CHAPTER 1

GETTING STARTED

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USER MANUAL OVERVIEW

OVERVIEW OF THIS PUBLICATION

The DURAPULSE GS10 Drive User Manual describes the installation, configuration, and methods of operation of the DURAPULSE GS10 Series AC Drive. Throughout this manual, please note:

• GS10 refers to GS11 and GS13 models only

Who Should Read This Manual

This manual contains important information for those who will install, maintain, and/or operate any of the GS10 Series AC Drives.

SUPPLEMENTAL PUBLICATIONS

The National Electrical Manufacturers Association (NEMA) publishes many different documents that discuss standards for industrial control equipment. Global Engineering Documents handles the sale of NEMA documents. For more information, you can contact Global Engineering Documents at:

15 Inverness Way East Englewood, CO 80112-5776 1-800-854-7179 (within the U.S.) 303-397-7956 (international) www.global.ihs.com

TECHNICAL SUPPORT

By Telephone: 770-844-4200

(Mon.-Fri., 9:00 a.m.-6:00 p.m. E.T.)

On the Web: www.automationdirect.com

Our technical support group is glad to work with you in answering your questions. If you cannot find the solution to your particular application, or, if for any reason you need additional technical assistance, please call technical support at **770-844-4200**. We are available weekdays from 9:00 a.m. to 6:00 p.m. Eastern Time.

We also encourage you to visit our web site where you can find technical and non-technical information about our products and our company. Visit us at www.automationdirect.com.

SPECIAL SYMBOLS



NOTE: When you see the "notepad" icon in the left-hand margin, the paragraph to its immediate right will be a special note.



WARNING: When you see the "exclamation mark" icon in the left-hand margin, the paragraph to its immediate right will be a warning. This information could prevent injury, loss of property, or even death (in extreme cases).

Chapter 1: Getting Started

PURPOSE OF AC DRIVES

AC drives are generally known by many different names: Adjustable Frequency Drives (AFD), Variable Frequency Drives (VFD), and Inverters. Drives are used primarily to vary the speed of three phase AC induction motors, and they also provide non-emergency start and stop control, acceleration and deceleration, and overload protection. By gradually accelerating the motor, drives can reduce the amount of motor startup inrush current.

AC drives function by converting incoming AC power to DC, which is then synthesized back into three phase output power. The voltage and frequency of this synthesized output power is directly varied by the drive, where the frequency determines the speed of the three phase AC induction motor.

SELECTING THE PROPER DRIVE RATING

DETERMINE MOTOR FULL-LOAD AMPERAGE (FLA)

Motor FLA is located on the nameplate of the motor.

NOTE: FLA of motors that have been rewound may be higher than stated.

DETERMINE MOTOR OVERLOAD REQUIREMENTS

Many applications experience temporary overload conditions due to starting requirements or impact loading. Most AC drives are designed to operate at 150% overload for 60 seconds. If the application requires an overload greater than 150% or longer than 60 seconds, the AC drive must be oversized.

NOTE: Applications that require replacement of existing motor starters with AC drives may require up to 600% overload.

DETERMINE APPLICATION TYPE; CONSTANT TORQUE OR VARIABLE TORQUE

This torque requirement has a direct effect on which drive to select. Variable Torque (VT) applications are generally easier to start; typically fans and pumps. Most other applications outside fans and pumps fall into the Constant Torque (CT) category (machine control, conveyors, etc.). If you are unsure of the application, assume Constant Torque. The specification, derating, and selection tables are generally segregated by Constant Torque and Variable Torque.



INSTALLATION ALTITUDE

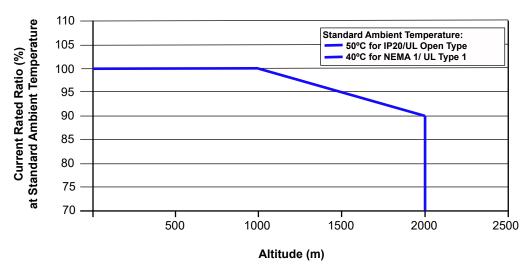
AC drives rely on air flow for cooling. As the altitude increases, the air becomes less dense, and this drop in air density decreases the cooling properties of the air. Therefore, the AC drive must be oversized to compensate for the decrease in cooling. Most AC drives are designed to operate at 100% capacity at altitudes up to 1000 meters.

NOTE: For use above 1000m, the AC drive must be derated as described below.

DERATE OUTPUT CURRENT BASED ON ALTITUDE ABOVE 1000 METERS

- If the AC drive is installed at an altitude of 0~1000m, follow normal operation restrictions.
- If installed at an altitude of 1000~2000m, decrease 1% of the rated current or lower 0.5°C of temperature for every 100m increase in altitude.
- Maximum altitude for Corner Grounded is 2000m. If installation at an altitude higher than 2000m is required, please contact AutomationDirect.

Derating for Altitude





DETERMINE MAXIMUM ENCLOSURE INTERNAL TEMPERATURE

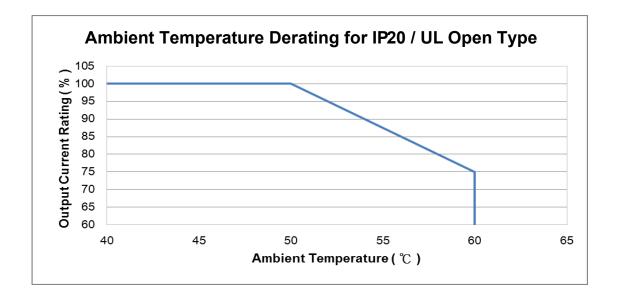
AC drives generate a significant amount of heat and will cause the internal temperature of an enclosure to exceed the rating of the AC drive, even when the ambient temperature is less than $104^{\circ}F$ ($40^{\circ}C$). Enclosure ventilation and/or cooling may be required to maintain a maximum internal temperature of $104^{\circ}F$ ($40^{\circ}C$) or less. Ambient temperature measurements/calculations should be made for the maximum expected temperature. When permissible, flange mounting the AC drive (mounting with the drive heatsink in open ambient air) can greatly reduce heating in the enclosure.

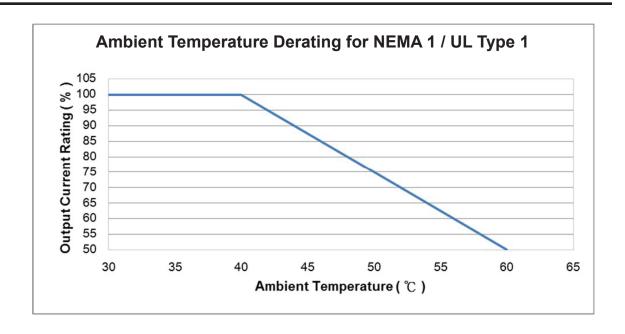


For use above 104°F (40°C), the AC drive must be derated as described below.

DERATE OUTPUT CURRENT BASED ON TEMPERATURE ABOVE 104°F (40°C)

	Drive Derating by Temperature and Protection Level					
Protection Level	Derating					
UL Open Type / IP20 *	If the AC motor drive operates at the rated current, the ambient temperature needs to be between -20–50°C. If the temperature is above 50°C, decrease 2.5% of the rated current for every 1°C increase in temperature. The maximum allowable temperature is 60°C.					
NEMA 1 / UL Type 1*	When the AC motor drive is operating at the rated current, the ambient temperature must be between -20–40°C. When the temperature is over 40 °C, for every increase by 1°C, decrease the rated current 2.5%. The maximum allowable temperature is 60°C.					
* For more information about environmental ratings, refer to the "DURApulse GS10 AC Drive						
Environmental Info	Environmental Information" on page 1–5 of this chapter.					







DERATE OUTPUT CURRENT BASED ON CARRIER FREQUENCY (IF NECESSARY)

CARRIER FREQUENCY EFFECTS

AC Drives rectify the incoming 50 or 60Hz line power resulting in DC power at 0Hz. The resulting DC power is then pulse-width modulated and supplied to the motor by the drive's power electronics. IGBTs invert the DC power, simulating a sine wave at the desired frequency (that's what allows variable speed in AC induction motors). The speed at which the IGBTs are turned ON and OFF is called Carrier Frequency. In AC drives, the Carrier Frequency can range from 2kHz to 15kHz. The Carrier Frequency can be adjusted in most AC Drives.

There are trade-offs between choosing High Carrier Frequencies and Low Carrier Frequencies.

BENEFITS OF HIGHER CARRIER FREQUENCIES:

- Better efficiency (lower harmonic losses) in the motor
- Lower audible noise

BENEFITS OF LOWER CARRIER FREQUENCIES:

- · Better efficiency in the drive
- Lower EMI (electrical noise)
- · Reduced reflective wave peak voltage

As a general rule, the Carrier Frequency should be set as low as possible without creating unacceptable audible noise in the motor. Smaller systems can have higher Carrier Frequencies, but larger drives (>20hp) should not have Carrier Frequencies set higher than 6kHz. Constant torque applications typically run around 2~4kHz.

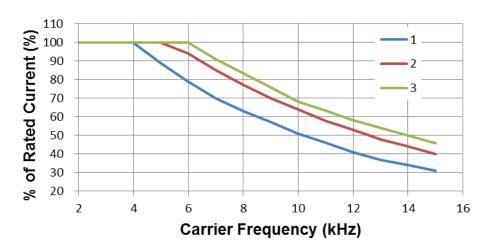
GS10 VARIABLE TORQUE CARRIER FREQUENCY DERATING

- Line 1: Ta = 50°C / Load = 100%
- Line 2: Ta = 50°C / Load = 75% or Ta = 40°C / Load = 100%
- Line 3: Ta = 50°C / Load = 50% or Ta = 35°C / Load = 100%

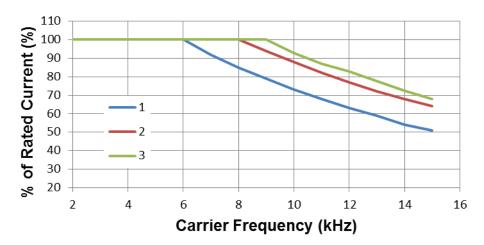


Note: Space Vector Pulse Width Modulation (SVPWM) and Two-Phase Pulse Width Modulation (DPWM) are determined by parameter P11.41. See Chapter 4 for details.

Variable Torque, SVPWM Mode

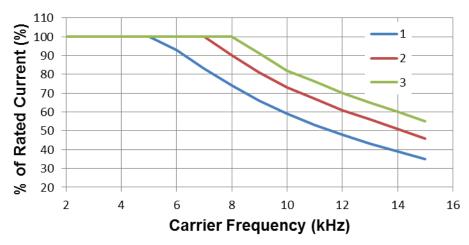


Variable Torque, DPWM Mode

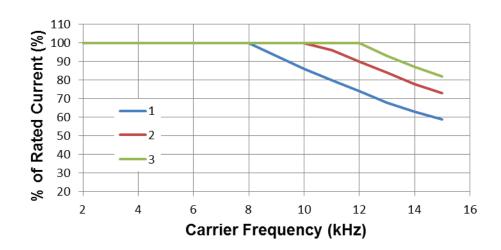


GS10 CONSTANT TORQUE CARRIER FREQUENCY DERATING

Constant Torque, SVPWM Mode



Constant Torque, DPWM Mode





DURAPULSE GS10 AC DRIVE ENVIRONMENTAL INFORMATION

STORAGE AND TRANSPORTATION

AC drives should be kept in the shipping cartons or crates until they are installed. In order to retain the warranty coverage, they should be stored as described below if not to be installed and used within three months.

- Store in a clean and dry location free from direct sunlight and corrosive fumes.
- Store within environmental conditions shown below in the "Environmental Conditions" table.
- DO NOT store in an area with rapid changes in temperature, to avoid condensation and frost.
- DO NOT place directly on the ground.



If the drive is stored or is otherwise unused for more than a year, the drive's internal DC link capacitors should be recharged before use. Otherwise, the capacitors may be damaged when the drive starts to operate. We recommend recharging the capacitors of any unused drive at least once per year. (Refer to Chapter 6, "Maintenance and Troubleshooting" for information about recharging DC link capacitors.)

GS10 Environmental Conditions

	Environmental Conditions for GS10 AC Drives								
Condition	Operation	Storage	Transportation						
Installation Location	IEC 60364-1/ IEC 60664-1 Pollution degree 2, Indoor use only.	n/a	n/a						
	IP20/UL Open Type: -20-50°C (-20-60°C w/derating)								
Ambient Temperature	IP20 side-by-side or NEMA1/UL Type 1: -20–40°C (-20–55°C w/derating)	-40–85°C	-20–70°C						
	Non-condensing, non-freezing								
Relative Humidity	90%, no water condensation	water condensation 95%, no water condensation							
Air Pressure	86–106 kPa	86–106 kPa 70–106 kPA							
Pollution Level	Concentrate prohibited								
Pollution Level	Class 3C2; Class 3S2	Class 2C2; Class 2S2	Class 1C2; Class 1S2						
Altitude	<1000 m (For altitudes > 1000 m, d	erating required)							
Package Drop	n/a	ISTA procedure 1A (ac 60068	cording to weight) IEC 3-2-31						
Vibration	1.0 mm, peak to peak value range from 2–13.2 Hz; 0.7–1.0 G range from 13.2–55 Hz; 1.0 G range from 55–512 Hz. Compliance with IEC 60068-2-6	2.5 G peak, 5 Hz–2 kHz 0.015" maximum displacement							
Impact	t 15 G, 11 ms, compliance with IEC/EN60068-2-27 30G								
DO NOT expose the	GS10 AC Drive to harsh environments such as dust	direct sunlight cor	cosive/flammable						

DO NOT expose the GS10 AC Drive to harsh environments such as dust, direct sunlight, corrosive/flammable gases, humidity, liquid, or vibrations. The salts in the air must be less than 0.01 mg/cm² every year.



GS10 GENERAL SPECIFICATIONS

General Specifications for GS10 AC Drives					
	Control Method	V/F, Sensorless Vector (SVC)			
	Applicable Motor	IM (Induction Motor), Permanent Mag	anet AC (IPM and SPM)		
	Starting Torque ¹	150% / 3 Hz	(V/F, SVC control for IM, CT)		
		100% / (motor rated frequency/20)	(SVC control for PM, CT)		
	Speed Control Range ¹	1: 50 (V/F, SVC control for IM, CT) 1: 20 (SVC control for PM, CT)			
	Max. Output Frequency	0.00-599.00 Hz			
	Overload Capacity	VT: rated output current of 120% 60 sec., 150% 3 sec. CT: rated output current of 150% 60 sec., 200% 3 sec.			
	Frequency Setting Signal	0–10 V / 4(0)–20 mA PWM pulse width input, pulse input (10kHz)		
	Digital Inputs	Five (5) - 24VDC NPN or PNP, include	s 1 frequency input 10kHz		
	Digital Outputs	Two (2) - (1)-48VDC, (1) Relay-250VA			
	Analog Inputs	One (1) - Selectable Voltage or Current			
	Analog Outputs	One (1) - Voltage			
Control Characteristics	Main Functions	Multiple motor switching (max 2 motor settings) Fast start-up Deceleration Energy Back (DEB) function Fast deceleration function Master and Auxiliary frequency source selectable Restart after momentary power loss Speed tracking Over-torque detection 16-step speed (including the master speed) Accel./decel. time switch S-curve accel./decel. Three-wire operation control JOG frequency, Frequency upper/lower limit settings DC brake at start-up and stop PID control Simple Positioning Function Multi Pump Sequence			
	Application Macro	Built-in application parameter groups (selected by industry) and user-defined application parameter groups.			
Protection	Motor Protection	Over-current, Over-voltage, Over-hea			
Characteristics	Stall Prevention	Stall prevention during acceleration, deceleration and running (independent settings).			
Agency Approvals	UL, CE, REACH				

^{1:} Control accuracy may vary depending on the environment, application conditions, or motor type. For more information contact AutomationDirect.

EFFICIENCY CLASS

The EU Ecodesign regulation directive establishes a framework to set mandatory ecological requirements for energy-using and energy-related products. The IEC 61800-9-2 standard defines the efficiency classes for AC drives. The efficiency classes range (low to high) from IEO to IE2. These classes apply to AC drives rated 100 to 1000 V and 0.12 to 1000 kW (1/6 to 1,340 HP).

Drive manufacturers must declare power losses in terms of percentage of rated apparent output power at eight different operating points, as well as standby losses. The International Efficiency (IE) level is given at the nominal point.

The power losses of GS10 series drives shall not exceed the maximum power losses corresponding to the IE2 efficiency level. For specific power losses of each drive model, see the drive specification tables.



DURAPULSE GS10 AC DRIVE SPECIFICATIONS

120V CLASS - 1-PHASE MODEL-SPECIFIC SPECIFICATIONS

GS10 <u>120V</u> Class Specifications; Frame Size A, C ¹								
lel Nai			GS11N-10P2	GS11N-10P5	GS11N-11P0			
ne Sizo	2		A1	A3	C1			
Max Motor Output hp			1/4	1/2	1			
Max I	notor Output	kW	0.2	0.4	0.75			
	Rated Output Capacity	kVA	0.6	1.0	1.8			
СТ	Rated Output Current	Α	1.6	2.5	4.8			
	Carrier Frequency⁴	kHz		2–15				
	Rated Output Capacity	kVA	0.7	1.0	2.1			
VT	Rated Output Current	Α	1.8	2.7	5.5			
	Carrier Frequency⁴	kHz	2–15					
СТ	Rated Input Current	Α	6	9.4	18			
VT	Rated Input Current	Α	6.8	10.1	20.6			
Rated	Voltage/Frequency³		One-phase: 100–120 VAC (-15% to +10%), 50/60 Hz					
Opera	nting Voltage Range (VAC)		85–132					
Frequ	ency Tolerance (Hz)		47–63					
IE2 Efficiency - Relative Power Loss			4.3%	3.2%	2.9%			
Weight (kg)			0.4	0.5	1			
Cooling Method			Convective Fan					
ating			IP20					
	Max I CT VT CT VT Rated Operor Freque Efficient ght (ku	me Size Max Motor Output Rated Output Capacity CT Rated Output Current Carrier Frequency ⁴ Rated Output Current Carrier Frequency ⁴ CT Rated Output Current Carrier Frequency ⁴ CT Rated Input Current VT Rated Input Current Rated Voltage/Frequency ³ Operating Voltage Range (VAC) Frequency Tolerance (Hz) Efficiency - Relative Power Loss ight (kg) ling Method Pating	me Size Max Motor Output Rated Output Capacity Rated Output Current Carrier Frequency ⁴ Rated Output Current A Carrier Frequency ⁴ Carrier Frequency ⁴ Rated Output Current A Carrier Frequency ⁴ CT Rated Input Current A VT Rated Input Current A Rated Voltage/Frequency ³ Operating Voltage Range (VAC) Frequency Tolerance (Hz) Efficiency - Relative Power Loss ght (kg) ling Method Pating	Max Motor Output Mp	Max Motor Output Mp			

^{1 -} For use with three-phase motors only.

^{2 -} Please refer to Appendix A - Accessories for input fusing information.

^{3 -} For 120V single phase input power, remove the drive RFI jumper. See Circuit Connections - RFI Jumpers in Chapter 2.

^{4 -} If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7



	GS10 <u>230V</u> Class Specifications; Frame Size A, B, C¹								
Mod	lel Nai	ne: GS11N-2xPx		GS11N-20P2	GS11N-20P5	GS11N-21P0	GS11N-22P0	GS11N-23P0	
Fran	ne Sizo	?	A1	A3	B2	C1	C1		
May Matax Output hp		1/4	1/2	1	2	3			
6	Max Motor Output		kW	0.2	0.4	0.75	1.5	2.2	
Rating		Rated Output Capacity	kVA	0.6	1.1	1.8	2.9	4.2	
Ra	СТ	Rated Output Current	A	1.6	2.8	4.8	7.5	11	
Output		Carrier Frequency⁴	kHz			2–15			
nt	VT	Rated Output Capacity	kVA	0.7	1.2	1.9	3.2	4.8	
0		Rated Output Current	A	1.8	3.2	5	8.5	12.5	
		Carrier Frequency⁴	kHz						
26	СТ	Rated Input Current	A	5.1	7.3	10.8	16.5	24.2	
Input Rating ²	VT	Rated Input Current	A	5.8	8.3	11.3	18.5	27.5	
t Re	Rated	Voltage/Frequency ³		One-phase 200-240 VAC (-15% to +10%), 50/60 Hz					
nd	Opera	ting Voltage Range (VAC)			170–265				
2	Frequ	ency Tolerance (Hz)			47–63				
IE2	IE2 Efficiency - Relative Power Loss			4.7%	3.1%	2.7%	2.5%	2.4%	
Wei	ght (k	g)		0.4	0.5	0.8	1	1	
Cooling Method				Convective Fan				Fan	
IP Rating					IP20				

^{1 -} For use with three-phase motors only.

^{2 -} Please refer to "Appendix A - Accessories" for input fusing information.

^{3 -} For input power that is a floating ground or IT type, the RFI jumper must be removed. See "Floating Ground System (IT Systems)" on page 2–12.

^{4 -} If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7.



	GS10 <u>230V</u> Class Specifications; Frame Size A, B¹							
Mod	lel Na	me: GS13N-2xPx		GS13N-20P2	GS13N-20P5	GS13N-21P0	GS13N-22P0	
Frai	ne Sizo	2		A1	A2	A5	B1	
hp			1/4	1/2	1	2		
	Max Motor Output		np .	[0.1]	[1/4]	[1/2]	[1]	
	(3-ph	ase [1-phase])	kW	0.2	0.4	0.75	1.5	
ng			VAA	[0.1]	[0.2]	[0.375]	[0.75]	
ati		Rated Output Capacity	kVA	0.6	1.1	1.8	2.9	
t R	СТ	Rated Output Current	A	1.6	2.8	4.8	7.5	
nd	CI	(3-phase [1-phase])	A	[0.8]	[1.4]	[2.4]	[3.75]	
Output Rating		Carrier Frequency⁴	kHz	2–15				
	VT	Rated Output Capacity	kVA	0.7	1.2	1.9	3.0	
		Rated Output Current	Α	1.8	3.0	5.0	8.0	
		Carrier Frequency⁴	kHz	2–15				
nput Rating²	ст	Rated Input Current (3-phase and 1-phase)	A	1.9	3.4	5.8	9.0	
Sati	VT	Rated Input Current	A	2.2	3.8	6.0	9.6	
nt 1	Rated	Voltage/Frequency ³		3-phase 200-240 VAC (-15% to +10%), 50/60 Hz				
du	Opera	nting Voltage Range (VAC)		170–265				
_	Frequ	ency Tolerance (Hz)		47–63				
IE2	Efficie	ncy - Relative Power Loss		4.7%	3.1%	2.7%	2.4%	
Wei	ght (k	g)		0.4	0.5	0.6	0.8	
Coo	Cooling Method			Convective Fan			Fan	
IP Rating								

^{1 -} For use with three-phase motors only.

^{2 -} Please refer to "Appendix A - Accessories" for input fusing information.

^{3 -} For input power that is a floating ground or IT type, the RFI jumper must be removed. See "Floating Ground System (IT Systems)" on page 2–12.

^{4 -} If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7.



	GS10 <u>230V</u> Class Specifications; Frame Size C, D¹							
Mod	lel Na	me: GS13N-2xPx		GS13N-23P0	GS13N-25P0	GS13N-27P5		
Fran	ne Siz	2		C1	C1	D1		
Max		Motor Output hp		3 [1.5]	5 [2.5]	7.5 [3.5]		
	(3-ph	(3-phase [1-phase]) kW		2.2 [1.1]	3.7 [1.85]	5.5 [2.75]		
ati		Rated Output Capacity	kVA	4.2	6.5	9.5		
Output Rating	ст	Rated Output Current (3-phase [1-phase])	A	11 [5.5]	17 [8.5]	25 [12.5]		
nt'		Carrier Frequency⁴	kHz		2–15			
J		Rated Output Capacity	kVA	4.8	7.4	10.3		
	VT	Rated Output Current	Α	12.5	19.5	27		
		Carrier Frequency⁴	kHz	2–15				
nput Rating²	СТ	Rated Input Current (3-phase and 1-phase)	A	13.2	20.0	30.0		
Rati	VT	Rated Input Current	A	15.0	23.4	32.4		
ut F	Ratea	Voltage/Frequency ³	'	3-phase 200-240 VAC (-15% to +10%), 50/60 Hz				
du	Opera	iting Voltage Range (VAC)		170–265				
	Frequ	ency Tolerance (Hz)			47–63			
IE2	IE2 Efficiency - Relative Power Loss			2.4%	2.2%	2.3%		
Wei	Weight (kg)			1	1	2		
Coo	ling M	ethod		Fan				
IP R	ating			IP20				

^{1 -} For use with three-phase motors only.

^{2 -} Please refer to "Appendix A - Accessories" for input fusing information.

^{3 -} For input power that is a floating ground or IT type, the RFI jumper must be removed. See "Floating Ground System (IT Systems)" on page 2–12.

^{4 -} If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7.



	GS10 <u>460V</u> Class Specifications; Frame Size A, B¹								
Mod	iel Na	me: GS13N-4xPx		GS13N-40P5	GS13N-41P0	GS13N-42P0			
Fran	ne Siz	е		A4	A6	B1			
Max Motor Output			1/2	1	2				
6	Max	40tor Output	kW	0.4	0.75	1.5			
Rating		Rated Output Capacity	kVA	1.1	2.1	3.2			
Ra	CT	Rated Output Current	A	1.5	2.7	4.2			
Output		Carrier Frequency⁴	kHz	2–15					
nth		Rated Output Capacity	kVA	1.4	2.3	3.5			
0	VT	Rated Output Current	A	1.8	3.0	4.6			
		Carrier Frequency⁴	kHz	2–15					
<i>3</i> 6	СТ	Rated Input Current	A	2.1	3.7	5.8			
Input Rating ²	VT	Rated Input Current	A	2.5	4.2	6.4			
t Re	Rated	Voltage/Frequency³		3-phase 380-480 VAC (-15% to +10%), 50/60 Hz					
nd	Opera	nting Voltage Range (VAC)		323-528					
7	Frequ	ency Tolerance (Hz)		47–63					
IE2	IE2 Efficiency - Relative Power Loss			3.7%	2.5%	2.2%			
Wei	Weight (kg)			0.6	0.7	0.8			
Coo	ling M	ethod		Convective Fan					
IP R	ating			IP20					

^{1 -} For use with three-phase motors only.

^{2 -} Please refer to "Appendix A - Accessories" for input fusing information.

^{3 -} For input power that is a floating ground or IT type, the RFI jumper must be removed. See "Floating Ground System (IT Systems)" on page 2–12.

^{4 -} If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7.



	GS10 <u>460V</u> Class Specifications; Frame Size C, D¹							
Mod	lel Na	me: GS13N-4xPx		GS13N-43P0	GS13N-45P0	GS13N-47P5	GS13N-4010	
Frame Size				C1	C1	D1	D1	
hp		3	5	7 1/2	10			
6	Max I	Motor Output	kW	2.2	3.7	5.5	7.5	
Rating		Rated Output Capacity	kVA	4.2	6.9	9.9	13	
Ra	СТ	Rated Output Current	A	5.5	9	13	17.5	
Output		Carrier Frequency⁴	kHz		2-	-15		
nth		Rated Output Capacity	kVA	5.0	8.0	12	15.6	
0	VT	Rated Output Current	A	6.5	10.5	14.5	19.8	
		Carrier Frequency⁴	kHz	2–15				
g ₂	СТ	Rated Input Current	A	6.1	9.9	14.3	19.3	
Input Rating ²	VT	Rated Input Current	A	7.2	11.6	16.0	21.8	
t Re	Ratea	Voltage/Frequency ³		3-phase 380-480 VAC (-15% to +10%), 50/60 Hz				
nd	Opera	nting Voltage Range (VAC)		323-528				
2	Frequency Tolerance (Hz)			47–63				
IE2	IE2 Efficiency - Relative Power Loss			2.3%	2.0%	1.9%	1.9%	
Wei	Weight (kg)			1	1	2	2	
Coo	ling M	ethod		Fan				
IP Rating								

- 1 For use with three-phase motors only.
- 2 Please refer to "Appendix A Accessories" for input fusing information.
- 3 For input power that is a floating ground or IT type, the RFI jumper must be removed. See "Floating Ground System (IT Systems)" on page 2–12.
- 4 If application requires adjustment of the carrier frequency above default, refer to "Derate Output Current Based on Carrier Frequency (if necessary)" on page 1–7.



NOTE: 120VAC models do not have DC bus terminals.



RECEIVING AND INSPECTION

DRIVE PACKAGE CONTENTS

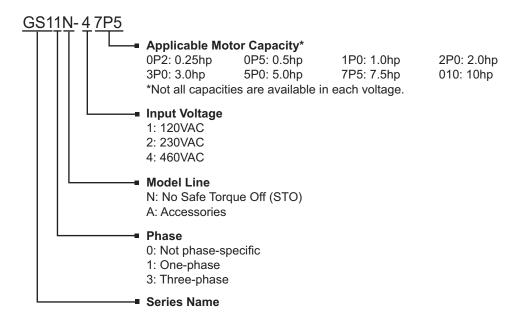
After receiving the GS10 AC drive, please check the following:

- 1) Make sure that the package includes the DURAPULSE GS10 AC drive and the Quick-Start Guide that matches your product.
- 2) Please inspect the unit after unpacking to assure it was not damaged during shipment. Make sure that the part number printed on the package corresponds with the part number indicated on the nameplate.
- 3) Make sure that the part number indicated on the nameplate corresponds with the part number of your order.
- 4) Make sure that the voltage for the wiring lies within the range as indicated on the nameplate. Please install the GS10 AC drive according to this manual.
- 5) Before applying the power, please make sure that all the devices, including power, motor, control board, and digital keypad are connected correctly.
- 6) When wiring the GS10 AC drive, please make sure that the wiring of input terminals "R/L1, S/L2, T/L3" and output terminals "U/T1, V/T2, W/T3" are correct to prevent drive damage.
- 7) When power is applied, select the language and set parameter groups via the digital keypad. When executing a trial run, please begin with a low speed, and then gradually increase the speed until the desired speed is reached.

The GS10 AC drive should be kept in the shipping carton before installation. In order to retain the warranty coverage, the GS10 AC drive should be stored properly when it is not to be used for an extended period of time. Refer to the preceding "Environmental Information" section for proper storage conditions.



MODEL NUMBER EXPLANATION



NAMEPLATE INFORMATION

