LSELECTRIC L7C AC Servo Systems

Drive features

- Power: 100W-1kW single-phase 220VAC
- Fully digital with up to 1kHz velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the DriveCM PC-based software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- · Command options include:
- ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with real-time selectable electronic gearing
- Internal Indexer for position/speed-based moves. 64 individual move statements can be configured in the drive. Each Index contains its own distance, speed, accel, decel, and dwell parameters. These indexes can be set up through DriveCM software or modified in realtime with serial communication (PLC, HMI, etc.). The indexes can be initiated via Digital Inputs or through serial comms.
- The 1 kHz bandwidth allows for high-level automatic tuning. Several
 modes of tuning are available including Off-Line Auto Tuning (the drive
 initiates its own move commands while Auto tuning), On-Line Auto
 Tuning (an external controller sends the move commands while the
 drive Auto tunes), and Manual Tuning (all tuning values are adjusted by
 the user).
- Optically isolated digital inputs (10) and (5) general purpose (user-configurable) outputs + (3) outputs permanently configured as alarm/status binary code, analog inputs for speed and torque control (2), and line driver output for encoder (with scalable resolution).
- Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.







Motor features

- · Low inertia models:
- 100W, 200W, 400W, 750W and 1kW
- Speeds up to 5,000 rpm
- Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style couplings
- Integrated encoder with 17-bit resolution (131,072 pulses per revolution)
- Optional 24 VDC spring-set holding brakes (AYK2 motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for brake motors)
- Motor cables available in standard or flex-rated lengths of 3, 5, 10, and 20m
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 50-pin cables with flying leads

Note: These parts available for sale to North American locations only.

Tuning Technology

The L7C drive closes the loop on current, velocity, and position (depending on control mode selection). The 1kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and four (4) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can tune FBL/FCL motors up to 20:1 inertia mismatch

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- Online Auto Tuning—the drive can either tune the load live while an external controller moves the load to different positions or using the drive's internal tuning motion profile.
- Offline Auto Tuning—the drive tunes the load using the drive's internal tuning motion profile.
- Manual Tuning–all parameters are available to give power users the ultimate flexibility to tune their systems.

Built-in Indexer

While the L7C drives can accept traditional commands from host controllers, they can also provide their own internal motion control. 64 point-to-point position moves can be configured in the drive. These moves can be populated through the DriveCM configuration software or they can be written to by a PLC through the drive's RS422/485 serial port. The moves can be initiated by digital inputs or by serial commands. and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful indexer inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

Optional Holding Brake

Each L7C motor can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

LS Electric MSS Series In-Line Planetary Precision Gearboxes for Servo Motors

Need more torque from the motor? Have an inertia balancing issue in your design? The LS Electric MSS series gearboxes easily mate to FBL/FCL motors. Everything you need to mount your LS electric servo is included!

- Three gear ratios available (5:1, 10:1, 20:1)
- Mounting hardware included for attaching to FBL/FCL motors.
- Industry-standard mounting dimensions
- Thread-in mounting style
- Very low backlash: 7 arc-min single stage (5:1 and 10:1 ratios), 9 arc-min for two-stage (20:1 ratios).
- 1-year warranty



Servo motor overview

Encoder Connector

9-pin watertight connector (8 pins used) for the 17-bit serial encoder. The encoder transmits motor/encoder identification information to the drive at power-up and it sends position feedback during operation.

Non-Braking Motor

Motor Power Connector

4-pin watertight connector for motor power (U, V, W, and ground)



Low Inertia Motors

Low inertia designs result in high responsiveness and high speeds.

- 100W 60mm flange
- 200W 60mm flange
- 400W 60mm flange
- 750W 80mm flange
- 1kW 80mm flange

Keyed Shafts

"FBL and FCL motors are supplied with extra-large keyways, and slightly oversized keys which must be "fitted" into the keyway for performance and longevity. Clamp or compression couplings (without key) are recommended".

- 100W 14mm diameter shaft
- 200W 14mm diameter shaft
- 400W 14mm diameter shaft
- 750W 19mm diameter shaft
- 1kW 19mm diameter shaft

All LS Electric L7C motors have keyed shafts for use with servo-grade clamp or compression couplings (recommended) or servo-grade keyed couplings. Some sanding/filing of the key may be required before pressing into the keyway. Do not modify the shaft/keyway.

Encoder Connector

9-pin watertight connector (8 pins used) for the 17-bit serial encoder. The encoder transmits motor/encoder identification information to the drive at power-up and it sends position feedback during operation.

Brake Motor

Motor Power Connector

4-pin watertight connector for motor power (U, V, W, and ground)



Brake Power Connector

2-pin watertight connector available on brake motors only. The 24VDC brake is located between the motor coils and the encoder. Motors ending in AYK2 have brakes. The brakes must have 24VDC applied to them before the motor is set in motion.

Keyed Shafts

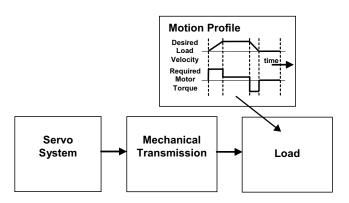
"FBL and FCL motors are supplied with extra-large keyways, and slightly oversized keys which must be "fitted" into the keyway for performance and longevity. Clamp or compression couplings (without key) are recommended".

- 100W 14mm diameter shaft
- 200W 14mm diameter shaft
- 400W 14mm diameter shaft
- 750W 19mm diameter shaft
- 1kW 19mm diameter shaft

LSELECTRIC L7C AC Servo Systems

How to select and apply L7C systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque servo system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or



measurement. The Drive CM software has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.

AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from https://support.automationdirect.com/products/sureservo.html.

1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system.

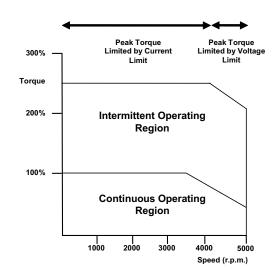
In general, applications that need high response or bandwidth

will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. L7C Auto Tuning will still tune a system with very high response, up to 20:1 inertia mismatch. Higher system ratios can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. The L7C servo systems may be tuned automatically by the software/drive or manually by the user.

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have an L7C system, these values are easily captured and recorded with the Scope feature built into the Drive CM software. If you are designing the system from scratch, use VisualSizer to define the system and calculate expected inertia and required power.

Compare the application's Continuous and Intermittent torque requirements to the torque-speed curves found in Chapter 16 of the L7C User Manual.



LSELECTRIC L7C AC Servo Systems

Application tip - coupling considerations

The LS Electric FBL/FCL motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. For standard keyed couplings, the servo key must be "fitted" into the keyway for optimum performance and longevity. Some minor filing and pressing of the key may be required. "Servo-grade" clamp-on or compression style couplings

are usually the best choice when you consider stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a trade-off between stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the servo's **peak** torque requirement of your application.

Click here for Available Couplings

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. Matched gearboxes are available from LS Electric that will work with the FBL and FCL motors. Each gearbox is selected to accept the 300% maximum available torque that could be generated by the motor. Gearboxes are available in 5:1, 10:1, and 20:1 ratios. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. The LS Electric motors can rotate at a rated speed of 3000rpm (rated torque at rated speed). Their max speed (slightly less available torque) is 5000rpm. See the speed-torque curves for more information.

Example: A gearbox reduces the motor's required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

FBL/FCL motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned.



Motor	Brake Motor	LS Electric I	MSS Planetary In-Line	Gearboxes
MOTOL			10:1 Gearbox	20:1 Gearbox
APMC-FBL01AYK-AD	APMC-FBL01AYK2-AD	96200004	96200005	96200103
APMC-FBL02AYK-AD	APMC-FBL02AYK2-AD	(MSS0601A-005KS-	(MSS0601A-010KS-	(MSS0902B-020KS-
APMC-FBL04AYK-AD	APMC-FBL04AYK2-AD	B3110103C14)	B3110103C14)	B3110103C14)
APMC-FCL08AYK-AD	APMC-FCL08AYK2-AD	96200007	96200008	96200257
APMC-FCL10AYK-AD	APMC-FCL10AYK2-AD	(MSS0901A-005KS- C3110103C19)	(MSS0901A-010KS- C3110103C19)	(MSS1152B-020KS- C3110103C19)

Here is a link to our **Timing Belts and Pulleys**

Ordering guide instructions

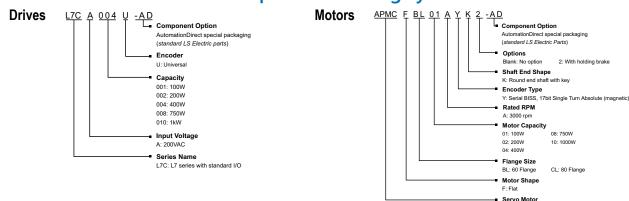
The following four pages are your ordering guide for LS Electric L7C servo systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

Each system needs:

- Motor
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either a 50-pin CN1 cable+terminals kit or a 50-pin flying lead cable(user provides terminal blocks))
- For brake motors you will also need a brake cable (connectorized on the motor end, two ferruled flying leads on the opposite end).

www.automationdirect.com

L7C series drives and motors part numbering system



Example of what you will need to build a complete servo system:





NOTE: Unit can be programmed via keypad. Optional programming software (free download). Use a standard USB-A to USB miniB cable for connectivity (SV2-PGM-USB15, MOSAIC-CSU, or equivalent)



NOTE: If you need a gear box for your configuration, reference the gearbox chart on the previous page. Ratios of 5:1, 10:1, and 20:1 are available for each FBL/FCL motor.



Torque to L7C System Quick Reference

System Rated Torque (N·m)	System Maximum Torque (N·m)	Suggested Servo Motor	Required Servo Drive
0.32	0.96	APMC-FBL01AYK-AD	
0.32	0.90	APMC-FBL01AYK2-AD	
0.64	1.91	APMC-FBL02AYK-AD	1.7CA00411.AD
0.04	1.91	APMC-FBL02AYK2-AD	<u>L7CA004U-AD</u>
1.27	3.82	APMC-FBL04AYK-AD	
1.27	3.02	APMC-FBL04AYK2-AD	
2.39	7.16	APMC-FCL08AYK-AD	
2.59	7.10	APMC-FCL08AYK2-AD	1.7CA04011.AD
3.18	9.55	APMC-FCL10AYK-AD	<u>L7CA010U-AD</u>
3.10	9.55	APMC-FCL10AYK2-AD	

L7C AC servo drive, motor, and cable combinations

xx = Cable length in meters
BN, EN, or PN = Standard cable (not continuous flex)
BF, EF, or PF = Flex-rated cable

AYK motors = no brake AYK2 motors = mechanical holding brake

rque(N.m) 200V 230V				Encoder Cable	Brake Cable	I/O Cable and Breakout			
		APMC-FBL01AYK-AD -	APCS-PNxxLSC-AD	APCS-ENxxES-AD	n/a				
Peak Operating Range	I 7CA004I LAD	AI MO-I DEUTATICAD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	n/a				
Continuous Operating Range		APMC-FRI 01AYK2-AD-	APCS-PNxxLSC-AD	APCS-ENxxES-AD	APCS-BNxxQS-AD				
0 1000 2000 3000 4000 5000 Speed(RPM)		7 II WO I BESTATILE ALE	APCS-PFxxLSC-AD	APCS-EFxxES-AD	APCS-BFxxQS-AD				
rque(N.m)		ADMC EDI 02AVK AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	n/a				
60 20 Peak Operating Range	L7CA004U-AD	170400411 40	AFMC-I BLUZATK-AD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	n/a	APC-VSCN1Txx-AD		
Continuous Operating Range		APMC-FRI 024YK2-AD-	APCS-PNxxLSC-AD	APCS-ENxxES-AD	APCS-BNxxQS-AD	or APC-CN10xA-AD			
0 1000 2000 3000 4000 5000 Speed(RPM)		THE RESERVING THE PLEA	APCS-PFxxLSC-AD	APCS-EFxxES-AD	APCS-BFxxQS-AD				
rque(N.m)		APMC-FRI MAYK-AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	n/a				
Peak Operating Range	L7CA004U-AD	. = 0.00 41. 15	. = 0.0041.15		A MOT BEOTATIONS	APCS-PFxxLSC-AD	APCS-EFxxES-AD	n/a	
Continuous Operating Range		ADMC EDI 04AVK3 AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	APCS-BNxxQS-AD				
0 1000 2000 3000 4000 5000 Speed(RPM)		AL WO-LDEVANTE-AD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	APCS-BFxxQS-AD				
rrcccccccccccccccccccccccccccccccccccc	Continuous Operating Range 1000 2000 3000 4000 5000 Speed(RPM) Que(N.m) 2000 Peak Operating Range 1000 2000 3000 4000 5000 Speed(RPM) Que(N.m) 2000 Speed(RPM) Que(N.m) 2000 Speed(RPM) Que(N.m) 2000 Speed(RPM) Que(N.m) 2000 Speed(RPM)	Continuous Operating Range O 1000 2000 3000 4000 5000 Speed(RPM) Continuous Operating Range O 1000 2000 3000 4000 5000 Speed(RPM) L7CA004U-AD Continuous Operating Range O 1000 2000 3000 4000 5000 Speed(RPM) L7CA004U-AD Continuous Operating Range O 1000 2000 3000 4000 5000 Continuous Operating Range O 1000 2000 3000 4000 5000	Continuous Operating Range 0 1000 2000 3000 4000 5000 Speed(RPM) APMC-FBL01AYK2-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL02AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD APMC-FBL04AYK-AD	APCS-PNxxLSC-AD APCS-PNxxLSC-AD APCS-PNxxLSC-AD	APCS-PFxxLSC-AD APCS-EFxxES-AD APCS-PFxxLSC-AD APCS-EFxxES-AD	APCS-PXXLSC-AD APCS-EXXES-AD APCS-BNxxQS-AD			

L7C AC servo drive, motor, and cable combinations, continued

Туре	System Torque Chart	L7C Drive	APMC Motor	Power Cable	Encoder Cable	Brake Cable	I/O Cable and Breakout							
tem	Torque(N.m) 200V 230V 8.00		APMC-FCL08AYK-AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	n/a								
750W Low Inertia System	6.40 Peak Operating Range	L7CA010U-AD		AFNIC-FCLUOATK-AD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	n/a							
W Low In	1.60 Continuous Operating Range		APMC-FCL08AYK2-AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	APCS-BNxxQS-AD								
750	0 1000 2000 3000 4000 5000 Speed(RPM)		ALIMO-I GEOGATIVE-AD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	APCS-BFxxQS-AD	APC-VSCN1Txx-AD							
							or							
tem	Torque(N.m) 200V 10.00 230V			APCS-PNxxLSC-AD	APCS-ENxxES-AD	n/a	APC-CN10xA-AD							
1.0k W Low Inertia System	8.00 Peak Operating Range	L7CA010U-AD				I 7CA010I LAD	 7CA010 -AD	I 7CA010I LAD	1.7C401011-4D	APMC-FCL10AYK-AD	APCS-PFxxLSC-AD	APCS-EFxxES-AD	n/a	
W Low I	2.00 Continuous Operating Range					APMC-FCL10AYK2-AD	APCS-PNxxLSC-AD	APCS-ENxxES-AD	APCS-BNxxQS-AD					
1.0k	0 1000 2000 3000 4000 5000 Speed(RPM)			APCS-PFxxLSC-AD	APCS-EFxxES-AD	APCS-BFxxQS-AD								

Non-brake Motor Specifications

	L7C Non-brake Motor Specifications								
Model	APMC-FBL01AYK-AD	APMC-FBL02AYK-AD	APMC-FBL04AYK-AD	APMC-FCL08AYK-AD	APMC-FCL10AYK-AD				
Price	\$058zq:	\$058zs:	\$;058zt: \$058zu:		\$058zv:				
Drawing	PDF	<u>PDF</u>	PDF	<u>PDF</u>	PDF				
Flange Size	60	60	60	80	80				
Rated Power [kW]	0.1	0.2	0.4	0.75	1				
Rated Torque [N·m] Note 1	0.32	0.64	1.27	2.39	3.18				
Max. Torque [N·m]	0.96	1.91	3.82	7.16	9.55				
Rated Speed [rpm]			3000						
Max. Speed [rpm]			5000						
Mechanical Time Constant [ms]	0.926	0.518	0.374	0.609	0.492				
Rated current [Amps] rms	0.95	1.45	2.6	5.02	5.83				
Max. Instantaneous Current [Amps] rms	2.85	4.35	7.8	15.07	17.5				
Rated Power Rate [kW/s]	11.09	27.6	27.07	45.09	62.08				
Electrical Time Constant [ms]	2.416	3.488	4.271	5.774	6.919				
Insulation Class			Class BE (CE, UL)						
Insulation Resistance			>10MΩ, 500VDC						
Insulation Strength			1.8 kVAC, 1 second		1				
Rotor Inertia [x10 ⁻⁴ kg m ²]	0.091	0.147	0.248	1.264	1.632				
Allowable Load Inertia Ratio		20 times motor inertia		15 times m	notor inertia				
Max Radial Loading [N]		206		25	55				
Max Axial Loading [N]		69		g	8				
Vibration Grade [µm]			V15						
Vibration Capacity			19.6m/s ² or lower (2.5G)						

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Non-brake Motor Specifications, continued

	L7C Non-brake Motor Specifications, continued							
Model	APMC-FBL01AYK-AD	APMC-FBL02AYK-AD	APMC-FBL04AYK-AD	APMC-FCL08AYK-AD	APMC-FCL10AYK-AD			
Speed/Position Detector		Serial Single-Turn Encoder (17-bit), built-in						
IP Rating			Fully closed, self cooling IP67	•				
Rated Time			Continuous					
Operating Temperature			0°C to 40°C					
Storage Temperature			-10°C to 60°C					
Operating Humidity			Below 80% relative humidity					
Storage Humidity		Below 9	0% relative humidity, no cond	ensation				
Atmosphere		Avoid direct sunlight,	no corrosive gas, inflammable	e gas, oil mist, or dust				
E/V		Elevation/vibration 49m/s² (5G)						
Weight [kg]	0.56	0.56 0.74 1.06 2.68 3.3						
Agency Approvals			_C UR _{US} (E255738), CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Brake Motor Specifications

		L7C Brake Motor	Specifications		
Model	APMC-FBL01AYK2-AD	APMC-FBL02AYK2-AD	APMC-FBL04AYK2-AD	APMC-FCL08AYK2-AD	APMC-FCL10AYK2-AD
Price	\$058zk:	\$-058zl:	\$058zn:	\$058zo:	\$058zp:
Drawing	<u>PDF</u>	PDF	<u>PDF</u>	<u>PDF</u>	<u>PDF</u>
Flange Size	60	60	60	80	80
Rated Power [kW]	0.1	0.2	0.4	0.75	1
Rated Torque [N·m]	0.32	0.64	1.27	2.39	3.18
Max. Torque [N·m]	0.96	1.91	3.82	7.16	9.55
Rated Speed [rpm]			3000		
Max. Speed [rpm]			5000		
Mechanical Time Constant [ms]	0.926	0.518	0.374	0.609	0.492
Rated current [Amps] rms	0.95	1.45	2.6	5.02	5.83
Max. Instantaneous Current [Amps] rms	2.85	4.35	7.8	15.07	17.5
Rated Power Rate [kW/s]	11.09	27.6	27.6 27.07 45.09		62.08
Electrical Time Constant [ms]	2.416	3.488	4.271	5.774	6.919
Insulation Class			Class BE (CE, UL)		
Insulation Resistance			>10MΩ, 500VDC		
Insulation Strength			1.8 kVAC, 1 second		
Rotor Inertia [x10 ⁻⁴ kg m ²]	0.091	0.147	0.248	1.264	1.632
Allowable Load Inertia Ratio		20 times motor inertia		15 times n	notor inertia
Max Radial Loading [N]		206		2	55
Max Axial Loading [N]		69		9	98
Brake Holding Torque [N·m (min)]		1.47		3.	23
Brake Power Consumption (at 20°C) [W]		6.5			9
Brake Release Time [ms (max)]			20		
Brake Pull-in Time [ms (max)]		50		6	60
Vibration Grade [μm]			V15		
Vibration Capacity			19.6m/s ² or lower (2.5G)		

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Brake Motor Specifications, continued

L7C Brake Motor Specifications, continued							
Model	APMC-FBL01AYK2-AD	APMC-FBL02AYK2-AD	APMC-FBL04AYK2-AD	APMC-FCL08AYK2-AD	APMC-FCL10AYK2-AD		
Speed/Position Detector		Serial Multi-Turn Built-in Type (17-bit)					
IP Rating			Fully closed, self cooling IP67	7			
Rated Time			Continuous				
Operating Temperature			0°C to 40°C				
Storage Temperature			-10°C to 60°C				
Operating Humidity			Below 80% relative humidity				
Storage Humidity		Below 9	00% relative humidity, no cond	lensation			
Atmosphere		Avoid direct sunlight,	no corrosive gas, inflammabl	e gas, oil mist, or dust			
E/V		Elevation/vibration 49m/s² (5G)					
Weight [kg]	1.28	1.46	1.78	3.45	4.07		
Agency Approvals			_C UR _{US} (E255738), CE				

Note 1-The rated torque is the continuous permissible torque between the 0° C and 40° C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: $250 \text{mm} \times 250 \text{mm} \times 6 \text{mm}$ made from aluminum (or mounted to equipment with an equivalent heat sinking capability).



L7C/L7P Series AC Servo Systems

Accessories

CN1 Accessories

For L7x series drives, two methods are available for creating I/O connections.

Option 1:

Terminal blocks + cables:

- APC-VSCN1T-AD
- APC-VSCN1T01-AD
- APC-VSCN1T02-AD

APC-VSCN1T terminals ship with a universal labeling strip (A1-A25, B1-B25). A labeling template with designations specifically for the L7x drive can be downloaded from any of the drive pages or the terminal block page (www.automationdirect.com/pn/apc-vscn1t-ad).



APC-VSCN1T-AD

Option 2:

Flying lead cables:

- APC-CN101A-AD
- APC-CN102A-AD
- APC-CN103A-AD



APC-CN101A-AD



NOTE: For L7C drives, do not use APC-VSCN1T(xx)-AD feedthrough terminal block if using PLC/Drive serial communication. Communication errors may occur due to disconnects in cable shields. Use APC-CN10xA-AD flying lead cables.

Part Number	Price	Description	Cable Length	Drawing	Compatible Drives
APC-VSCN1T-AD	\$58zg:	LO Electic ONA feedible about	0.5 m [1.6 ft]	PDF	
APC-VSCN1T01-AD	\$58zh:	LS Electric CN1 feedthrough terminal block, 50-pole, DIN rail mount	1.0 m [3.2 ft]	PDF	
APC-VSCN1T02-AD	\$-058zi:	Tall Mount	2.0 m [6.5 ft]	PDF	All L7C and L7P drives
APC-CN101A-AD	\$;58]k:		1.0 m [3.2 ft]	PDF	All L/C and L/F drives
APC-CN102A-AD	\$;-58]I:	LS Electric control cable, 50- pin connector to pigtail.	2.0 m [6.5 ft]	PDF	
APC-CN103A-AD	\$;58]n:		3.0 m [9.8 ft]	<u>PDF</u>	

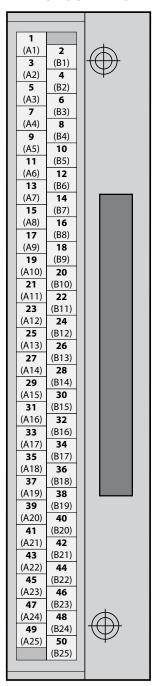
Accessories

L7C Terminal Assignment Table



CAUTION: This terminal assignment table is for use with L7C drives ONLY. Using this table with non-L7C series drives could damage your equipment as terminal assignments are different for each drive series.

APC-VSCN1T-AD



You can download a printable terminal label at https://www.automationdirect.com/pn/APC-VSCN1T-AD

	L7C Drive Terminal Assignments							
		e lellillia	i Assiyii					
Terminal	Drive I/O Pin/Wire #	Description	Wire Color	Stripe Color	Number of Stripes			
A1	1	AI-1 (TRQCOM)	Orange	Black	1			
B1	2	TXD+	Orange	Red	1			
A2	3	TXD-	Orange	Black	2			
B2	4	Z0	Orange	Red	2			
A3	5	/Z0	Orange	Black	3			
В3	6	RXD+	Orange	Red	3			
A4	7	RXD-	Orange	Black	4			
B4	8	A-GND	Orange	Red	4			
A5	9	PF+	Orange	Black	5			
B5	10	PF-	Orange	Red	5			
A6	11	PR+	Yellow	Black	1			
В6	12	PR-	Yellow	Red	1			
A7	13	N/C	Yellow	Black	2			
B7	14	DO-8	Yellow	Red	2			
A8	15	DO-7	Yellow	Black	3			
B8	16	DO-6	Yellow	Red	3			
A9	17	DI-5	Yellow	Black	4			
В9	18	DI-9	Yellow	Red	4			
A10	19	DI-8	Yellow	Black	5			
B10	20	DI-7	Yellow	Red	5			
A11	21	DI-4	Gray	Black	1			
B11	22	DI-3	Gray	Red	1			
A12	23	DI-2	Gray	Black	2			
B12	24	DO-GND24	Gray	Red	2			
A13	25	DO-GND24	Gray	Black	3			
B13	26	N/C	Gray	Red	3			
A14	27	Al-2 (SPDCOM)	Gray	Black	4			
B14	28	N/C	Gray	Red	4			
A15	29	N/C	Gray	Black	5			
B15	30	В0	Gray	Red	5			
A16	31	/B0	White	Black	1			
B16	32	AO	White	Red	1			
A17	33	/AO	White	Black	2			
B17	34	+12V	White	Red	2			
A18	35	-12V	White	Black	3			
B18	36	ENC SG	White	Red	3			
A19	37	N/C	White	Black	4			
B19	38	DO-1+	White	Red	4			
A20	39	DO-1-	White	Black	5			
B20	40	DO-2+	White	Red	5			
A21	41	DO-2-	Pink	Black	1			
B21	42	N/C	Pink	Red	1			
A22	43	DO-3	Pink	Black	2			
B22	44	DO-4	Pink	Red	2			
A23	45	DO-5	Pink	Black	3			
B23	46	DI-6	Pink	Red	3			
A24	47	DI-1	Pink	Black	4			
B24	48	DI-A	Pink	Red	4			
A25	49	PULCOM	Pink	Black	5			
B25	50	+24v	Pink	Red	5			



LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH System Motor Encoder Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Compatible Motors
APCS-EN03ES-AD	\$;58z,:		3m [9.8 ft]		PDF	
APCS-EN05ES-AD	\$;58]0:	N	5m [16.4 ft]		PDF	
APCS-EN10ES-AD	\$;58]6:	IN IN	10m [32.8 ft]		PDF	ADMC
APCS-EN20ES-AD	\$;58]7:		20m [65.6 ft]	24AWG	PDF	APMC motors with 17-bit incremental
APCS-EF03ES-AD	\$;58]8:		3m [9.8 ft]	Z4AVVG	PDF	encoders (AYK/AYK2 motors)
APCS-EF05ES-AD	\$;58]9:	Υ	5m [16.4 ft]		PDF	(ATRATRZ IIIOlois)
APCS-EF10ES-AD	\$;058]a:	ı	10m [32.8 ft]		PDF	
APCS-EF20ES-AD	\$;058]b:		20m [65.6 ft]		PDF	
APCS-EN03ES1-AD	\$-5i64:		3m [9.8 ft]		PDF	
APCS-EN05ES1-AD	\$-5i65:	N	5m [16.4 ft]		PDF	
APCS-EN10ES1-AD	\$-05i66:	IN	10m [32.8 ft]		PDF	FBL/FCL series motors with 19-bit
APCS-EN20ES1-AD	\$-05i67:		20m [65.6 ft]		PDF	
APCS-EF03ES1-AD	\$-05i68:		3m [9.8 ft]		PDF	encoders
APCS-EF05ES1-AD	\$;-05i5,:	Υ	5m [16.4 ft]		PDF	
APCS-EF10ES1-AD	\$-05i60:	ı	10m [32.8 ft]		PDF	
APCS-EF20ES1-AD	\$-05i61:		20m [65.6 ft]	24AWG	PDF	
APCS-EN03DS1-AD	\$-5i62:		3m [9.8 ft]	Z4AVVG	PDF	
APCS-EN05DS1-AD	\$-05i63:	N	5m [16.4 ft]		PDF	
APCS-EN10DS1-AD	\$-05i69:	IN	10m [32.8 ft]		PDF	
APCS-EN20DS1-AD	\$-05i6a:		20m [65.6 ft]		PDF	APM-FE/APM-FF
APCS-EF03DS1-AD	\$-05i6b:	·	3m [9.8 ft]		PDF	series motors
APCS-EF05DS1-AD	\$-05i6c:	Υ	5m [16.4 ft]		PDF	
APCS-EF10DS1-AD	\$-05i6d:	ı	10m [32.8 ft]		PDF	
APCS-EF20DS1-AD	\$-05i6e:		20m [65.6 ft]		PDF	



APCS-EN series encoder cable



APCS-ENxxxES1 series encoder cable



L7P/iX7NH System Encoder Accessories

Part Number	Price	Description	Compatible Drives
APC-EF00BS-AD	\$-5i5s:	17-pin motor encoder connector.	APM-FE and APM- FF series motors
APCS-BATT36-AD	\$5yn3:	Encoder battery. One (1) AA ER6V lithium battery with extended leads and an encoder cable connector.	All LS Electric motors with 19-bit encoders

APC-EF00BS-AD



APCS-BATT36-AD

www.automationdirect.com



LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH System Motor Brake Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Compatible Motors
<u>APCS-BN03QS-AD</u>	\$;58]c:		3m [9.8 ft]	18AWG	PDF	
APCS-BN05QS-AD	\$;58]d:	NI NI	5m [16.4 ft]		<u>PDF</u>	
APCS-BN10QS-AD	\$;58]e:	N	10m [32.8 ft]		PDF	
APCS-BN20QS-AD	\$;;58]f:		20m [65.6 ft]		PDF	APMC FBL/FCL brake motors
APCS-BF03QS-AD	\$;58]g:		3m [9.8 ft]		PDF	(100W – 1kW)
APCS-BF05QS-AD	\$;58]h:		5m [16.4 ft]		PDF	
APCS-BF10QS-AD	\$;-58]i:	Y	10m [32.8 ft]		PDF	
APCS-BF20QS-AD	\$;-058]j:		20m [65.6 ft]		<u>PDF</u>	



APCS-BN series brake cable

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C System Motor Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Compatible Motors	
APCS-PN03LSC-AD	\$;58]1:		3m [9.8 ft]	18AWG	PDF		
APCS-PN05LSC-AD	\$;58]2:	N	5m [16.4 ft]		PDF		
APCS-PN10LSC-AD	\$;58]3:		10m [32.8 ft]		PDF	ADMO EDI /EOI	
APCS-PN20LSC-AD	\$;58]4:		20m [65.6 ft]		PDF	APMC FBL/FCL motors	
APCS-PF03LSC-AD	\$;58]5:		3m [9.8 ft]		PDF	(100W – 1kW) used with L7C drives	
APCS-PF05LSC-AD	\$58z#:	v	5m [16.4 ft]		PDF	used with L/C drive	
APCS-PF10LSC-AD	\$;058z!:	Y	10m [32.8 ft]		PDF		
APCS-PF20LSC-AD	\$058z?:		20m [65.6 ft]		<u>PDF</u>		



APCS-PN series motor cable

LS Drive System Accessories

Accessories, continued

LS Drive System Replacement Connectors

Part Number	Price	Description	Compatible Drives	Image		
<u>5452573</u>	\$;58]u:	AutomationDirect replacement drive power connector.	All L7C drives	AND STREET		
APC-CN1NNA-AD	\$;58]s:	LS solder-type CN1 50-pin Electric I/O connector.	All L7C and L7P series drives			
APC-CN2NNA-AD	\$;5?b,:	LS Electric I/O connector, replacement, 20-pin.	All iX7NH series drives			
APC-CN3NNA-AD	\$;;58]t:	LS Electric solder-type CN2 14-pin drive encoder connector.	All L7C, L7P, and iX7NH series drives			
APCS-CN6K-AD	\$;5!?o:	LS Electric STO connector, replacement, 6-pin. For use with all LS Electric iX7 series drives.	All iX7NH series drives			
IX7-CON-A	\$;5!?p:	AutomationDirect drive power connector, replacement, 11-pin. Note: Do not wire to pin 4 (the "-" terminal).	iX7NH series drives, 400W, 750W, and 1kW			
<u>IX7-CON-B</u>	\$;5!?q:	AutomationDirect drive power connector for motor power, replacement, 4-pin.	iX7NH series drives, 400W, 750W, and 1kW	1		
<u>IX7-CON-C</u>	\$;5!?s:	AutomationDirect drive power connector release, replacement.	iX7NH series drives, 400W, 750W, and 1kW			
<u>IX7-CON-D</u>	\$;;5!?t:	AutomationDirect drive power connector for motor power, replacement, 4-pin	iX7NH series drives, 2kW and 3.5 kW			
<u>IX7-CON-E</u>	\$;5!?u:	AutomationDirect drive control power connector, replacement, 5-pin.	iX7NH series drives, 2kW and 3.5 kW			
IX7-CON-F	\$;5!?n:	AutomationDirect drive main power connector, replacement, 6-pin.	iX7NH series drives, 2kW and 3.5 kW	2000-00		
L7P-CON-A	\$;-5i5t:	Replacement 11-pin drive power connector. Do not wire to pin 4 (the "N" terminal)	L7PA series 230VAC 400W and 1kW drives	and the state of t		
L7P-CON-B	\$-5i5u:	Replacement 3-pin drive power connector.	L7PA series 230VAC 400W and 1kW drives	Ser.		
		Continued on nex	t page			



LS Electric AC Servo Systems

Accessories, continued

L7C/L7P/iX7NH System Braking Resistors

Use external braking resistors to provide additional regenerative capacity and to dissipate heat away from the servo drive.

Part Number	Price	Description	Drawing	Compatible Drive Series	Compatible Drive Models	
<u>APCS-140R50-AD</u>	\$58zd:	LS Electric 140W 30Ω encapsulated braking resistor	<u>PDF</u>	All 400W LS drives	L7CA004U-AD L7PA004U-AD IX7NHA004U-AD	
<u>APCS-300R30-AD</u>	\$58ze:	LS Electric 300W 30Ω encapsulated braking resistor	PDF	All 230VAC 750W and 1kW LS drives	L7CA010U-AD L7PA010U-AD IX7NHA008U-AD IX7NHA010U-AD	
<u>APC-600R30-AD</u>	\$5i5i:	LS Electric 600W 30Ω encapsulated braking resistor.	PDF	All 230VAC 2.2 kW and 3.5 kW LS drives	L7PA020U-AD L7PA035U-AD IX7NHA020U-AD IX7NHA035U-AD	
<u>APC-600R28-AD</u>	\$5i5j:	LS Electric 600W 28Ω encapsulated braking resistor.	<u>PDF</u>	All 230VAC 5.5 kW and 7.5 kW LS drives	L7PA050U-AD L7PA075U-AD	
APCS-300R82-AD	\$-5i5k:	LS Electric 300W 82Ω encapsulated braking resistor.	<u>PDF</u>	All 460VAC 1kW LS drives	L7PB010U-AD	
<u>APCS-600R140-AD</u>	\$5i5l:	LS Electric 600W 140Ω encapsulated braking resistor.	<u>PDF</u>	Alternate resistor for 460VAC 2.2 kW and 3.5 kW LS drives	Alternate resistor for L7PB020U-AD L7PB035U-AD	
APCS-600R75-AD	\$-5i5n:	LS Electric 600W 75 Ω encapsulated braking resistor.	PDF	All 460VAC 2.2, 3.5, 5.5, and 7.5 kW LS drives	L7PB020U-AD L7PB035U-AD L7PB050U-AD L7PB075U-AD	



NOTE: 600W resistors require customer-supplied M5-.8 bolts and cable lugs for connection.



APCS-140R50-AD



LECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH/PHOX System Planetary Gearboxes

Precision planetary gearboxes can increase the torque output of servo systems while reducing the reflected load inertia for higher response. Gearboxes offer high stiffness, high efficiency, and very quiet operation. Input motor shaft clamp, oversized output shaft key, and mounting hardware are included for mating to LS Electric motors.

Features.

- Maintenance free (no need to replace lubrication)
- IP65
- Operating temperature range of -10°C to +90°C [14°F to 194°F]
- Uses VIGO Grease RE #0



MSS Series Planetary Gearbox

tSRV-92

MSS Series Planetary Gearbox Specfications											
Model	96200004	96200005	96200103	96200007	96200008	96200257	96200373	96200378	96200393	96200459	
Manufacturer Part Number	MSS0601A- 005KS- B3110103C14	MSS0601A- 010KS- B3110103C14	MSS0902B- 020KS- B3110103C14	MSS0901A- 005KS- C3110103C19	MSS0901A- 010KS- C3110103C19	MSS1152B- 020KS- C3110103C19	MSS0901A- 005KS- C4120103C19	MSS0901A- 010KS- C4120103C19	MSS1152B- 020KS- C4120103C19	MSS1151A- 005KS- D3110103C22	
Compatible Motors	APMC-FBL series 100, 200, 300, and 400 W motors			APMC FCL	PMC FCL series 750W and 1kW motors			APM-FE series 900W and 1.5 kW motors			
Price	\$058zy:	\$058zz:	\$;058z]:	\$;058z[:	\$058z_:	\$058zx:	\$-05i42:	\$-05i43:	\$-05i44:	\$-05i45:	
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
Ratio	5:1	10:1	20:1	5:1	10:1	20:1	5:1	10:1	20:1	5:1	
Nominal Output Torque	54 N·m	42 N·m	143 N·m	160 N·m	121 N·m	295 N·m	160 N·m	121 N·m	295 N·m	332 N·m	
Inertia	0.13 kg/cm ²	0.13 kg/cm ²	0.13 kg/cm ²	0.48 kg/cm ²	0.44 kg/cm ²	0.48 kg/cm ²	0.48 kg/cm ²	0.44 kg/cm ²	0.48 kg/cm ²	2.81 kg/cm ²	
Output Shaft Diameter	16mm	16mm	22mm	22mm	22mm	32mm	22mm	22mm	32mm	32mm	
Stage	1	1	2	1	1	2	1	1	2	1	
Frame	60mm	60mm	90mm	90mm	90mm	115mm	90mm	90mm	115mm	115mm	
Nominal Input Speed (rpm)	5,000	5,000	4,000	4,000	4,000	4,000	4,000	4,000	4,000	4,000	
Max Input Speed (rpm)	10,000	10,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	8,000	
Emergency Stop Torque					3 times nomina	al output torque					
Noise (dB)	≤54	≤54	≤56	≤56	≤56	≤59	≤56	≤56	≤59	≤59	
Efficiency (%)	≥97	≥97	≥94	≥97	≥97	≥94	≥97	≥97	≥94	≥97	
Backlash (Arcmin)	≤7	≤7	≤9	≤7	≤7	≤9	≤7	≤7	≤9	≤7	
Max Radial Load (N)	1,280	1,280	3,200	3,200	3,200	6,800	3,200	3,200	6,800	6,800	
Max Axial Load (N)	690	690	1,600	1,600	1,600	3,400	1,600	1,600	3,400	3,400	
Service Life (Hours)	20,000 (10,000 under continuous operation)										
	Continued on next page										



LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

MSS Series Planetary Gearbox Specfications											
Model	96200464	96200479	96200010	96200011	96200445	96200013	96200014	96200701	96200016	96200017	96200862
Manufacturer Part Number	MSS1151A- 010KS- D3110103C22	MSS1422B- 020KS- D3110103C22	MSS1151A- 005KS- D3110103C24	MSS1151A- 010KS- D3110103C24	MSS1422B- 020KS- D3110103C24	MSS1421A- 005KS- E3110103C35	MSS1421A- 010KS- E3110103C35	MSS1802B- 020KS- E3110103C35	MSS1801A- 005KS- F3110103C42	MSS1801A- 010KS- F3110103C42	MSS1802A- 015KS- F3110103C42
Compatible Motors	APM-FE series 1.6 kW motors		APM-FI	E series 2.2 kW	motors	motors APM-FF series 3.5 kW and 5.5 kW motors			APM-FF series 7.5 kW motors		
Price	\$-05i46:	\$;-005i47:	\$-05i48:	\$-05i49:	\$;-005i4a:	\$-05i4b:	\$-05i4c:	\$;-005i4d:	\$;-005i4e:	\$;;-005i4f:	\$;-005i4g:
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
Ratio	10:1	20:1	5:1	10:1	20:1	5:1	10:1	20:1	5:1	10:1	15:1
Nominal Output Torque	262 N·m	295 N·m	332 N·m	262 N·m	295 N·m	634 N·m	500 N·m	1060 N·m	1195 N·m	960 N·m	897 N·m
Inertia	2.59 kg/cm ²	2.81 kg/cm ²	2.81 kg/cm ²	2.59 kg/cm ²	2.81 kg/cm ²	7.52 kg/cm ²	7.05 kg/cm ²	7.52 kg/cm ²	24.29 kg/cm ²	23.51 kg/cm ²	24.29 kg/cm ²
Output Shaft Diameter	32mm	40mm	32mm	32mm	40mm	40mm	40mm	55mm	55mm	55mm	55mm
Stage	1	2	1	1	2	1	1	2	1	1	2
Frame	115mm	142mm	115mm	115mm	142mm	142mm	142mm	180mm	180mm	180mm	180mm
Nominal Input Speed (rpm)	4,000	3,000	4,000	4,000	3,000	3,000	3,000	3,000	3,000	3,000	3,000
Max Input Speed (rpm)	8,000	6,000	8,000	8,000	6,000	6,000	6,000	6,000	6,000	6,000	6,000
Emergency Stop Torque					3 times	nominal output	t torque				
Noise (dB)	≤59	≤62	≤59	≤59	≤62	≤62	≤62	≤64	≤64	≤64	≤64
Efficiency (%)	≥97	≥94	≥97	≥97	≥94	≥97	≥97	≥94	≥97	≥97	≥94
Backlash (Arcmin)	≤7	≤9	≤7	≤7	≤9	≤7	≤7	≤9	≤7	≤7	≤9
Max Radial Load (N)	6,800	9,300	6,800	6,800	9,300	9,300	9,300	15,100	15,100	15,100	15,100
Max Axial Load (N)	3,400	4,500	3,400	3,400	4,500	4,500	4,500	7,500	7,500	7,500	7,500
Service Life (Hours)					20,000 (10,00	0 under continu	ious operation)				