Motor/Drive	NEMA Size	Price	Drawing					
STP-MTRD-17038	17	\$;02b[o:	PDF					
STP-MTRD-17038E	17	\$;02b[n:	PDF					
STP-MTRD-23042	23	\$;02b[q:	PDF					
STP-MTRD-23042E	23	\$;02b[p:	<u>PDF</u>					
STP-MTRD-23065	23	\$;;02b[t:	PDF					
STP-MTRD-23065E	23	\$;02b[s:	<u>PDF</u>					

Note: Standard Integrated motor/drives with an "E" have an external encoder that can be wired to an external controller.



Advanced NEMA 17, 23, and 24 motor/drives

SureStep Series Part Numbers Advanced Integrated Motor/Drives								
Integrated Motor/Drive	NEMA Size	Price	Drawing					
STP-MTRD-17030R	17	\$;02b[d:	PDF					
STP-MTRD-17030RE	17	\$;02b[c:	PDF					
STP-MTRD-17038R	17	\$;;02b[f:	PDF					
STP-MTRD-17038RE	17	\$;02b[e:	PDF					
STP-MTRD-23042R	23	\$;02b[h:	PDF					
STP-MTRD-23042RE	23	\$;02b[g:	PDF					
STP-MTRD-23065R	23	\$;-02b[j:	PDF					
STP-MTRD-23065RE	23	\$;-02b[i:	<u>PDF</u>					
STP-MTRD-24075RV	24	\$;-02b[l:	PDF					
STP-MTRD-24075RVE	24	\$;02b[k:	PDF					

Note: Advanced Integrated motor/drives with an "E" have an internal encoder used for stall prevention (cannot be wired to an external PLC or controller).



**SureStep**® **Advanced Integrated Motor/Drives** 



		Sur	eStep Integrated S	Series Specificatio	ns – Advanced				
Integrated Motor/Drive			STP-MTRD- 17030RSTP-MTRD- 17030RE STP-MTRD-17030RE	STP-MTRD-         17038RSTP-MTRD-         STP-MTRD-23042R         STP-MTRD-23042R         STP-MTRD-23042R         STP-MTRD-23042RE         STP-MTRD-23042RE					
Input Voltage (external p/s required)			12-48	VDC	12-70	VDC			
Con	figuration l	Method		SureMotion Pro software	(SM-PRO: free download)				
Sup	ply Output			+4.8 - 5 volts @	50mA maximum				
Curi	ent Contro	ller	Dual H-Bridge, 4 Quadra	nt, 4 state PWM @ 16kHz	Dual H-Bridge, 4 Quadra	nt, 4 state PWM @ 20kHz			
Enc	oder Feedb	ack	"E" models only. Enco	oder is internal and provides posi	tion verification and stall preven	tion control by default.			
Mot	or/Drive Pi	otection		Short circuit, over-voltage,	, under-voltage, over-temp				
	Step/Puls	e	5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, i current draw = 12mA Function = Step Input, Jog CW, Limit CW, Start/Stop, General Purpose						
Input Signals	Direction		5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, General Purpose						
Input	Enable		5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Reset Input, Change Speed, General Purpose						
	Analog			AIN referenced to GND). Input in des and general purpose analog filte	usage; programmable for signal				
Out	out Signal			maximum. Optically isolated, op Brake Output, Alarm Output, Mo					
Con	nmunicatio	n Interface		RS-485	5 ASCII				
Non	-volatile M	emory Storage	Configurations are saved in FLASH memory on-board the DSP						
	Current R	eduction		Selectable in SureMotion Pro software					
res	Idle Curre	nt Reduction	Reduction range of 0–90% of running current after delay selectable in ms						
Features		Resolution	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev						
Ĭ.	Modes of	Operation	,	rection, CW/CCW, A/B quadratur	. , ,				
	Self Test		Checks internal and external	power supply voltages. Diagnos		or resistance changes > 40%			
		DC Power	2-position screw terminal: Weidmuller 1615780000						
Con	nectors	I/O	11-position spring cage: Phoenix 1881419						
		Comm	5-position spring cage: Phoenix 1881354						
Driv	e Cooling I	Method	Natural convection (mount to suitable heat sink)						
Stat	us LEDs			1 red, 1	1 green				
Мοι	ınting		Four M3	3 screws	Four #6	screws			
_				·	C.				

## **SureStep**® **Advanced Integrated Motor/Drives**

Integrated Motor/Drive Input Voltage (external p/s required) Configuration Method SureMotion Pro software (SM-PRO: free download) **Supply Output** Current Controller Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz Encoder Feedback "E" models only. Encoder is internal and provides position verification and stall prevention control by defaution Motor/Drive Protection    I/O 1 (Step/Pulse)   INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
(external p/s required)  Configuration Method  Surphy Output  Current Controller  Encoder Feedback  "E" models only. Encoder is internal and provides position verification and stall prevention control by defaut Motor/Drive Protection  I/O 1 (Step/Pulse)  INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
Supply Output +4.8 - 5 volts @ 50mA maximum  Current Controller Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz  Encoder Feedback "E" models only. Encoder is internal and provides position verification and stall prevention control by defaution Short circuit, over-voltage, under-voltage, over-temp  INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
Current Controller  Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz  Encoder Feedback  "E" models only. Encoder is internal and provides position verification and stall prevention control by defaut Motor/Drive Protection  Short circuit, over-voltage, under-voltage, over-temp  INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
### Figure   **E" models only. Encoder is internal and provides position verification and stall prevention control by default	
Motor/Drive Protection  Short circuit, over-voltage, under-voltage, over-temp  INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose  OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	1Hz, max current
draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	1Hz, max current
	Brake Output,
INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Direction Input, Jog CCW, Alarm Reset Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
Fault Output, Motion Output, Tach Output, General Purpose  INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3M draw = 12mA, Function = Limit CW Input, Enable Input, Change Speed Input, General Purpose  OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency current draw = 12mA, Function = Limit CCW Input, Alarm Reset Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Fault Output, Motion Output, Tach Output, General Purpose	
Analog  0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits, Function = a modes and general purpose analog usage; programmable for signal range, offset, dead band, and filterin	
Communication Interface RS-485 ASCII (2- or 4-wire)	
Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP	
Current Reduction Selectable in SureMotion Pro software	
Reduction range of 0–90% of running current after delay selectable in ms	
## Address of Operation   Pulse (step) & direction CW/CCW A/B quadrature velocity (oscillator) SCI streaming commands	
Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands	
Self Test  Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance chang	jes > 40%
DC Power 2-position screw terminal: Weidmuller 1615780000	
Connectors I/O 11-position spring cage: Phoenix 1881419	
Comm 5-position spring cage: Phoenix 1881354	
Drive Cooling Method  Natural convection (mount to suitable heat sink)	
Status LEDs 1 red, 1 green	-
Mounting Four #6 screws	

## **SureStep**® **Advanced Integrated Motor/Drives**

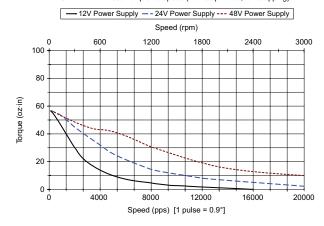
SureStep Integrated Series Specifications – Advanced									
Integrated Motor/Dri	ve	STP-MTRD-17030R STP-MTRD-17030RE	STP-MTRD-17038R STP-MTRD-17038RE	STP-MTRD-23042R STP-MTRD-23042RE	<u>STP-MTRD-23065R</u> <u>STP-MTRD-23065RE</u>	STP-MTRD-24075RV STP-MTRD-24075RVE			
NEMA Frame Size		NEMA 17	NEMA 17	NEMA 23	NEMA 23	NEMA 24			
	(lb·in)	3.375	4.25	7.8125	13.125	21.25			
* Maximum Holding Torque	(oz·in)	54	68	125	210	340			
101qu0	(N·m)	0.381326	0.480189	0.8827	1.482936	2.400944			
Dotor Inortio	(oz·in2)	0.310	0.448	1.420	2.515	4.900			
Rotor Inertia	(kg·cm2)	0.057	0.082	0.260	0.460	0.897			
Insulation Class				Class B (130°C)					
Basic Step Angle				1.8 degrees					
Shaft Runout (in)		0.0	)3		0.05				
Max Shaft Radial Pla load	y @ 1lb	0.02							
Perpendicularity (mn	1)	0.08							
Concentricity (mm)		0.05							
* Maximum Radial Lo (lb [kg])	oad	6.	7	13.9					
* Maximum Thrust Lo (lb [kg])	pad	3	4		63				
Storage Temperature	Range	0-40°C (32-104°F)							
Operating Temperatu	re Range	0-85°C 0-70°C							
Operating Humidity F	Range	90% max, non-condensing							
Product Material		Aluminum, steel, plastic, FR4, etc.							
Environmental Rating	1			IP40					
Weight (oz [g])		12.7 [360]	15.6 [441]	30 [850]	42 [1191]	56 [1580]			
Agency Approvals		CE*							
Design Tips		Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor.  DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided.  DO NOT connect or disconnect the step motor during operation.  Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation.  Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings from minor misalignment and to prevent loosening due to vibration.							

<sup>\*</sup> For NEMA 24 motors, an EMI filter (RES10F03) is needed on the power supply for CE compliance.

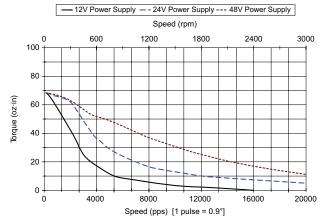


### SureStep® Integrated Motor/Drives Motor Torque vs. Speed

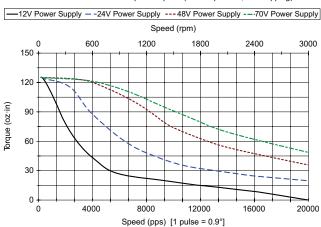
STP-MTRD-17030 Torque vs Speed (1.8° step motor; 1/2 stepping)



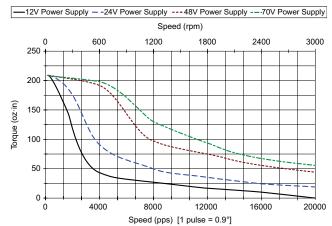
STP-MTRD-17038 Torque vs Speed (1.8° step motor; 1/2 stepping)



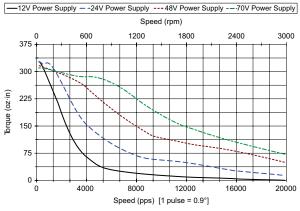
STP-MTRD-23042 Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTRD-23065 Torque vs Speed (1.8° step motor; 1/2 stepping)



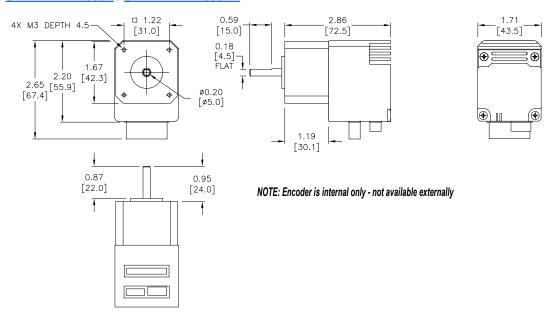
#### STP-MTRD-24075 Torque vs Speed (1.8° step motor; 1/2 stepping)



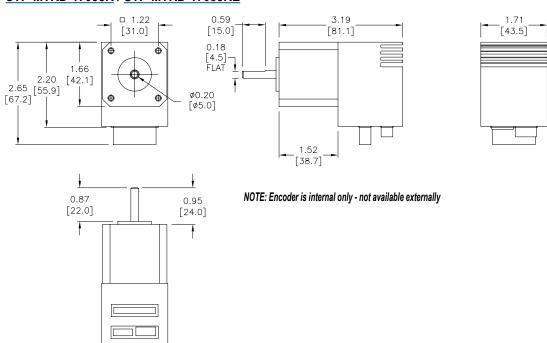
## SureStep® Advanced Integrated Motor/Drives Dimensions

Dimensions = in [mm]

#### STP-MTRD-17030R / STP-MTRD-17030RE



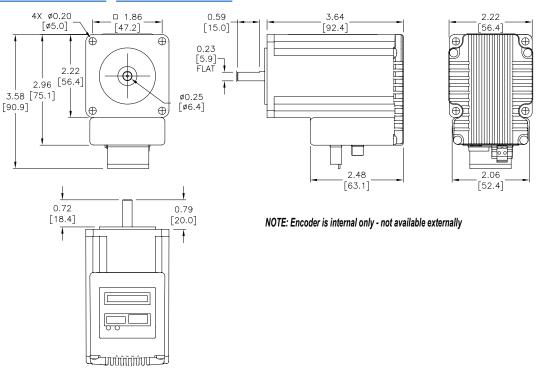
#### STP-MTRD-17038R / STP-MTRD-17038RE



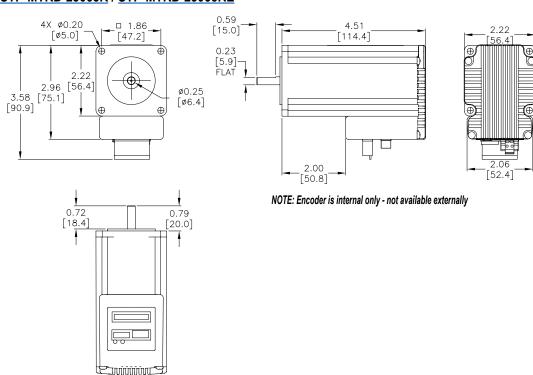
## SureStep® Advanced Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]

#### STP-MTRD-23042R / STP-MTRD-23042RE



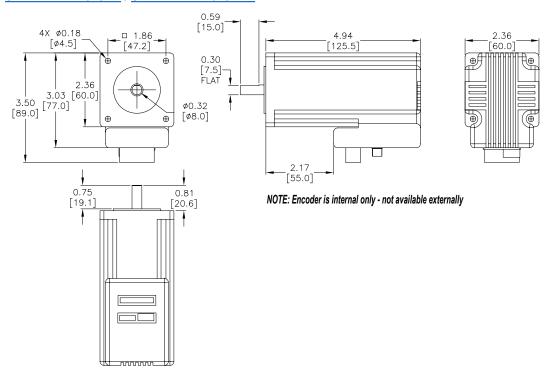
#### STP-MTRD-23065R / STP-MTRD-23065RE



## SureStep® Advanced Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]

#### STP-MTRD-24075RV / STP-MTRD-24075RVE





### SureStep® Microstepping Drives Accessories

#### **Braking Accessories**

As a load rapidly decelerates from a high speed, much of the kinetic energy of that load is transferred back to the motor. This energy is then pushed back to the drive and power supply, resulting in increased system voltage. If there is enough overhauling load on the motor, the DC voltage will go above the drive and/or power supply limits. In general, the more torque the motor is capable of producing then the more energy it can push back into the drive.

When using a regulated/switching power supply, this can trip the overvoltage protection of the power supply or drive, and cause it to shut down.

To solve this problem, AutomationDirect offers a regeneration clamp as an optional accessory. The regen clamp has a built-in 50W braking resistor. The STP-DRVA-RC-050A does not have the ability to use an external resistor.



Regeneration Clamp STP-DRVA-RC-050A

#### **Regeneration Clamp Features**

#### STP-DRVA-RC-050A

- Built-in 50W power resistor for more continuous current handling
- · Mounted on a heat sink
- Voltage range: 24-80 VDC; no user adjustments required
- Power: 50W continuous; 800W peak
- Indicators (LED):
- Green = power supply voltage is present Red = clamp is operating (usually when stepper is decelerating)
- Protection: The external power supply is internally connected to an "Input Diode" in the regen clamp that protects the power supply from high regeneration voltages. This diode protects the system from connecting the power supply in reverse. If the clamp circuit fails, the diode will continue to protect the power supply from over-voltage.
- Three drive connections, 7A max per channel, 15A total output current
- Removable terminal blocks (replacement kit STP-CON-4)
- Uses 18-20 AWG wire for connections

#### SureStep Damper

A step motor inertia damper can smooth out steps in a typical step motor resulting in a quieter and smoother motion when rotating between steps. Reducing the resonance and possible micro oscillations when moving from step to step is the main purpose of a "hockey puck" style damper, but it can also be used as a hand wheel to directly rotate the position of the rotor when power is removed from the motor. The damper is a properly sized machined piece of aluminum encased in plastic. It is sized and weighted for general damping of the respective frame size motor.



Sure Step Series Specifications – Microstepping Drives Optional Accessories Part Number Price Description Drawing Regen Clamp: 50W, for DC input stepper and servo drives, enclosed STP-DRVA-RC-050A\* \$4327: **PDF** SureStep damper, metal body. For use with NEMA 17 stepper motors with 5mm shafts. Mounting set screw STP-MTRA-17DMP \$2e9y: **PDF** included. SureStep damper, metal body. For use with NEMA 23 stepper motors with 1/4 inch shafts. Mounting set STP-MTRA-23DMP \$2e9z PDF screw included

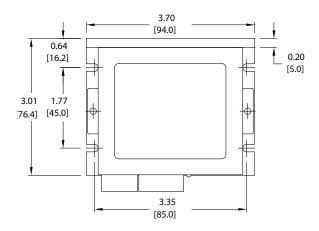
<sup>\*</sup> Do not use the regeneration clamp in an atmosphere containing corrosive gases.

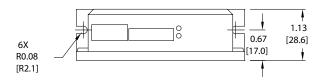


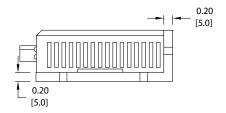
## **SureStep®** Microstepping Drives Accessories

Dimensions = in [mm]

#### STP-DRVA-RC-050A









### SureStep® Microstepping Drives Accessories

#### **USB to RS-485 Adapter**

The <u>STP-USB485-4W</u> is a USB to RS-232/RS-485 converter that can be used in 2-wire or 4-wire serial networks. Serial communication can be wired up via the 9-pin D-sub connector or through the 6-screw terminals.

The STP-USB485-4W can be set for several different configurations. These modes are set up by the 4 DIP switches on the outside of the case (RS-232/RS-485, full/half duplex) and by the 7 jumpers located inside the case (termination/bias resistors).

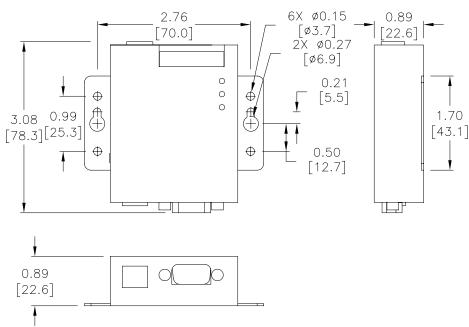
SureStep Advanced Drives communicate via RS-232 (for control and for configuration via SureMotion Pro).

The Advanced Integrated motor/drives use RS-485. While the Advanced Integrated motor/drives can be wired for either 2- or 4-wire networks, 4-wire is require for use with SureMotion Produe to the Firmware Download utility and the Status Monitor Screen.

Depending on the host controller's RS-485 implementation, either 2- or 4-wire RS-485 can be used for control. All RS-485 PLCs that have 2-wire capability (Productivity, BRX, Click, DirectLogic, etc.) can control the Advanced Integrated steppers.

SureStep PC Adapter - STP-USB485-4W						
Price	\$;02b[_:					
Drawing	PDF					
Communications	2-wire RS-232 2- or 4-wire RS-485					
Configure With	Internal jumpers and external DIP switches					
Compatible Cables	STP-232RJ11-CBL STP-485DB9-CBL-2 USB					

#### Dimensions = in [mm]







### SureStep® Stepping System Encoders

#### **Replacement Encoders**

The <u>STP-MTRA-ENC1</u> is a replacement for the encoder that comes standard with the <u>STP-MTRD-17038E</u>, <u>STP-MTRD-23042E</u>, and <u>STP-MTRD-23065E</u> integrated motor/drives. Note that the encoder included with (E) model advanced integrated motor/drives is internal and cannot be replaced.

The <u>AMT112Q-V</u> is a replacement for the encoder that comes standard with the STP-MTR(x)-xxxxE stand alone step motors.

Installation tool and mounting hardware is included with all replacement encoders. For more information and details on how to wire the replacement encoders, please see the SureStep User Manual.

#### **Optional Encoders**

Optional encoders can be purchased separately for standard integrated motor/drives and standalone dual-shaft motors in all NEMA 14, 17, and 23 sizes, and also for STP-MTRAC-34xxxD motors (currently not available for STP-MTRx-34xxxD motors). All (D) model (dual-shaft) step motors come with pre-drilled holes in the rear end cap for easy encoder mounting. Pre-installed encoders on standalone dual-shaft motors and standard integrated motor/drives can be retrofitted with an appropriate optional encoder if desired. Please see the chart on the following page for encoder compatibility.

#### Features:

- Fixed resolutions include 400ppr or 1000ppr
- Configurable models have up to 4096ppr (default = 400ppr)
- Choose line driver or push-pull (totem) output signals



STP-MTRA-ENC2



AMT112Q-V



STP-MTRA-ENC11

		Sure Step Series Specifications – Encoders	
Part Number	Price	Description	Drawing
STP-MTRA-ENC1	\$2e69:	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	PDF
STP-MTRA-ENC2	\$;2e9]:	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
\$\frac{\text{STP-MTRA-ENC3}}{\text{\$\text{sp-step} incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.		<u>PDF</u>	
STP-MTRA-ENC4	\$2e9_:	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
STP-MTRA-ENC5	\$2e9#:	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
\$:2e9!: SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with Stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.		SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
STP-MTRA-ENC7	\$2e9?:	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
STP-MTRA-ENC8	\$;2e9,:	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>
STP-MTRA-ENC11	\$02ea2:	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.	<u>PDF</u>
STP-MTRA-ENC12	\$2ea3:	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.	<u>PDF</u>
STP-MTRA-ENC13	\$04328:	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.	<u>PDF</u>
STP-MTRA-ENC14	\$4329:	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.	PDF

## **SureStep®** Stepping System Encoders

Sure Step Series Encoder Compatibility								
Part Number	PPR	Bore Diameter	Output Type	Encoder Cable	PLC Compatibility	Motor Compatibility		
STP-MTRA-ENC1	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-14xxxD		
STP-MTRA-ENC2		- 5mm	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-14xxxE STP-MTRx-17xxxD		
STP-MTRA-ENC3	400	mine	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-17xxxE Standard STP-MTRD- xxxxxE		
STP-MTRA-ENC4			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*			
STP-MTRA-ENC5	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*			
STP-MTRA-ENC6		0.25 inch	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-23xxxD STP-MTRx-23xxxE		
STP-MTRA-ENC7	400	U.25 Inch	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRAC-23xxxE STP-MTRAC-23xxxD		
STP-MTRA-ENC8			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*			
STP-MTRA-ENC11	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*			
STP-MTRA-ENC12			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	CTD MTDAC 24vovD		
STP-MTRA-ENC13	400	0.375 inch	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRAC-34xxxD		
STP-MTRA-ENC14			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*			

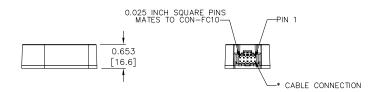
<sup>\*</sup> Requires FC-ISO-C

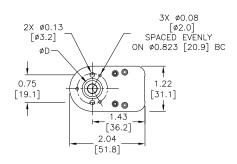


## **SureStep®** Stepping System Encoders

Dimensions = in [mm]

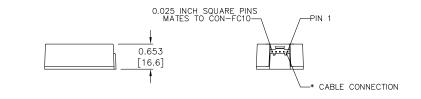
#### **STP-MTRA-ENC1**, 3, 5, 7

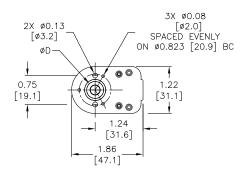




Bolt Hole Circles for Mounting						
Encoder Holes						
ENC1, ENC2, ENC3, ENC4, ENC5, ENC6, ENC7, ENC8	2 holes @ 19.05mm (.75") 3 holes @ 20.9mm (.823")					

#### **STP-MTRA-ENC2, 4, 6, 8**



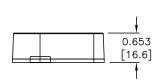


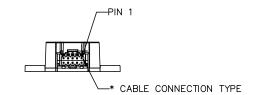


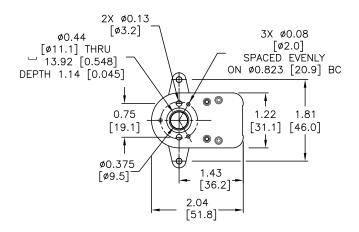
## **SureStep® Stepping System Encoders**

Dimensions = in [mm]

#### STP-MTRA-ENC11, 13

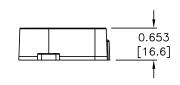


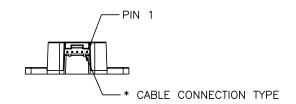


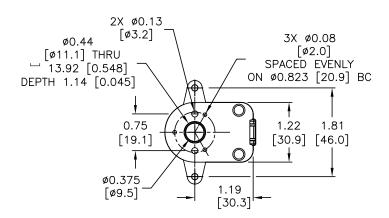


Bolt Hole Circles for Mounting						
Encoder Holes						
ENC11, ENC12, ENC13, ENC14	2 holes @ 19.05mm (.75") 3 holes @ 20.9mm (.823") 2 holes @ 46.02mm (1.812")					

#### STP-MTRA-ENC12, 14







### SureStep® Cables

		SureStep Se	ries – S	Stepping System Cables		
Cable	Price	Purpose	Length	Use With	Cable End Connectors	Drawing
STP-EXT-006	\$-2e9i:		6 ft			PDF
STP-EXT-010	\$-2e9j:		10 ft	STP-MTR-xxxxx(x)	pigtail / Molex 43020-0401 connector	PDF
STP-EXT-020	\$04vd:		20 ft		Connector	PDF
STP-EXTH-006	\$2e9k:		6 ft			PDF
STP-EXTH-010	\$-2e9l:		10 ft	STP-MTR <b>H</b> -xxxxx(x)	pigtail / Molex 39-01-2041 connector	PDF
STP-EXTH-020	\$04ve:		20 ft		CONTROCTOR	PDF
STP-EXTHW-006	\$;3?]8:		6 ft			PDF
STP-EXTHW-010	\$;3?]3:	motor to drive extension	10 ft	STP-MTR <b>HW</b> -xxxxx(x)	Bulgin # PXP4011/06P/6065	PDF
STP-EXTHW-020	\$;03?]5:		20 ft			PDF
STP-EXTL-006	\$2e9n:		6 ft			PDF
STP-EXTL-010	\$2e9d:		10 ft	STP-MTRL-xxxxx(x)	pigtail / Molex 105308-22004 connector	PDF
STP-EXTL-020	\$2e9e:		20 ft			<u>PDF</u>
STP-EXTW-006	\$;3?]6:		6 ft			<u>PDF</u>
STP-EXTW-010	\$;3?]7:		10 ft	STP-MTR <b>W</b> -xxxxx(x)	Bulgin # PXP4011/06P/6065	<u>PDF</u>
STP-EXTW-020	\$;03?]4:		20 ft			PDF
STP-EXT42-006	\$;4!qb:		6 ft			PDF
STP-EXT42-010	\$;4!qc:		10 ft	STP-MTRAC-42xxxx		PDF
STP-EXT42-020	\$;4!qd:	motor to drive extension	20 ft		- 10-pin / pigtail -	PDF
STP-EXT42H-006	\$;4!qe:	motor to drive extension	6 ft		10-pii17 pigtaii	PDF
STP-EXT42H-010	\$;;4!qf:		10 ft	STP-MTRACH-42xxxxx		PDF
STP-EXT42H-020	\$;4!qa:		20 ft			PDF
<u>STP-232RJ11-CBL</u> *	\$04yx:	programming/ communication	10 ft	STP-DRV-4850, STP-DRV-80100	DB9 female / RJ11(6P4C)	PDF
STP-232HD15-CBL-2**	\$;04yf:	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL06, D2-250-1, D2-260	HD 15-pin male / RJ12 6-pin plug	n/a
STP-232RJ12-CBL-2**	\$04yg:	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL05, CLICK	RJ11 (6P4C) plug / RJ12 6-pin plug	n/a
STP-CBL-CA6	\$;2b[y:	control cable	6 ft		11-pin / pigtail	PDF
STP-CBL-CA10	\$;2b[z:	control cable	10 ft	STP-MTRD-17038 STP-MTRD-17038E	11-pin / pigtail	PDF
STP-CBL-CA20	\$;;02b[]:	control cable	20 ft		11-pin / pigtail	PDF
STP-CBL-EA6	\$;2b[u:	encoder cable	6 ft	STP-MTRD-xxxxxE	10-pin / pigtail	PDF
STP-CBL-EA10	\$;2b[v:	encoder cable	10 ft	STP-MTRA-ENC1, STP-MTRA-ENC3 STP-MTRA-ENC5, STP-MTRA-ENC7 STP-MTRA-ENC11, STP-MTRA-ENC13	10-pin / pigtail	PDF
STP-CBL-EA20	\$;2b[x:	encoder cable	20 ft	(for line driver encoders)	10-pin / pigtail	PDF
STP-CBL-EB3	\$3?8z:	encoder cable	3 ft	AMT4420 \/	17-pin / pigtail	PDF
STP-CBL-EB6	\$;2e9f:	encoder cable	6 ft	AMT112Q-V AMT112S-V	17-pin / pigtail	PDF
STP-CBL-EB10	\$02e9g:	encoder cable	10 ft	(for both line driver and push-pull (totem) encoders)	17-pin / pigtail	<u>PDF</u>
STP-CBL-EB20	\$02e9h:	encoder cable	20 ft	GIIOUUGISJ	17-pin / pigtail	<u>PDF</u>
STP-CBL-ED6	\$2e9s:	encoder cable	6 ft	STP-MTRA-ENC2, STP-MTRA-ENC4	5-pin / pigtail	PDF
STP-CBL-ED10	\$;2e9t:	encoder cable	10 ft	STP-MTRA-ENC6, STP-MTRA-ENC8 STP-MTRA-ENC12, STP-MTRA-ENC14	5-pin / pigtail	PDF
STP-CBL-ED20	\$2e9u:	encoder cable	20 ft	(for push-pull (totem) encoders)	5-pin / pigtail	<u>PDF</u>
STP-CON-1	\$;2b[#:	replacement connector kit	n/a	STP-DRV-4845 & -6575	-	n/a
STP-CON-2	\$;;2b[!:	replacement connector kit	n/a	STP-DRV-4850 & 80100	-	n/a
		1 CPI is sysilable for eners or ren				

<sup>\*</sup> Programming/communication cable STP-232RJ11-CBLis available for spare or replacement purposes.

<sup>(</sup>One cable is included with each software programmable drive.)

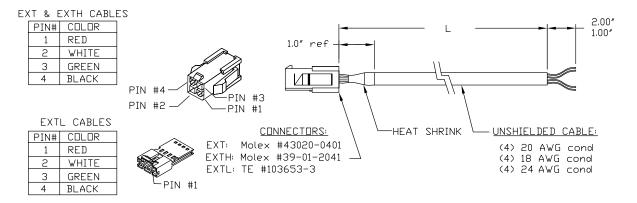
\*\* Refer to the ZIPLinks Wiring Solutions section for complete information regarding cables STP-232HD15-CBL-2 and STP-232RJ12-CBL-2.



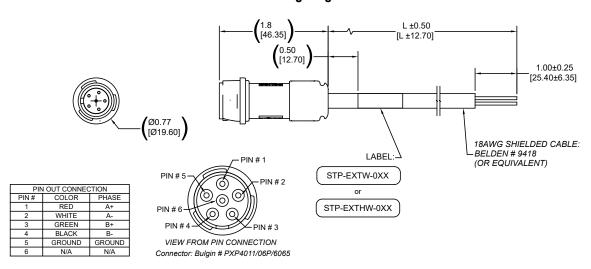
## SureStep® Cables, continued

SureStep Series – Stepping System Cables								
Cable Price		Purpose	Length	Use With	Cable End Connectors	Drawing		
STP-CON-3	\$;2b[?:	replacement connector kit	n/a	STP-MTRD-xxxxxR	-	n/a		
STP-CON-4	\$432s:	replacement connector kit	n/a	STP-DRVA-RC-050A	-	n/a		
STP-CON-5	\$;432t:	replacement connector kit	n/a	STP-DRV-4830	-	<u>PDF</u>		
STP-CON-6	\$432u:	replacement connector kit	n/a	STP-DRVAC-24025	-	n/a		
STP-485DB9-CBL-2	\$;;2b[[:	4-wire programming cable	6.5 ft	STP-MTRD-xxxxxR	DB9 / Phoenix 5-conductor plug	PDF		

#### STP-EXT(x)-0xx Extension Cable Wiring Diagram

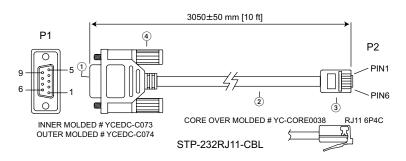


#### STP-EXTW-0xx and STP-EXTHW-0xx Extension Cable Wiring Diagram



## SureStep® Cables, continued

#### STP-232RJ11-CBL Programming Cable Wiring Diagram

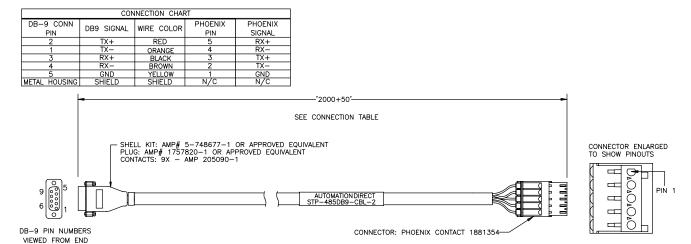


		WIRE CONNEC	CTION	
	(DB9) P1			P2 (RJ11 6P4C)
	2	RX	TX	3
	3	TX	RX	5
	4	nc	nc	4
	5	GND	GND	2
)			SHELL	.: FRONT NICKEL BACK
_	INSULATOR C	OLOR: BLACK		

# DB 9P FEMALE CONNECTOR SHELL: FRONT NICKEL BACK TIN INSULATOR COLOR: BLACK CABLE: CAT-5 UTP 24AWG (7/0.203BA\*2PR) 100MHz COLOR: BLACK OD: 4.5mm RJ11 6P4C PLATED GOLD 3U"

(4) SCREW: #4-40UNC PD40\*175TNP COLOR: BLACK

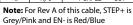
#### STP-485DB9-CBL-2 4-wire Programming Cable Wiring Diagram

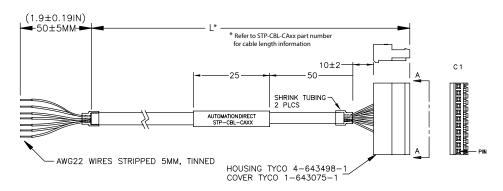


### SureStep® Cables, continued

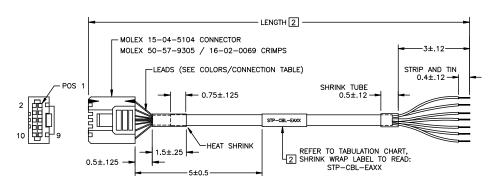
#### STP-CBL-CAxx Control Cable Wiring Diagram







#### STP-CBL-EAxx Encoder Cable Wiring Diagram



CONN	CONNECTION T			
PIN	LEAD COLOR	SIGNAL		
2	GREEN/WHITE	GROUND	TWISTED PAIR	
7	GREEN	POWER+		
3	ORANGE/WHITE	Z-	TWISTED PAIR	
4	ORANGE	Z+		
5	BLUE/WHITE	A	TWISTED PAIR	
6	BLUE	A+	IWISTED FAIR	
9	BROWN/WHITE	B-	TWISTED PAIR	
10	BROWN	B+		
1	N/C	N/A	NO CONNECTION	
8	N/C	N/A	NO CONNECTION	

WIRE: 24AWG, CABLE: UL2464.

#### STP-CBL-EBxx Encoder Cable Wiring Diagram

