Inverter System Accessories



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Introduction

A motor control system will obviously include a motor and inverter, as well as fuses for safety. If you are connecting a motor to the inverter on a test bench just to get started, that's all you may need for now. But a fully developed system can also have a variety of additional components. Some can be for noise suppression, while others may enhance the inverter's braking performance. The figure below shows a system with several possible optional components, and the table gives part number information.

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Component Descriptions

AC Reactors, Input Side

This is useful in suppressing harmonics induced on the power supply lines, or when the main power voltage imbalance exceeds 3% (and power source capacity is more than 500 kVA), or to smooth out line fluctuations. It also improves the power factor.

In the following cases for a general-purpose inverter, a large peak current flows on the main power supply side, and is able to destroy the inverter module:

- If the unbalanced factor of the power supply is 3% or higher
- If the power supply capacity is at least 10 times greater than the inverter capacity (the power supply capacity is 500 kVA or more)
- If abrupt power supply changes are expected

Examples of these situations include:

- 1. Several inverters are connected in parallel, sharing the same power bus
- **2.** A thyristor converter and an inverter are connected in parallel, sharing the same power bus
- 3. An installed phase-advance (power factor correction) capacitor opens and closes

Where these conditions exist or when the connected equipment must be highly reliable, you MUST install an input-side AC reactor of 3% (at a voltage drop at rated current) with respect to the supply voltage on the power supply side. Also, where the effects of an indirect lightning strike are possible, install a lightning conductor.

Example calculation:

 $V_{RS} = 205V, V_{ST} = 203V, V_{TR} = 197V,$ where V_{RS} is R-S line voltage, V_{ST} is S-T line voltage, V_{TR} is T-R line voltage

Unbalance factor of voltage =
$$\frac{\text{Max. line voltage (min.) - Mean line voltage}}{\text{Meanline voltage}} \times 100$$

$$= \frac{V_{RS} - (V_{RS} + V_{ST} + V_{TR})/3}{(V_{RS} + V_{ST} + V_{TR})/3} \times 100 = \frac{205 - 202}{202} \times 100 = 1.5\%$$

Please refer to the documentation that comes with the AC reactor for installation instructions.

AC Reactors, Output Side

This reactor reduces the vibrations in the motor caused by the inverter's switching waveforms, by smoothing the waveforms to approximate commercial power quality. It is also useful to reduce the reflected voltage wave phenomenon when wiring from the inverter to the motor is more than 10m in length. Please refer to the documentation that comes with the AC reactor for installation instructions.

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Zero-phase Reactor (RF Noise Filter)

The zero-phase reactor helps reduce radiated noise from the inverter wiring. It can be used on the input or output side of the inverter. The example zero-phase reactor shown to the right comes with a mounting bracket. The wiring must go through the opening to reduce the RF component of the electrical noise. Loop the wires three times (four turns) to attain the full RF filtering effect. For larger wire sizes, place multiple zero-phase reactors (up to four) side-by-side for a greater filtering effect.



ZCL–xxx

EMI Filter

The EMI filter reduces the conducted noise on the power supply wiring generated by the inverter. Connect the EMI filter to the inverter primary (input side). The FFL100 series filter is required for compliance to the EMC Class A directive (Europe) and C-TICK (Australia). See "CE–EMC Installation Guidelines" on page C–2.



WARNING: The EMI filter has high internal leakage current from power wiring to the chassis. Therefore, connect the chassis ground of the EMI filter before making the power connections to avoid danger of shock or injury.



FFL100-xxx

RF Noise Filter (Capacitive)

This capacitive filter reduces radiated noise from the main power wires in the inverter input side. This filter is not for achieving CE compliance and is applicable to the input side only of the inverter. It comes in two versions—for 200V class inverters or 400V class inverters. Please refer to the documentation that comes with the radio noise filter for installation instructions.

DC Link Choke

The DC choke (reactor) suppresses harmonics generated by the inverter. It attenuates the high-frequency components on the inverter's internal DC bus (link). However, note that it does not protect the diode rectifiers in the inverter input circuit.

Dynamic Braking

Introduction

The purpose of dynamic braking is to improve the ability of the inverter to stop (decelerate) the motor and load. This becomes necessary when an application has some or all of the following characteristics:

- High load inertia compared to the available motor torque
- The application requires frequent or sudden changes in speed
- System losses are not great enough to slow the motor as needed

When the inverter reduces its output frequency to decelerate the load, the motor can temporarily become a generator. This occurs when the motor rotation frequency is higher than the inverter output frequency. This condition can cause the inverter DC bus voltage to rise, resulting in an over-voltage trip. In many applications, the over-voltage condition serves as a warning signal that we have exceeded the deceleration capabilities of the system. The L100 inverter can connect to an external braking unit, which sends the regenerative energy from the motor during deceleration to the optional braking resistor(s). The dynamic braking resistor serves as a load, developing heat to stop the motor just as brakes on an automobile develop heat during braking.

A switching circuit and power resistor are the main components of the dynamic braking unit that includes a fuse and thermally activated alarm relay for safety. However, be careful to avoid overheating its resistor. The fuse and thermal relay are safeguards for extreme conditions, but the inverter can maintain braking usage in a safe zone.

Dynamic Braking Usage

Dynamic braking usage must follow guidelines to avoid overheating. The timing diagram to the right shows the output frequency versus time. Dynamic braking is in effect during the deceleration ramp, and has the following constraints:

- Dynamic braking maximum duty cycle = 10%, where $T_b/T_c \le 0.1$ sec.
- Dynamic braking maximum continuous ON time $T_b \le 10$ sec.

Selecting Braking Resistors for External Braking Units

200V Class Inverters – The following tables specify the braking options for 200V class L100 inverters and the braking torque for each option. You can connect a single braking unit to the inverter, or two braking units for additional stopping torque.



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Output freq. Dynamic braking $T_c \rightarrow T_b \leftarrow t$ Use one BRD–E2 braking unit for the braking torque listed in the following table.

Note the column meanings in the tables:

- Column "A" = Average braking torque from 60 Hz to 3 Hz.
- Column "B" = Average braking torque from 120 Hz to 3 Hz

L100 Inverter 200V Models			Braking Torque with BRD–E2 Braking Unit									
Model Number HP	НР	Braking torque without braking unit	Using built-in resistor only		External resistor added							
					HRB1		HRB2		HRB3			
			Α	В	A	В	Α	В	A	В		
002NFE/NFU	1/4	50%	150%	120%								
004NFE/NFU	1/2	50%	150%	120%								
005NFE/NFU	3/4	50%	150%	120%								
007NFE/NFU	1	50%	100%	80%	150%	120%						
011NFE/NFU	1.5	50%	60%	60%	100%	80%						
015NFE/NFU	2	50%	50%	50%	100%	80%						
022NFE/NFU	3	20%	50%	50%	100%	80%						
037LFU	5	20%	40%	40%	60%	60%	100%	100%	150%	120%		
055LFU	7.5	20%	30%	30%	50%	50%	70%	70%	100%	80%		
075LFU	10	20%	20%	20%	40%	40%	50%	50%	80%	80%		

Connect a second braking unit in parallel for additional braking torque listed in the following table.

L100 Inverter 200V Models			Braking Torque with TWO (2) BRD–E2 Braking Units									
Model Number HP	НР	Braking torque without braking unit	Using built-in resistor only		External resistor added							
					HRB1		HRB2		HRB3			
			Α	В	Α	В	Α	В	Α	В		
002NFE/NFU	1/4	50%	150%	120%								
004NFE/NFU	1/2	50%	150%	120%								
005NFE/NFU	3/4	50%	150%	120%								
007NFE/NFU	1	50%	150%	120%								
011NFE/NFU	1.5	50%	100%	80%								
015NFE/NFU	2	50%	100%	80%								
022NFE/NFU	3	20~40%	70%	70%	150%	120%						
037LFU	5	20~40%	50%	50%	110%	90%						
055LFU	7.5	20%	30%	30%	80%	80%	100%	100%	150%	150%		
075LFU	10	20%	30%	30%	60%	60%	80%	80%	100%	100%		

400V Class Inverters – The following tables specify the braking options for 400V class L100 inverters and the braking torque for each option. You can connect a single braking unit to the inverter, or two braking units for additional braking torque.



Use one BRD–EZ2 braking unit for the braking torque listed in the following table.

L100 Inverter 400V Models			Braking Torque with BRD–EZ2 Braking Unit									
Model Number HP	HP	Braking torque without braking unit	Using built-in resistor only		External resistor added							
					HRB1 x (2)		HRB2 x (2)		HRB3 x (2)			
			Α	В	Α	В	Α	В	A	В		
004HFE/HFU	1/2	50%	150%	150%								
007HFE/HFU	1	50%	150%	150%								
015HFE/HFU	2	50%	100%	100%								
022HFE/HFU	3	20%	60%	60%								
030HFE/HFU	4	20%	50%	50%	150%	150%						
040HFE/HFU	5	20%	40%	40%	130%	130%	150%	150%				
055HFE/HFU	7.5	20%	30%	30%	100%	100%	130%	130%				
075HFE/HFU	10	20%	20%	20%	70%	70%	100%	100%				

Connect a second braking unit in parallel for additional braking torque listed in the following table.

L100 Inverter 400V Models			Braking Torque with TWO (2)BRD-EZ2 Braking Units									
Model Number HP	HP	Braking torque without braking unit	Using built-in resistor only		External resistor added							
					HRB1 x (2)		HRB2 x (2)		HRB3 x (2)			
			Α	В	Α	В	Α	В	Α	В		
004HFE/HFU	1/2	50%	150%	150%								
007HFE/HFU	1	50%	150%	150%								
015HFE/HFU	2	50%	150%	150%								
022HFE/HFU	3	20%	130%	130%								
030HFE/HFU	4	20%	100%	100%								
040HFE/HFU	5	20%	70%	70%								
055HFE/HFU	7.5	20%	50%	50%	150%	150%						
075HFE/HFU	10	20%	40%	40%	140%	140%						

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