

AUTOMATIONDIRECT.com

LS ELECTRIC

XMC

MOTION CONTROLLER



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The XMC motion controller has it all, EtherCAT control, PLC power, and so much more!

The LS Electric XMC motion controller has numerous state-of-the-art features built into its compact brick-style design. These controllers are optimized for advanced motion control, are available in 8- or 16-axis models, and offer a variety of high-tech capabilities for a price that can't be beat.

XMC for Xact motion control - XMC controllers utilize the EtherCAT high-performance protocol which is specifically designed for real-time communication and deterministic data exchange, making it ideal for motion control applications like robotics, assembly lines, and packaging machines. EtherCAT boasts incredibly low communication jitter (variations in timing), ensuring precise synchronization between devices and smooth motion control. This is crucial for applications requiring high accuracy and repeatability (*pulse/direction control is not supported*).



XMC for EtherCAT Xpansion - XMC controllers feature full EtherCAT Master capabilities, meaning they can communicate and control any EtherCAT device. This allows the XMC controller to seamlessly communicate with EtherCAT I/O, encoders, AC drives, etc.



XMC for Xtensive automation - Not only can XMC controllers handle numerous EtherCAT devices, they also support G-code, M-code, and programming specific to robot control including Delta3, Delta3R, Linear Delta, and more. On top of that, XMC controllers can also be used for PLC functions providing an enhanced programming environment for discrete and/or process control needs.



XMC for blazing fast Xecution - The XMC controllers offer extremely fast processing capabilities, not just with motion commands, but with basic PLC logic as well. Basic commands are executed with a scan time of only 6.25ns, motion commands with a 5ns scan, and arithmetic commands with a 30ns scan. EtherCAT-based high-speed communication cycle times are also 0.5/1/2/4ms.



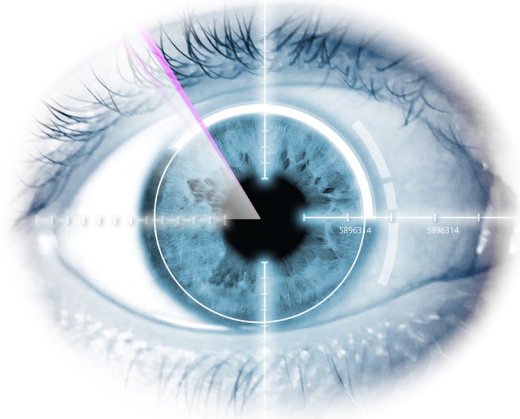
XMC for Xtreme value - The XMC controller provides both highly advanced motion control with EtherCAT communication and built-in PLC functionality for a price well below the competition. By using the powerful XMC controller for your next motion control application, you could save thousands on hardware costs alone. The 8-axis XMC controllers start at \$779.00 with competitor controllers ranging anywhere from \$1,500 (Mitsubishi Q170MSCPU) to \$4,000 (Allen Bradley 5069-L320ERM) and higher! Not to mention the savings you'll get with the FREE, comprehensive XG5000 programming software and the many perks that come with being an AutomationDirect customer including FREE shipping, FREE tech support, and more.



LS
XMC
MOTION CONTROLLER

EtherCAT

The XMC motion controller is super small, lightning fast, and highly capable



Millions of updates in the blink of an eye!

The time it takes most people to blink ranges from 100 to 150ms. Well, with the XMC controller's lightning fast execution, in that same time frame the positions of 16 servo systems **AND** over 8,000 discrete I/O points can be updated *more than 200 times!* With that kind of processing speed, the blink of an eye is an eternity to this controller. The XMC is capable of executing basic logic commands in 6.25ns and performing EtherCAT updates in as little as 0.5ms. This execution speed provides utmost positioning accuracy and precise, real-time motion control.

Data Logging and More

Log data to a removable microSD card (sold separately). Troubleshoot processes, spot trends, collect valuable historical data, along with program transfer and backup.

Mini B USB

Mini B USB port for easy plug-and-play programming

Encoder Inputs

Built-in support for two external 5VDC encoders (@500kpps) for full closed-loop control. A great solution for monitoring position and correcting for "slippage" and other process variations in your application.

Compact Footprint

The XMC motion controller packs all these great hardware features into a small, approximately 7 1/2 inch, brick style form factor.

Analog Inputs

Two built-in 14 bit analog input channels. Used to monitor analog sensors and devices using current or voltage signals.

Analog Outputs

Two built-in analog voltage output channels, providing dependable process control using 14 bit resolution signals.

Convenient Status Indicators

See digital I/O and encoder signal status at a glance

**XMC MOTION
CONTROLLERS
STARTING AT
\$779.00**

10/100 Mbps Ethernet Communication Port

RJ45 Ethernet port for factory network. Connect to Modbus TCP capable HMIs, data collection systems, etc.

EtherCAT Communication Port

EtherCAT port for connection of up to 32 slaves including servo systems, stepper systems, VFDs, or numerous additional I/O racks via XEL-BSSCT bus couplers.

Digital Inputs

Eight embedded general purpose digital inputs for monitoring various sensors, pushbuttons, switches, contactors, etc. around your facility.

Digital Outputs

16 general purpose transistor based digital outputs built in that are ideal for controlling ON/OFF devices including relays, actuators, solenoid valves, etc.



EtherCAT[®]
Modbus[®]

Expansive EtherCAT Motion Control

EtherCAT, which stands for Ethernet for Control Automation Technology offers a powerful and versatile networking solution for high-performance motion control applications. EtherCAT provides speed, accuracy, scalability, and cost-effectiveness making it suitable for complex multi-axis motion control systems. Additionally, its open communication standard allows for easy integration with numerous devices and controllers for various other industrial automation tasks.

The XMC controller is a full EtherCAT master meaning it can communicate with any EtherCAT capable device including up to 16 EtherCAT servo or stepper systems and up to 32 remote EtherCAT I/O racks. The XMC utilizes the powerful XG5000 software to configure and program all the control logic for advanced motion as well as basic PLC applications.



EtherCAT®

Add up to 16 Motion Axes

Add servos, steppers, or VFDs with simple Ethernet (EtherCAT) connections. Easily load configuration files in the ESI Library and jump start your project. You can also add up to 18 virtual axes to coordinate tricky multi-axis solutions.

Fast, Accurate Motion Control

Use EtherCAT cyclic mode to update the position of ALL axes on every EtherCAT cycle, with selectable update times of 0.5/1/2/4ms. These super-fast updates ensure highly accurate motion profiles.

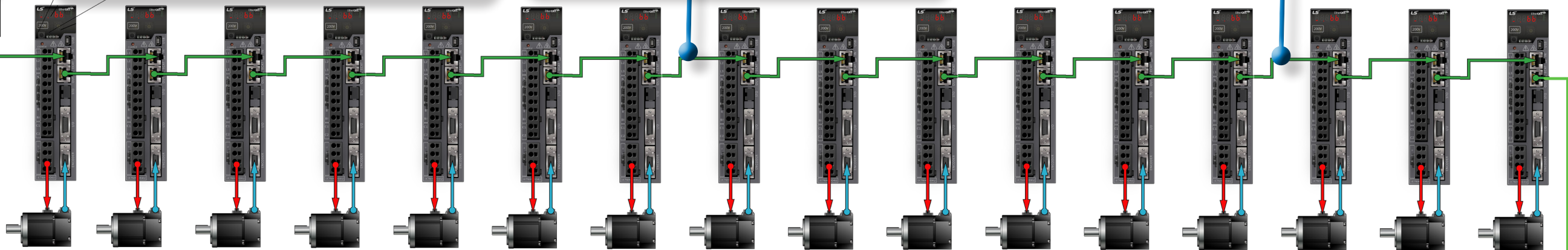
Simple System Connections

EtherCAT is a relief to anyone familiar with wiring pulse and direction based servo or stepper systems. That's because you won't have to be deal with the discrete signal wiring of the past, no sinking/sourcing concerns, no common reference voltages, totem-pole or linedriver headaches, etc. Just daisy-chain simple network cables (any Ethernet cable CAT 5 or 6) from the controller to each motion axis and I/O bus coupler as needed. It's that simple!



LS XMC
MOTION CONTROLLER

LS XG5000
PLC Programming



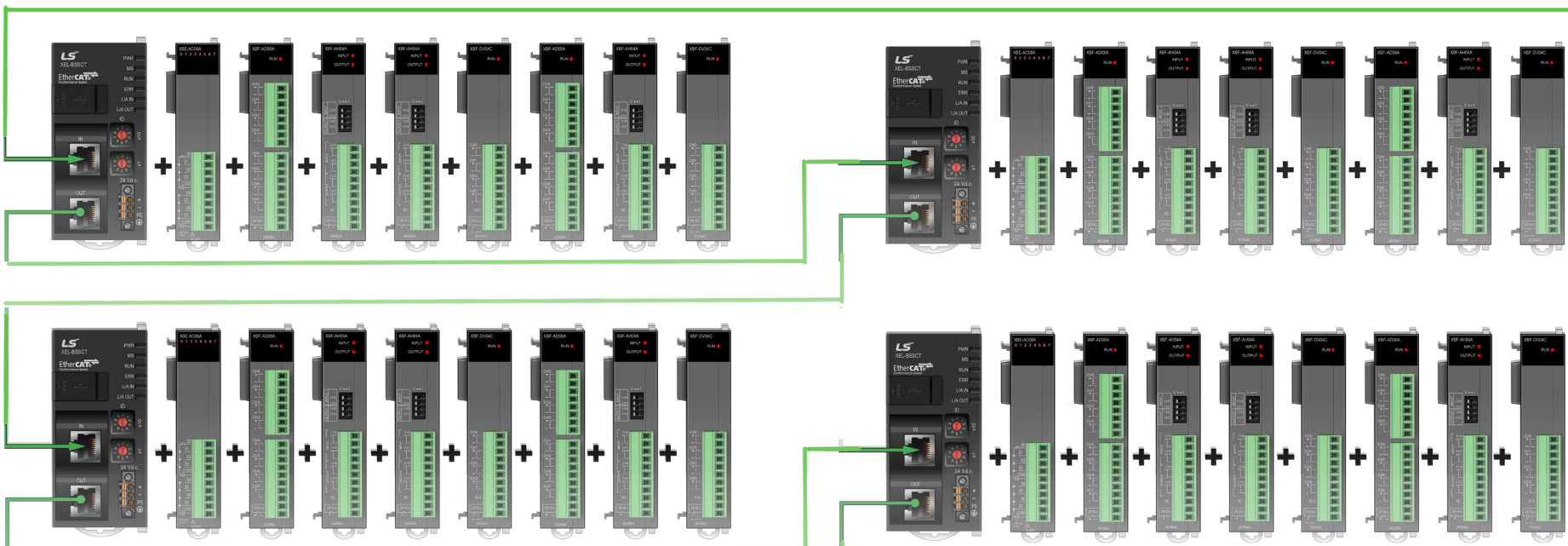
Add up to 32 I/O Racks

With the XEL-BSSCT bus coupler you can add thousands of additional I/O and integrate into the same XG5000 project as the XMC controller.. Up to eight I/O modules can be installed per bus coupler - that's 256 discrete or 64 analog channels *per coupler*! AND it's ALL updated synchronously on EVERY EtherCAT cycle.



BUS COUPLER (XEL-BSSCT)
\$199.00

I/O EXPANSION MODULES STARTING AT \$59.00



The XMC controller is THE motion master

With the XMC as your primary controller, you can control a wide variety of advanced motion control systems. The FREE powerful XG5000 programming software offers IEC 61131 programming languages (Ladder, Structured Text), 64 bit data types, motion axis graphing, and numerous motion control function blocks based on the PLCopen standard for quick and efficient coding. With this dynamic hardware and software duo you can create:

- Up to 32 CAM profiles (32,769 points each)
- Full G-code (and M-code) programs for traditional CNC machines such as mills, lathes, and router tables

- Robot control programs using Delta3, Delta3R, Linear Delta, and others
- Many other motion control programs that need to follow a complex or variable tool path:
 - Laser cutters
 - Additive manufacturing
 - Gasket/glue applicators
 - Forming/burnishing machines

Milling Machines, Routers, and Laser Cutters

When milling, cutting, or routing materials to match specifications, precision is key. Just the slightest misstep can cause a complete redo and wasted material. Most of these machines utilize three axes of motion (X, Y, and Z axes) and require servo accuracy that is repeatable time and time again, making these types of applications perfect for the XMC controller.

Printing Machines

Printing machines can use numerous servo drives/motors to control the feed, printing, and collection rollers of the printing process. The XMC controller can coordinate these drives to keep the required uniform tension in the printable media and ensure proper contact with the printing mechanism and a quality output.

Packaging Machines

Servos control several aspects of a typical packaging machine. The product feed servos provide adequate spacing between products, the film wrap servo guides products through the wrapping process, and the heat sealing servo ensures proper application of the heating element for a complete seal. With one XMC controller, all of the timing, staging, and conveying can be accurately controlled.

Numerous
Motion Function
Blocks
for efficient code
development

- MC_Stop
- MC_Halt
- MC_Move
- MC_Move
- MC_Move
- MC_Move
- MC_Stop
- MC_Halt
- MC_Move
- MC_Move
- MC_Move
- MC_Move
- MC_SetPosition
- MC_SetOverride
- MC_AddAxisToGroup
- MC_RemoveAxisFromGroup
- MC_UngroupAllAxes
- MC_GroupEnable
- MC_GroupDisable
- MC_GroupSetPosition
- MC_GroupStop
- MC_GroupHalt
- MC_GroupReset
- MC_MoveLinearAbsolute
- MC_MoveLinearRelative
- MC_MoveCircularAbsolute
- MC_MoveCircularRelative
- MC_SetKinTransform
- MC_SetCartesianTransform
- MC_MoveCircularAbsolute2D
- MC_MoveCircularRelative2D
- MC_TrackConveyorBelt
- MC_TrackRotaryTable
- MC_CamIn
- MC_CamOut
- MC_GearIn
- MC_GearOut
- MC_GearInPos
- MC_Phasing
- LS_Connect
- LS_Disconnect
- LS_Read
- LS_Write
- LS_Set
- LS_Esc
- LS_CamSkip
- LS_VarCamIn
- LS_VarGearIn
- LS_VarGearInPos
- LS_ReadCamInSlavePos
- LS_InverterWriteVel
- LS_InverterReadVel

FREE software with the tools you need to succeed!

The XG5000 software is a powerful tool for programming the XMC controllers. This FREE software can be downloaded anytime from our website and offers many features for efficient code development whether its for basic PLC control or a high-tech motion application.

Project Tree

The XG5000's Project Tree offers a super convenient way to see all the configuration items of the current project. It also allows for easy access to the parameter files of the EtherCAT master and slave devices configured for the project and their associated axis profiles.

Program Editor

The Program Editor provides ladder logic or structured text programming and offers a user-friendly development window for the XMC controller. Using numerous PLCopen compliant function blocks, users can quickly code all of the many automated functions and tasks performed by the controller (no separate motion control software application required).

Manual Motion Commands

The Motion Command window allows user to manually start, stop, or jog an axis or to change presets, reset errors, and more. Easily select the desired motion axis from the drop-down and run the desired command.

Status Monitor

The Status Monitor is available to give users insight into how the axis is performing with details on position, speed, torque, error codes, operation status, and more.

ESI Library

The ESI Library provides easy access and organization of the various EtherCAT devices for the XMC. EtherCAT Slave Information (ESI) files are XML files used by EtherCAT masters to configure the slaves and generate network description files. The main purpose is to describe how data will be shared with the slave device, making it super simple to connect with 3rd party EtherCAT devices.



Need help getting your EtherCAT axis up and running?

No problem, we've got your back with 100% FREE technical support. Just reach out to us at 1-800-633-0405, 9am to 6pm, Monday through Friday or submit a technical support request at our [Contact Support page](#) and one of our experienced technical support staff members will be glad to help.

SDO/PDO Parameters

A Process Data Object (PDO) is used for synchronous transmission of data between the master and slave nodes and is utilized by the master for input/output signals and to control the position of EtherCAT servo drives.

A Service Data Object (SDO) is used for asynchronous transmission of data between the master and slave nodes and is the method by which error information in the slave is gathered and parameter reading/writing is done.

The XG5000 software offers quick access to the SDO/PDO parameters simply by clicking the device in the Project Tree of the program. From there, parameters can be viewed and modified for the slave device directly from the project.

PLCopen in motion

PLCopen is a global, independent organization dedicated to standardizing control programming and application engineering to reduce costs and increase productivity. Their standards are widely used in various industries, including packaging, robotics, machine tools, automotive, and semiconductor. PLCopen has developed several standards specifically for motion control that involve function blocks for single axis control, advanced motion control functions like electronic gearing, and interpolation, and standards for homing procedures.

The XG5000 software utilizes function blocks that meet the standards of PLCopen to ensure interoperability, efficiency, and easier code development for motion applications.

The screenshot displays the XG5000 software interface. On the left, the Project Tree shows the hierarchy: XMC_XYZ_Gantry > Network Configuration > Undefined Network > LSPLC [Local Ethernet Parameter] > Motion Control Module > System Variable > LSPLC(XMC-E16A)-RUN/Warning > Global/Direct Variables > Parameter > Basic Parameter > I/O Parameter > Internal Parameter > Motion Data > EtherCAT Parameter > Master > Slave > Slave 1(X7NH - Standard EtherCAT drive) > Slave 2(X7NH - Standard EtherCAT drive) > Slave 3(X7NH - Standard EtherCAT drive) > Axis Parameter > Axis 1(Slave 1(X7NH - Standard EtherCAT drive) connect) > Axis 2(Slave 2(X7NH - Standard EtherCAT drive) connect) > Axis 3(Slave 3(X7NH - Standard EtherCAT drive) connect) > Axis Group Parameter > Axis group 1 > NC Parameter > NC Program > CAM Data > CAM Block > CAM Profile > Main Task > GantryControl > Periodic Task > Initialization Task > User Function/Function Block > User Data Type > Library.

The main window shows the SDO Parameter settings for the selected axis. The General Information tab is active, displaying the following parameters:

Index	Name	Set Value	Initial Value	Access
1000.00	Device Type	0		ro
100A.00	Software Version	1.47		ro
1010.00	Identity Object	4		ro
1010.01	Vendor ID	750		ro
1010.02	Product Code	16		ro
1010.03	Revision Number	11		ro
1010.04	Serial Number	305419896		ro
8000.00	Params_Enabled	0		nw
8001.00	Params_Head_NetX	5		ro
8001.01	Not used	0		nw

The Basic Settings tab is also visible, showing parameters for Axis 1:

Unit	Name	Value
0: pulse	Pulse/Rev Value	524288 pls
70 pls	Travel Distance Per Rotation	70 pls
0: Unit/sec	Speed command unit	0: Unit/sec
20000000 pls/s	Speed limit	20000000 pls/s
0 pls/s2	Emg. stop deceleration	0 pls/s2
0: Incremental encoder	Encoder selection	0: Incremental encoder
5	Gear ratio of Motor side	5
1	Gear ratio of Machine side	1
0: Deceleration stop	Operating mode of the reverse rotation	0: Deceleration stop
0: No	Position Control range expansion	0: No
0: CSP (Cyclic Sync. Position)	Velocity control operation mode	0: CSP (Cyclic Sync. Position)
0 unit/s2	Maximum Allowable Acceleration Of Coordinate System Operation	0 unit/s2
0 unit/s2	Maximum Allowable Deceleration Of Coordinate System Operation	0 unit/s2
2147483647 pls	S/W upper limit	2147483647 pls
-2147483648 pls	S/W lower limit	-2147483648 pls
360 pls	Infinite running repeat pos	360 pls
0: Disable	Infinite running repeat	0: Disable
0 pls	Command in-position range	0 pls
0 pls	Tracking error over-range value	0 pls
0: Warning	Tracking error level	0: Warning
0 pls	Current pos. compensation amount	0 pls
0 ms	Current speed filter time constant	0 ms
100 ms	Error reset monitoring time	100 ms
0: Do not detect	S/W limit during speed control	0: Do not detect
0: Specified by ratio	Override mode	0: Specified by ratio
0: Sync to bi-directional operation of master axis	The sync method depending on the	0: Sync to bi-directional operation of master axis

The NC Spindle Origin Settings tab is also visible, showing parameters for the spindle:

Unit	Name	Value
100000 pls/s	Spindle Position Mode Feed Forward Gain	100000 pls/s
60 rpm	Home position driving method	0: Server Drive Support
12 rpm	Origin driving switch navigation speed	60 rpm
1000 deg/s2	Origin driving zero navigation speed	12 rpm
%IX0	Origin driving Acc/deceleration	1000 deg/s2
60 rpm	Z-phase variable/address	%IX0
0: Forward	Orientation speed	60 rpm
0 deg	Orientation direction	0: Forward
0 deg	Orientation offset	0 deg
95 %	Spindle command speed ack range	0 4 0 5
5 rpm	Spindle zero speed ack. rpm	5 rpm

Axis Parameters

The XMC controller allows for expansive configuration of each motion axis and the XG5000 programming software provides convenient access to their parameters. By clicking the desired axis from the Project Tree, all configuration options are easily viewed and can be modified as needed. Application specific parameters, in particular spindle parameters for CNC applications, are clearly listed as well.

The screenshot displays the GantryControl[Program] ladder logic. The main function block is MC_POWER, which is used to control the power of the axes. The function block has inputs for Power_On_Axis1, _AX01_RDY, and Enable, and outputs for Status, Axis1_Power_Status, Axis1_Power_Valid, Axis1_Power_Error, Axis1_MCP_Power_Error, and ErrorID.

The Multi-Axis Function Block is also shown, which is used to control multiple axes simultaneously. It has inputs for Execute, All_Axes_Pwr_On, and All_Axes_Ready, and outputs for Master_Axis, Slave_Axis, GearIn_ContinuousUpdate, GearIn_RatioNumerator, GearIn_RatioDenominator, GearIn_MasterValueSource, GearIn_Acceleration, GearIn_Deceleration, and GearIn_Jerk.

The Single-Axis Function Block is also shown, which is used to control a single axis. It has inputs for Execute, All_Axes_Pwr_On, and All_Axes_Ready, and outputs for Master_Axis, Slave_Axis, GearIn_ContinuousUpdate, GearIn_RatioNumerator, GearIn_RatioDenominator, GearIn_MasterValueSource, GearIn_Acceleration, GearIn_Deceleration, and GearIn_Jerk.

Software with numerous benefits built in!

This highly developed software has been fine-tuned over the years to provide a wealth of features and capabilities, including:

- Program segmentation with different Scan programs and various Task programs
- Numerous data types including IEC standard data types (64 bit available) and 3-dimensional arrays
- Handy two-dimensional trend graph (X-Y plotter)
- Easy edits of global and local variables using MS Excel or View Variable, View Device, View Flag, Auto-fill options in software
- Convenient program edits with unlimited Undo/Redo functions, block edits in cell units, an enhanced Find/Replace function, program execution controls, and more
- Various monitoring functions such as variable monitoring, device monitoring, system monitoring, trend monitoring, special module monitoring, etc.
- Editing, monitoring, or managing multiple interlocked PLCs included in the same project at the same time
- Online editing capabilities
- Setup data logging to record program data with many configurable options
- NC program editor for modifying G-code in a NC file (shown on right)

Convenient
G-CODE editor
for easy, efficient
CNC coding

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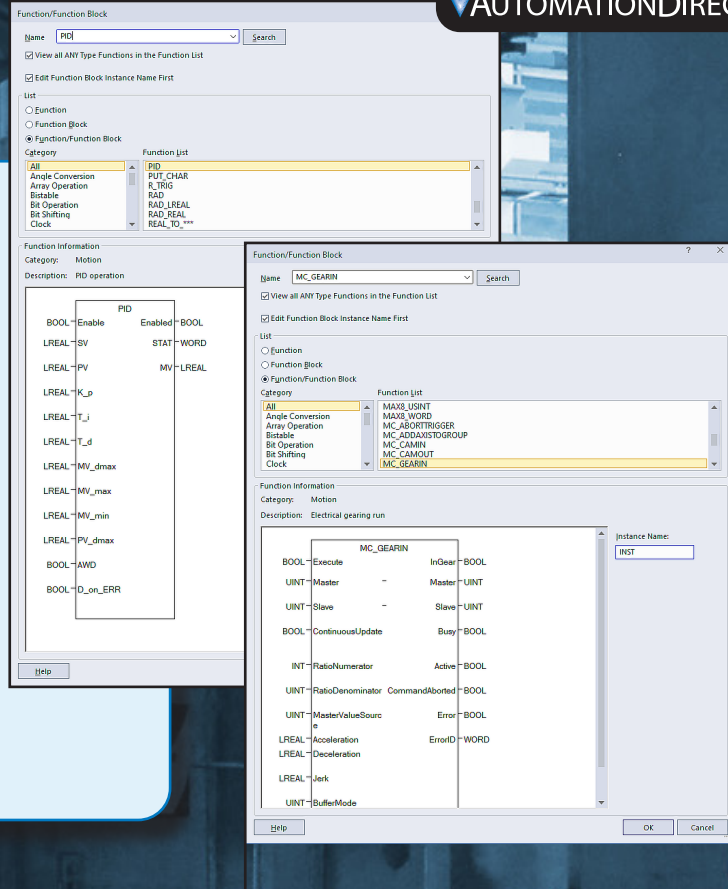
1: G21 ; Set units to mm
2: G90 ; Absolute positioning
3: G1 Z2.54 F2540 ; Move to clearance level
4:
5:
6: ; Operation: 0
7: ; Name:
8: ; Type: Pocket
9: ; Paths: 23
10: ; Direction: Conventional
11: ; Cut Depth: 3.175
12: ; Pass Depth: 3.175
13: ; Plunge rate: 127
14: ; Cut rate: 1016
15:
16:
17: ; Path 0
18: ; Rapid to initial
19: G1 X137.9416 Y-77.8419 F2540
20: G1 Z0.0000
21: ; plunge
22: G1 Z-3.1750 F127
23: ; cut
24: G1 X137.9324 Y-77.8419
25: G1 X137.8562 Y-77.9074
26: G1 X137.8521 Y-77.9109
27: G1 X137.8212 Y-77.9335
28: G1 X137.7597 Y-77.9803
29: G1 X137.7246 Y-78.0057
30: G1 X137.7147 Y-78.0125
31: G1 X137.5893 Y-78.1012
32: G1 X137.5151 Y-78.1507
33: G1 X137.4884 Y-78.1680
34: G1 X137.4783 Y-78.1743
35: G1 X137.4554 Y-78.1891
36: G1 X137.3904 Y-78.2279
37: G1 X137.3579 Y-78.2244
38: G1 X137.3523 Y-78.2241
39: G1 X137.3421 Y-78.2229
40: G1 X137.2667 Y-78.2127
41: G1 X137.2512 Y-78.2102
42: G1 X137.1554 Y-78.1969
43: G1 X137.1389 Y-78.1942
44: G1 X137.0376 Y-78.1787
45: G1 X137.0266 Y-78.1766
46: G1 X136.9910 Y-78.1703
47: G1 X136.9624 Y-78.1649
48: G1 X136.9113 Y-78.1545
49: G1 X136.8727 Y-78.1472
50: G1 X136.7742 Y-78.1248
51: G1 X136.7600 Y-78.1218
52: G1 X136.7155 Y-78.1106
53: G1 X136.6876 Y-78.1037
54: G1 X136.6223 Y-78.0877
55: G1 X136.6076 Y-78.0834
56: G1 X136.4767 Y-78.0476
57: G1 X136.4717 Y-78.0463
58: G1 X136.4513 Y-78.0417

```

State-of-the-art instructions and convenient function blocks

The XG5000 programming software has all the usual commands you would expect from an industrial controller software including timer, counter, compare, etc., but it also features a wide variety of specialized and state-of-the-art instructions for efficient code development including:

- Data processing
- High-level math
- Advanced motion control
- Multiple data and code conversion
- PID function block
- SD card read/write
- Ethernet socket programming



Project simulators provide huge time savings

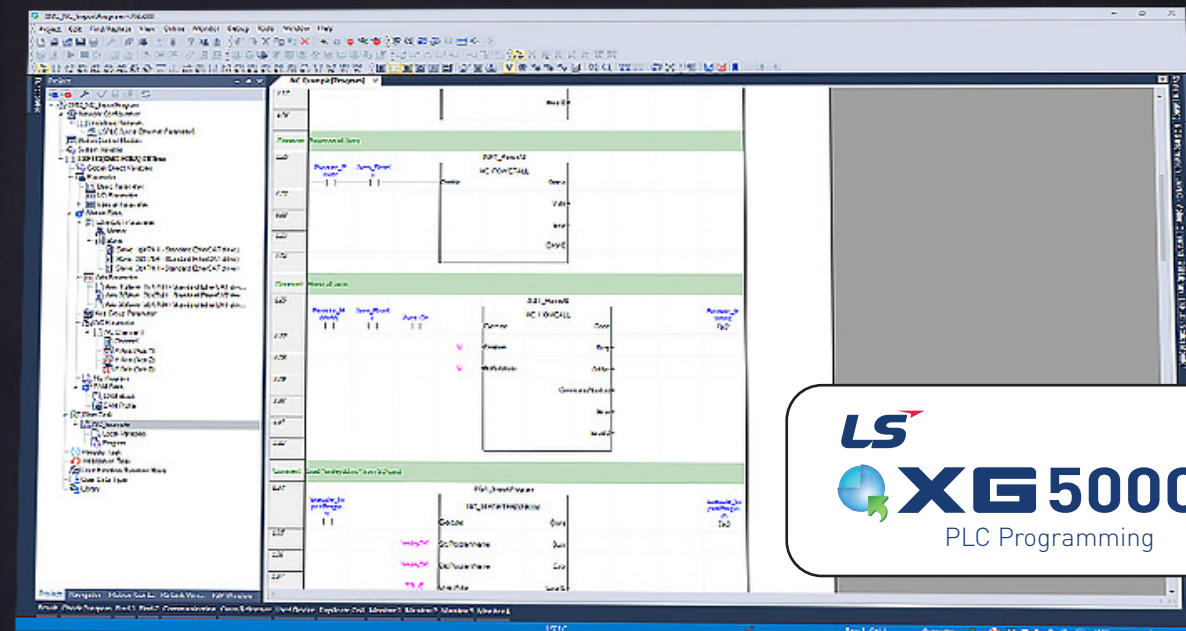
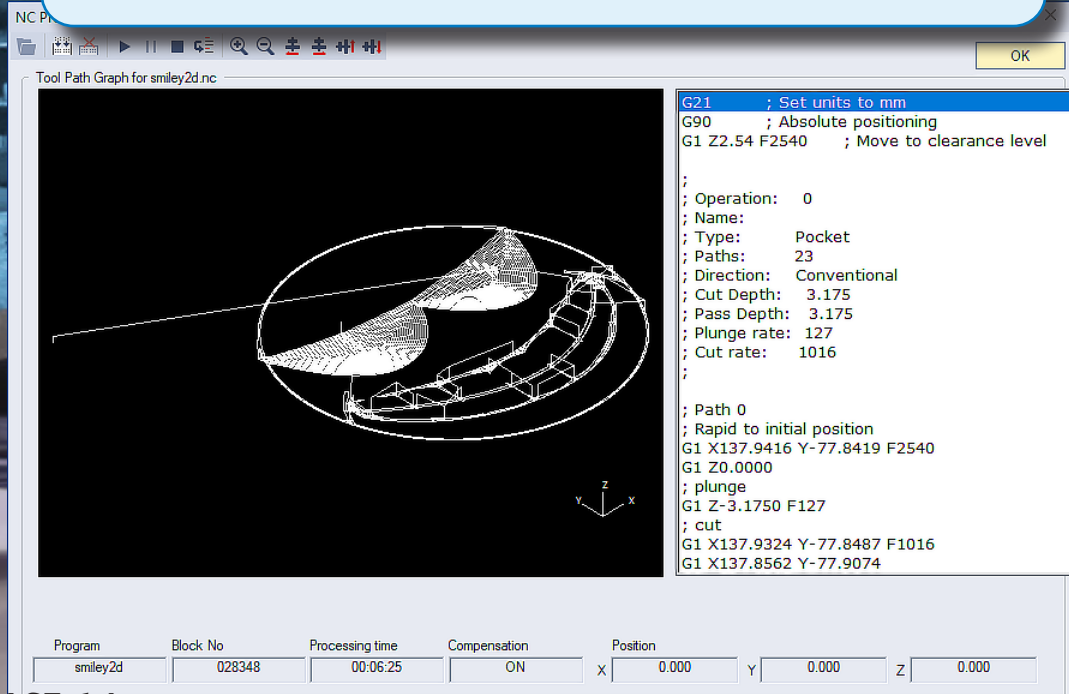
The XG5000 software offers several convenient simulators for programmers to verify logic operations without a physical controller present. With these simulators, you can test your control logic as it is created instead of in the field for much easier startups.

XG-SIM for PLC logic simulation:

- Simulate a program created with ladder or structured text
- Use functions such as system monitor, device monitor, trend monitor, data trace, and user events as if online with a real controller
- Simulate I/O as if field devices are connected to ensure proper system-wide control

NC Profile Simulator for easy verification of advanced axis configurations for CNC machines:

- Simulate an NC program to validate G-code
- Step through profile with a visual representation of resulting tool path



LS
XG5000
PLC Programming

SAVE THOUSANDS IN
SOFTWARE COSTS!

LS PLC XG5000 software is
100% FREE

Download as often as you need.
No license or key needed.

Click here to download.

LS Electric XMC Motion Controller



More than just a motion controller...

Monitor and control multiple applications

The XMC's primary function centers around accurate motion control, but this controller also offers PLC functionality so you can employ the XMC in more ways than one. Along with controlling multiple EtherCAT devices, you can use the embedded encoder inputs and discrete and analog I/O to monitor and control several processes around your plant. And don't forget, with the EtherCAT XEL-BSSCT bus coupler, you can install even more I/O and control many more applications with one XMC controller.

Discrete operations

The XMC controller offers several built-in discrete I/O points that can work hand in hand with industrial object detection devices including proximity switches, photoelectric sensors, and limit switches. These devices are used extensively in product conveying and sorting applications. High-speed encoder inputs (up to 500 kHz) are also built in and are available to handle the rapid pulse trains produced by belt- or shaft- mounted encoders, often used to track belt speeds and object positions. If more I/O is needed, thousands more discrete I/O points can be added using the XEL-BSSCT bus couplers and XGB I/O modules. Incorporate the XEL-BSSCT configuration/programming in the same XG5000 project with the XMC controller.

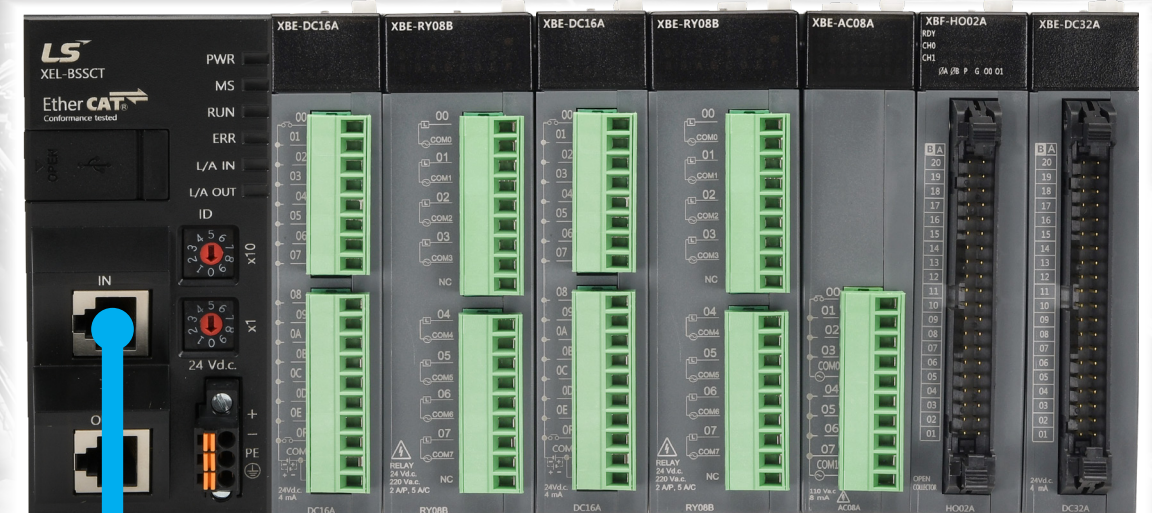
Processing and production

Using embedded and expansion analog I/O, a variety of process control functions can be reliably handled. Monitor and/or control the temperature of an oven, the level of raw material in a feed hopper, or the amount of pressure being used at your filling stations. With the XMC controller and the XG5000's super capable PID programming, you can do it all!



LS
XMC
MOTION CONTROLLER

EtherCAT



XEL-BSSCT Bus Coupler with several XGB I/O modules

With the LS XMC controller you can also monitor and control many other processes around your facility, including those involving:

SPEED



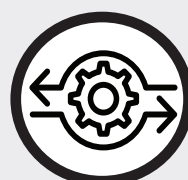
PRESSURE



LEVEL



FLOW



Looking for more PLC power?
Check out the LS XGB PLC.

If your application is heavy on the process /discrete control side and lighter on motion requirements, check out the LS Electric XGB PLC series. This low-cost controller uses the same FREE powerful XG5000 software but offers several additional capabilities for a more robust PLC control solution.

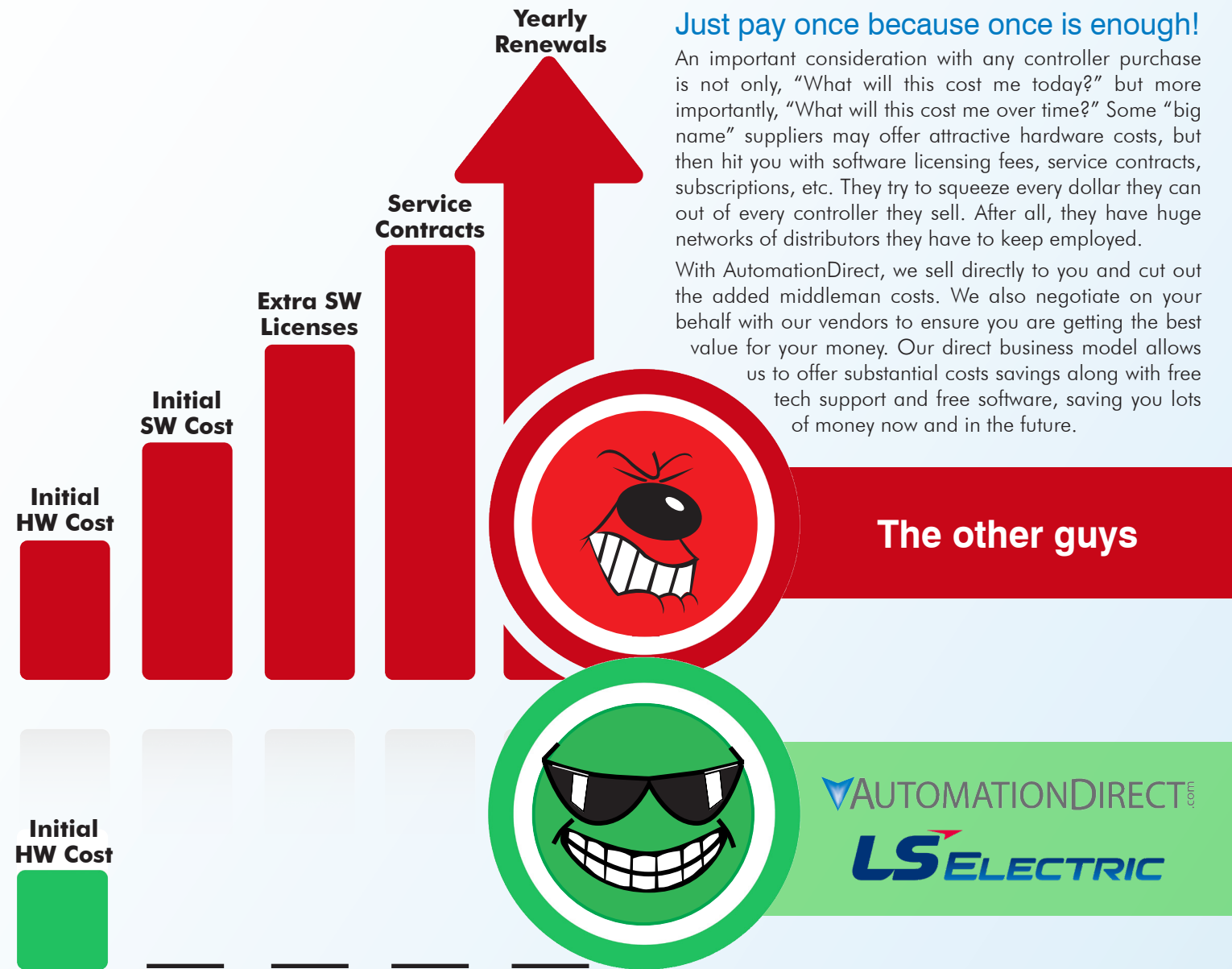


LS
XGB
PLC

STARTING AT
\$279.00

[CLICK HERE](#) to learn more

Low prices are just the beginning!



Just pay once because once is enough!

An important consideration with any controller purchase is not only, "What will this cost me today?" but more importantly, "What will this cost me over time?" Some "big name" suppliers may offer attractive hardware costs, but then hit you with software licensing fees, service contracts, subscriptions, etc. They try to squeeze every dollar they can out of every controller they sell. After all, they have huge networks of distributors they have to keep employed.

With AutomationDirect, we sell directly to you and cut out the added middleman costs. We also negotiate on your behalf with our vendors to ensure you are getting the best value for your money. Our direct business model allows us to offer substantial costs savings along with free tech support and free software, saving you lots of money now and in the future.



FREE Tech Support

Are you tired of calling a local distributor to discover their "product expert" is not in? How about waiting hours for technical service to return a message? Or paying for phone support service and then having to be on hold waiting for it?

It's no accident that our Tech Team routinely demonstrates the best attitude and manners in the industry!

We send our customers surveys to score our attitude, accuracy, and timeliness, then take these scores and use them as part of the Tech Team's report card. The bottom line is that you get great service by design.

Over 85% of customers who have used our service and responded to surveys say it's better than what they have been getting from other automation suppliers. 91% say we are above average to excellent in accuracy, 90% say we are above average to excellent in thoroughness, 91% say we are above average in response time, and 96% rate us above average in courtesy.

Isn't it time you got better service AND a better price? We definitely think so!

FREE Software!
Download as often
as you need.
**No license or key
needed.**

[Click here to download.](#)



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LS Electric XMC Motion Controller

mLSE-19

