USER MANUAL TABLE OF CONTENTS



CONTENTS OF SURESERVO USER MANUAL

Varnings and $Trademarks$	N–1
~ WARNING ~	N–1
Trademarks	N–1
~ AVERTISSEMENT ~	N–2
Marques de commerce	N–2
Warnings	N–3
Jser Manual Revision History	H–1
Jser Manual Table of Contents	C–1
Chapter 1: Getting Starting	1–1
Manual Overview	
Overview of This Publication	1–2
Who Should Read This Manual	1–2
Supplemental Publications	1–2
Technical Support	1–2
Special Symbols	1–2
SureServo® AC Servo Systems Introduction	1–3
SureServo Basic Overview	1–3
Unpacking Your New SureServo	1–4
Nameplate Information	1–4
Model Explanation	
Identification and Labeling: SureServo® AC Servo Drive	1–5
Drive and Motor Combinations	1–5
SureServo® AC Servo Drive Control Modes	1–6
SureServo® AC Servo System Specifications	1–7
Drive Specifications	1-7
Motor Specifications	1–9
Motor Velocity-Torque Curves	1–10
Motor Overload Characteristics	1–11
Quick Start for SureServo® Drives	-12
Spin the Motor	-12
Position Mode Quick Start (Pt & Pr)	1–14
Velocity Mode Quick Start (V & Vz)	1–17
Torque Mode Quick Start (T & Tz)	-18
Tuning Quick Start for SureServo® Drives	-20

User Manual Table of Contents

Chapter 2: Installation and Wiring
Storage Conditions
Installation
Servo Drive Mounting
Servo Drive Minimum Clearances and Air Flow
Servo Motor Mounting
Dimensions
Servo Drive Dimensions
Servo Motor Dimensions
Accessory I/O Terminal Module Dimensions
Circuit Connection Warnings
Danger!
Wiring Notes: PLEASE READ PRIOR TO INSTALLATION
Servo Drive Terminals
Drive Power Terminals.
CN1 – Drive Input/Output Terminal
CN2 – Drive Encoder Terminal
CN3 – Drive Serial Communication Terminal
Servo Motor Terminal Connections
Motor Power Connections
Motor Encoder Connections
Wiring Diagrams
Connecting to Peripheral Devices
Power Wiring Connections
Wiring for Position (Pr & Pt) Control Modes
Wiring for Velocity and Torque Control Modes
CN1 Input/Output Wiring Diagrams
CN2 Encoder Wiring Diagram
CN3 Serial Communication Wiring Diagram
Cables and Terminal Connectors
Drive, Motor, and Cable Combinations
Drive Terminal Connection Module & Cables
Serial Cables for Connection to CN3
Servo Drive Circuit Protection

Chapter 3: Keypad and Display Operation
Digital Keypad
Display Flowchart
Display Messages
Parameter Setting Value Change Messages
Abort Parameter Setting Value Change Message
Fault Message Display
Polarity Display of Parameter Setting Values
Monitor Mode Function Display
Polarity Display of Monitor Values
Servo Drive General Operation
Display Fault History
JOG Function
Teach Position Function
DO Force Output Function
Display Digital Input Status
Display Digital Output Status
Chapter 4: Servo Drive Parameters
Parameter Overview and Note Symbols
Parameter Groups
Reset Parameter Defaults
Parameter Firmware Versions
Parameter Summary
Parameter Summary Listings
Detailed Parameter Listings
Sample Parameter Listing
Monitor Parameters
Basic Parameters
Extended Parameters
Communication Parameters
Diagnostic Parameters

Chapter 5: Control Modes of Operation and Tuning	1a
Control Modes of Operation.	.2
How to Change Control Modes	.2
Position Control Modes	. 3
Structure of Position Control Modes	. 3
Electronic Gear Ratio	.4
Position Command Low-pass Filter	.4
Position Loop Gain Adjustment	. 5
Command Source of Pt Position Control Mode	. 6
Command Source of Pr Position Control Mode	. 6
Timing Chart of Pr Position Control Mode	. 7
Teach Position Function for Pr Absolute Position Control.	. 8
S-curve Filter for Pr Position Control	. 8
Parameters for Absolute and Incremental Pr Control (P1-33 = 0,1)	. 9
Parameters for Index Mode Pr Control (P1-33 = 2,3,4)	
Parameters for Absolute and Incremental Auto Pr Control (P1-33 = 5,6)	
Velocity Control Mode	
Command Source of Velocity Control Mode	
Structure of Velocity Control Mode	
Smoothing Strategy of Velocity Control Mode.	
Analog Velocity Input Scaling	
Timing Chart of Velocity Control Mode.	
Velocity Loop Gain Adjustment	
Resonance Suppression	
Torque Control Mode.	
Command Source of Torque Control Mode	
Structure of Torque Control Mode.	
Smoothing Strategy of Torque Control Mode	
Timing Chart of Torque Control Mode	
Dual Control Modes Selection	
Position / Velocity Control Mode Selection.	
Position / Torque Control Mode Selection	
Velocity / Torque Control Mode Selection	
Velocity Limit	
Torque Limit	
Regenerative Resistor.	
Built-in Regenerative Resistor	
External Regenerative Resistor.	
Electromagnetic Brake	
Timing charts of control circuit power and main circuit power:	
Tuning Modes Overview	
Purpose of Tuning; Why and When it is Necessary	
SureServo™ Tuning Modes Available	
Tuning Modes and Their Relevant Parameters	
Monitoring System Performance	
Tuning Modes Details	
Auto-Tuning Modes	
Using Auto-Tune PDFF Mode	
•	
Using Easy-Tune Mode	
Using Manual Tuning Mode	
Manual Tuning Mode Details	21

Chapter 6: Modbus Communications
SureServo ^{m} Communication Parameters
SureServo™ Parameter Memory Addresses
Connecting to DirectLogic PLCs
Step 1: Modbus RTU Master PLCs
Step 2: Make the Connections
Step 3: Confirm/Set Servo Communication Parameters
Step 4: Configure the DirectLOGIC CPU Port 2
SureServo™ / DirectLOGIC PLC Control Example
DirectLOGIC Ladder Logic Programming Example
Communicating with Third-party Devices
Common Modbus RTU Masters
Modbus Protocol Modes
Modbus ASCII and RTU Data Format
Communication Protocol
Chapter 7: Maintenance and Troubleshooting
-7 Maintenance and Inspection
Basic Inspection
Maintenance
Expected Life of Replacement Components
DC BUS Filter Capacitor.
Precharge Relay
Cooling fan (SVA-2100 and SVA-2300 Models Only)
Troubleshooting
Fault & Warning Message Table
Fault Message Potential Causes and Corrective Actions
Warning Message Potential Causes and Corrective Actions
Clearing Faults

Appendix A: Selecting the SureServo System	4–1
Selecting the SureServo® Servo System	A–2
The Selection Procedure	A–2
How many pulses from the PLC to make the move?	A–2
What is the positioning resolution of the load?	A–3
What is the indexing speed to accomplish the move time?	A–3
Calculating the Required Torque	A–4
Leadscrew – Example Calculations	A–8
Step 1 – Define the Actuator and Motion Requirements.	A–8
Step 2 – Determine the Positioning Resolution of the Load	A–8
Step 3 – Determine the Motion Profile	A–9
Step 4 – Determine the Required Motor Torque	A–9
Step 5 – Select and Confirm the Servo Motor and Driver System	-10
Belt Drive – Example Calculations	-11
Step 1 – Define the Actuator and Motion Requirements	-11
Step 2 – Determine the Positioning Resolution of the Load	-11
Step 3 – Determine the Motion Profile	-12
Step 4 – Determine the Required Motor Torque	-12
Step 5 – Select and Confirm the Servo Motor and Driver System	-13
Index Table – Example Calculations	-14
Step 1 – Define the Actuator and Motion Requirements.	-14
Step 2 – Determine the Positioning Resolution of the Load	-14
Step 3 – Determine the Motion Profile	-14
Step 4 – Determine the Required Motor Torque	-15
Step 5 – Select and Confirm the Servo Motor and Driver System	-15
Engineering Unit Conversion Tables, Formulas, & Definitions	-16
Appendix B: Using SureServo® with DirectLOGIC PLCs	B–1
Compatible DirectLOGIC PLCs and Modules	
Typical Connections to a DL05 PLC	
Typical Connections to an H0-CTRIO	
Typical Connections to a DL06 PLC	
Typical DL06 Connections – Multiple Drives/Motors Through Communication	
Connecting SureServo® to ADC Line Driver Encoders.	
Connecting SureServo® to ADC Open-Collector Encoders	
Appendix C: Latest SureServo® Firmware Revisions	C–1
SureServo® Firmware Identification.	
Overview of Changes in New Firmware Versions.	
Firmware Version 2.105.	
Firmware Version 2.10.	
Drive Operation Changes in Firmware Version 2.10	
Summary of Firmware v2.10 Parameter Changes.	
Detailed Parameter Listings	
	- '