Bipolar Step Motors:

STP-MTRL-14026(x), 14034(x) STP-MTR-17040(x), 17048(x), 17060(x), 23055(x), 23079(x), 34066(x)

STP-MTRH-23079(x), 34066(x), 34097(x), 34127(x)

Motor Extension Cables:

STP-EXT-0xx, STP-EXTH-0xx, STP-EXTL-0xx



Note: SureStep™ motors are all connectorized four lead bipolar step motors.

WARNING

To minimize the risk of potential safety problems, you should follow all applicable local and national codes that regulate the installation and operation of your equipment. These codes vary from area to area. It is your responsibility to determine which codes should be followed, and to verify that the equipment, installation, and operation are in compliance with the latest revision of these codes.

Equipment damage or serious injury to personnel can result from the failure to follow all applicable codes and standards. We do not guarantee the products described in this publication are suitable for your particular application, nor do we assume any responsibility for your product design, installation, or operation.

If you have any questions concerning the installation or operation of this equipment, or if you need additional information, please call our technical support group at 770-844-4200.

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SureStep™ Series Specifications – Connectorized Bipolar Stepping Motors													
Bipolar Stepping Motors		Low Torque Motors		High Torque Motors						Higher Torque Motors			
		STP- MTRL- 14026(x)	STP- MTRL- 14034(x)	STP- MTR- 17040(x)	STP- MTR- 17048(x)	STP- MTR- 17060(x)	STP- MTR- 23055(x)	STP- MTR- 23079(x)	STP- MTR- 34066(x)	STP- MTRH- 23079(x)	STP- MTRH- 34066(x)	STP- MTRH- 34097(x)	STP- MTRH- 34127(x)
NEMA Frame Size		14	14	17	17	17	23	23	34	23	34	34	34
	(lb·in)	0.5	1.25	3.81	5.19	7.19	10.37	17.25	27.12	17.87	27.12	50.00	80.50
* Maximum Holding Torque	(oz·in)	8	20	61	83	115	166	276	434	286	434	800	1288
Tiolaling Torque	(N·m)	0.06	0.14	0.43	0.59	0.81	1.17	1.95	3.06	2.02	3.06	5.65	9.10
B. ()	(oz·in²)	0.06	0.08	0.28	0.37	0.56	1.46	2.60	7.66	2.60	7.66	14.80	21.90
Rotor Inertia	(kg·cm ²)	0.0003	0.00035	0.05	0.07	0.10	0.27	0.48	1.40	0.48	1.40	2.71	4.01
Rated Current (A/phase)		0.35	0.8	1.7	2.0	2.0	2.8	2.8	2.8	5.6	6.3	6.3	6.3
Resistance (Ω/phase)		8.5	7.66	1.6	1.4	2.0	0.75	1.1	1.1	0.4	0.25	0.3	0.49
Inductance (mH/phase)		5.77	6.92	3.0	2.7	3.3	2.4	3.8	6.6	1.2	1.5	2.1	4.1
Insulation Class		130°C [266°F] Class B; 300V rms											
Basic Step Angle		1.8°											
Shaft Runout		0.002 in [0.051 mm]											
Max Shaft Radial Play @ 1-lb load	(in [mm])		0.001 in [0.025 mm]										
Perpendicularity		0.003 in [0.076 mm]											
Concentricity		0.003 in [0.051 mm]											
* Maximum Radial Load (lb [kg])			6.0 [2.7] 15.0 [6.8] 39.0 [17.7]							15.0 [6.8]	· · · ·		
* Maximum Thrust Load (lb [kg])		6.0 [2.7] 13.0 [5.9] 25.0 [11.3]							13.0 [5.9]	13.0 [5.9] 25.0 [11.3]			
Storage Temperature Range		-20°C to 100°C [-4°F to 212°F]											
Operating Temperature Range		-20°C to 50°C [-4°F to 122°F] (motor case temperature should be kept below 80°C [176°F])											
Operating Humidity Ra	nge	55% to 85% non-condensing											
Product Material		steel motor case; stainless steel shaft(s)											
Environmental Rating		IP40 (IP65 for "W" motors)											
Weight (lb [kg])		0.25 [0.11]	0.35 [0.15]	0.6 [0.3]	0.7 [0.3]	0.9 [0.4]	1.5 [0.7]	2.2 [1.0]	3.9 [1.7]	2.4 [1.1]	3.9 [1.7]	5.9 [2.7]	8.4 [3.8]
(E models)		(0.3 [0.1])	(0.4 [0.2])	(0.7 [0.3])	(0.8 [0.4])	(0.9 [0.4])	(1.5 [0.7])	(2.4 [1.1])	5.5 [1.7]	(2.4 [1.1])	5.5 [1.7]	0.0 [2.7]	U.+ [U.0]
Agency Approvals		CE											
Accessory Extension Cable		STD EV	STP-EXTL-0xx STP-EXTW-0xx (for W motors)							STP-EXTH-0xx			
		SIP-EX							STP-EXTHW-0xx (for W motors)				
* For dual-shaft motors (STP-MTR-xxxxxD): The sum of the front and rear Torque Loads, Radial Loads, and Thrust Loads must not exceed													

SureStep™ Motor / Drive Recommended Compatibility									
Motor ⁽¹	1)(2)				Recommen	ded Drive ⁽¹⁾			
Model # (1)(2)	Rated Amps	Extension Cable ⁽²⁾	STP-DRV-4035 ⁽¹⁾ (3.5A max output)	STP-DRV-4830 (3.0A max output)	STP-DRV-4845 (4.5A max output)	STP-DRV-4850(1) (5.0A max output)	STP-DRV-6575(1) (7.5A max output)	STP- DRV-80100 ⁽¹⁾ (10.0A max output)	
STP-MTRL-14026(x)	0.35	STP-	V	√	-	√			
STP-MTRL-14034(x)	0.8	EXTL-0xx	V	√	√	√	_	_	
STP-MTR-17040(x)	1.7	STP- EXTx- 0xx	V	√	√	√	√	√	
STP-MTR-17048(x)	2.0		√	√	√	√	√	√	
STP-MTR-17060(x)	2.0		√	√	√	√	√	√	
STP-MTR-23055(x)	2.8		√	√	√	√	√	√	
STP-MTR-23079(x)	2.8		√	√	√	√	√	√	
STP-MTR-34066(x)	2.8		V	√	√	√	√	√	
STP-MTRH-23079(x)	5.6	STP- EXTHx- 0xx					√	√	
STP-MTRH-34066(x)	6.3						√	√	
STP-MTRH-34097(x)	6.3			-	-		√	√	
STP-MTRH-34127(x)	6.3						√	√	

- 1) The combinations above will perform according to the published speed/torque curves. However, any STP motor can be used with any STP drive. Using a motor with a current rating higher than the drive's output rating will proportionally limit the motor torque.
- 2) MTR motors have connectors compatible with the EXT extension cables. MTRH motors have connectors compatible with the EXTH extension cables. MTRL motors have connectors compatible with the EXTL extension cables. W-series motors have connectors compatible with the EXTW and EXTHW extension cables.

Connecting the Motor

WARNING: When connecting a step motor to a drive or indexer, be sure that the motor power supply is switched off. Never disconnect the motor while the drive is powered up. Never connect the motor leads to ground or directly to the power supply. (See the Typical Wiring Diagram for the step motor lead color code of AUTOMATION DIRECT supplied motors.)

Mounting the Motor

We recommend mounting the motor to a metallic surface to help dissipate heat generated by the motor. The motor can be mounted in any orientation (horizontal or vertical).

Torque vs Speed Curves

The torque vs speed curves are published in the SureStep User Manual, which is available for free download from our website. Motor Extension Cable

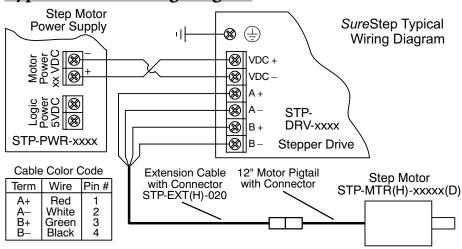
(www.automationdirect.com)

Design and Installation Tips

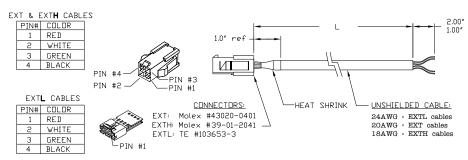
Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. DO NOT connect or disconnect the step motor during operation. Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissi-

pation. Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings from minor misalignment.

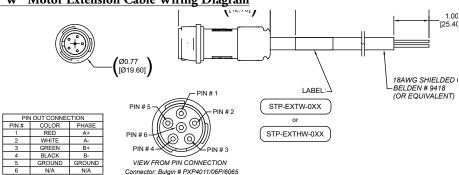
Typical Motor Wiring Diagram



Extension Cable Wiring Diagram



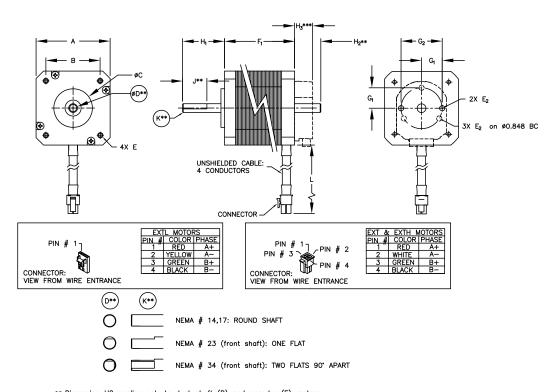




Dimensions & Cabling - Connectorized Step Motors

STP-MTRx-xxxxx Typical Dimension Diagram

Note: See table on page 5 for dimension values



** Dimension H2 applies only to dual—shaft (D) and encoder (E) motors.

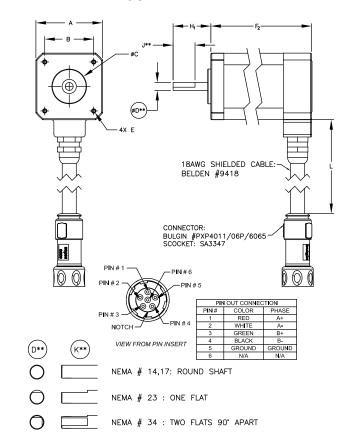
Dimension D is the same for both front and rear shafts of dual—shaft and encoder motors.

Dimensions J & K do NOT apply to rear shafts of dual—shaft and encoder motors (all rear shafts are round style).

 $See \ \underline{http://automation direct.com} \ for \ programmable \ AMT \ Series \ modular \ encoders \ from \ CUI \ Devices \ and \ fixed-resolution \ SureStep-MTRA-ENCxx \ encoders.$

STP-MTR-xxxxxW Typical Dimension Diagram

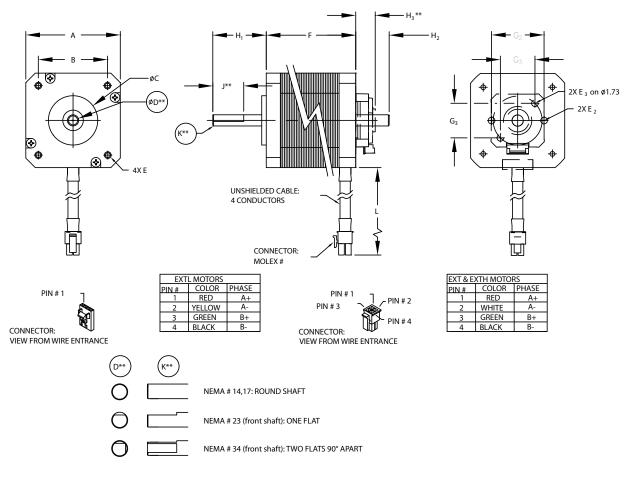
Note: See table on page 5 for dimension values



Dimensions & Cabling - Connectorized Step Motors

STP-MTRx-34xxx Typical Dimension Diagram

Note: See table on next page for dimension values



- ** Dimension H2 applies only to dual-shaft (D) and encoder (E) motors.
- * Dimension D is the same for both front and rear shafts of dual-shaft and encoder motors.
- ** Dimensions J & K do NOT apply to rear shafts of dual-shaft and encoder motors (all rear shafts are round style).

See http://automationdirect.com for programmable AMT Series modular encoders from CUI Devices and fixed-resolution SureStep-MTRA-ENCxx encoders.

Note: See diagrams on previous page

SureStep™ Series Dimensions & Cabling – Connectorized Bipolar Stepping Motors													
Dimensions (in [mm]*)	Low Torq	ue Motors	High Torque N				e Motors			Higher Torque Motors			
	STP-MTRL -14026(x)	STP-MTRL -14034(x)	STP-MTR -17040(x)			STP-MTR -23055(x)		STP-MTR -34066(x)	STP-MTRH -23079(x)	STP-MTRH -34066(x)	STP-MTRH -34097(x)	STP-MTRI -34127(x)	
Α	1.39 [35.3]	1.39 [35.3]		1.67 [42.3]		2.25	[57.2]	3.39 [86.1]	2.25 [57.2]	3.39 [86.1]			
В	1.02 [25.9]	1.02 [25.9]		1.22 [31.0]		1.86 [47.2]		2.74 [69.6]	1.86 [47.2]	2.74 [69.6]			
С				Ø 1.50 [38.1] Ø 2.88 [73.0]			Ø 1.50 [38.1]	Ø 2.88 [73.0]					
D**				Ø 0.25 [6.4] Ø 0.50 [12.7]			Ø 0.25 [6.4]	Ø 0.50 [12.7]					
E	4-40 t 0.15 [3.8]	hread min depth	M3 x 0.5 thread 0.15 [3.8] min depth			Ø 0.20 [5.1] through		Ø 0.26 [6.6] through	Ø 0.20 [5.1] through	Ø 0.26 [6.6] through			
E ²	M2.5 x 0.45 thread	M2.5 x 0.45 thread	M2.5 x 0.45 thread			4-	40	n/a	4-40	n/a			
E ³		n/a						M3 x 0.5 thread on a 1.73 in. bolt circle			M3 x 0.5 thread on a 1.73 in. bolt circle		
F ₁ **	1.02 [25.9]	1.34 [34.0]	1.58 [40.1]	1.89 [48.0]	2.34 [59.5]	2.22 [56.4]	3.10 [78.7]	2.64 [67.1]	3.10 [78.7]	2.64 [67.1]	3.82 [97.0]	5.00 [127.0]	
F ₂ **	n	/a	1.90 [48.3]	2.24 [56.9]	2.67 [67.8]	2.33 [59.1]	3.19 [81.0]	2.64 [67.1]	3.19 [81.0]	2.64 [67.1]	3.82 [97.0]	5.00 [127.0]	
G1	0.375	0.375	0.375	0.375	0.411	0.906	0.906	0.906	0.906	0.906	0.906	0.906	
G ²	0.75	0.75	0.75	0.75	n/a	1.812	1.812	1.812	1.812	1.812	1.812	1.812	
G ³		•	·	n/a		1.22 [31]			n/a	1.22 [31]			
H ₁	0.60 [15.2]	0.60 [15.2]		0.94 [24.0]		0.81 [20.6]		1.46 [37.1]	0.81 [20.6]	1.46 [37.1]			
H ₂ **	0.51 [13.0]	0.51 [13.0]		0.51 [13]		0.51 [13]		1.13 [28.7]	0.51 [13]	1.13 [28.7]			
H _{3**}				0.40		n/a		n/a	0.40	n/a			
J**			n/a			0.59 [15.0]		0.98 [25.0]	0.59 [15.0]	0.98 [25.0]			
K**			n/a			0.23 [5.8] 0.45 [11.4]		0.23 [5.8]	0.45 [11.4]				
L	12.0	12.0	12 [305]						12 [305]				
Conductor	(4) #26	(4) #26 AWG					O AWG (for W motors)			(4) #18 AWG (5) #18 AWG (for W motors)			
Connector	Tyco Elec.	# 104257-3		PXF		3025-0400 65 (for W mo	025-0400 5 (for W motors)			Molex # 39-01-3042 PXP4010/06S/6065 (for W motors)			
Pin	Tyco Elec. # 1-104480-5										;)		

^{*} mm dimensions are for reference purposes only.

^{**} Dimension D (shaft diameter) is the same for both front and rear shafts of dual-shaft and encoder motors. Dimension H2 applies only to dual-shaft (D) and encoder (E) motors. Dimensions J & K do NOT apply to rear shafts of dual-shaft or encoder motors (all rear shafts are round style). Dimension H3 applies only to "E" models with the encoder pre-mounted. Dimension F2 applies to "W" models only.