# MAINTENANCE AND TROUBLESHOOTING

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### Hardware Maintenance

#### Standard Maintenance

The Productivity® 1000 is a low maintenance system requiring only a few periodic checks to help reduce the risks of problems. Routine maintenance checks should be made regarding two key items.

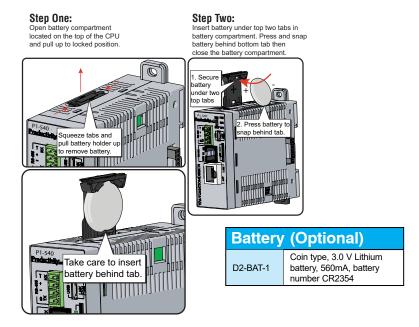
- Air quality (cabinet temperature, airflow, etc.)
- CPU battery

#### Air Quality Maintenance

The quality of the air your system is exposed to can affect system performance. If you have placed your system in an enclosure, verify that the ambient temperature is not exceeding the equipment operating specifications. If there are filters in the enclosure, clean or replace them as necessary to ensure adequate airflow. A good rule of thumb is to check your system environment every one to two months. Make sure the Productivity1000 is operating within the system operating specifications.

#### **CPU Battery Replacement**

A battery may be included with the CPU, but is not installed. The battery can be installed to retain the Time and Date along with any Tagname values that are set up as retentive.



The battery is not needed for program backup.

# **Diagnostics**

### Diagnostics

Your Productivity <sup>®</sup> 1000 system performs many pre-defined diagnostic routines with every CPU scan. The diagnostics have been designed to detect various types of failures for the CPU and I/O modules. There are two primary error classes, critical and non-critical.

#### **Critical Errors**

Critical errors are errors the CPU has detected that offer a risk of the system not functioning safely or properly. If the CPU is in Run Mode when a critical error occurs, the CPU will switch to Stop Mode (Remember, in Stop Mode all outputs are turned off). If a critical error is detected while the CPU is in Stop Mode, the CPU will not enter Run Mode until the error has been corrected. Here are some examples of critical errors:

- Power supply failure
- Parity error or CPU malfunction
- I/O configuration errors
- Certain programming errors.

### **Non-Critical Errors**

Non-critical errors are flagged by the CPU as requiring attention. They can neither cause the CPU to change from Run Mode to Stop Mode, nor do they prevent the CPU from entering Run Mode. There are system tags the application program can use to detect if a non-critical error has occurred. The application program can be used to take the system to an orderly shutdown or to switch the CPU to Stop Mode if necessary.

- Some examples of non-fatal errors are:
- Backup battery voltage low
- All I/O module errors
- · Certain programming errors.

### **Finding Diagnostic Information**

The CPU automatically logs critical and non-critical error codes. Logged errors can be found in the following places marked with a time and date stamp:

• Under the Monitor Debug tool of Productivity Suite in the CPU Error History window. The 20 most recent critical and non-critical errors are listed.

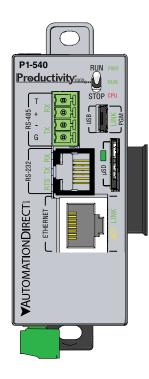
### **Error Codes**

See Appendix B "Productivity1000 Error Codes" for a complete list of error messages sorted by error types.

# **CPU Functions Indicators**

The Productivity1000 CPUs have indicators on the faceplate to help diagnose problems with the system. The table below gives a quick reference of potential problems associated with each status indicator. The pages following the table contain a detailed analysis of each of these indicator problems.

| <b>Indicator Status</b> | Potential Problems   |  |  |  |  |
|-------------------------|--|--|--|--|--|
|                         | 1. System voltage is incorrect.  |  |  |  |  |
| PWR (off)               | 2. Power supply/CPU is faulty.   |  |  |  |  |
| ()                      | <ol> <li>Other components such as an I/O module has power supply<br/>shorted.</li> </ol> |  |  |  |  |
| DUN (will not come on)  | 1. CPU programming error   |  |  |  |  |
| RUN (will not come on)  | 2. Switch in STOP position   |  |  |  |  |
| CPU (blink)             | CPU internal error   |  |  |  |  |





| CPU | Status Indicators   |
|-----|---|
| PWR | Green LED is illuminated when power is on   |
| RUN | Green LED is illuminated when CPU is in RUN mode                                    |
| CPU | Red LED is illuminated during power on<br>reset, power down, or watch-dog time-out. |

# **PWR Indicator**

There are three general reasons for the CPU power status LED (PWR) to be OFF:

- 1. Power to the module is incorrect or is not applied.
- 2. Module power supply is faulty.
- 3. Other component(s) have the power supply shut down.

### Faulty or Incorrect Power Supply

If the voltage to/from the power supply is not correct, the CPU may not operate properly or may not operate at all. Use the following guidelines to correct the problem.



WARNING: To minimize the risk of electrical shock, always disconnect the system power before inspecting the physical wiring.

- 1. First, disconnect the system power and check all incoming wiring for loose connections.
- 2. If you are using a separate termination panel, check those connections to make sure the wiring is connected to the proper location.
- 3. If the connections are acceptable, reconnect the system power and measure the voltage at the base terminal strip to ensure it is within specification. If the voltage is not correct, shut down the system and correct the problem.
- 4. If all wiring is connected correctly and the incoming power is within the specifications required, the power supply should be replaced.

### Faulty CPU

There is no simple test for a faulty CPU other than substituting a known good one to see if this corrects the problem. If you have experienced major power surges, it is possible the CPU and power supply have been damaged. If you suspect this is the cause, a line conditioner should be installed on the incoming line. This will keep damaging voltage spikes from reaching the CPU.

## **PWR Indicator, continued**

#### Device or Module Causes the Power Supply to Shutdown

Module:

If the PWR LED is operating normally but the power supply shuts down, check each module for a possible connector problem as follows:

- 1. Turn off power to the system.
- 2. Remove a module from the system.
- 3. Reapply power to the system.
- 4. Check for power supply normal operation.
- 5. Repeat procedure until defective module is found and replaced.

#### Device:

A 5V charge may be originating from the CPU communications port.

Test as follows:

- 1. Turn off power to the CPU.
- 2. Disconnect all external devices (i.e., communication cables) from the CPU.
- 3. Reapply power.
- 4. If power supply operates normally then check for a shorted device or shorted cable.

# **Run Indicator**

If the CPU will not enter the Run mode (the RUN indicator is off), the problem is usually in the application program, unless the CPU has a critical error. If a critical error has occurred, the CPU LED should be on. You can use a programming device to determine the cause of the error.

A complete list of error codes can be found in Appendix B.

# **CPU Indicator**

If the CPU indicator is on, a critical error has occurred in the CPU. Generally, this is not a programming problem but an actual hardware error. The CPU indicator should blink briefly and then do an automatic reboot.

If the error clears, you should monitor the system and determine what caused the problem. You will find this problem is sometimes caused by high frequency electrical noise introduced into the CPU from an outside source. Check your system grounding and install electrical noise filters if the grounding is suspected. If power cycling the system does not reset the error, or if the problem returns, you should replace the CPU.

# **Communications Problems**

If a communication error occurs, the indicator will come on and stay on until a successful communication has been completed. If you cannot establish communications with the CPU, check these items:

- The cable is disconnected.
- The cable has a broken wire or has been wired incorrectly.
- The cable is improperly terminated or grounded.
- The device connected is not operating at the correct baud rate.
- The device connected to the port is sending data incorrectly.
- A grounding difference exists between the two devices.
- Electrical noise is causing intermittent errors.
- The CPU has a bad communication port; the CPU should be replaced.

# I/O Module Troubleshooting

### Things to Check

If you suspect an I/O error, there are several things that could be causing the problem.

- A blown fuse
- A loose terminal block
- The 24VDC supply has failed
- The module has failed
- The I/O configuration check detects a change in the I/O configuration

### Error Codes

See Appendix B for Productivity®1000 error code information.

Also, in the Productivity Suite programming software, you can go to:

Tools > CPU Error History, and

Tools > CPU Event History

Next, click on "CPU Error" or "Event History" tab to get an updated list of critical errors, non-critical errors and event history that should indicate problems or changes to the I/O. This list will give the "GS" (group, slot numbers).

### Some Quick Steps

When troubleshooting the Productivity1000 I/O modules there are a few facts you should be aware of which may assist you in quickly correcting an I/O problem:

- The output modules cannot detect shorted or open output points. If you suspect one or more points on a output module to be faulty, you should measure the voltage drop from the common to the suspect point. Remember, when using a Digital Volt Meter, leakage current from an output device, such as a triac or a transistor, must be considered. A point which is off may appear to be ON if no load is connected to the point.
- The I/O point status indicators on the modules are logic side indicators. This means the LED which indicates the ON or OFF status reflects the status of the point in respect to the CPU. For an output module, the status indicators could be operating normally, while the actual output device (transistor, triac etc.) could be damaged. With an input module, if the indicator LED is ON, the input circuitry should be operating properly. To verify proper functionality, check to see that the LED goes off when the input signal is removed.
- Leakage current can be a problem when connecting field devices to I/O modules. False input signals can be generated when the leakage current of an output device is great enough to turn on the connected input device. To correct this, install a resistor in parallel with the input or output of the circuit. The value of this resistor will depend on the amount of leakage current and the voltage applied but usually a 10K to 20K resistor will work. Ensure the wattage rating of the resistor is correct for your application.
- The easiest method to determine if a module has failed is to replace it if you have a spare. However, if you suspect another device to have caused the failure in the module, that device may cause the same failure in the replacement module as well. As a point of caution, you may want to check devices or power supplies connected to the failed module before replacing it with a spare module.

#### **Testing Output Points**

Output points can be set ON or OFF using the force function to override a point even while the program is running. However, this is not a recommended method to test the output points. If you want to do an I/O check independent of the application program, follow the procedure in the table below:

| Step | Action  |
|------|---|
| 1.   | Use Productivity Suite programming software to communicate online to the CPU.   |
| 2.   | Change to Program Mode.   |
| 3.   | Go to the first rung of the ladder.   |
| 4.   | Insert a rung with an "END" statement. (This will cause program execution to occur only at<br>address 0 and prevent the application program from turning the I/O points on or off). |
| 5.   | Change to Run Mode.   |
| 6.   | Use the programming device to set (turn) on or off the points you wish to test.   |
| 7.   | When you finish testing I/O points delete the "END" statement at the first rung.  |



WARNING: Depending on your application, forcing I/O points may cause unpredictable machine operation that can result in a risk of personal injury or equipment damage. Make sure you have taken all appropriate safety precautions prior to testing any I/O points.



# Noise Troubleshooting

#### **Electrical Noise Problems**

Noise is one of the most difficult problems to diagnose. Electrical noise, whether conducted or radiated, can enter a system in many different ways. It may be difficult to determine how the noise is entering the system but the corrective actions for either type of noise problem are similar.

- Conducted noise is when the electrical interference is introduced into the system by way of an attached wire, panel connection, etc. It may enter through an I/O module, a power supply connection, the communication ground connection, or the chassis ground connection.
- Radiated noise is when the electrical interference is introduced into the system without a direct electrical connection, much in the same manner as radio waves.

### **Reducing Electrical Noise**

While electrical noise cannot be eliminated completely, it can be reduced such that it will not adversely affect system function. Proper grounding of components and signal wiring along with proper isolation of voltages can minimize noise in the system.

- 1. Grounding:
  - Most noise problems result from improper grounding of the system. A good earth ground can be the single most effective way to correct noise problems. If a ground is not available, install a ground rod as close to the system as possible.
  - Ensure all ground wires are single point grounds and are not daisy chained from one device to another. Ground metal enclosures around the system. A loose wire is no more than a large antenna waiting to introduce noise into the system; therefore, you should tighten all connections in your system. Loose ground wires are more susceptible to noise than the other wires in your system. Review Chapter 5, "Installation and Wiring", if you have questions regarding how to ground your system.
- 2. Isolation:
  - Electrical noise can enter the system through the power source for the CPU and I/O. Installing an isolation transformer for all AC sources can correct this problem.
  - DC power sources should be well grounded, good quality power supplies. Switching DC power supplies commonly generate more noise than linear supplies.
  - Separate input wiring from output wiring.
  - Never run I/O wiring close to high voltage wiring.

## **Run Time vs. Stop Mode Transfer Instruction**

Here we describe the actions and differences between Run Time & Stop Mode transfers as shown in this dialog box.



The above dialog is accessed two ways: (only when CPU is online AND in run mode) Perform either of the following to transfer project to the CPU:

- 1. Click on the "To CPU" icon on the Tool Bar, or 🙀 Couple Project 🗇 To CPU...
- 2. Click through from the File menu > Transfer Project > To CPU.

| lite |  |        |   |                      |            |              |
|------|--|--------|---|----------------------|------------|--------------|
| 00   | New Project<br>Open Project<br>Close Project |        |   |                      |            |              |
| •    | Save Project<br>Save Project As              | Ctrl+S |   |                      |            |              |
| 8.8  | Import<br>Export                             | :      |   |                      |            |              |
| 8    | Compile Project                              | F8     | - |                      |            |              |
| -    | Transfer Project                             |        | 0 | To CPU               | Shift+F9   |              |
| 101  | Page Setup                                   |        | - | From CPU             | Ctrl+F9    |              |
| 3    | Print  | Ctrl+P | * | To Removable Media   | Transfer P | oject to CPU |
|      | Project Properties                           |        | 2 | From Removable Media | 2 1        |              |

### **Run Time Transfers**

Run Time Transfer allows the user to transfer edits to a project in the CPU without stopping the CPU scan, therefore not stopping the process. Be aware that a Run Time Transfer will affect the length of your scan time, which should be considered if your process is susceptible to varying or lengthy scan times. The download time is longer compared to a Stop Mode transfer.

During a Run Time transfer, the current project file continues running until the entire project file is transferred to the CPU. Once downloaded, the ladder logic files swap and begin executing the new file. The Tag Database is shared between the two project files during a Run Time transfer, therefore current operating values will not be effected.

Because the Tag database is shared, any edits to the Tag database will force a Stop Mode transfer.



### Stop Mode Transfers

Stop Mode Transfers allows the user to transfer any and all ladder, Tag Database and configuration changes to the CPU.

Because the CPU is in stop mode, the project transfer is much faster than a Run Time Transfer and also loads all initial values to the tags once the project is switched from Stop to Run.

Following are conditions that will force the user to perform a Stop Mode Transfer:

- 1. Any changes to the hardware configuration, such as:
  - A. Adding or removing hardware.
  - B. Changing the configuration of a piece of hardware.
    - Ethernet or serial port configuration.
  - C. Adding an EhterNet/IP device and any configured changes
- 2. Adding > 5000 tags of any type (Excluding Strings and Structures).

NOTE: This limit is accumulated between each stop mode transfer.



3. Adding >50,000 characters or changing the length of a String data type Tag.



**NOTE:** This limit is accumulated between each stop mode transfer.

- 4. Changes to Data Logger.
- 5. Changes to Modbus Server settings under Project Properties.

- 6. Changes to the buffer size for a FILI instruction.
- 7. Adding > 5,000 elements of a Structures data type to Tag Database.

NOTE: This limit is accumulated between each stop mode transfer.

- 8. Enabling Bit of Word under Project Properties.
- 9. Enabling Structures in Project Properties.
- 10. Enable and Disable of EhterNet/IP Adapter.

As the CPU goes from Stop to Run after a Stop Mode Transfer, tags are initialized as if the project is being executed for the first time. This includes Retentive Tags. If it's desirable that the values of Retentive Tags be retained through a Stop Mode Transfer, there are two methods available. Both options may be enabled and they can be found under Tools > Options > Project Transfer

- 1. Upload current retentive values and copy to initial values. This option works during program upload. When selected, place the CPU in Stop Mode so Retentive Tag values are stable, then upload the project. Productivity Suite will copy the current value of all Retentive Tags to their Initial Values in the Tag Database of the project. Perform your edits and transfer the project back to the CPU. When the CPU goes back to run, your Retentive Tags will be initialized with their old values. This is a simple process and is convenient for quick edits to the program, but the CPU must remain in Stop Mode while the project is edited to ensure that no retentive values have changed during editing.
- 2. Copy current retentive tag values to initial values. This option works during program download. This process is more involved, but the CPU will use the values from the project currently running as the initial values of the project being transferred. For more information refer to the Options topic in the help file.

|     | al Project Save Project Transfer Ladder   Data Vew   Connection   Tag DB       |
|-----|--|
| ene | al   Project Save   Project (Tarber   Ladder   Cata Vesi   Connection   Tag DB |
| Tre | nafer Project from CPU Options   |
| 18  | Upbad current retentive values and copy to initial values                      |
| Tre | nafer Project to CPU Options   |
| 5   | ) Transfer documentation (instruction and ladder rung comments)                |
| 5   | Transfer GS drive configuration  |
| 10  | Copy current retentive lag values to initial values                            |



| 1 | <del>333</del> | <u> </u> | 31 |
|---|----------------|----------|----|
| / |                |          | Ξ  |
| / |                | _        | Ξ  |
| - | -              |          | _  |

### Forcing I/O Points

Following is a description of the actions, expectations and indications of forcing a value in the Productivity ® 1000 controller.

#### Advantages of Forces

Almost all tags can be written to in the software without Forcing. However, if the ladder logic or an external device (operator interface panel, Modbus device, etc.) is connected to your controller and writing to those tags, the values you write from a Data View will be over-written. Conversely, if you write a Forced value, this will not be overwritten or reset until you manually remove the force or reset by means of a Stop to Run mode transition, a Stop Mode Transfer, or a controller power cycle.

#### **Enabling Forces**

The Productivity1000 CPU is a Tag based controller where forcing a tag begins by identifying any tag you wish to be "Force-able" within the Tag database.

| Orac Al<br>Joint   | Edución Davis (2)<br>Edución Davis (2)<br>Edución Costan (2)<br>Vitable Sector (2)  | Mercen   |        |               |                 | 97 sartar lastr<br>98 sartar lastr      | R unie tado<br>R unie tado  |   |
|--|---|----------|--------|---------------|-----------------|---|---|---|
| die :  |   |          |        | 0             | 2               | 3                                       |   |   |
| M97-5.1.15<br>M97-5.5.10<br>M97-5.5.10<br>M97-5.5.10<br>M97-5.5.10<br>M97-5.5.10   | Tige<br>Marke Sonia Si<br>Marke Sonia Si<br>Marke Sonia Si<br>Marke Sonia Si<br>Marke Sonia Si  | Holitari | No.114 | Front LOID DO | HTest<br>DDDDDD |   | Camerol Barrot, Defbul F<br>Rec131, 0<br>Not12F, 0<br>Not12F, 0<br>Not12F, 0<br>Not14F, 0 | 1 000000                                |
| 100 121<br>100 121<br>100 123<br>100 123<br>100 123<br>100 128<br>100 | Heads Stock and<br>Description Type I<br>Description Type |          |        |               |                 | 000000000000000000000000000000000000000 |   | 000000000000000000000000000000000000000 |

There are three columns within the Tag database that affect the forcing of all tags.

- 1. "Forceable" Checking the box in this column identifies the corresponding tag as being able to be forced within the system.
- "Init Forced" Checking the box in this column identifies that corresponding tag as being forced as soon as the project is loaded and the processor is switched to Run mode.
- 3. "Init Force Value" The state of the box in this column identifies the initial forced state of the Boolean tag:
- A check mark in a box equates to a logical "1" or "ON", and
- An unchecked box equates to a logical "0" or "OFF". The value placed in this field for Integer or Floating point tags will be written into the tag.

#### Forcing Tags in Your System

All forcing of tags can be accomplished through the Data View window or directly in the program interface while in "Monitor" mode, as long as the "Forceable" box has been checked in Tag Database. I/O may also be directly forced in I/O View by clicking on individual I/O points.

| Date View 1  |                |       |       |       |  |           |             |
|--|----------------|-------|-------|-------|--|-----------|-------------|
| gnane  | Hodbue Address | Take  | Ede   | Force | Tag Cista Type   | Vev la :: | Comment     |
| D040131<br>D040133<br>D04133<br>OPURKUN<br>Cerveyor Run<br>Reset |                | 00×00 | 00000 | 00000 | Discrete Output<br>Discrete Output<br>Discrete Output<br>Bodiear, System, Kr.,<br>Bodiear<br>Bodiear |           | ün dung kun |

From the DataView Window, enter the tags you wish to force, or you can view all forceable tags from the "Forceable Tags" tab automatically created for you when you enable tags as forceable in the tag database.

| Forceable Tags | Data Vew 1     |      |      |       |                      |         |  |
|----------------|----------------|------|------|-------|----------------------|---------|--|
| Tagname        | Nodius Address | Take | Edit | Force | Tag Data Type        | View As |  |
| NGT-0.1.1.81   |                | 10   | 1000 | 100   | Module Status Bit    |         |  |
| MST-0.1.1.82   |                | 19   | 15   | 10    | Module Status Bit    |         |  |
| MST-0.1.1.8J   |                | 12   | 100  | 10    | Module Status Bit    |         |  |
| 00-0.1.2.1     |                | 10   | 100  | 100   | Discrete Typel       |         |  |
| 01-0-1-2-2     |                | 10   | 10   | 10    | Decrete Input        |         |  |
| DI-0.1.2.3     |                | 10   | 23   | 10    | Durrete Input        |         |  |
| 01-0.1.2.4     |                | 10   | 10   | 10    | Discrete Input       |         |  |
| Was_000.13.1   |                | 1    | 1.12 | - 23  | Discrete Output      |         |  |
| Web_000.13.2   |                | 10   | 1.23 | 13    | Discrete Output      |         |  |
| Was_DO-0.13.3  |                | 13   | 10   | 12    | Discrete Output      |         |  |
| Was_000.13.4   |                |      | E .  | 13    | Discrete Output      |         |  |
| A0832-0.1.5.2  |                | 0    |      | 0     | Analog Ovlpait, Inte | Decimal |  |
| A0632-0.1.5.3  |                | 0    |      | 0     | Analog Output, Inte  | Decimal |  |
| A0530-0-1,5-4  |                | 0    |      | 5 13  | Analog Output, Inte  | Decimal |  |
| A0532-0.1.5.6  |                | .0   |      | 0     | Analog Output, Inte  | Decimal |  |
| MST-0.1.5.26   |                | 8    | 13   | 13    | Medule Startus Bit   |         |  |
| MST-0.1.5.25   |                | 1    | 10   |       | Module Status Bit    |         |  |
| 00-01.34       |                |      |      |       | Decrete Output       |         |  |
| DO-0.1.3.15    |                |      |      |       | Deprete Output       |         |  |
| DO-0.1.3.14    |                | C    |      | 0     | Discrete Output      |         |  |
| 00-0-1-3-13    |                |      | - 12 | - C3  | Decrete Output       |         |  |
| 00-0.1.3.12    |                | 0    | - 12 |       | Discrete Output      |         |  |
| DO-0.1.3.11    |                | 13   | - 0  | - 63  | Discrete Output      |         |  |
| DO-0.1.3.10    |                | 0    | 0    | - 0   | Discrete Output      |         |  |
| DO-0.1.3.9     |                | 10   | 10   | 0     | Discrete Output      |         |  |
| DO-0.1.3.8     |                |      | - D- |       | Discrete Output      |         |  |

From either of these windows you have the option to select the check box in the Force column. When this box is checked and the row is selected (selected rows show high-lighted blue) and you select the Send Edit(s) button, the current row(s) will be forced.

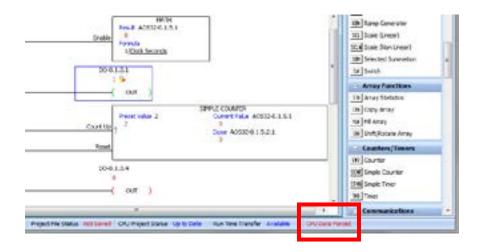


**NOTE:** You can select multiple rows by clicking and holding down the left mouse button and dragging up or down. This selects consecutive rows. If you wish to select various rows, simple hold the "Ctrl" control key on your keyboard while left mouse clicking the rows.

### **Identifying Forced Values**

There are two indications that forces are active on your controller.

- 1. All active forces will be shown in the Force-able tab of the Data View window as shown in the previous view.
- 2. You will also see "CPU Data Forced" in Red in the lower right of the Status bar of your software interface.





**NOTE:** Only Forced tags with an initial force value specified in the Tag database will be retained after a Stop to Run transition, Stop Mode transfer, or a power cycle. All forced values are retained during a Run Time transfer.



### Force Value Timing Chart

The chart below illustrates how the states of a discrete output are varied when forces and edits are applied. The ladder rung at the top of the chart (a) shows the logical arrangement of Logical Contact1 and discrete Output DO-0.1.3.1.

Under normal operation, Logical Contact1 (b) is driven by a clock pulse. This clock pulse is then fed to the discrete Output DO-0.1.3.1 (c). Edits written to the contact or the coil from the Data View window within the software will be written one time and will not be forced. With the clock pulse driving the contact, any software edits made to this contact will be allowed but will be overwritten by the logic on the very next scan. Any software edits made to the output will not be allowed and will not register. Edits can only change the state of the output if there are no other logistic or outside factors influencing the output.

In order to change the state of Logical Contact1 or discrete Output DO-0.1.3.1 while the clock pulse is driving it, a force must be introduced. The DO-0.1.3.1 Output Edit line (d) represents edits sent to the discrete output from the Data View window. The DO-0.1.3.1 Output Force Enabled line (e) shows the point at which the software forces the output edit to take effect. The dotted lines represent the force being enabled and then disabled by the user. When the force is enabled, any edits made will register at the output regardless of the state of Logical Contact1. When the force is disabled, all output edits will be ignored.

