### Quick Start Guide

1. Run all current carrying conductors through sensor window.

2. Mount the sensor to a surface if needed.

3. Connect power and output wiring.
   
   **A.** Use up to 14 AWG copper wires.
   
   **B.** Ensure load matches the output shown on the sensor label.

4. Test the sensor.
   
   **A.** Press the “Test” button to test the sensor’s internal circuits.

**CAUTION:** The output and any connected loads will switch!

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### Power Supply Notes

All low-current Ground-Fault Sensors are sensitive devices and require reasonable care in system design to avoid false trips caused by high electrical noise levels. The best way to reduce noise in a system is to suppress it at its source.

1. Keep the sensor power isolated from noisy circuits.
2. Do not power the sensor with the same circuit that switches contactors or other high-current, inductive loads.

### System Grounding

Good design practice and code require that all AC power systems be grounded. GFS series sensors are designed to work on grounded AC power systems. They may not operate properly on underground systems.
Description
GFS Series sensors monitor all current carrying wires in single or three phase systems to detect ground faults. They provide a contact output that can operate relays and contactors or signal automation systems.

Principal of Operation
Under normal conditions, the current in one wire of a two wire load is equal in strength but opposite in polarity to the current in the other wire. The two wires create magnetic fields that cancel, a condition known as “Zero Sum Current”. If any current leaks to ground (Ground Fault), the two currents become unbalanced and there is a net resulting magnetic field. The GFS sensor detects this minute field and changes the output state. This concept extends to three-phase systems such as 3-wire Delta and to 4-wire Wye.

Installation and Wiring
GFS Series sensors work in the same environment as motors, contactors, heaters, pull-boxes, and other electrical enclosures. They can be mounted in any position or hung directly on wires with a wire tie. Leave at least one inch distance between sensor and other magnetic devices. Run all current carrying conductors through the sensor aperture in the same direction (see "Principal of Operation").

Power Wiring
Connect power wiring to Terminals 1 and 2. Use up to 10 AWG copper wire for M1A and M1B models and up to 14 AWG for D1C and E1C models. Tighten terminals to 4.5 inch-pounds of torque for M1A and M1B models and 7 inch-pounds for D1C and E1C models.

Output Wiring
Connect output wiring to Terminals 3 and 4. Use up to 10 AWG copper wire for M1A and M1B models and up to 14 AWG for D1C and E1C models. Tighten terminals to 4.5 inch-pounds of torque for M1A and M1B models and 7 inch-pounds for D1C and E1C models.

Reset Switch Wiring (M1A/M1B models only)
Connect a momentary dry contact to the reset terminals (5 and 6). Limit wire run to 200 feet of 18 AWG or larger wire. Tighten terminals to 4.5 inch-pounds of torque.

Diagrams

Power Supply
Input 1 and 2
Power Supply
Input 1 and 2
Power Supply
Input 1 and 2

Output Contact
Output Contact
Output Contact

Green Power LED
(ON when Powered)
Green Power LED
(ON when Powered)
Green Power LED
(ON when Powered)

Red Status LED
(ON when tripped)
Red Status LED
(ON when tripped)
Red Status LED
(ON when tripped)

Test button
(Activates output relay)
Test button
(Activates output relay)
Test button
(Activates output relay)

Move jumper to select setpoint
Remove for 5mA setting

Operation/Setup

Auto Reset Sensors (E1C and D1C)
GFS Auto Reset sensors monitor all current carrying conductors and will trip when a ground fault is sensed. The output of these sensors will automatically reset when the ground fault condition is cleared. Select from three factory calibrated setpoints by moving the setpoint jumper to the desired position.

- 5mA setpoint: Detect sensitive ground fault conditions that may be injurious to personnel or processes. Remove jumper for lowest setting of 5mA
- 10 mA and 30 mA setpoints: These higher setpoints help eliminate nuisance tripping while still providing adequate ground fault protection for machine electronics.

Normally Energized Models (E1C)
Used to detect both ground faults and loss of control power.

<table>
<thead>
<tr>
<th>NO POWER</th>
<th>CONTROL POWER APPLIED</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output</td>
<td>LED</td>
</tr>
<tr>
<td>N.C. Normally Closed</td>
<td>Closed</td>
</tr>
<tr>
<td>N.O. Normally Open</td>
<td>Open</td>
</tr>
</tbody>
</table>

Normally De-energized Models (D1C)
Used to detect ground faults.

<table>
<thead>
<tr>
<th>NO POWER</th>
<th>CONTROL POWER APPLIED</th>
</tr>
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Manual Reset Sensors
GFS Manual Reset Sensors monitor all current carrying conductors and will trip when a ground fault is sensed. When the output of these sensors trips it will latch in the tripped position even after the ground fault is cleared. If control power is removed, the sensor remains in its last output state. To reset the sensor, the ground fault condition must be removed and a momentary dry contact closed at the reset terminals (5 and 6).

- For model with M1A suffix: The contact is normally open with no ground fault condition, and open when a ground fault is sensed.
- For model with M1B suffix: The contact is normally closed with no ground fault condition, and open when a ground fault is sensed.

Testing:
To test operation, gently press the TEST button. This simulates a fault and tests the internal switching circuits. After the test is complete, reset the sensor with a momentary dry contact on Terminals 5 and 6 for manual reset models M1A and M1B. Auto Reset models D1C and E1C will reset when the test button is released.

CAUTION: Any circuit connected to the sensor will be operated.