

SureStep[®] Integrated Motors System

General integrated motor/drive features

- DC power supply required (12-48 VDC or 12-70 VDC)
- Pulse/Direction or CW Pulse/CCW Pulse
- Digital input filtering
- "E" models include an encoder
- Three optically isolated digital inputs, 5 to 24 volts
- Step input signal smoothing (microstep emulation), performs high resolution stepping by synthesizing coarse steps into fine microsteps
- Dynamic smoothing, software-configurable filtering for use in removing spectral components from command sequence, reduces jerk, limiting excitation of system resonance
- Anti-resonance (electronic damping): raises the system-damping ratio to eliminate midrange instability and allow stable operation throughout the speed range of the motor
- Idle current reduction range of 0-90% of running current after a delay selectable in milliseconds (Standard models = 50/90%, DIP switch selectable)
- Configurable hardware digital noise filter, software noise filter
- Non-volatile storage, configurations are saved in FLASH memory on-board the DSP
- Dynamic current control, software configurable for running current, accel current, idle current, to make motion smoother and the motor run cooler

Standard integrated motor/drive features

(STP-MTRD-x)

- "E" models have an externally wireable encoder which can provide feedback to an external controller
- Configurable via DIP switches
- Available torque from 68 to 210 oz-in

Advanced integrated motor/drive features

(STP-MTRD-xR)

- Step and Direction, CW/CCW, and AB Quadrature/Encoder following
- Velocity (Oscillator) and position mode
- Control via streaming SCL commands
- RS-485 ASCII (2- or 4-wire) communications
- On "E" models, the internal encoder provides improved position and speed control
- Four "Variable I/O" points, 5 to 24 volts (NEMA 24 models)
- Analog input for speed and position, 0 to 5 VDC
- Configurable via SureMotion Pro software
- Available torque from 54 to 340 oz-in

	SureStep Series Part Numbers Standard Integrated Motor/Drives							
Integrated Motor/Drive	NEMA Size	Price	Drawing					
STP-MTRD-17038	17	\$142.00	PDF					
STP-MTRD-17038E	17	\$228.00	PDF					
STP-MTRD-23042	23	\$187.00	PDF					
STP-MTRD-23042E	23	\$307.00	PDF					
STP-MTRD-23065	23	\$217.00	<u>PDF</u>					
STP-MTRD-23065E	23	\$320.00	PDF					

Note: Standard Integrated motor/drives with an "E" have an external encoder that can be wired to an external controller.



Standard NEMA 17 and 23 motor/drives



Advanced NEMA 17, 23, and 24 motor/drives

	SureStep Series Part Numbers Advanced Integrated Motor/Drives							
Integrated Motor/Drive	NEMA Size	Price	Drawing					
STP-MTRD-17030R	17	\$288.00	PDF					
STP-MTRD-17030RE	17	\$435.00	PDF					
STP-MTRD-17038R	17	\$296.00	PDF					
STP-MTRD-17038RE	17	\$433.00	PDF					
STP-MTRD-23042R	23	\$318.00	PDF					
STP-MTRD-23042RE	23	\$451.00	PDF					
<u>STP-MTRD-23065R</u>	23	\$316.00	PDF					
STP-MTRD-23065RE	23	\$458.00	PDF					
STP-MTRD-24075RV	24	\$414.00	PDF					
STP-MTRD-24075RVE	24	\$499.00	PDF					

Note: Advanced Integrated motor/drives with an "E" have an internal encoder used for stall prevention (cannot be wired to an external PLC or controller).



SureStep[®] Advanced Integrated Motor/Drives



Step/Public Step/IRD-23093KE Step/IRD-23083KE Step/IRD-23083KE Step/IRD-23083KE Step/IRD-23083KE Step/IRD-23083KE Step/IRD-23083KE Step/IRD-23083KE			Sur	eStep Integrated S	Series Specificatio	ns – Advanced			
reizternal pix required) 1240 VDC 1240 VDC Configuration Method SureMotion Pro software (SML-PEQ): free download) Carrent Controller Dual H-Bridge, 4 Quadrant, 4 state PVM @ 16kHz Dual H-Bridge, 4 Quadrant, 4 state PVM @ 20kHz Carrent Controller Dual H-Bridge, 4 Quadrant, 4 state PVM @ 16kHz Dual H-Bridge, 4 Quadrant, 4 state PVM @ 20kHz Encoder Feedback "E" models only. Encoder is internal and provides position verification and stall prevention control by default. Motor/Drive Protection 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Step Input, Jog CW, Limit CW, Start/Stop, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Step Input, Jog CW, Limit CW, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CW, Limit CW, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = analog control modes and general purpose analog usege; programmable for signal range, offset, dead band, an filtering 30/VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Netron Output, J	Inte	Integrated Motor/Drive		<u>17030RSTP-MTRD-</u> <u>17030RE</u>	<u>17038RSTP-MTRD-</u> <u>17038RE</u>		<u>STP-MTRD-23065R</u> <u>STP-MTRD-23065RE</u>		
Supply Output +4.85 volts @ 50m A maximum Current Controller Dual H-Bridge, 4 Quadrant, 4 state PVMM @ 16kHz Dual H-Bridge, 4 Quadrant, 4 state PVMM @ 20kHz Encoder Feedback "E" models only. Encoder is internal and provides position verification and stall prevention control by default. Motor/Drive Protection Stop/Pulse 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Step Input, Jog CW, Limit CW, Start/Stop, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CW, Limit CW, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CW, Limit CW, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, an filtering Output Signal 30VDC, 40mA maximum. Optically isolated, peen collector. Maximum pulse frequency 10kHz. Function = Brake Output, Ram Output, Tach Output, General Purpose Motor Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Releated from 200 to			quired)	12-48	VDC	12-70	VDC		
Current Controller Dual H-Bridge, 4 Quadrant, 4 state PWM @ 16kHz Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz Encoder Feedback "E" models only. Encoder is internal and provides position verification and stall prevention control by default. Short circuit, over-voltage, under-voltage, over-temp 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Step/Pulse 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Direction 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Bilter 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Bilter 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Analog 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Analog 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Analog 0-5 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current Analog 30VDC, 40mA maximum. Optically isolated. Open collector. Maximum pulse frequency 10kHz. Function = analog control modes and general purpose analog usage; progra	Con	figuration N	<i>lethod</i>		SureMotion Pro software	(<u>SM-PRO</u> : free download)			
Incoder Feedback	Sup	ply Output			+4.8 - 5 volts @	50mA maximum			
Motor/Drive Protection Short circuit, over-voltage, under-voltage, over-temp Step/Pulse 5-24 VDC nominal. Optically isolated. Minimum pulse witht = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Step Input, Jog CW. Limit CW. Start/Stop, General Purpose Direction 5-24 VDC nominal. Optically isolated. Minimum pulse witht = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW. Limit CCW, General Purpose Analog 5-24 VDC nominal. Optically isolated. Minimum pulse witht = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Age COW, Limit CCW, General Purpose Output Signal 5-24 VDC nominal. Optically isolated. Minimum pulse witht = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Reset Input, Charge Speed, General Purpose Output Signal 0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits Function = analog control modes and general purpose analog use; programmable for signal range, offset, dead band, an filtering Output Signal 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10KHz. Function = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface RS 485 ASCII Wicrostep Resolution Selectable in SureMotion Pro software Idle Current Reduction Reduction range of 0-30% of running current after delay selectable in	Curi	rent Control	ller	Dual H-Bridge, 4 Quadrar	nt, 4 state PWM @ 16kHz	Dual H-Bridge, 4 Quadrar	nt, 4 state PWM @ 20kHz		
Step/Pulse 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Step Input, Jog CW, Limit CW, Start/Stop, General Purpose Direction 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, Start/Stop, General Purpose Enable 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, General Purpose Analog 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, General Purpose Analog 0-5-24 VDC nominal. (NI referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits Function = analog control modes and general purpose analog usage, programmable for signal range, offset, dead band, an filtering Output Signal 30/VDC, 40mA maximum. Optically isolated open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface RS-485 ASCII Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Mide Current Reduction Selectable from 200 to 51200 s	Enco	oder Feedba	ack	"E" models only. Enco	der is internal and provides posi	tion verification and stall prevent	tion control by default.		
Step/Pulse Current draw = 12mA Function = Step Input, Jog CW, Limi CW, Start/Stop, General Purpose Direction 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limi CCW, General Purpose Enable 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Direction Input, Jog CCW, Limi CCW, General Purpose 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Reset Input, Change Speed, General Purpose 0-5 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum, resolution = 12 bits Function = analog control modes and general purpose analog usage, programmable for signal range, offset, dead band, an filtering Output Signal 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Marin Output, Motion Output, Tach Output, General Purpose Communication Interface RS-485 ASCII Non-votatile Microstep Resolution Selectable in SureMotion Pro software Idle Current Reduction Selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Microstep Resolution Selectable from 200 to 512000 Selectable in sureMotion Pro software Selectable res <th>Mot</th> <th>or/Drive Pr</th> <th>otection</th> <th></th> <th>Short circuit, over-voltage</th> <th>, under-voltage, over-temp</th> <th></th>	Mot	or/Drive Pr	otection		Short circuit, over-voltage	, under-voltage, over-temp			
Birection current draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, General Purpose Enable 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Reset Input, Change Speed, General Purpose Analog 0-5 VDC nominal (AIN referenced to GND). Input Impedance: 30K ohms minimum, resolution = 12 bits Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, an filtering OUTput J Signal 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface Reduction Selectable in SureMotion Pro software Current Reduction Reduction range of 0-90% of running current after delay selectable in ms Self Test Microsstep Resolution Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Self Test Commerctorst DC Power 2-position screw terminal: Weidmuller 1615780000 1/0 11-position spring cage: Phoenix 188154 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green		Step/Pulse	,		curi draw =	rent : 12mA			
Enable Grave = 12mA Grave = 12mA Function = Enable Input, Reset Input, Change Speed, General Purpose Analog 0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, an influening Output Signal 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface RS-485 ASCII Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Reduction range of 0-90% of running current after delay selectable in ms Microstep Resolution Software selectable form 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Self Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% LI/O 11-position spring cage: Phoenix 1881354 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Signals	Direction			cur draw =	rent : 12mA			
Analog Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, and filtering Output Signal 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface RS-485 ASCII Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Reduction range of 0-90% of running current after delay selectable in ms Idle Current Reduction Reduction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Set Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% I/0 11-position spring cage: Phoenix 1881454 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Input	Enable		current draw = 12mA					
Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose Communication Interface RS-485 ASCII Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Reduction Reduction range of 0–90% of running current after delay selectable in ms Microstep Resolution Mote software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Self Test Concectors I/O 11-position screw terminal: Weidmuller 1615780000 II/O OF Power Comm Colspan="2">Self Test DC Power Comm Common volspan= I/O OF Power Control Drive Cooling Wethod Non-volspan="2">Non-volspan= Self Test DC		Analog			les and general purpose analog	usage; programmable for signal			
Non-volatile Memory Storage Configurations are saved in FLASH memory on-board the DSP Current Reduction Selectable in SureMotion Pro software Idle Current Reduction Reduction range of 0–90% of running current after delay selectable in ms Microstep Resolution Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands self Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% I/O 11-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881419 Drive Cooling Wethod Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Outp	out Signal							
Current Reduction Selectable in SureMotion Pro software Idle Current Reduction Reduction range of 0–90% of running current after delay selectable in ms Microstep Resolution Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Self Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% Voltage 1/0 10 11-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881354 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Соп	nmunication	n Interface		RS-485	5 ASCII			
Idle Current Reduction Reduction range of 0–90% of running current after delay selectable in ms Microstep Resolution Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Self Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% Image: Connectors DC Power 2-position screw terminal: Weidmuller 1615780000 1/0 11-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881354 Drive Cooling Wethod Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Non	-volatile Me	emory Storage	Configurations are saved in FLASH memory on-board the DSP					
Microstep Resolution Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev Modes of Operation Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands Self Test Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40% Image: Connectors DC Power 2-position screw terminal: Weidmuller 1615780000 Image: Connectors Image: Connectors Comm 5-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881354 Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green		Current Re	duction		Selectable in Sure	Notion Pro software			
DC Power 2-position spring cage: Phoenix 1881419 I/O 11-position spring cage: Phoenix 1881419 Comme Cooling Method Natural convection (mount to suitable heat sink)	res				U	,			
DC Power 2-position spring cage: Phoenix 1881419 I/O 11-position spring cage: Phoenix 1881419 Comme Cooling Method Natural convection (mount to suitable heat sink)	eatu	· ·							
DC Power 2-position screw terminal: Weidmuller 1615780000 I/O 11-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881354 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green			Operation						
Connectors I/O 11-position spring cage: Phoenix 1881419 Comm 5-position spring cage: Phoenix 1881354 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green		Self Test		Checks internal and external			or resistance changes > 40%		
Comm 5-position spring cage: Phoenix 1881354 Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	DC Power		DC Power		2-position screw terminal	: Weidmuller 1615780000			
Drive Cooling Method Natural convection (mount to suitable heat sink) Status LEDs 1 red, 1 green	Con	nectors	1/0	11-position spring cage: Phoenix 1881419					
Status LEDs 1 red, 1 green			Comm		5-position spring cag	ge: Phoenix 1881354			
	Driv	e Cooling N	<i>lethod</i>		Natural convection (mor	unt to suitable heat sink)			
	Stat	us LEDs			1 red, 7	1 green			
Mounting Four M3 screws Four #6 screws	Мои	Inting		Four M3	screws	Four #6	screws		

www.automationdirect.com

Stepper Systems



SureStep[®] Advanced Integrated Motor/Drives

		Sure	Step Integrated Series Specifications – Advanced Variable I/O				
Integrated Motor/Drive			<u>STP-MTRD-24075RV</u> / <u>STP-MTRD-24075RVE</u>				
Input Voltage (external p/s required)		quired)	12-70 VDC				
Con	figuration I	Nethod	SureMotion Pro software (<u>SM-PRO</u> : free download)				
Sup	ply Output		+4.8 - 5 volts @ 50mA maximum				
Curi	ent Contro	ller	Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz				
Enco	oder Feedba	ack	"E" models only. Encoder is internal and provides position verification and stall prevention control by default.				
Mot	or/Drive Pr	otection	Short circuit, over-voltage, under-voltage, over-temp				
	I/O 1 (Step)/Pulse)	INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose				
e I/O	I/O 2 (Dire	ction)	INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Direction Input, Jog CCW, Alarm Reset Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose				
Variable I/O	1/0 3		INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Limit CW Input, Enable Input, Change Speed Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose				
	I/O 4		INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Limit CCW Input, Alarm Reset Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose				
Anal	log		0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits, Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, and filtering				
Com	munication	n Interface	RS-485 ASCII (2- or 4-wire)				
Non	-volatile Me	emory Storage	Configurations are saved in FLASH memory on-board the DSP				
	Current Re	eduction	Selectable in SureMotion Pro software				
sə.	Idle Curre	nt Reduction	Reduction range of 0–90% of running current after delay selectable in ms				
Features	Microstep	Resolution	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev				
Modes of Opera		Operation	Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands				
Self Test			Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40%				
	DC Power		2-position screw terminal: Weidmuller 1615780000				
Con	nectors	1/0	11-position spring cage: Phoenix 1881419				
		Comm	5-position spring cage: Phoenix 1881354				
Driv	e Cooling I	Nethod	Natural convection (mount to suitable heat sink)				
Stat	us LEDs		1 red, 1 green				
Мои	nting		Four #6 screws				



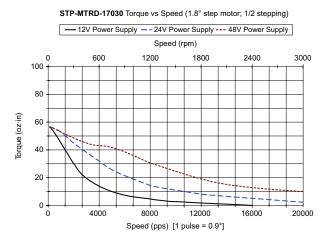
SureStep[®] Advanced Integrated Motor/Drives

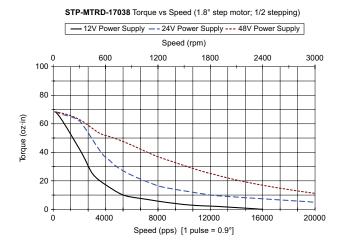
		SureStep In	tegrated Series	Specifications –	Advanced			
Integrated Motor/Driv	/e	STP-MTRD-17030R STP-MTRD-17030RE	STP-MTRD-17038R STP-MTRD-17038RE	STP-MTRD-23042R STP-MTRD-23042RE	<u>STP-MTRD-23065R</u> <u>STP-MTRD-23065RE</u>	<u>STP-MTRD-24075RV</u> STP-MTRD-24075RVE		
NEMA Frame Size		NEMA 17	NEMA 17	NEMA 23	NEMA 23	NEMA 24		
	(lb∙in)	3.375	4.25	7.8125	13.125	21.25		
* Maximum Holding Torque	(oz∙in)	54	68	125	210	340		
Torque	(N·m)	0.381326	0.480189	0.8827	1.482936	2.400944		
Dotor Inortio	(oz∙in2)	0.310	0.448	1.420	2.515	4.900		
Rotor Inertia	(kg·cm2)	0.057	0.082	0.260	0.460	0.897		
Insulation Class				Class B (130°C)				
Basic Step Angle				1.8 degrees				
Shaft Runout (in)		0.0	03		0.05			
Max Shaft Radial Pla load	y @ 1lb			0.02				
Perpendicularity (mn	ı)	0.08						
Concentricity (mm)		0.05						
* Maximum Radial Lo (lb [kg])	oad	6.7		13.9				
* Maximum Thrust Lo (lb [kg])	ad	3	4		63			
Storage Temperature	Range	0-40°C (32-104°F)						
Operating Temperatu	re Range	0-85°C 0-70°C						
Operating Humidity R	lange	90% max, non-condensing						
Product Material		Aluminum, steel, plastic, FR4, etc.						
Environmental Rating				IP40				
Weight (oz [g])		12.7 [360]	15.6 [441]	30 [850]	42 [1191]	56 [1580]		
Agency Approvals		CE*						
Design Tips		Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. DO NOT connect or disconnect the step motor during operation. Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. Jse a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings from minor misalignment and to prevent loosening due to vibration.						

* For NEMA 24 motors, an EMI filter (RES10F03) is needed on the power supply for CE compliance.

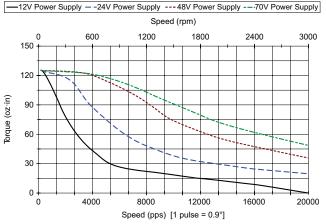


SureStep[®] Integrated Motor/Drives Motor Torque vs. Speed

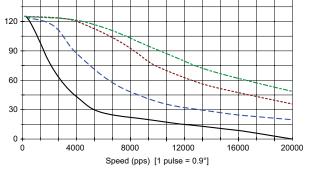


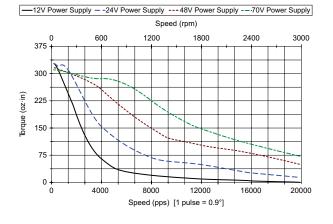


STP-MTRD-23042 Torque vs Speed (1.8° step motor; 1/2 stepping)

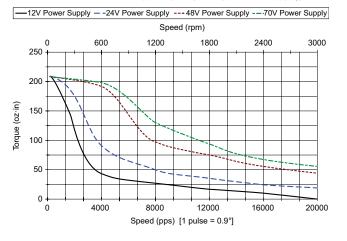


STP-MTRD-24075 Torque vs Speed (1.8° step motor; 1/2 stepping)





STP-MTRD-23065 Torque vs Speed (1.8° step motor; 1/2 stepping)

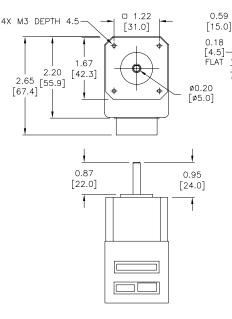


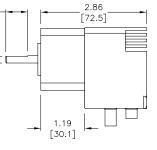


SureStep[®] Advanced Integrated Motor/Drives Dimensions

Dimensions = in [mm]

STP-MTRD-17030R / STP-MTRD-17030RE

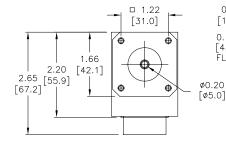


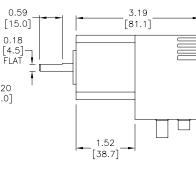


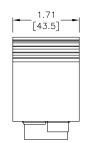


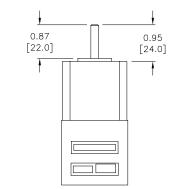
NOTE: Encoder is internal only - not available externally

STP-MTRD-17038R / STP-MTRD-17038RE









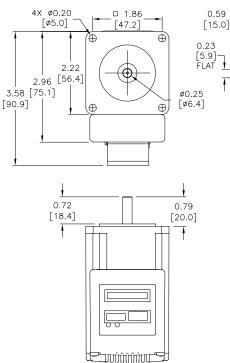
NOTE: Encoder is internal only - not available externally

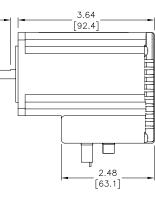


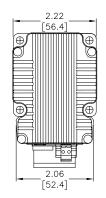
SureStep[®] Advanced Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]

STP-MTRD-23042R / STP-MTRD-23042RE

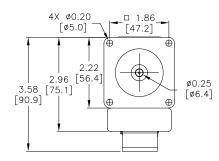


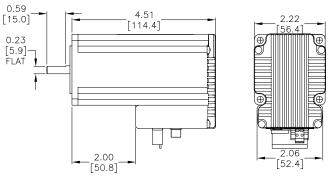




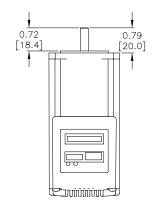
NOTE: Encoder is internal only - not available externally

STP-MTRD-23065R / STP-MTRD-23065RE





NOTE: Encoder is internal only - not available externally



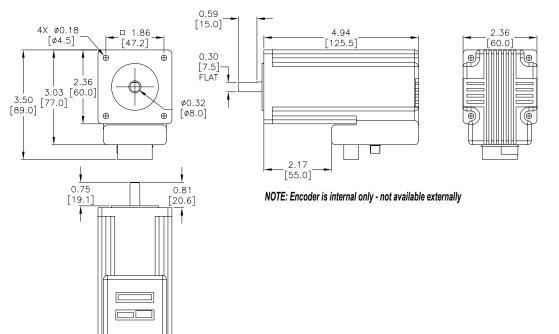


SureStep[®] Advanced Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]

STP-MTRD-24075RV / STP-MTRD-24075RVE

uuuu





SureStep[®] Microstepping Drives Accessories

Braking Accessories

As a load rapidly decelerates from a high speed, much of the kinetic energy of that load is transferred back to the motor. This energy is then pushed back to the drive and power supply, resulting in increased system voltage. If there is enough overhauling load on the motor, the DC voltage will go above the drive and/or power supply limits. In general, the more torque the motor is capable of producing then the more energy it can push back into the drive.

When using a regulated/switching power supply, this can trip the overvoltage protection of the power supply or drive, and cause it to shut down.

To solve this problem, AutomationDirect offers a regeneration clamp as an optional accessory. The regen clamp has a built-in 50W braking resistor. The STP-DRVA-RC-050A does not have the ability to use an external resistor.

Regeneration Clamp Features

STP-DRVA-RC-050A

- Built-in 50W power resistor for more continuous current handling
- Mounted on a heat sink
- Voltage range: 24-80 VDC; no user adjustments required
- Power: 50W continuous; 800W peak
- Indicators (LED): Green = power supply voltage is present Red = clamp is operating (usually when stepper is decelerating)
- Protection: The external power supply is internally connected to an "Input Diode" in the regen clamp that protects the power supply from high regeneration voltages. This diode protects the system from connecting the power supply in reverse. If the clamp circuit fails, the diode will continue to protect the power supply from over-voltage.

SureStep Damper

A step motor inertia damper can smooth out steps in a typical step motor resulting in a quieter and smoother motion when rotating between steps. Reducing the resonance and possible micro oscillations when moving from step to step is the main purpose of a "hockey puck" style damper, but it can also be used as a hand wheel to directly rotate the position of the rotor when power is removed from the motor. The damper is a properly sized machined piece of aluminum encased in plastic. It is sized and weighted for general damping of the respective frame size motor.



Regeneration Clamp STP-DRVA-RC-050A

- Three drive connections, 7A max per channel, 15A total output current
- Removable terminal blocks (replacement kit STP-CON-4)
- Uses 18-20 AWG wire for connections



Sure Ste	Sure Step Series Specifications – Microstepping Drives Optional Accessories						
Part Number	art Number Price Description						
STP-DRVA-RC-050A*		Regen Clamp: 50W, for DC input stepper and servo drives, enclosed	PDF				
STP-MTRA-17DMP	STP-MTRA-17DMP \$15.00 SureStep damper, metal body. For use with NEMA 17 stepper motors with 5mm shafts. Mounting set screw included.						
STP-MTRA-23DMP	Sure Stan damper, metal body. For use with NEMA 23 stepper metars with 1/4 inch shefts. Mounting set						

* Do not use the regeneration clamp in an atmosphere containing corrosive gases.

0.20 [5.0]

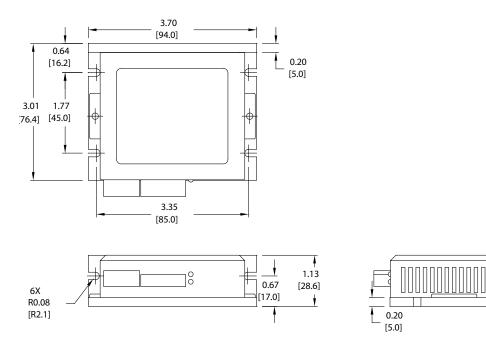


Stepping System Accessories

SureStep[®] Microstepping Drives Accessories

Dimensions = in [mm]

STP-DRVA-RC-050A





SureStep[®] Microstepping Drives Accessories

USB to RS-485 Adapter

The <u>STP-USB485-4W</u> is a USB to RS-232/RS-485 converter that can be used in 2-wire or 4-wire serial networks. Serial communication can be wired up via the 9-pin D-sub connector or through the 6-screw terminals.

The STP-USB485-4W can be set for several different configurations. These modes are set up by the 4 DIP switches on the outside of the case (RS-232/RS-485, full/half duplex) and by the 7 jumpers located inside the case (termination/bias resistors).

SureStep Advanced Drives communicate via RS-232 (for control and for configuration via SureMotion Pro).

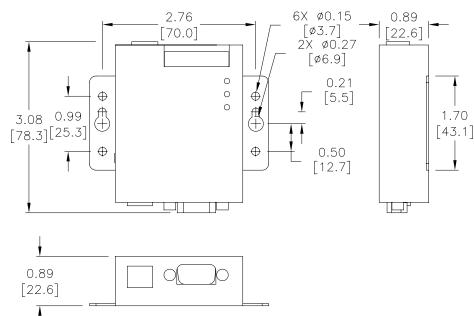
The Advanced Integrated motor/drives use RS-485. While the Advanced Integrated motor/drives can be wired for either 2- or 4-wire networks, 4-wire is require for use with SureMotion Pro due to the Firmware Download utility and the Status Monitor Screen.

Depending on the host controller's RS-485 implementation, either 2- or 4-wire RS-485 can be used for control. All RS-485 PLCs that have 2-wire capability (Productivity, BRX, Click, DirectLogic, etc.) can control the Advanced Integrated steppers.



SureStep PC A	dapter - <u>STP-USB485-4W</u>
Price	\$129.00
Drawing	PDF
Communications	2-wire RS-232 2- or 4-wire RS-485
Configure With	Internal jumpers and external DIP switches
Compatible Cables	STP-232RJ11-CBL STP-485DB9-CBL-2 USB

Dimensions = in [mm]





SureStep[®] Stepping System Encoders

Replacement Encoders

The <u>STP-MTRA-ENC1</u> is a replacement for the encoder that comes standard with the <u>STP-MTRD-17038E</u>, <u>STP-MTRD-23042E</u>, and <u>STP-MTRD-23065E</u> integrated motor/drives. Note that the encoder included with (E) model advanced integrated motor/drives is internal and cannot be replaced.

The <u>AMT112Q-V</u> is a replacement for the encoder that comes standard with the STP-MTR(x)-xxxxE stand alone step motors.

Installation tool and mounting hardware is included with all replacement encoders. For more information and details on how to wire the replacement encoders, please see the SureStep User Manual.

Optional Encoders

Optional encoders can be purchased separately for standard integrated motor/drives and standalone dual-shaft motors in all NEMA 14, 17, and 23 sizes, and also for STP-MTRAC-34xxxD motors (currently not available for STP-MTRx-34xxxD motors). All (D) model (dual-shaft) step motors come with pre-drilled holes in the rear end cap for easy encoder mounting. Pre-installed encoders on standalone dual-shaft motors and standard integrated motor/drives can be retrofitted with an appropriate optional encoder if desired. Please see the chart on the following page for encoder compatibility.

Features:

- Fixed resolutions include 400ppr or 1000ppr
- Configurable models have up to 4096ppr (default = 400ppr)
- Choose line driver or push-pull (totem) output signals



STP-MTRA-ENC2





STP-MTRA-ENC11

	Sure Step Series Specifications – Encoders						
Part Number	Price	Description	Drawing				
<u>STP-MTRA-ENC1</u>	\$91.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
STP-MTRA-ENC2	\$79.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC3</u>	\$89.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC4</u>	\$76.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC5</u>	\$91.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC6</u>	\$79.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC7</u>	\$89.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	PDF				
<u>STP-MTRA-ENC8</u>	\$76.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.	<u>PDF</u>				
<u>STP-MTRA-ENC11</u>	\$72.00	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.	PDF				
STP-MTRA-ENC12	\$60.00	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.	<u>PDF</u>				
STP-MTRA-ENC13	\$61.00	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.	<u>PDF</u>				
STP-MTRA-ENC14	\$52.00	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.	<u>PDF</u>				



SureStep[®] Stepping System Encoders

		Sure Ste	p Series Enco	der Compatib	oility	
Part Number	PPR	Bore Diameter	Output Type	Encoder Cable	PLC Compatibility	Motor Compatibility
STP-MTRA-ENC1	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-14xxxD
<u>STP-MTRA-ENC2</u>	400	- 5mm	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-14xxE STP-MTRx-17xxD
STP-MTRA-ENC3		mmc	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-17xxxE Standard STP-MTRD- xxxxxE
<u>STP-MTRA-ENC4</u>			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	
STP-MTRA-ENC5	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	
<u>STP-MTRA-ENC6</u>		- 0.25 inch	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-23xxxD
STP-MTRA-ENC7	400	0.25 inch	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	STP-MTRx-23xxxE STP-MTRAC-23xxxD
<u>STP-MTRA-ENC8</u>			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	
STP-MTRA-ENC11	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	
<u>STP-MTRA-ENC12</u>	400	- 0.375 inch	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	STP-MTRAC-34xxxD
STP-MTRA-ENC13		0.375 11101	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0- 1xDxE-D*	317-WIKA0-34XXD
<u>STP-MTRA-ENC14</u>			Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0- 1xDxE-D*	<u> </u>

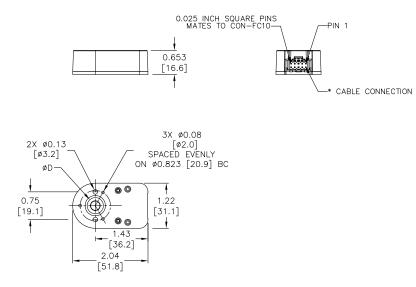
* Requires FC-ISO-C



SureStep[®] Stepping System Encoders

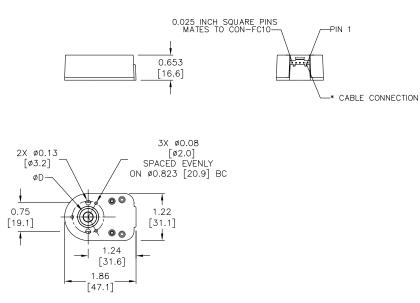
Dimensions = in [mm]

STP-MTRA-ENC1, 3, 5, 7



Bolt Hole Circles for Mounting				
Encoder Holes				
ENC1, ENC2, ENC3, ENC4, ENC5, ENC6, ENC7, ENC8	2 holes @ 19.05mm (.75") 3 holes @ 20.9mm (.823")			

STP-MTRA-ENC2, 4, 6, 8

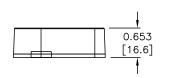


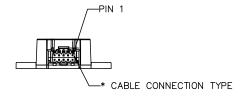


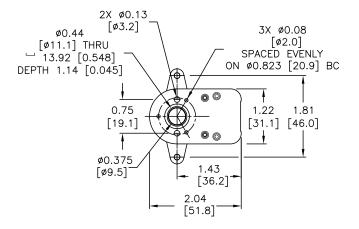
SureStep[®] Stepping System Encoders

Dimensions = in [mm]

STP-MTRA-ENC11, 13



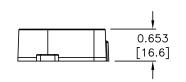


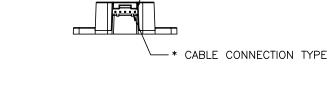


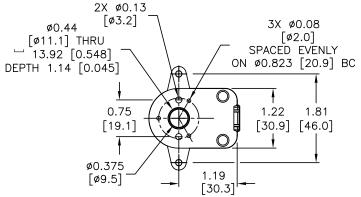
Bolt Hole Circles for Mounting					
Encoder Holes					
ENC11, ENC12, ENC13, ENC14	2 holes @ 19.05mm (.75") 3 holes @ 20.9mm (.823") 2 holes @ 46.02mm (1.812")				

PIN 1

STP-MTRA-ENC12, 14









Stepping System Cables

SureStep[®] Cables

		Sur <u>eStep Se</u>	ries <u>– S</u>	tepping System Cables		
Cable	Price	Purpose	Length	Use With	Cable End Connectors	Drawing
STP-EXT-006	\$13.00		6 ft			PDF
STP-EXT-010	\$14.50		10 ft	STP-MTR-xxxxx(x)	pigtail / Molex 43020-0401 connector	PDF
STP-EXT-020	\$18.50		20 ft			PDF
STP-EXTH-006	\$26.50		6 ft			PDF
STP-EXTH-010	\$31.50		10 ft	STP-MTR H -xxxxx(x)	pigtail / Molex 39-01-2041 connector	PDF
STP-EXTH-020	\$38.00		20 ft			PDF
STP-EXTHW-006	\$57.00		6 ft			PDF
STP-EXTHW-010	\$69.00	motor to drive extension	10 ft	STP-MTR HW -xxxxx(x)	Bulgin # PXP4011/06P/6065	PDF
STP-EXTHW-020	\$105.00		20 ft		PDF	
STP-EXTL-006	\$11.50		6 ft			PDF
STP-EXTL-010	\$14.50		10 ft	STP-MTRL-xxxxx(x)	pigtail / Molex 105308-22004 connector	PDF
STP-EXTL-020	\$18.00		20 ft			PDF
TP-EXTW-006	\$56.00	1	6 ft			PDF
TP-EXTW-010	\$68.00		10 ft	STP-MTR W -xxxxx(x)	Bulgin # PXP4011/06P/6065	PDF
TP-EXTW-020	\$99.00		20 ft			PDF
TP-EXT42-006	\$29.00		6 ft			PDF
TP-EXT42-010	\$34.00		10 ft	STP-MTRAC-42xxxx	-	PDF
TP-EXT42-020	\$49.00		20 ft			PDF
TP-EXT42H-006	\$29.00	motor to drive extension	tor to drive extension 6 ft		10-pin / pigtail	PDF
TP-EXT42H-010	\$34.00	0 10 ft STP-MTRACH-42xxxxx	-	PDF		
TP-EXT42H-020	\$49.00	-	20 ft		_	PDF
STP-232RJ11-CBL*	\$15.00	programming/ communication	10 ft	STP-DRV-4850, STP-DRV-80100	DB9 female / RJ11(6P4C)	PDF
STP-232HD15-CBL-2**	\$19.00	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL06, D2-250-1, D2-260	HD 15-pin male / RJ12 6-pin plug	n/a
STP-232RJ12-CBL-2**	\$12.00	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL05, CLICK	RJ11 (6P4C) plug / RJ12 6-pin plug	n/a
STP-CBL-CA6	\$32.00	control cable	6 ft		11-pin / pigtail	PDF
STP-CBL-CA10	\$47.00	control cable	10 ft	STP-MTRD-17038 STP-MTRD-17038E	11-pin / pigtail	PDF
STP-CBL-CA20	\$85.00	control cable	20 ft		11-pin / pigtail	PDF
TP-CBL-EA6	\$31.00	encoder cable	6 ft	STP-MTRD-xxxxxE	10-pin / pigtail	PDF
STP-CBL-EA10	\$37.00	encoder cable	10 ft	STP-MTRA-ENC1, STP-MTRA-ENC3 STP-MTRA-ENC5, STP-MTRA-ENC7	10-pin / pigtail	PDF
STP-CBL-EA20	\$52.61	encoder cable	20 ft	STP-MTRA-ENC11, STP-MTRA-ENC13 (for line driver encoders)	10-pin / pigtail	PDF
STP-CBL-EB3	\$60.00	encoder cable	3 ft	AMT4400 \/	17-pin / pigtail	PDF
TP-CBL-EB6	\$83.00	encoder cable	6 ft	AMT112Q-V AMT112S-V	17-pin / pigtail	PDF
TP-CBL-EB10	\$113.00	encoder cable	10 ft	(for both line driver and push-pull (totem)	17-pin / pigtail	PDF
TP-CBL-EB20	\$187.00	encoder cable	20 ft	encoders)	17-pin / pigtail	PDF
TP-CBL-ED6	\$34.00	encoder cable	6 ft	STP-MTRA-ENC2, STP-MTRA-ENC4	5-pin / pigtail	PDF
TP-CBL-ED10	\$46.00	encoder cable	10 ft	STP-MTRA-ENC6, STP-MTRA-ENC8 STP-MTRA-ENC12, STP-MTRA-ENC14	5-pin / pigtail	PDF
TP-CBL-ED20	\$55.00	encoder cable	20 ft	(for push-pull (totem) encoders)	5-pin / pigtail	PDF
STP-CON-1	\$31.00	replacement connector kit	n/a	STP-DRV-4845 & -6575	-	n/a
STP-CON-2	\$31.00	replacement connector kit	n/a	STP-DRV-4850 & 80100	-	n/a

* Refer to the ZIPLinks Wiring Solutions section for complete information regarding cables STP-232HD15-CBL-2 and STP-232RJ12-CBL-2.

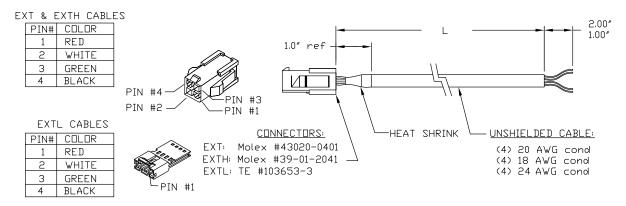
1-800-633-0405

Stepping System Cables

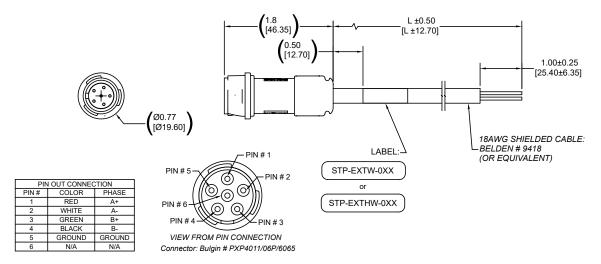
SureStep[®] Cables, continued

SureStep Series – Stepping System Cables								
Cable	Price	Purpose	Length	Use With	Cable End Connectors	Drawing		
STP-CON-3	\$62.00	replacement connector kit	n/a	STP-MTRD-xxxxR	-	n/a		
STP-CON-4	\$28.62	replacement connector kit	n/a	STP-DRVA-RC-050A	-	n/a		
STP-CON-5	\$28.62	replacement connector kit	n/a	STP-DRV-4830	-	PDF		
STP-CON-6	\$34.12	replacement connector kit	n/a	STP-DRVAC-24025	-	n/a		
<u>STP-485DB9-CBL-2</u>	\$52.00	4-wire programming cable	6.5 ft	STP-MTRD-xxxxR	DB9 / Phoenix 5-conductor plug	PDF		

STP-EXT(x)-0xx Extension Cable Wiring Diagram



STP-EXTW-0xx and STP-EXTHW-0xx Extension Cable Wiring Diagram

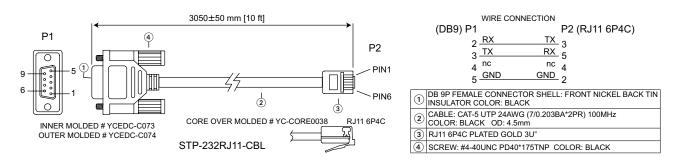




Stepping System Cables

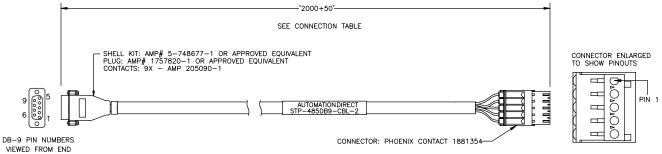
SureStep[®] Cables, continued

STP-232RJ11-CBL Programming Cable Wiring Diagram



STP-485DB9-CBL-2 4-wire Programming Cable Wiring Diagram

CONNECTION CHART								
DB-9 CONN	DB9 SIGNAL	WIRE COLOR	PHOENIX	PHOENIX				
PIN	DB9 SIGNAL	WIRE COLOR	PIN	SIGNAL				
2	TX+	RED	5	RX+				
1	TX-	ORANGE	4	RX-				
3	RX+	BLACK	3	TX+				
4	RX-	BROWN	2	TX-				
5	GND	YELLOW	1	GND				
METAL HOUSING	SHIELD	SHIELD	N/C	N/C				

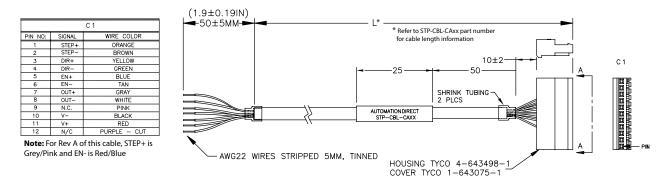




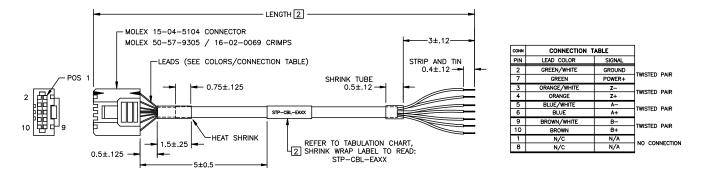
Stepping System Cables

SureStep[®] Cables, continued

STP-CBL-CAxx Control Cable Wiring Diagram



STP-CBL-EAxx Encoder Cable Wiring Diagram



WIRE: 24AWG, CABLE: UL2464.

STP-CBL-EBxx Encoder Cable Wiring Diagram

