

Note: STP-DRV-4845 and -6575 Drives are suitable for driving 2-phase and 4-phase stepping motors with 4, 6, or 8 leads.

### WARNING

To minimize the risk of potential safety problems, you should follow all applicable local and national codes that regulate the installation and operation of your equipment. These codes vary from area to area. It is your responsibility to determine which codes should be followed, and to verify that the equipment, installation, and operation are in compliance with the latest revision of these codes.

*Equipment damage or serious injury to personnel can result from the failure to follow all applicable codes and standards. We do not guarantee the products described in this publication are suitable for your particular application, nor do we assume any responsibility for your product design, installation, or operation.*

If you have any questions concerning the installation or operation of this equipment, or if you need additional information, please call our technical support at 770-844-4200.

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SureStep™ Microstepping Drive Specifications		
Part Number	STP-DRV-4845	STP-DRV-6575
Input Power	24–48 VDC (external power supply required; fuse at 4A fast-acting)	24–75 VDC (external power supply required; fuse at 7A fast-acting)
Output Current	1.1–4.5 A/phase (peak of sine)	0.5–7.5 A/phase (peak of sine)
Current Controller	Dual H-bridge digital MOSFET, 4-quadrant PWM at 20 kHz	
Input Signals	Step	5–24 VDC nominal (range: 4–30 VDC) (5mA @ 4V, 15mA @ 30V); optically isolated, differential. Maximum pulse frequency = 150 kHz or 2MHz (user selectable). Minimum pulse width: 3µsec at 150kHz setting jumper 4, 1µsec at 2MHz setting jumper 4. Function = Step or Step CW pulse.
	Direction	5–24 VDC nominal (range: 4–30 VDC) (5mA @ 4V, 15mA @ 30V); optically isolated, differential. Maximum pulse frequency = 150 kHz or 2MHz (user selectable). Minimum pulse width: 3µsec at 150kHz setting jumper 4, 1µsec at 2MHz setting jumper 4. Function = Direction or Step CCW pulse.
	Enable	5–24 VDC nominal (range: 4–30 VDC) (5mA @ 4V, 15mA @ 30V); optically isolated, differential. Maximum pulse frequency: 10kHz. Minimum pulse width: 500µsec. Function = disable motor when closed.
Output Signal	Fault	30VDC / 80mA max, optically isolated photodarlington, sinking or sourcing. Function = closes on drive fault.
Rotary Switch	Selectable Function	Select motor based on motor current for STP-DRV-4845. Select motor based on part number for STP-DRV-6575..
Internal Jumper Selectable Functions	Step Pulse Type	Step and Direction: Step signal = step/pulse; Direction signal = direction. Step CW & CCW: Step signal = CW step; Direction signal = CCW step.
	Step Pulse Noise Filter	Select 150kHz or 2MHz (switch to 2MHz if pulsing faster than 150kHz)
DIP Switch Selectable Functions	Current Reduction	Reduce power consumption and heat generation by limiting motor running current to 100%, 90%, or 80%, (70% possible for -4845 only, 120% possible for -6575 only) of maximum. Current should be increased to the maximum current reduction setting if microstepping. (Torque is reduced/increased by the same %.)
	Idle Current Reduction	Reduce power consumption and heat generation by limiting motor idle current to 90% or 50% of running current. (Holding torque is reduced by the same %.)
	Load Inertia	Anti-resonance and damping features improve motor performance. Set motor and load inertia range to 0–4x or 5–10x.
	Step Resolution	For smoother motion and more precise speed, set the pulse step resolution to 20000, 12800, 5000, 2000, 400 smooth, 400, 200 smooth, or 200 steps/rev.
	Self Test	Automatically rotate the motor back and forth two turns in each direction in order to confirm that the motor is operational.
Drive Cooling Method	Natural convection (mount drive to metal surface)	
Mounting	Use (2) #6 screws to mount wide or narrow side to metal surface	

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Motor & Power Supply:	Motor & Power Supply: screw terminal blocks Phoenix Contact 1757051	
Removable Connectors	Signals: screw terminal blocks Phoenix Contact 1803633 Replacement connectors are available in kit STP-CON-1	
Weight	10.8 oz [306g] – (including mating connectors)	
Operating Temperature	0–85 °C [32–185 °F] – (interior of electronics section)	
Ambient Temperature	0–50 °C [32–122 °F] – (drive must be mounted to suitable heat sink)	
Humidity	maximum 90% non-condensing	
Agency Approvals	CE & cURus	

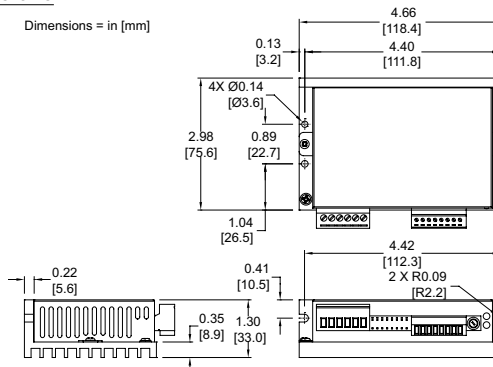
### MOUNTING THE DRIVE

The drive can be mounted on the wide or the narrow side of the chassis using (2) #6 screws. Fasten the drive securely to a smooth, flat, metal surface that will help conduct heat away from the chassis. Otherwise, forced air flow from a fan may be required to prevent overheating.

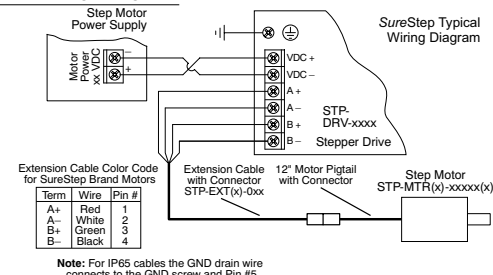
### WARNING:

- Never mount the drive in a space where there is no air flow, or where other devices can heat the surrounding air to 50°C [122°F].
- Never put the drive where it can get wet, or where metal or other electrically-conductive particles can get on the circuitry.
- Always provide air flow around the drive. Minimum allowable spacing between multiple drives is 0.5 in [13 mm].

### DIMENSIONS

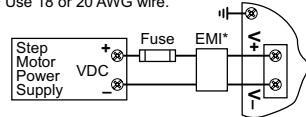


### TYPICAL WIRING DIAGRAM



### CONNECTING THE POWER SUPPLY

- Connect the green ground screw to earth ground
- Use 18 or 20 AWG wire.



\* CE use requires an EMI line filter.

STP-PWR-xxxx or PSBxx-xxxS power supplies from AutomationDirect are good choices to power the step-motor drive.

If the power supply you choose does not have a fuse on the output, you will need to install a fast-acting fuse on the “+” power supply lead.

**WARNING:** Do not to reverse the polarity from the power supply to the drive. Reverse connection will destroy your drive and void the warranty.

### CONNECTING THE MOTOR

**WARNING:** When connecting a step motor to the drive, be sure that the power supply is switched off. When using a motor not supplied by AutomationDirect, secure any unused motor leads so that they can't short out. Never disconnect the motor while the drive is powered up. Never connect the motor leads to ground or directly to the power supply. (See Typical Wiring Diagram on the front side of this data sheet for the step motor lead color code of AutomationDirect-supplied motors.

### CONNECTING THE INPUT SIGNALS

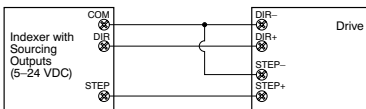
The STP-DRV-4845 and -6575 drive have three inputs:

- **STEP:** a high speed digital input for step pulse commands; 5–24 VDC logic
- **DIR:** a high speed digital input for the direction signal; 5–24 VDC logic
- **EN:** a 5-24V input for commanding the removal of power from the motor; also clears faults and re-enables the motor in the case of drive faults, e.g. over-current/short-circuit faults

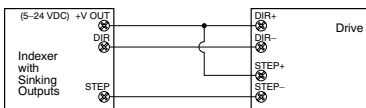
Note: STEP and DIR inputs can be converted to STEP CW and STEP CCW by moving the internal jumper S3 (see picture at top right of this page).

#### Connecting the Input Signals – Step & Direction

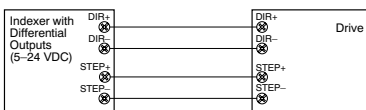
Connecting Drive to Indexer with Sourcing Outputs



Connecting Drive to Indexer with Sinking Outputs

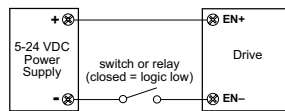


Connecting Drive to Indexer with Differential Outputs

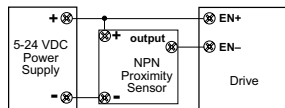


### CONNECTING THE INPUT SIGNALS – ENABLE

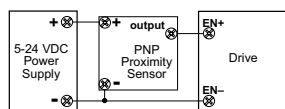
Connecting Drive EN to Switch or Relay



Connecting Drive EN to NPN



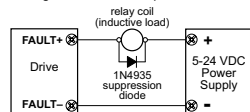
Connecting Drive EN to PNP



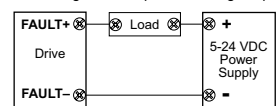
### CONNECTING THE FAULT OUTPUT SIGNAL

Do not connect more than 30VDC. Current must not exceed 80mA.

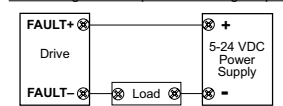
Connecting Drive's Fault Output to Inductive Relay



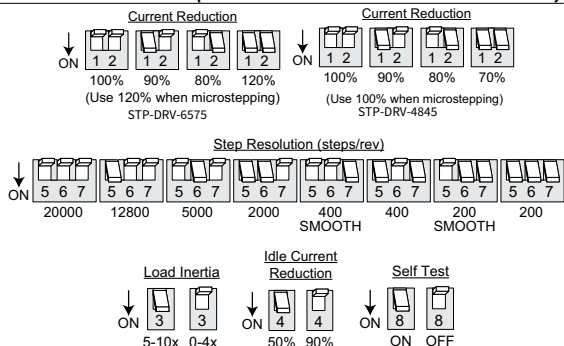
Connecting Fault Output as Sinking Output



Connecting Fault Output as Sourcing Output



### DIP SWITCH SETTINGS (FACTORY DEFAULT = ALL SWITCHES OFF)



### JUMPER SETTINGS

Jumpers S3 and S4 are located on the internal circuit board. They can be accessed by removing the drive's front cover.

#### Jumper S3 – Step Pulse Type

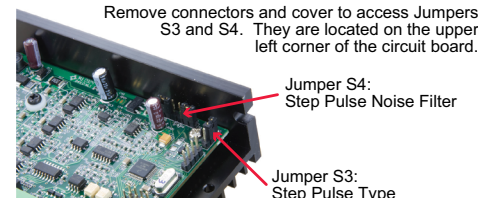
- Jumper in “1-2” position – Step & Direction (factory default)

- Jumper in “1-3” position – Step CW / Step CCW

#### Jumper S4 – Step Pulse Noise Filter

- Jumper in “1-2” position – 2MHz (factory default)

### • Jumper in “1-3” position – 150 kHz



### ROTARY SWITCH SETTINGS – MOTOR SELECTION

STP-DRV-4845 Motor Selection Table (A/Phase)(Peak of Sine A)				
Rotary Switch Position	SW1 & SW2 @100%	SW1 & SW2 @90%	SW1 & SW2 @80%	SW1 & SW2 @70%
0	1.1	1.0	0.9	0.8
1	1.3	1.2	1.0	0.9
2	1.5	1.4	1.2	1.1
3	1.7	1.5	1.4	1.2
4	2.0	1.8	1.6	1.4
5	2.2	2.0	1.8	1.5
6	2.4	2.2	1.9	1.7
7	2.6	2.3	2.1	1.8
8	2.8	2.5	2.2	2.0
9	3.1	2.8	2.5	2.2
A	3.4	3.1	2.7	2.4
B	3.6	3.2	2.9	2.5
C	3.8	3.4	3.0	2.7
D	4.0	3.6	3.2	2.8
E	4.3	3.9	3.4	3.0
F	4.5	4.1	3.6	3.2

STP-DRV-6575 Motor Selection Table										
Motor Data						Drive Configuration Data				
Motor STP-MTR -xxxx	Current (RMS A/phase)	Holding Torque (oz-in)	Rotor Inertia (oz-in <sup>2</sup> )	Inductance (mH)	Resistance (Ω)	Torque (mN-m)	Inertia (g-cm <sup>2</sup> )	Current (peak sine A)	Rotary Switch Position	
n/a									reserved	
n/a*	1.3								custom NEMA 17	
n/a*	4.0								custom NEMA 23	
n/a*	4.0								custom NEMA 34	
-17040	1.7	61	0.28	3.03	1.60	434	51	2.04	6	
-17048	2.0	83	0.37	2.65	1.40	586	82	2.40	7	
-17060	2.0	125	0.56	3.30	2.00	883	37	2.40	8	
-23055	2.8	166	1.46	2.36	0.08	1172	271	3.36	9	
-23079	2.8	276	2.60	3.82	1.10	1949	475	3.36	A	
-34066	2.8	434	7.66	7.70	1.11	3065	1402	3.36	B	
H-23079	5.6	287	2.60	1.18	0.40	2025	371	6.72	C	
H-34066	6.3	428	7.66	1.52	0.25	3021	1402	7.56	D	
H-34097	6.3	803	14.80	2.07	0.03	5668	2708	7.56	E	
H-34127	6.3	1292	21.90	4.14	0.49	9123	4008	7.56	F	

\* Rotary positions 3-5 are for non-SureStep motors. For third party motors of the indicated frame size with similar phase current these selections can be used.