1-800-633-0405

For the latest prices, please check AutomationDirect.com.

AC Servo Systems



Drive features

• Power:

- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW
- Fully digital with up to 3.1 kHz bandwidth velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the SureServo2 Pro PCbased software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- Communications include:
- Serial Modbus (native/built-in)
- Optional Modbus TCP card
- Optional Ethernet/IP card (this card can use implicit and explicit messaging. SureServo2 Pro software can generate an EDS file to transfer custom data between PLC and drive)
- · Command options include:
- ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
- Powerful built-in motion controller for position control using 99 preset positions (enter these during development, or send them through the communications options above during runtime)
- Internal sequencing for position/speed

SureServo2 tuning technology

The SureServo2 drive closes the loop on current, velocity, and position (depending on control mode selection). The 3.1 kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and five (5) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can easily tune systems with as much as 60:1 inertia mismatch.

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- One Touch Auto Tuning-the drive tunes the motor without any motion (static motor/ system analysis)
- Normal Auto Tuning-the drive tunes the load while an external controller or the drive's internal indexer provides point-to-point moves
- Assisted Tuning-3 modes where the drive tunes the motor while moving. The user can adjust responsiveness while the drive is analyzing the system
- Manual Tuning-20+ parameters are available to give power users the ultimate flexibility to tune their systems.



commands, registration (capture/compare), electronic camming, homing (10 different options), Jumps, and arithmetic statements.

- The 3.1 kHz bandwidth allows for high-level automatic tuning. Several modes of tuning are available including Auto Tune that can estimate the load inertia and fine-tune the system when all the loads are attached.
- Optically isolated digital inputs (10) and outputs (6), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution).
- Other Features:
 - Secondary/Auxiliary encoder feedback (for true closed loop control)
 - Registration ability
 - Analog positioning
 - Safe Torque Off (STO) included so no need for large, bulky contactors to disconnect power from the drive in E-stop situations
 - Absolute Encoder operation (with optional encoder battery backup)
 - Electronic camming (you can define the cam with SureServo2 Pro software or you can import an Excel spreadsheet)
 - Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.

SureServo2 Built-in motion controller

While the SureServo2 drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to 99 index moves can be pre-defined and stored in the drive and then selected and executed using digital inputs (inputs as events or inputs used as a multiplexer) or communication (serial Modbus, Modbus TCP, or Ethernet/IP). The index profiles can also be changed while in-process with digital events or via comms. The internal motion can consist of incremental or absolute moves, and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial/Ethernet communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful motion controller inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion

Motor features

- · Low inertia models:
 - 100W, 200W, 400W, 750W, 1kW, 1.5 kW, and 2kW
- Speeds up to 6,000 rpm • Medium inertia models:
- 1kW, 1.5 kW, 2kW, and 3kW
- Speeds up to 3,000 rpm
- · High inertia models:
- 3kW, 4.5 kW, 5.5 kW, 7.5 kW, 11kW, and 15kW
- Speeds up to 3,000 rpm
- Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style couplings
- Integrated encoder with 16,777,216 encoder pulses/revolution plus marker pulse (once per revolution)
- Optional 24 VDC spring-set holding brakes (xxxxB series motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for brake motors 230V systems 5.5kW and larger or 460V systems 11kW and larger)
- · Motor cables available in standard or flexrated lengths of 3, 5, 10, and 20m
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 20-pin spring clamp terminal block (limited I/O) that mounts directly to the drive

SureServo2 **Optional Holding Brake**

Each SureServo2 motor rating can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

SureGear[®] Precision Gearboxes for Servo motors

Inertia balancing issue in your design?



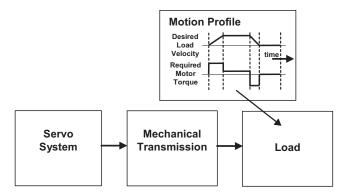
- Four gear ratios available (5, 10, 15, 25:1)
- Mounting hardware included for attaching to SureServo2 motors
- Industry-standard mounting dimensions
- · Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty



AC Servo Systems

How to select and apply SureServo2 systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo2 system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement. SureServo2 Pro has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.



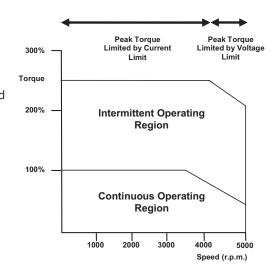
1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system. AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from www. automationdirect.com on the store page for your drive.

In general, applications that need high response or bandwidth will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo2 systems may be tuned manually, fully Automatically, or via a hybrid mode where the software tunes the system with input for system responsiveness from the user.

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have a SureServo2 system, these values are easily captured and recorded with the Scope feature built into SureServo2 Pro. If you are designing the system, use VisualSizer to define the system and calculate expected inertia and required power.





AC Servo Systems

Application tip - coupling considerations

The SureServo2 motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider the stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a tradeoff between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo2 **peak** torque requirement of your application.

Available Couplings

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo2 systems can go up to 6,000 rpm for the low inertia motors and up to 3,000 rpm for the medium inertia motors.

Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo

system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

SureServo2 motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.

For more information, refer to the website listed below.

Mechanical Transmission: <u>Timing Belts and Pulleys</u> <u>Precision Gearboxes</u>

Ordering guide instructions

The following four pages are your ordering guide for SureServo2 systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

Each system needs:

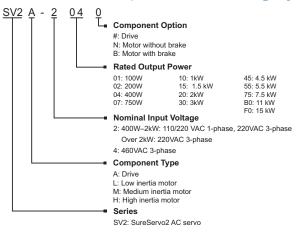
- MotorDrive
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either CN1 cable + RTB breakout board, or an LTB20 breakout board that mounts on the drive)
- For brakemotors 4.5 kW and below, the brake wiring is included in the power cable. For brakemotors 5.5 kw and above, a separate brake cable is required.

A wide variety of optional accessories are also available, such as Ethernet cards, RS485 splitters/terminators, toroids, etc.

You can also use the SureServo2 selector tool on the AutomationDirect.com website to help you configure your system.



SureServo2 series drives and motors part numbering system



Here is what you will need to order a complete servo system:



NOTE: Unit can be programmed via keypad. Optional programming software (free download) and optional programming cable available.

NOTE: If you need a gear box for your configuration, you can do it easily online: http://www.sureservo.com/gearbox/selector





Torque to SureServo2 System Quick Reference

	230V System Torque								
System Rated Torque (N·m)	System Maximum Torque (N∙m)	Suggested Servo Motor	Required Servo Drive						
0.32	1.12	SV2L-201N or SV2L-201B	<u>SV2A-2040</u>						
0.64	2.24	SV2L-202N or SV2L-202B	<u>SV2A-2040</u>						
1.27	3.96	SV2L-204N or SV2L-204B	<u>SV2A-2040</u>						
2.39	7.86	SV2L-207N or SV2L-207B	<u>SV2A-2075</u>						
3.18	8.12	SV2L-210N or SV2L-210B	<u>SV2A-2150</u>						
4.77	14.32	SV2M-210N or SV2M-210B	<u>SV2A-2150</u>						
7.16	14.88	SV2M-215N or SV2M-215B	<u>SV2A-2150</u>						
9.55	24.54	SV2M-220N or SV2M-220B	<u>SV2A-2200</u>						
17.55	48.29	SV2M-230N or SV2M-230B	<u>SV2A-2300</u>						
28.65	71.62	SV2H-245N or SV2H-245B	<u>SV2A-2550</u>						
35.01	87.53	SV2H-255N or SV2H-255B	<u>SV2A-2550</u>						
47.74	119.36	SV2H-275N or SV2H-275B	<u>SV2A-2750</u>						
70	175	SV2H-2B0N or SV2H-2B0B	SV2A-2F00						
95.4	224.0	SV2H-2F0N or SV2H-2F0B	<u>SV2A-2F00</u>						

	460V System Torque							
System Rated Torque (N∙m)	System Maximum Torque (N∙m)	Suggested Servo Motor	Required Servo Drive					
1.27	4.45	<u>SV2L-404N</u> or <u>SV2L-404B</u>	<u>SV2A-4040</u>					
2.24	7.58	<u>SV2L-407N</u> or <u>SV2L-407B</u>	<u>SV2A-4075</u>					
3.18	9.54	<u>SV2L-410N</u> or <u>SV2L-410B</u>	<u>SV2A-4150</u>					
4.77	14.32	<u>SV2M-410N</u> or <u>SV2M-410B</u>	<u>SV2A-4150</u>					
7.16	18.1	<u>SV2L-415N</u> or <u>SV2L-415B</u>	<u>SV2A-4150</u>					
9.55	28.65	<u>SV2L-420N</u> or <u>SV2L-420B</u>	<u>SV2A-4200</u>					
19.1	49.38	SV2H-430N or SV2H-430B	<u>SV2A-4300</u>					
28.65	64.61	<u>SV2H-445N</u> or <u>SV2H-445B</u>	SV2A-4550					
35.01	73.48	<u>SV2H-455N</u> or <u>SV2H-455B</u>	<u>SV2A-4550</u>					
47.74	93.71	<u>SV2H-475N</u> or <u>SV2H-475B</u>	<u>SV2A-4750</u>					
70	175	<u>SV2H-4B0N</u> or <u>SV2H-4B0B</u>	SV2A-4F00					
95.4	224.0	SV2H-4F0N or SV2H-4F0B	SV2A-4F00					



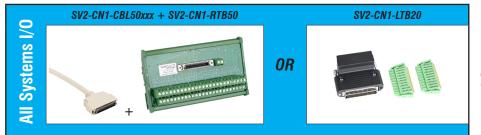
SureServo2 AC servo drive, motor, and cable combinations

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(350%) F	<u>SV2L-201N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
em	120V	EF, and a second secon		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
100W Low Inertia System	1200	0.32 (100%) Continuous Region	<u>SV2L-201B</u>	012112040	SV2C-PB18-xxNB	SV2C-E122-xxNN
Inertia		1,600 3,000 4,200 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
/ Low		1.12	SV/2L-201N	<u>SV2A-2040</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
100M	230V	(188%) 0.60 0.50 0.22 (188%) 0.32 (100%) 0.16 (50%) Continuous Region 3,000 4,800 6,000 Speed (r/min)	<u>SV2L-201N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
			<u>SV2L-201B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
	120V	(350%)	<u>SV2L-202N</u>	<u>SV2A-2040</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
n		E about the second sec			SV2C-PA18-xxFN	SV2C-E122-xxFN
Syster		0.64 (100%) Continuous Region			SV2C-PB18-xxNB	SV2C-E122-xxNN
ertia		1,400 3,000 3,700 Speed (r/min)	<u>SV2L-202B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
200W Low Inertia System		224 (350%)	SV2L-202N		SV2C-PA18-xxNN	SV2C-E122-xxNN
MOO	230V	1.90 (297%) (E: 2010) (297%) Intermittent Region	<u>3v2L-20211</u>	- <u>SV2A-2040</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
2	230V	0.64 (100%) 0.32 Continuous Region	<u>SV2L-202B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
		(50%) 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

SV2C-xxxx-xxNB is a non-flex, brake motor cable

The final two digits indicate flex rating and motor brake compatibility: SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







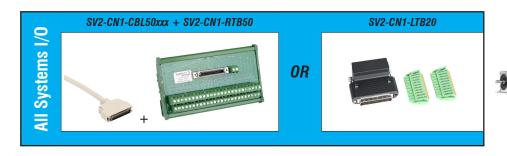
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(m-N	3.96 (312%)	<u>SV2L-204N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2040</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200		1.27 (100%) Continuous Region	<u>SV2L-204B</u>	<u>372A-2040</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,000 2,700 3,600 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
System			3.96 (312%) 3.48 2724%)	SV2L-204N		SV2C-PA18-xxNN	SV2C-E122-xxNN
400W Low Inertia System	230V	Torque (N-m)	Intermittent Region		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
N LOW	2300	Tor	1.27 (100%) 0.65 Continuous Region	<u>SV2L-204B</u>	<u></u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
400			(50%) 3,000 4,400 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
			4.45 (350%)			SV2C-PA18-xxNN	SV2C-E122-xxNN
	1001	Torque (N-m)	3.45 (272%) Intermittent Region	SV2L-404N	SV2A-4040	SV2C-PA18-xxFN	SV2C-E122-xxFN
	460V	ToT	1.27 (100%) 0.65 (50%) Continuous Region	SV2L-404B		SV2C-PB18-xxNB	SV2C-E122-xxNN
			(50%) Continuous Region 3,000 3,900 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







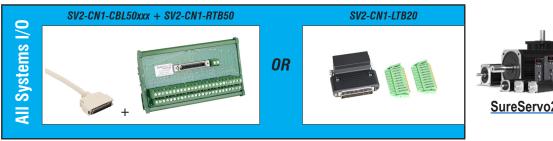
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		2	7.86 (329%)	<u>SV2L-207N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2075</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200		2.39 (100%) Continuous Region	<u>SV2L-207B</u>	<u>572A-2075</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,300 2,550 3,200			SV2C-PB18-xxFB	SV2C-E122-xxFN
System		Torque (N-m)	7.86 (329%) 6.63	SV2L-207N	<u>SV2A-2075</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
750W Low Inertia System	230V		(277%) Intermittent Region	<u>3V2L-207N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low		Torq	2.39 (100%) Continuous Region	<u>SV2L-207B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
750			1.195 (50%) 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
			7.58 (338%) 6.48	SV2L-407N		SV2C-PA18-xxNN	SV2C-E122-xxNN
	460V	Torque (N-m)	(289%) Intermittent Region	3V2L-40/N	- SV2A-4075	SV2C-PA18-xxFN	SV2C-E122-xxFN
	4007	Tor	2.24 (100%) 1.195 (53%)	SV2L-407B		SV2C-PB18-xxNB	SV2C-E122-xxNN
			(53%) Continuous Region 3,200 4,350 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





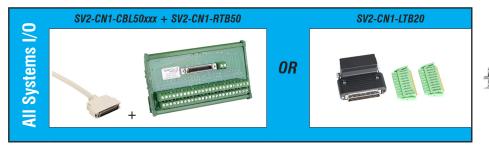
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(4	8.12 (255%)		SV2L-210N		SV2C-PC16-xxNN	SV2C-E222-xxNN
	120V	Torque (N-m)		Intermittent Region		01/04 0450	SV2C-PC16-xxFN	SV2C-E222-xxFN
	1200		3.18 (100%)	Continuous Region	SV2L-210B	<u>SV2A-2150</u>	SV2C-PC16-xxNB	SV2C-E222-xxNN
1			L	1,800 2,800 3,500	0721-2100		SV2C-PC16-xxFB	SV2C-E222-xxFN
Systen	230V		8.12 (255%)		<u>SV2L-210N</u>	— <u>SV2A-2150</u>	SV2C-PC16-xxNN	SV2C-E222-xxNN
1.0 kW Low Inertia System		Torque (N-m)		Intermittent Region			SV2C-PC16-xxFN	SV2C-E222-xxFN
W Low		Torq	3.18 (100%)	Continuous Region	<u>SV2L-210B</u>		SV2C-PC16-xxNB	SV2C-E222-xxNN
1.0 k			1.91 (60%)	3,000 3,300 5,000 Speed (r/min)	0721-2100		SV2C-PC16-xxFB	SV2C-E222-xxFN
			9.54 (300%)				SV2C-PC16-xxNN	SV2C-E222-xxNN
	460V	Torque (N·m)		Intermittent Region	SV2L-410N	SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
	4007	þ	3.18 (100%) 1.91 (60%)	Continuous Region	SV2L-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
				3,000 5,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







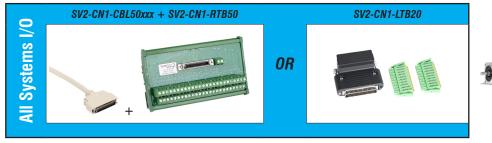
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		14.32 (300%)		<u>SV2M-210N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
	120V	Torque (N-m)		<u> </u>	SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
	1200	₽ 4.77 (100%)	Intermittent Region Continuous Region	CV/2M 240D	<u>372A-2130</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
ша			700 1,550 2,000 Speed (r/min)	<u>SV2M-210B</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
1.0 kW Medium Inertia System		14,32 (300%)		SV2M-210N	<u>SV2A-2150</u>	SV2C-PC12-xxNN	SV2C-E222-xxNN
m Inert	230V	Torque (N·m)	Intermittent Region	<u>5721014</u>		SV2C-PC12-xxFN	SV2C-E222-xxFN
Mediu		4.77 (100%)	Continuous Region	<u>SV2M-210B</u>		SV2C-PC12-xxNB	SV2C-E222-xxNN
1.0 KW		3.20 (67%)	2,000 3,000 Speed (r/min)			SV2C-PC12-xxFB	SV2C-E222-xxFN
		14.32 (300%)		SV2M-410N		SV2C-PC16-xxNN	SV2C-E222-xxNN
	1001	Torque (N-m)	Intermittent Region		SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
	460V	2 (100%) 3.20 (67%)	Continuous Region	SV2M-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
			2,000 3,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







SureServo2 AC servo drive, motor, and cable combinations, continued

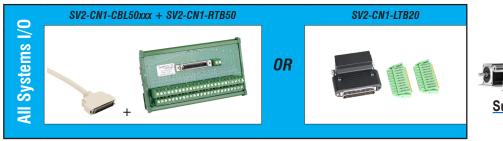
	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			14.88 (208%)		<u>SV2M-215N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
m	120V	Torque (N-m)	7.16 (100%)	Intermittent Region	<u>57219721514</u>	<u>SV2A-2150</u>	SV2C-PC12-xxFN	SV2C-E222-xxFN
1.5 kW Medium Inertia System	1200	Ĕ.	(100%)	Continuous Region	<u>SV2M-215B</u>	<u>372A-2130</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
n Inerti				1,000 1,400 1,800 Speed (r/min)	<u>372M-2130</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
Mediur		Torque (N:m)	14.88 (208%)	7.16	<u>SV2M-215N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
1.5 kW	230V		716			01/04 0450	SV2C-PC12-xxFN	SV2C-E222-xxFN
			Continuous Region		<u>SV2A-2150</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN	
			4.60 (67%)	2,000 2,400 3,000 Speed (r/min)	<u>SV2M-215B</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
ystem			18.1 (253%)	18.1 (253%)	SV2L-415N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Torque (N·m)		Intermittent Region	5V2L-415IV		SV2C-PC16-xxFN	SV2C-E222-xxFN
1.5 kW Low Inertia System	7007	Тог	5 7.16 (100%) 4.77 (67%) Continuous Region		SV2A-4150	SV2C-PC16-xxNB	SV2C-E222-xxNN	
1.5 kV				2,000 3,000 Speed (r/min)	SV2L-415B		SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility: SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable







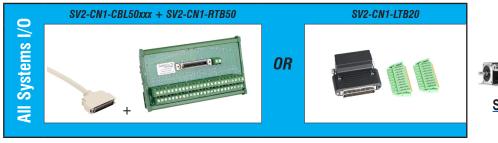
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		24. (257	24.54 (257%)	SV2M-220N		SV2C-PD12-xxNN	SV2C-E222-xxNN
m	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2200</u>	SV2C-PD12-xxFN	SV2C-E222-xxFN
a Syste	1200	بے ب (100	55 %) Continuous Region	<u>SV2M-220B</u>	<u>372A-2200</u>	SV2C-PD12-xxNB	SV2C-E222-xxNN
2.0 kW Medium Inertia System			800 1,500 1,950 Speed (r/min)	37210-2200		SV2C-PD12-xxFB	SV2C-E222-xxFN
Mediu		24 (257	.54	SV2M-220N		SV2C-PD12-xxNN	SV2C-E222-xxNN
2.0 kW	230V	Forque (N-m)	Intermittent Region	<u>3vzm-zzon</u>		SV2C-PD12-xxFN	SV2C-E222-xxFN
		9 100 (100	Continuous Region	<u>SV2M-220B</u>	<u>SV2A-2200</u>	SV2C-PD12-xxNB	SV2C-E222-xxNN
		6 (67	.40 %6) 2,000 2,200 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		28.65 (300%)		SV2L-420N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Torque (N-m)	Intermittent Region	0721-42014	SV2L-420N SV2A-4200	SV2C-PC16-xxFN	SV2C-E222-xxFN
2.0 kW Low Inertia System	4007	9.55 (100%) 6.40 (67%)	9.55 (100%) 6.40 (67%) Continuous Region 2,000 3,000 Speed (r/min)	SV/21 420P		SV2C-PC16-xxNB	SV2C-E222-xxNN
2.0 KN				SV2L-420B		SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







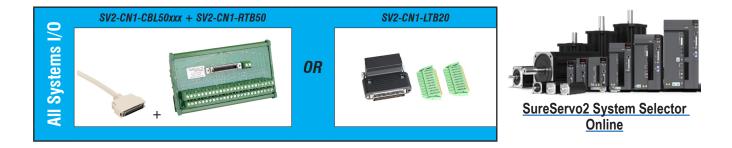
SureServo2 AC servo drive, motor, and cable combinations, continued

u	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
a Syster		48.29	SV2M-230N		SV2C-PD12-xxNN	SV2C-E222-xxNN
m Inerti	2201/	Intermittent Region	<u>37210-23010</u>	<u>SV2A-2300</u>	SV2C-PD12-xxFN	SV2C-E222-xxFN
3.0 kW Medium Inertia System	230V	b 17.55 (100%) 10.00 (57%) 9.55 (54%) € Continuous Region			SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 K		1,700 1,800 3,000 Speed (r/min)	<u>SV2M-230B</u>		SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		49.38	SV2H-430N	- SV2A-4300	SV2C-PD12-xxNN	SV2C-E222-xxNN
3.0 kW High Inertia System		Intermittent Region			SV2C-PD12-xxFN	SV2C-E222-xxFN
N High I	460V	9.00 (47%) Continuous Region			SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 K	3.0 KV	1,500 1,800 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		71.62 (250%)	SV2H-245N		SV2C-PD08-xxNN	SV2C-E222-xxNN
	230V	(E. ž) and the second	<u>57511-24514</u>	<u>SV2A-2550</u>	SV2C-PD08-xxFN	SV2C-E222-xxFN
System	2007	28.65 (100%) 14.33 (50%) Continuous Region	SV2H-245B		SV2C-PD08-xxNB	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	<u>3V2I1-243D</u>		SV2C-PD08-xxFB	SV2C-E222-xxFN
4.5 kW High Inertia System		64.61 (226%)		- SV2A-4550	SV2C-PD08-xxNN	SV2C-E222-xxNN
4.5	460V	Intermittent Region	SV2H-445N		SV2C-PD08-xxFN	SV2C-E222-xxFN
	4007	← (100%) 14.33 (50%) Continuous Region	SV2H-445B		SV2C-PD08-xxNB	SV2C-E222-xxNN
		1,500 1,700 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		87.53 (250%)	SV2H-255N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	<u></u>		SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2300	b (100%) 17.51 (50%) Continuous Region	SV2H-255B	<u>SV2A-2550</u>	SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	<u>37211-2336</u>		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
5.5 kW High Inertia System		73.48		SV2A-4550	SV2C-PD08-xxNN	SV2C-E222-xxNN
5.2	460V	E Intermittent Region	SV2H-455N		SV2C-PD08-xxFN	SV2C-E222-xxFN
	4007	19.1 (55%) 17.51 (50%)	SV2H-455B		SV2C-PD08-xxNN	SV2C-E222-xxNN
		1,500 1,900 3,000 Speed (r/min)			SV2C-PD08-xxFN	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		119. (250	36	SV2H-275N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Torque (N-m)	Intermittent Region	3751-51314	01/04 0750	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2300	47. (100 23. (50	%) 87 -	SV2H-275B	<u>SV2A-2750</u>	SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia			1,500 3,000 Speed (r/min)	37211-2730		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
7.5 kW High Inertia System		93.71 (196%)		SV2H-475N		SV2C-PD08-xxNN	SV2C-E222-xxNN
7.5	460V	Lordue (N-m)	Intermittent Region	3V211-473N	SV2A-4750	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	20. (42%		SV2H-475B	072744700	SV2C-PD08-xxNN	SV2C-E222-xxNN
			1,500 2,000 3,000 Speed (r/min)	0.1141.00		SV2C-PD08-xxFN	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		17 (250	5.0	SV2H-2B0N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Torque (N-m)	Intermittent Region	<u>37211-2000</u>	01/24 2500	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2307		25-	SV2H-2B0B	<u>SV2A-2F00</u>	SV2C-PF06-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
h Inertia			1,500 2,000 Speed (r/min)	<u>3721-2000</u>		SV2C-PF06-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN
11.0 kW High Inertia System		17 (250	5.0	SV/2H ADON		SV2C-PF08-xxNN	SV2C-E222-xxNN
11.0	460V	Torque (N·m)	Intermittent Region	SV2H-4B0N	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	4000	- (100	2.5	SV2H-4B0B	SV2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
			1,500 2,000 Speed (r/min)	ονzπ-4606		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		22 (235	14.0	SV2H-2F0N		SV2C-PF04-xxNN	SV2C-E222-xxNN
	230V	Torque (N-m)	Intermittent Region	<u>3v2n-2run</u>	01/24 2500	SV2C-PF04-xxFN	SV2C-E222-xxFN
System	2300	. (100	75.4 0966) 1.6 5969) Continuous Region	SV2H-2F0B	<u>SV2A-2F00</u>	SV2C-PF04-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
15.0 kW High Inertia System			1,500 2,000 Speed (r/min)	<u>3v2n-2rub</u>		SV2C-PF04-xxFB and SV2C-B120-xxFB	SV2C-E222-xxFN
kW Higl		224 (235	4.0	SV2H-4F0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
15.0	460V	Torque (N·m)	Intermittent Region	3v2n-4run	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	4000	(100) (100) (75%	1.6		SV2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
			1,500 2,000 Speed (r/min)	SV2H-4F0B		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





AC Servo System Software

The SureServo2 Pro configuration tool logically organizes

all servo drive parameters for viewing and editing using the Parameter Editor screen. Each parameter has a factory default that usually allows the servo to run "out-of-the-box". The parameters can be easily changed with available setting ranges displayed. Tuning modes and parameters can also be changed using SureServo2 Pro. After the parameters have been defined, the complete setup can be stored and archived. Drive configurations can be uploaded, edited,

Parameter editor



SureServo2 Pro configuration software

SureServo2 Pro is an optional free downloadable configuration software package for the SureServo2 drives. With SureServo2 Pro installed, a PC may be directly connected to the servo drive via a USB programming cable (part# SV2-PGM-USB15 or SV2-PGM-USB30).

Features

- Easy-to-use Parameter Wizards to guide you through the most common setup functions.
- Digital IO/Jog Control allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.
- Parameter Editor The complete setup for all the drive parameters
- Tune and check the servo response live using the scope feature.
- Upload and download the drive setup. Save the drive setup as a file for backup or future use.
- Edit the drive setup
- View all drive faults
- View drive variable trends in real time
- Create a custom EtherNet/IP EDS file for data transfer to a PLC using pull-down menus
- Motion Programming ability the PR Window lets you cofigure the 99 "Paths" that store the motion and sequencing commands in the drive

USB Programming Cables

Part Number	Prico		Length	Drawing	Compatible Drives
SV2-PGM-USB15	\$32.00	Programming cable,	1.5 m	PDF	All SureServo2
SV2-PGM-USB30	\$34.50	USB A to miniB-USB	3m	PDF	drives

SV2-PGM-USB15

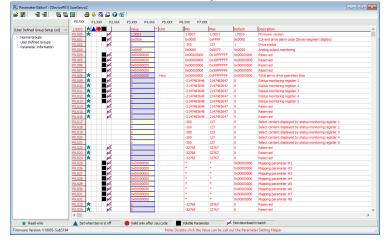
Parameter Editor Example Screen

SS2 Pro software even has an "Offline Mode" so you can

configure your drive and program your motion without

saved, and downloaded as often as necessary.

having to be connected to the drive.

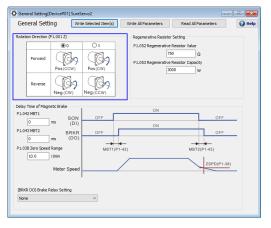




AC Servo System Software

SureServo2 Pro configuration software - (continued)

General Setting Example Screen



Digital IO/Jog Control screen

The Digital IO/Jog Control screen allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.

Edit DI/O Item	Start	🕜 Help			
Digital Input (DI)	Status	Enable	> Digital Output (DO) Enable	DO Control Sta	itus Enable
DI1:[0x00]Disabled (B)		On/Off	DO1:[0x00]Disabled (B)		
DI2:[0x00]Disabled (8)		On/Off	DO2:[0x00]Disabled (B)		
DI3:[0x00]Disabled (B)		On/Off	DO3:[0x00]Disabled (B)		
DI4:[0x00]Disabled (B)		On/Off	DO4:[0x00]Disabled (B)		
DI5:[0x00]Disabled (B)		On/Off	DOS:[0x00]Disabled (B)		
DI6:[0x00]Disabled (B)		On/Off	DO6:[0x00]Disabled (B)		
DI7:[0x00]Disabled (B)		On/Off			
DI8:[0x00]Disabled (B)		On/Off	Remain the DI/O control status	when this winodw is cl	osed.
DI9:[0x00]Disabled (B)		On/Off	Jog:	Set Servo OFF	Set Servo 0
DI10:[0x00]Disabled (B)		On/Off	Speed (P4.005): 100 rpm	SCOUTOOT	Dec Dervo o
VDI11:[0x00]Disabled (B)		On/Off	Reverse direction		
VDI12:[0x00]Disabled (B)		On/Off	Reverse direction		
VDI13:[0x00]Disabled (B)		On/Off			

Alarm Information Example Screen

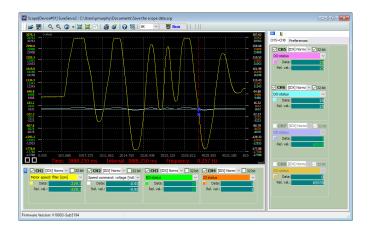
urrent Alarm	Alarm History Search	
	AL: 0x 1 Search	
AL001 Overcurrent		
Trigger condition and cause	Condition: main circuit current is greater than 1.5 times the maximum instantaneous current of the servo drive. Cause: 1. The servo drive output is short-circuited. 2. Motor wining is in error. 3. IGBT a abnormal. 4. Parameter senting is in error. 5. Control command setting is in error.	
Checking method and corrective action	 Check the connection between the motor and servo drive and make sure that the wire is not short-circuited. Do not est the metal part of the wiring. Check if you have followed the wiring sequence for connecting the motor to the servo driv diversived at this manual. If the temperature of the heat sink is abnormal, send your servo drive back to the distributor or contact Dela. Check if set value of the parameter is muck parater than the default is recommended to reset the parameter bencher the the factory drive setting and then modify the setting gradually. Check if the input control command changes greatly. If so, modify the rate of change in the command or enable the filts function. 	e as f the iault
How to clear the alarm?	DLARST	

PR Mode Setting Example Screen

🛎 🗋 📲 📲 🚱 🚳 🛱	SureServ	o2 Ver: 10003 Sub:51	94			
Show currrent PR. Path	0	Run PR. Path	Stop PR. Path	Forced Srv ON	Indexing Coordinates Wizard	
Speed and Time Setti.	Speed/Time !	Setting Chart Star	tements User Variab	le		
ccel / Decel Time	× P5.020+	PS.035: Accel / De	cel Time			
slay Time	AC00	200	(ms) (P5.020	0) (1~65500)		
ternal Target Speed	AC01	300	(ms) (P5.02:	1) (1~65500)		
General Parameter S.,	AC02	500	(ms) (P5.02)	2) (1~65500)		
ectronic Gear Ratio	AC03	600	(ms) (P5.02)	3) (1~65500)		
iftware Limit	AC04	800	(ms) (P5.02+	4) (1~65500)		
eceleration Time for A	AC05	900	(ms) (P5.025	5) (1~65500)		
vent ON/OFF Setting	AC05	1000	(ms) (P5.028	5) (1~65500)		
Homing Setting	AC07	1200	(ms) (P5.02)	7) (1~65500)		
oming Mode	AC08	1500	(ms) (P5.02)	8) (1~65500)		
oming Speed Setting	AC09	2000	(ms) (P5.02)	9) (1~65500)		
oming Definition	AC10	2500	(ms) (P5.030	0) (1~65500)		
PR Mode Setting	AC11	3000	(ms) (P5.03)	1) (1~65500)		
R#01] T:0	AC12	5000	(ms) (P5.03)	2) (1~65500)		
9R#02] T:0	AC13	8000	(ms) (P5.03)	3) (1~65500)		
9R#03] T10	AC14	50	(ms) (P5.03-	4) (1~1500)		
R#04] T:0	AC15	30	(ms) (P5.03)	5) (1~1200)		
9R#05] T:0	» P5.040-	P5.055: Delay Tim	e			
9R#06] T10	» P5.060+	PS.075: Internal T	arget Speed			
9R#07] T:0						
R#08] T:0						
9R#09] T10						
9R#10] T:0						
R#11] T:0						
9R#12] T:0						
9R#13] T:0						
9R#14] T:0						
9R#15] T:0						
PR#16] T:0				Download	1	

Scope

SureServo2 Pro includes a powerful scope function that allows the user to have as many as eight channels of data displayed simultaneously. Each channel has a drop-down table to select the data to be displayed. The scope has the ability to save traces to a file and load those traces for offline review/analysis. This function is a valuable tool for tuning SureServo2 drives.





For the latest prices, please check AutomationDirect.com. AC Servo Drive Specifications

Servo drive overview

Charge

LED is lit when DC bus is energized (may take several seconds for power to dissipate after incoming power is removed)

Control Power Terminal

220VAC drives: control power = 120 or 220 VAC single phase.

460VAC drives: control power = 24VDC

Main Power Terminal

- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW

Regenerative Resistor Terminal

- 1. When the internal
- regenerative resistor is used, the P3 and D terminal are connected together while the P3 and C connection is left open.
- 2. When an external regenerative resistor is used, it is connected across the P3 and C terminals while the P3 and D connection is left open. See the user manual for recommended resistance and power requirements for each system.

Motor Output Terminal

The servo motor power cable is connected to U, V and W. Use our factory made and tested cables available in 3, 5, 10, or 20 meter lengths for easy and trouble free connection.

LED Display The LED display has 5 full digits and is used to indicate servo status and alarms

5 Safe Torque Off d (STO) Connector Port Keypad

- Five Function keys: • MODE: Press to change mode
- SHIFT: Press to change parameter group or move cursor left
- UP: Press to increase values
- DOWN: Press to decrease values
- SET: Press to enter value

USB Connector

Used to connect a PC for configuration with SureServo2 Pro software

Serial Communication Interface

RJ45 connectors for RS485 Modbus communication between drives and controllers. Modbus RTU/ ASCII protocol. Use our factorymade cables for easy connection to the PC or the host controller.

I/O Interface

50-pin connector for interfacing the host controller and other types of I/O signals.

- CBL50 + RTB50 = Cable and remote DIN-rail mount module. All I/O pins available.
- LTB20 = Mounted and wired directly at CN1. Most commonly used pins available.
- Command inputs: Pulse and Direction Encoder Follower Analog Velocity/Torque
- (10) Digital Inputs
- (6) Digital Outputs
- (2) Analog Monitors
- Encoder Output (scalable)
- A+, A-, B+, B-, Z+, Z-

Encoder Interface

Connector for interfacing the servo motor encoder.

Use our factory-made and tested cables available in 3, 5, 10, or 20 meter lengths for easy and trouble free connection.



Ground Terminals

ance a

High Density DB15 Connector CN5: Auxiliary/Secondary Encoder input. Used for

applications requiring Full Closed

Loop, Linear Measurement, etc.

AA 80

*Sure*Servo2 systems run "out-of-the-box"... but may be reconfigured for many applications!

The SureServo2 drives are fully digital and include over 400 programmable parameters. For convenience, the parameters are grouped into five categories:

- 1. Monitor parameters
- 2. Basic parameters
- 3. Extended parameters
- 4. Communication parameters
- 5. Diagnostic and analog parameters
- 6. Motion control parameters
- 7. PATH definition parameters

All parameters have commonly used default values which allow you to operate the SureServo2 system "out-of-thebox". However, the programmability and large variety of parameters make the SureServo2 systems suitable for a very broad range of applications, including almost all types of general purpose industrial machinery such as assembly, test, packaging, machine tool, and robotics.

The SureServo2 Pro configuration software has Parameter Wizards to quickly and easily guide you through the most common setup routines.



230V Servo drive specifications

		SureS	ervo2 230	OV Drive S	Specificat	ions				
	Model	<u>SV2A-2040</u>	<u>SV2A-2075</u>	<u>SV2A-2150</u>	<u>SV2A-2200</u>	<u>SV2A-2300</u>	<u>SV2A-2550</u>	<u>SV2A-2750</u>	<u>SV2A-2F00</u>	
	Price	\$383.00	\$477.00	\$509.00	\$598.00	\$660.00	\$836.00	\$977.00	\$1,277.00	
	Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
	Power Rating	400W	750W	1.5 kW	2kW	3kW	5.5 kW	7.5 kW	15kW	
	Input Voltage	Singl	e-phase 200–23	0 VAC, -15% to 0 VAC, -15% to 0 VAC, -15% to -	+10%	Thre	e-phase 200–23	0 VAC, -15% to -	+10%	
	Input Current 200–230 VAC 3-phase [Amps] rms	2.76	5.09	8.09	11.36	14.52	27.06	37.33	69.95	
	Input Current 100–120 VAC 1-phase [Amps] rms	3.98	7.73	12.56	18.03	-	-	-	-	
Power	Input Current 200–230 VAC 1-phase [Amps] rms	4.69	8.71	14.82	20.83	-	_	-	-	
	Continuous Output Current [Amps] rms	2.60	5.10	8.33	13.40	17.92	41.33	49.04	78	
	Max. Instantaneous Output Current [Amps] rms	8.56	15.43	20.16	40.57	55.93	91.44	127.46	162.04	
	Main Circuit Inrush Current [Amps]	1.44	1.40	1.44	4.64	4.42	9.55	28.68	32.0	
	Control Circuit Inrush Current [Amps]	37.0	37.40	39.80	32.40	36.40	32.80	40.0	37.0	
	Cooling Method	Air Conv. Cooling Fan Cooling								
	Encoder Resolution		24-bit (16777216 p/rev)							
	Main Circuit Control				SVPWN	I control				
	Control Mode				Manua	I / Auto				
	Regenerative Resistor		Built-in (ext	ernal options als	,			External (optiona	l)	
	Pulse Type			Pulse + Dire	ction, CCW pulse	e + CW pulse, Al	B Quadrature			
Position Control Mode	Max. Input Pulse Frequency			AE	CCW pulse + C\ 3 Quadrature: sir	ction: 4 Mpps; N pulse: 4 Mpps ngle-phase 4 Mp or: 200 Kpps	; ps;			
n Co	Command Source				External pulse /	Internal registers	3			
ositio	Smoothing Method	d Low-pass and P-curve filter								
P	Torque Limit				Paramete	er settings				
	Feed Forward Compensation				Paramete	er settings				



230V Servo drive specifications (continued)

		Su	ireServo2	230V Dr	ive Speci	ications (Continued					
		Model	<u>SV2A-2040</u>	<u>SV2A-2075</u>	<u>SV2A-2150</u>	<u>SV2A-2200</u>	<u>SV2A-2300</u>	<u>SV2A-2550</u>	<u>SV2A-2750</u>	<u>SV2A-2F00</u>		
		Voltage Range		±10VDC								
	Analog	Resolution				15	bit					
	Command Input	Input Impedance		1ΜΩ								
e.		Time Constant				25	μs					
Speed Control Mode		Speed Control Range1				1:6	000					
ntrol		Command Source			Exterr	nal analog comm	and / Internal re	gisters				
ed Co		Smoothing Method			-	Low-pass and	S-curve filter					
Spe		Torque Limit				Parameter settin	gs / Analog inpu	t				
		Bandwidth				Maximum 3.1 kl	Hz (closed-loop)					
				±0.01% at 0% to 100% load fluctuation								
	S	peed Calibration Ratio2				±0.01% at ±10%						
		Voltage Range			±0.01% at	0°C to 50°C amb ±10						
apc	Analog Command		1ΜΩ									
ol Mi	Input	· · ·										
Torque Control Mode		Time Constant Command Source			Evtor	20 nal analog comm		nietore				
rque		Smoothing Method			LX(GII	Low-pa		9151615				
20		Speed Limit				Parameter settin		t				
		Analog Monitor Output		Monitor si		by parameters (v			ution:10-bit			
Digital Input/Output		Input	Servo on, Fault trigger, Torque PT / PR com	reset, Gain swit e limit, Speed lim	ch, Pulse clear, it, Internal positi Speed / torque r , motor override,	Zero speed clam on command sel mode switching, Forward / revers / reverse JOG in	ping, Command ection, Motor sto vitching, forque / position e limit, Original	input reverse co p, Speed comm mode switching point, Forward / I	ntrol, Internal po and selection, Sp , reverse operatior	beed / position		
ital In						A, B, Z line						
Digi		Output	Magnetic brak	e control, Homir	ng completed, Ea are limit (forward	, Target speed re rrly warning for o direction), Intern ure completed, N	verload, Servo v al position comm	varning, Position nand completed,	command overfl	ows, Software		

1 - Within the rated load, the speed ratio is: the minimum speed (smooth operation) / rated speed.

2 - Within the rated speed, the speed calibration ratio is: (rotational speed with no load - rotational speed with full load) / rated speed.



230V Servo drive specifications (continued)

	Sui	eServo2	230V Driv	ve Specifi	cations C	ontinued			
	Model	<u>SV2A-2040</u>	<u>SV2A-2075</u>	<u>SV2A-2150</u>	<u>SV2A-2200</u>	<u>SV2A-2300</u>	<u>SV2A-2550</u>	<u>SV2A-2750</u>	<u>SV2A-2F00</u>
	Protection Function	speed deviati	on, Excessive po eviation of full-cl	sition deviation, osed loop contro	Encoder error, A I, Serial commun	djustment error, nication error, RS	Emergency stop	error, Overload, o, Forward / reve ierial communica	erse limit error,
	Communication Interface		R	S-485 / Modbus	RTU / USB / Op	tional EtherNet/	IP or Modbus TC	P	
	Weight [kg (lb)]	0.92 (2.03)	1.3 (2.87)	1.3 (2.87)	2.7 (5.95)	2.7 (5.95)	4.9 (10.8)	7.2 (15.9)	13 (29)
	Installation Site		Indoors (avoid direct sunlight), no corrosive vapor (avoid fumes, flammable gases, and dust)						
	Altitude	Altitude 1000m or lower above sea level							
	Atmospheric Pressure	86kPa - 106kPa							
Environment	Operating Temperature		(If operating temp	0°C to perature is above		ooling is required	I)	
inviro	Storage Temperature				-20°C t	to 65°C			
E	Humidity			U	nder 0 - 90% RH	(non-condensin	ıg)		
	Vibration		ę	9.80665 m/s2 (1	G) less than 20 l	Hz, 5.88 m/s2 (0	.6 G) 20 to 50 H	Z	
	IP Rating	IP20							
	Power System	TN system3,4							
	Approvals			IEC/EN	61800-5-1, UL 5	08C, TUV (for S	TO), CE		

3 - TN system: the neutral point of the power system connects directly to the ground. The exposed metal components connect to the ground through the protective ground conductor.

4 - Use a single-phase three-wire power system for the single-phase power model.



460V Servo drive specifications

		SureS	ervo2 46(OV Drive S	Specificat	ions					
	Model	<u>SV2A-4040</u>	<u>SV2A-4075</u>	<u>SV2A-4150</u>	<u>SV2A-4200</u>	<u>SV2A-4300</u>	<u>SV2A-4550</u>	<u>SV2A-4750</u>	<u>SV2A-4F00</u>		
	Price	\$460.00	\$485.00	\$665.00	\$648.00	\$730.00	\$836.00	\$1,050.00	\$1,363.00		
	Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF		
	Power Rating	400W	750W	1.5 kW	2kW	3kW	5.5 kW	7.5 kW	15kW		
	Input Voltage			Т	hree-phase 380	-480 VAC, ±10	%		1		
	Input Current 380–480 VAC 3-phase [Amps] rms	1.49	2.31	4.98	6.29	9.92	16.83	23.06	36.65		
	Continuous Output Current [Amps] rms	1.6	2.91	6.05	6.7	12.6	23.6	28.7	40.5		
Power	Max. Instantaneous Output Current [Amps] rms	5.4	9.7	13.94	21.35	30.46	47.5	57.69	95.3		
	Control Power Input Current	1.17	1.17	1.17	1.35	1.63	1.91	1.91	4.26		
	Main Circuit Inrush Current [Amps]	5.6	5.6	5.6	12.5	12.5	12.5	12.5	12.5		
	Control Circuit Inrush Current [Amps]	5	5 5 5 4.8 4.8 5.5 5.5 6								
	Control Circuit Voltage	24VDC									
	Cooling Method		Fan cooling								
	Encoder Resolution	24-bit (16777216 p/rev)									
	Main Circuit Control	SVPWM control									
	Control Mode	Manual/Auto									
	Regenerative Resistor	Built-in (ext	ernal options als	o available)		E	External (optiona	I)			
	Pulse Type			Pulse + Directi	on, CCW pulse ·	⊦ CW pulse, A pł	nase + B phase				
Position Control Mode	Max. Input Pulse Frequency				ase + B phase:	ction: 4 Mpps; V pulse: 4 Mpps single-phase 4 M or: 200 Kpps					
ontro	Command Source				External pulse /	Internal registers	3				
ion C	Smoothing Method			Low-pa	ss, moving-aver	aging, and S-cur	rve filter				
Positi	E-Gear Ratio					(1/4 < N/M < 262 M: 1–21474836					
	Torque Limit				Paramete	er settings					
	Feed Forward Compensation				Paramete	er settings					



460V Servo drive specifications (continued)

		Su	reServo2	460V Dr	ive Speci	ications (Continued					
		Model	<u>SV2A-4040</u>	<u>SV2A-4075</u>	<u>SV2A-4150</u>	<u>SV2A-4200</u>	<u>SV2A-4300</u>	<u>SV2A-4550</u>	<u>SV2A-4750</u>	<u>SV2A-4F00</u>		
		Voltage Range		1	1	±10	VDC	1	1	1		
	Analog	Resolution				12-	bit					
	Command Input	Input Impedance		1ΜΩ								
e,		Time Constant				25	μs					
Mod		Speed Control Range1				1:6	000					
Speed Control Mode		Command Source			Exteri	nal analog comm	and / Internal re	gisters				
ed Cc		Smoothing Method				Low-pass and	S-curve filter					
Spe		Torque Limit				Parameter settin	gs / Analog inpu	t				
		Bandwidth				Maximum 3.1 kł	Hz (closed-loop)					
			±0.01% at 0% to 100% load fluctuation									
	S	Speed Calibration Ratio2				±0.01% at ±10%	•					
		Vellege Denge	±0.01% at 0°C to 50°C ambient temperature fluctuation ±10VDC									
de	Analog	Voltage Range										
Torque Control Mode	Command Input	Input Impedance										
ontro		Time Constant	25µs									
Jue C		Command Source			Exteri	nal analog comm		gisters				
Torc		Smoothing Method				Low-pa						
		Speed Limit				Parameter settin	• • •					
		Analog Monitor Output			•	by parameters (v	•	• /				
Digital Input/Output		Input	trigger, Torque PT / PR comn	e limit, Speed lim nand switching,	nit, Internal positi Speed / torque r Emergency Stop	Zero speed clam on command sel mode sw node switching, , Forward / rever / reverse JOG in	ection, Motor sto vitching, forque / position se limit, Original	mode switching point, Forward /	and selection, S _l	peed / position		
tal In						A, B, Z line						
Digi		Output	Servo ready, Servo on, Zero speed detection, Target speed reached, Target position reached, Torque limiting, Servo alarm, Magnetic brake control, Homing completed, Early warning for overload, Servo warning, Position command overflows, Software limit (reverse direction), Software limit (forward direction), Internal position command completed, Capture procedure completed, Servo procedure completed, Master position area of E-Cam.									

1 - Within the rated load, the speed ratio is: the minimum speed (smooth operation) / rated speed.

2 - Within the rated speed, the speed calibration ratio is: (rotational speed with no load - rotational speed with full load) / rated speed.



460V Servo drive specifications (continued)

SureServo2 460V Drive Specifications Continued											
	Model	<u>SV2A-4040</u>	<u>SV2A-4075</u>	<u>SV2A-4150</u>	<u>SV2A-4200</u>	<u>SV2A-4300</u>	<u>SV2A-4550</u>	<u>SV2A-4750</u>	<u>SV2A-4F00</u>		
	Protection Function	Overcurrent, Overvoltage, Undervoltage, Overheat, Regeneration error, Overload, Excessive speed deviation, Excessive position deviation, Encoder error, Adjustment error, Emergency stop, Forward / reverse limit error, Excessive deviation of full-closed loop control, Serial communication error, RST leak phase, Serial communication timeout, Short-circuit protection for terminals U, V, W and CN1, CN2, CN3									
	Communication Interface				RS-48	5 / USB					
	Weight [kg (lb)]	5.96 [13.1]	5.96 [13.1]	5.96 [13.1]	9.71 [21.4]	9.71 [21.4]	12.14 [26.8]	12.14 [26.8]	15.01 [33.1]		
	Installation Site	Indoors (avoid direct sunlight), no corrosive vapor (avoid fumes, flammable gases, and dust)									
	Altitude	1000m or lower above sea level									
	Atmospheric Pressure	86kPa – 106kPa									
Environment	Operating Temperature	0°C to 55°C [32°F to 131°F] (If operating temperature is above 45°C, forced cooling is required)									
inviro	Storage Temperature				-20°C to 65°C	[-4°F to 149°F]					
μ	Humidity				Under 90% RH (non-condensing)				
	Vibration		9	9.80665 m/s2 (1	G) less than 20	Hz, 5.88 m/s2 (0	.6 G) 20 to 50 H	Z			
	IP Rating				IP	20					
	Power System				TN sys	stem ^{3,4}					
	Approvals	IEC/EN 61800-5-1, UL 508C, TUV (for STO), CE									

3 - TN system: the neutral point of the power system connects directly to the ground. The exposed metal components connect to the ground through the protective ground conductor.

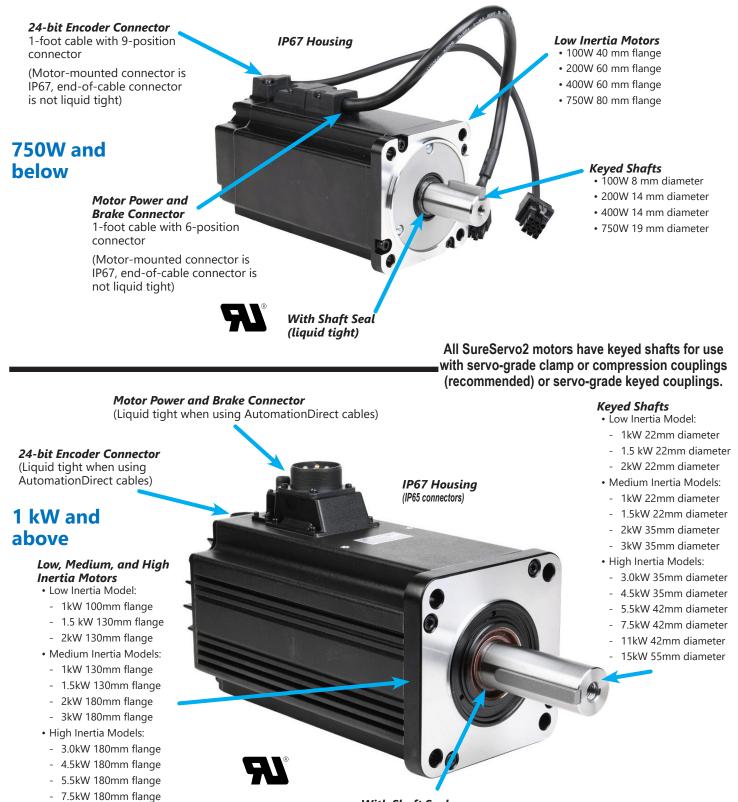
4 - Use a single-phase three-wire power system for the single-phase power model.

For the latest prices, please check AutomationDirect.com.



AC Servo Motor Specifications

Servo motor overview



With Shaft Seal (liquid tight)

- 11kW 220mm flange



230V Low Inertia Motor Specifications

		230V Sur	eServo2	Low Iner	tia Moto	r Specifi	cations						
Model	SV2L-201N	SV2L-201B	SV2L-202N	SV2L-202B	SV2L-204N	SV2L-204B	SV2L-207N	SV2L-207B	SV2L-210N	SV2L-210B			
Price	\$286.00	\$419.00	\$315.00	\$465.00	\$340.00	\$479.00	\$364.00	\$510.00	\$477.00	\$702.00			
Drawing	#200.00 PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF			
Rated Power [kW]	0.1	0.1	0.2	0.2	0.4	0.4	0.75	0.75	1.0	1.0			
Rated Torque (N·m)Note 1	0.32	0.32	0.64	0.64	1.27	1.27	2.39	2.39	3.18	3.18			
Max. Torque (N·m)	1.12	1.12	2.24	2.24	3.96	3.96	7.86	7.86	8.12	8.12			
Rated Speed [rpm]		3000											
Max. Speed [rpm]		6000 5000											
Rated current [Amps] rms	0.9	0.9	1.45	1.45	2.60	2.60	4.5	4.5	8.04	8.04			
Max. Instantaneous Current [Amps] rms	3.3	3.3	5.4	5.4	8.56	8.56	15.41	15.41	20.16	20.16			
Change of Rated Power [W/s]	16.3	14.90	16.4	14.60	35.8	33.60	37.8	34.40	38.2	30.40			
Rotor Inertia [x10-4 kg m2]	0.0627	0.0689	0.25	0.28	0.45	0.48	1.51	1.66	2.65	3.33			
Mechanical Time Constant [ms]	1.13	1.24	1.38	1.54	0.94	1.01	0.91	1.00	0.83	1.05			
Torque Constant-KT [N-m/A]	0.356	0.356	0.441	0.441	0.488	0.488	0.531	0.531	0.396	0.396			
/Voltage Constant-KE [mV rpm]	13.66	13.66	16.4	16.4	17.2	17.2	18.7	18.7	16.8	16.8			
Armature Resistance [Ohm]	8.34	8.34	3.8	3.8	1.68	1.68	0.57	0.57	0.20	0.20			
Armature Inductance [mH]	9.85	9.85	8.15	8.15	4.03	4.03	2.2	2.2	1.81	1.81			
Electrical Time Constant [ms]	1.18	1.18 1.18 2.14 2.40 2.40 3.86 3.86											
Insulation Class					Class A (UL),	Class B (CE)							
Insulation Resistance						, 500VDC							
Insulation Strength		1				, 1 second		1	1				
Weight [kg]	0.5	0.8	1.1	1.6	1.4	1.9	2.8	3.6	4.3	4.7			
Max. Radial Loading [N]	78	78	245	245	245	245	392	392	490	490			
Max. Axial Loading [N]	54	54	74	74	74	74	147	147	98	98			
Brake Holding Torque [N·m (min)]Note 2		0.32		1.3		1.3		2.5	-	8			
Brake Power Consumption (at 20°C) [W]	n/a	6.1	n/a	7.2	n/a	7.2	n/a	8	n/a	18.7			
Brake Release Time [ms (max)]		20		20		20		20		10			
Brake Pull-in Time [ms (max)]		35		50		50		60		70			
Vibration Grade [µm]						15							
Operating Temperature [°C]					0–40 °C (3	32–104 °F)							
Storage Temperature [°C]						-14°F to 176°F	-						
Operating Humidity						idity (non-conde							
Storage Humidity				20–90		idity (non-conde	ensing)						
Vibration Capacity						5 G			IP65 (when us	ing waterpres			
IP Rating ³			IP67	(when using wa	aterproof conne	,			Conne				
Encoder Resolution					(7216 p/rev)							
Agency Approvals					cURU	_{IS} , CE							

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating termperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



230V Medium Inertia Motor Specifications

					tor Specifi			-			
Model	<u>SV2M-210N</u>	<u>SV2M-210B</u>	<u>SV2M-215N</u>	<u>SV2M-215B</u>	<u>SV2M-220N</u>	<u>SV2M-220B</u>	<u>SV2M-230N</u>	<u>SV2M-230B</u>			
Price	\$497.00	\$711.00	\$537.00	\$795.00	\$651.00	\$863.00	\$735.00	\$947.00			
Drawing	<u>PDF</u>	PDF	PDF	<u>PDF</u>	PDF	PDF	PDF	PDF			
Rated Power [kW]	1.0	1.0	1.5	1.5	2.0	2.0	3.0	3.0			
Rated Torque [N·m]Note 1	4.77	4.77	7.16	7.16	9.55	9.55	17.55	17.55			
Max. Torque [N·m]	14.32	14.32	14.88	14.88	24.54	24.54	48.29	48.29			
Rated Speed [rpm]			20				17	00			
Max. Speed [rpm]					00		1	1			
Rated current [Amps] rms	5.66	5.66	8.33	8.33	12.1	12.1	17.9	17.9			
Max. Instantaneous Current [Amps] rms	19.73	19.73	20.16	20.16	33.66	33.66	55.93	55.93			
Change of Rated Power [W/s]	27.1	24.90	45.8	43.10	26.3	24.10	56.0	53.90			
Rotor Inertia [x10-4 kg m2]	8.41	9.14	11.2	11.9	34.7	37.8	55	57.1			
Mechanical Time Constant [ms]	1.54	1.67	1.12	1.18	1.75	1.90	1.29	1.34			
Torque Constant-KT [N-m/A]	0.843	0.843	0.860	0.860	0.789	0.789	0.980	0.980			
Voltage Constant-KE [mV/ rpm]	31.9	31.9	31.8	31.8	31.4	31.4	35	35			
Armature Resistance [Ohm]	0.47	0.47	0.26	0.26	0.119	0.119	0.077	0.077			
Armature Inductance [mH]	5.99	5.99	4.01	4.01	2.84	2.84	1.27	1.27			
Electrical Time Constant [ms]	12.74	12.74	15.42	15.42	23.87	23.87	16.49	16.49			
Insulation Class				Class A (UL),	Class B (CE)						
Insulation Resistance				> 100MΩ	, 500VDC						
Insulation Strength				1.8 kVAC	second						
Weight [kg]	7.0	8.4	7.5	8.9	13.5	17.5	18.5	22.5			
Max. Radial Loading [N]		49	90		1176 1470						
Max. Axial Loading [N]		g	8		490						
Brake Holding Torque [N∙m (min)]Note 2		10		10		25		25			
Brake Power Consumption (at 20°C) [W]	n/a	19	n/a	19	n/a	20.4		20.4			
Brake Release Time [ms (max)]	11/d	10	11/a	10	11/a	10	n/a	10			
Brake Pull-in Time [ms (max)]		70		70		70	1	70			
Vibration Grade [µm]				V	15						
Operating Temperature [°C]				0–40 °C (3	32–104 °F)						
Storage Temperature [°C]				-10°C to 80°C (-14°F to 176°F)						
Operating Humidity			20-	-90% relative humi	dity (non-condensi	ng)					
Storage Humidity			20-	-90% relative humi	idity (non-condensi	ng)					
Vibration Capacity				2.5							
IP Rating ³			IF	65 (when using wa	aterproof connector	s)					
Encoder Resolution				24-bit (1677	7216 p/rev)						
Agency Approvals	24-bit (16777216 p/rev) _C UR _{US} , CE										

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



230V High Inertia Motor Specifications

	2	30V Sure	Servo2	High Ine	rtia Moto	r Specifi	cations					
Model	<u>SV2H-245N</u>	<u>SV2H-245B</u>	<u>SV2H-255N</u>	<u>SV2H-255B</u>	<u>SV2H-275N</u>	<u>SV2H-275B</u>	SV2H-2BON	SV2H-2B0B	SV2H-2FON	SV2H-2F0B		
Price	\$911.00	\$1,415.00	\$1,050.00	\$1,568.00	\$1,273.00	\$1,989.00	\$1,956.00	\$2,682.00	\$2,257.00	\$3,091.00		
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF		
Rated Power [kW]	4.5	4.5	5.5	5.5	7.5	7.5	11	11	15	15		
Rated Torque [N·m]Note 1	28.65	28.65	35.01	35.01	47.74	47.74	70	70	95.4	95.4		
Max. Torque [N·m]	71.62	71.62	87.53	87.53	119.36	119.36	175	175	224.0	224.0		
Rated Speed [rpm]		1500										
Max. Speed [rpm]		r	30	00	1	1		20	00	r		
Rated current [Amps] rms	32.5	32.5	40.12	40.12	47.5	47.5	51.1	51.1	67	67		
Max. Instantaneous Current [Amps] rms	91.4	91.4	108.0	108.0	127.46	127.46	129.5	129.5	162	162		
Change of Rated Power [W/s]	105.6	101.8	122.8	119.3	159.7	156.6	145.0	141.4	201.8	197.1		
Rotor Inertia [x10-4 kg m2]	77.75	80.65	99.78	102.70	142.7	145.55	338	346.5	451	461.8		
Mechanical Time Constant [ms]	0.93	0.96	0.97	0.99	0.84	0.85	1.38	1.41	1.22	1.25		
Torque Constant-KT [N·m/A]	0.878	0.878	0.873	0.873	1.005	1.005	1.370	1.370	1.424	1.424		
Voltage Constant-KE [mV/rpm]	32.0	32.0	31.0	31.0	35.5	35.5	49	49	50	50		
Armature Resistance [Ohm]	0.032	0.032	0.025	0.025	0.02	0.02	0.0261	0.0261	0.0184	0.0184		
Armature Inductance [mH]	0.89	0.89	0.71	0.71	0.6	0.6	0.65	0.65	0.48	0.48		
Electrical Time Constant [ms]	27.81	27.81	28.4	28.4	30.0	30.0	24.9	24.9	26.09	26.09		
Insulation Class			Class A (UL),		Class F (UL),	Class F (CE)						
Insulation Resistance		> 100MΩ, 500VDC										
Insulation Strength	1.8 kVAC, 1 second								1			
Weight [kg]	23.5	29	30.5	36	40.5	46	56.4	68.4	75	87		
Max. Radial Loading [N]	14	-			/64		3300					
Max. Axial Loading [N]	49	90		5	88		1100					
Brake Holding Torque [N·m (min)]Note 2		55.0		55.0	-	55.0	-	115		115		
Brake Power Consumption (at 20°C) [W]	n/a	19.9	n/a	19.9	n/a	19.9	n/a	28.8	n/a	28.8		
Brake Release Time [ms (max)]	11/04	10		10		10	, ind	10		10		
Brake Pull-in Time [ms (max)]		70		70		70		70		70		
Vibration Grade [µm]					V	15						
Operating Temperature [°C]					0–40 °C (3	32–104 °F)						
Storage Temperature [°C]					-10°C to 80°C (-14°F to 176°F	-)					
Operating Humidity				20–90	% relative humi	dity (non-cond	ensing)					
Storage Humidity				20–90	% relative humi		ensing)					
Vibration Capacity					2.5							
IP Rating ³				IP	65 (when using		es)					
Encoder Resolution					24-bit (1677	7216 p/rev)						
Agency Approvals				0°C and 40°C		_{IS} , CE						

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm,400mm x 400mm x 20mm,550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability) Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



460V Low Inertia Motor Specifications

	4	460V Sur	eServo2	Low Ine	rtia Moto	r Specifi	cations				
Model	<u>SV2L-404N</u>	<u>SV2L-404B</u>	<u>SV2L-407N</u>	<u>SV2L-407B</u>	<u>SV2L-410N</u>	<u>SV2L-410B</u>	<u>SV2L-415N</u>	<u>SV2L-415B</u>	<u>SV2L-420N</u>	<u>SV2L-420B</u>	
Price	\$360.00	\$515.00	\$388.00	\$555.00	\$505.00	\$745.00	\$580.00	\$855.00	\$687.00	\$899.00	
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
Rated Power [kW]	0.4	0.4	0.75	0.75	1.0	1.0	1.5	1.5	2.0	2.0	
Rated Torque [N·m]Note 1	1.27	1.27	2.24	2.24	3.18	3.18	7.16	7.16	9.55	9.55	
Max. Torque [N·m]	4.45	4.45	7.58	7.58	9.54	9.54	18.1	18.1	28.65	28.65	
Rated Speed [rpm]	30	00	32	00	3000			20	00		
Max. Speed [rpm]	60	00	60	00	50	00		30	00		
Rated current [Amps] rms	1.43	1.43	2.90	2.90	4.36	4.36	5.1	5.1	6.7	6.7	
Max. Instantaneous Current [Amps] rms	5.25	5.25	9.70	9.70	13.74	13.74	13.28	13.28	21.35	21.35	
Change of Rated Power [W/s]	35.8	33.6	33.2	30.2	38.2	30.40	45.9	43.10	62.5	57.4	
Rotor Inertia [x10-4 kg m2]	0.45	0.48	1.51	1.66	2.65	3.33	11.18	11.9	14.59	15.88	
Mechanical Time Constant [ms]	1.05	1.12	1.02	1.12	0.81	1.02	1.26	1.34	1.11	1.21	
Torque Constant-KT [N-m/A]	0.888	0.888	0.772	0.772	0.729	0.729	1.404	1.404	1.425	1.425	
/Voltage Constant-KE [mV/ rpm]	31.83	31.83	27.83	27.83	29.00	29.00	55.00	55.00	55.00	55.00	
Armature Resistance [Ohm]	6.28	6.28	1.38	1.38	0.617	0.617	0.83	0.83	0.57	0.57	
Armature Inductance [mH]	13.34	13.34	4.78	4.78	6.03	6.03	11.67	11.67	8.29	8.29	
Electrical Time Constant [ms]	2.12	2.12	3.46	3.46	9.77	9.77	14.06	14.06	14.54	14.54	
Insulation Class		Class A (UL), Class B (CE)									
Insulation Resistance		> 100 MΩ, 500VDC									
Insulation Strength					2.3 kVA	C, 1 sec					
Weight [kg]	1.4	1.9	2.8	3.6	4.3	4.7	7.5	8.9	7.8	9.2	
Max. Radial Loading [N]	245	245	392	392	490	490	490	490	490	490	
Max. Axial Loading [N]	74	74	147	147	98	98	98	98	98	98	
Brake Holding Torque [N·m (min)]Note 2		1.3		2.5		8		10		10	
Brake Power Consumption (at 20°C) [W]	n/a	7.2	n/a	8	n/a	18.7	n/a	19	n/a	19	
Brake Release Time [ms (max)]		20		20	n/a	10		10		10	
Brake Pull-in Time [ms (max)]		50		60		70		70		70	
Vibration Grade [µm]						15					
Operating Temperature [°C]					0–40 °C (3						
Storage Temperature [°C]					-10°C to 80°C (/				
Operating Humidity					% relative humi						
Storage Humidity				20–90	% relative humi		ensing)				
Vibration Capacity	ID67 (when	ning weterner-	f aannactora	d when an all	1	G		luihan an ail	ol io fitted to the	rotating about	
IP Rating			f connectors an shaft (for an oil					i when an oil se eal model))	al is fitted to the	e rotating shaft	
Encoder Resolution					24-bit (1677						
Agency Approvals					CURU	_{IS} , CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.



460V Medium Inertia Motor Specifications

3.6 11.41 27.1 8.41 1.85	SV2M-410B \$765.00 PDF 1.0 4.77 14.32 2000 3000 3.6 11.41 24.90 9.14 2.01			
PDF 1.0 4.77 14.32 3.6 11.41 27.1 8.41 1.85	PDF 1.0 4.77 14.32 2000 3000 3.6 11.41 24.90 9.14			
1.0 4.77 14.32 3.6 11.41 27.1 8.41 1.85	1.0 4.77 14.32 2000 3000 3.6 11.41 24.90 9.14			
4.77 14.32 3.6 11.41 27.1 8.41 1.85	4.77 14.32 2000 3000 3.6 11.41 24.90 9.14			
14.32 2 3.6 11.41 27.1 8.41 1.85	14.32 2000 3000 3.6 11.41 24.90 9.14			
3.6 11.41 27.1 8.41 1.85	2000 3000 3.6 11.41 24.90 9.14			
3.6 11.41 27.1 8.41 1.85	3000 3.6 11.41 24.90 9.14			
3.6 11.41 27.1 8.41 1.85	3.6 11.41 24.90 9.14			
11.41 27.1 8.41 1.85	11.41 24.90 9.14			
27.1 8.41 1.85	24.90 9.14			
8.41 1.85	9.14			
1.85	-			
	2 01			
1 325	2.01			
1.020	1.325			
53.20	53.20			
1.477	1.477			
17.79	17.79			
12.04	12.04			
Class A (UL), Class B (CE)				
> 100 MΩ, 500VDC				
2.3 kVAC, 1 sec				
7.0 8.4				
490				
98				
	10			
n/a	19			
	10			
	70			
	V15			
0–40 °C	(32–104 °F)			
	C (-14°F to 176°F)			
20–90% relative hu	midity (non-condensing)			
	midity (non-condensing)			
	2.5 G			
P65 (when using waterproof conne	ctors and when an oil seal is fitted to the			
0 (777216 p/rev)			
	. ,			
	1.325 53.20 1.477 17.79 12.04 Class A (UI > 100 M 2.3 kV 7.0 0-40 °C -10°C to 80°C 20–90% relative hu 20–90% relative hu			

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.



460V High Inertia Motor Specifications

460V	SureServo	2 High Iner	tia Motor S	pecification	S				
Model	<u>SV2H-430N</u>	<u>SV2H-430B</u>	<u>SV2H-445N</u>	<u>SV2H-445B</u>	<u>SV2H-455N</u>	<u>SV2H-455B</u>			
Price	\$823.00	\$1,001.00	\$939.00	\$1,456.00	\$1,082.00	\$1,614.00			
Drawing	PDF	PDF	PDF	PDF	PDF	PDF			
Rated Power [kW]	3.0	3.0	4.5	4.5	5.5	5.5			
Rated Torque [N·m]Note 1	19.1	19.1	28.65	28.65	35	35			
Max. Torque [N·m]	49.38	49.38	64.61	64.61	73.48	73.48			
Rated Speed [rpm]									
Max. Speed [rpm]		3000							
Rated current [Amps] rms	12.2	12.2	21.9	21.9	23.6	23.6			
Max. Instantaneous Current [Amps] rms	30.46	30.46	47.5	47.5	47.5	47.5			
Change of Rated Power [W/s]	66.4	63.9	105.6	101.8	122.8	119.3			
Rotor Inertia [x10-4 kg m2]	54.95	57.1	77.75	80.65	99.78	80.65			
Mechanical Time Constant [ms]	1.20	1.24	1.06	1.10	0.84	0.86			
Torque Constant-KT [N·m/A]	1.566	1.566	1.308	1.308	1.483	1.483			
Voltage Constant-KE [mV/rpm]	64.4	64.4	53.00	53.00	58.9	58.9			
Armature Resistance [Ohm]	0.21	0.21	0.09	0.09	0.07	0.07			
Armature Inductance [mH]	4.94	4.94	2.36	2.36	2.20	2.20			
Electrical Time Constant [ms]	23.52	23.52	26.22	26.22	31.43	31.43			
Insulation Class	Class A (UL), Class B (CE)								
Insulation Resistance	> 100 MΩ, 500VDC								
Insulation Strength		2.3 kVAC, 1 sec							
Weight [kg]	18.5	22.5	23.5	29	30.5	36			
Max. Radial Loading [N]		14	70		1764				
Max. Axial Loading [N]		4	90		588				
Brake Holding Torque [N·m (min)]Note 2		25		55		55			
Brake Power Consumption (at 20°C) [W]		20.4		19.9		19.9			
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10			
Brake Pull-in Time [ms (max)]		70		70		70			
Vibration Grade [µm]			V	15					
Operating Temperature [°C]			0–40 °C (3	32–104 °F)					
Storage Temperature [°C]			-10°C to 80°C (-14°F to 176°F)					
Operating Humidity		20	0–90% relative humi	dity (non-condensin	g)				
Storage Humidity		20	0–90% relative humi	dity (non-condensin	g)				
Vibration Capacity			2.5	5 G					
IP Rating	IP65 (when using	g waterproof connec	ctors and when an o	il seal is fitted to the	rotating shaft (for a	n oil seal model))			
Encoder Resolution			24-bit (1677	7216 p/rev)					
Agency Approvals			_c UR _u	_{IS} , CE					
		Continued on ne							

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.



460V High Inertia Motor Specifications, continued

460V S	ureServo2	High Inerti	a Motor Sp	ecifications	3				
Model	<u>SV2H-475N</u>	<u>SV2H-475B</u>	SV2H-4BON	<u>SV2H-4B0B</u>	SV2H-4F0N	SV2H-4F0B			
Price	\$1,311.00	\$2,047.00	\$2,014.00	\$2,760.00	\$2,324.00	\$3,182.00			
Drawing	PDF	PDF	PDF	PDF	PDF	PDF			
Rated Power [kW]	7.5	7.5	11	11	15	15			
Rated Torque [N·m]Note 1	47.74	47.74	70	70	95.4	95.4			
Max. Torque [N·m]	93.71	93.71	175	175	224.0	224.0			
Rated Speed [rpm]	15	00	1500						
Max. Speed [rpm]	30	00		20	00				
Rated current [Amps] rms	28.7	28.7	26.8	26.8	37.5	37.5			
Max. Instantaneous Current [Amps] rms	57.69	57.69	67.7	67.7	95.3	95.3			
Change of Rated Power [W/s]	159.7	156.6	145.0	141.4	201.8	197.1			
Rotor Inertia [x10-4 kg m2]	142.7	145.5	338	346.5	451	461.8			
Mechanical Time Constant [ms]	0.81	0.83	1.40	1.44	1.21	1.23			
Torque Constant-KT [N·m/A]	1.663	1.663	2.612	2.612	2.544	2.544			
Voltage Constant-KE [mV/rpm]	66.40	66.40	96.00	96.00	83.90	83.90			
Armature Resistance [Ohm]	0.06	0.06	0.0994	0.0994	0.0545	0.0545			
Armature Inductance [mH]	1.70	1.70	2.51	2.51	1.43	1.43			
Electrical Time Constant [ms]	28.33	28.33	25.25	25.25	26.24	26.24			
Insulation Class	Class A (UL),	Class B (CE)	Class F (UL),	Class F (CE)					
Insulation Resistance	> 100 MΩ, 500VDC								
Insulation Strength			2.3 kVAC, 1 sec						
Weight [kg]	40.5	46	56.4	68.4	75	87			
Max. Radial Loading [N]	17	64	3300						
Max. Axial Loading [N]	58	38	1100						
Brake Holding Torque [N·m (min)]Note 2		55		115		115			
Brake Power Consumption (at 20°C) [W]		19.9		28.8		28.8			
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10			
Brake Pull-in Time [ms (max)]		70		70		70			
Vibration Grade [µm]			V	15					
Operating Temperature [°C]			0–40 °C (3	82–104 °F)					
Storage Temperature [°C]			-10°C to 80°C (-14°F to 176°F)					
Operating Humidity		20	–90% relative humi	dity (non-condensir	g)				
Storage Humidity		20	–90% relative humi	dity (non-condensir	g)				
Vibration Capacity			2.5	G					
IP Rating	IP65 (when using	waterproof connect	tors and when an oi	I seal is fitted to the	rotating shaft (for a	n oil seal model)			
Encoder Resolution			24-bit (1677	7216 p/rev)					
Agency Approvals			cURU	_S , CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

550mm x 550mm x 30mm

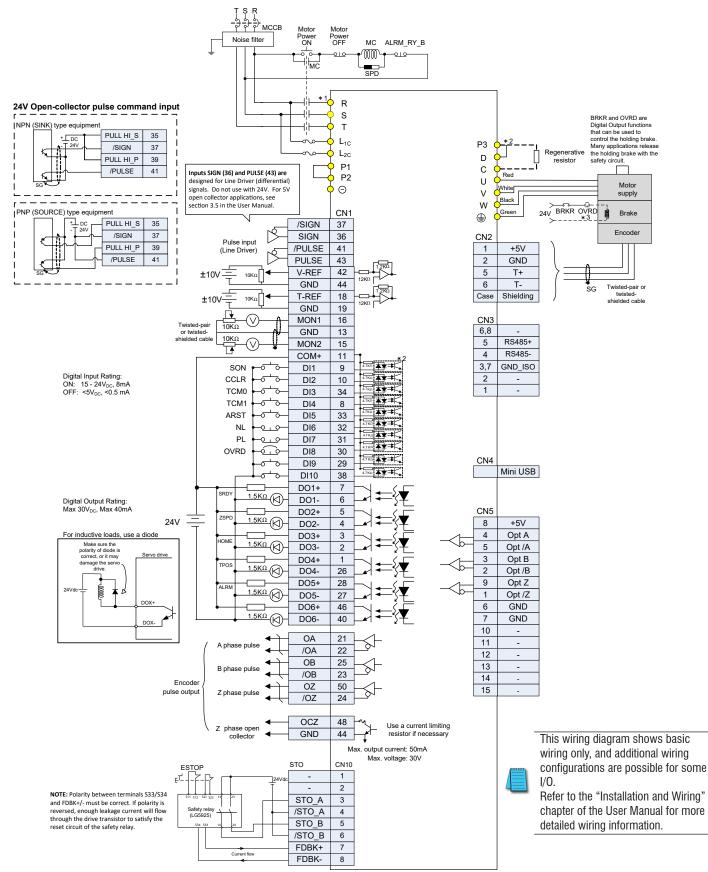
All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.



AC Servo System Wiring

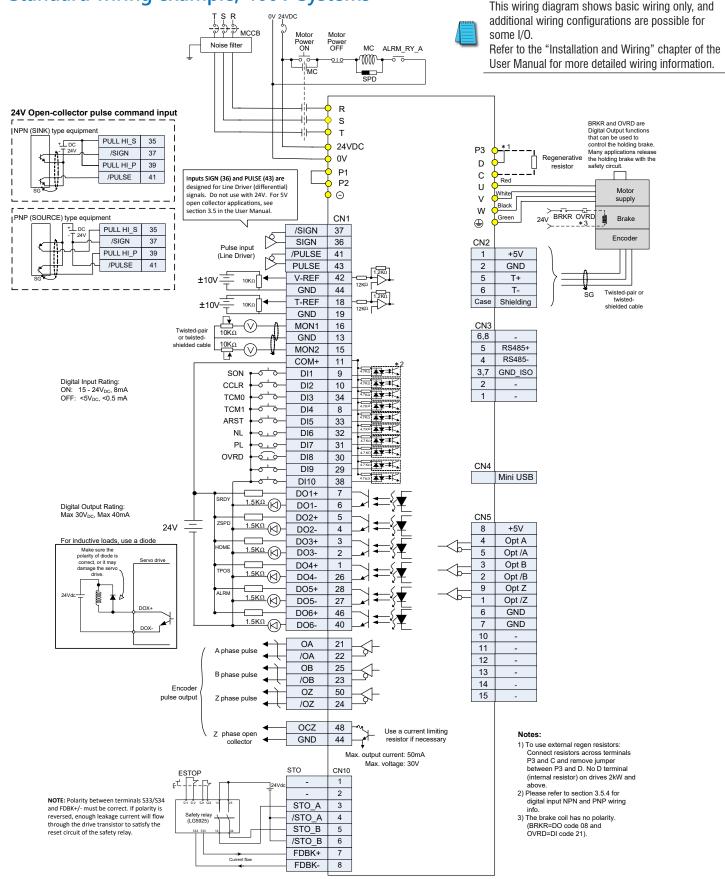
Standard wiring example, 230V Systems



1-800-633-0405 Sure//-2

AC Servo System Wiring

Standard wiring example, 460V Systems

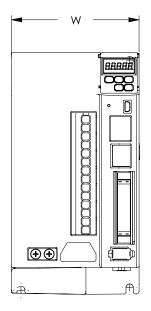


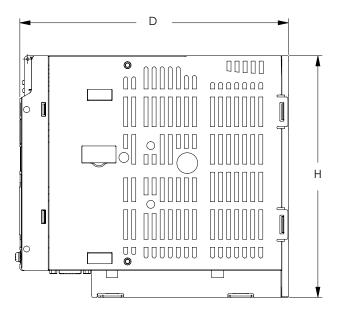
www.automationdirect.com



AC Servo System Dimensions

Servo drive dimensions





S	ureServo2	Drive Dime	nsions	
Model	Drawing Link	W mm [inches]	D mm [inches]	H mm [inches]
<u>SV2A-2040</u>	PDF	35 [1.38]	170 [6.69]	170 [6.69]
<u>SV2A-2075</u>	PDF	50 [1.97]	180 [7.09]	180 [7.09]
<u>SV2A-2150</u>	PDF	50 [1.97]	180 [7.09]	180 [7.09]
<u>SV2A-2200</u>	PDF	95 [3.74]	200 [7.87]	180 [7.09]
<u>SV2A-2300</u>	PDF	95 [3.74]	200 [7.87]	180 [7.09]
<u>SV2A-2550</u>	PDF	120 [4.72]	206 [8.12]	273 [10.75]
<u>SV2A-2750</u>	<u>PDF</u>	141 [5.56]	226 [8.90]	312 [12.28]
<u>SV2A-2F00</u>	PDF	186 [7.32]	281 [11.08]	390 [15.35]
<u>SV2A-4040</u>	<u>PDF</u>	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4075</u>	PDF	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4150</u>	<u>PDF</u>	65 [2.55]	204 [8.03]	180 [7.09]
<u>SV2A-4200</u>	PDF	110 [4.33]	200.8 [7.9]	260 [10.24]
<u>SV2A-4300</u>	PDF	110 [4.33]	200.8 [7.9]	260 [10.24]
<u>SV2A-4550</u>	PDF	110 [4.33]	200.8 [7.9]	260 [10.24]
<u>SV2A-4750</u>	PDF	120 [4.72]	206.3 [8.12]	273 [10.75]
<u>SV2A-4F00</u>	PDF	141 [5.55]	225.5 [8.88]	312 [12.28]

For additional dimensions, see the AutomationDirect website or click on the drawing links.

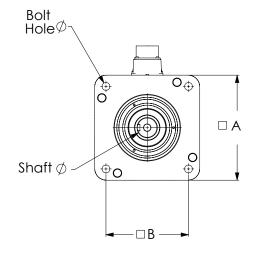
Requires 2" above and below the drive for air flow. For proper air flow clearance, please see section 2.3.1 of the SureServo2 User Manual.

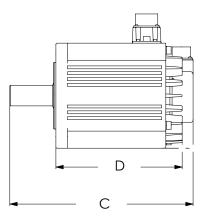
For cabinet depth, add approximately 100mm (4 inches) for CN1 (I/O) and CN2 (encoder) cable bend radius.



AC Servo System Dimensions

230V Servo motor dimensions





		SureServo	2 230V Mo	tor Dimens	ions		
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]
<u>SV2L-201N</u>	PDF	40.0 [1.57]	32.2 [1.27]	110.3 [4.34]	85.3 [3.36]	4.5 [0.18]	8.0 [0.31]
<u>SV2L-201B</u>	PDF	40.0 [1.57]	32.2 [1.27]	145.1 [5.71]	120.1 [4.73]	4.5 [0.18]	8.0 [0.31]
<u>SV2L-202N</u>	PDF	60.0 [2.36]	49.5 [1.95]	113.9 [4.49]	84.0 [3.31]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-202B</u>	PDF	60.0 [2.36]	49.5 [1.95]	147.6 [5.81]	117.1 [4.61]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-204N</u>	PDF	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-204B</u>	PDF	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-207N</u>	PDF	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [2.51]	19.0 [0.75]
<u>SV2L-207B</u>	PDF	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [2.51]	19.0 [0.75]
<u>SV2L-210N</u>	PDF	100.0 [3.94]	81.3 [3.20]	198.3 [7.81]	110.2 [4.34]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-210B</u>	PDF	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	149.5 [5.89]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-210N</u>	PDF	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	104.5 [4.11]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-210B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	140.5 [5.53]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-215N</u>	PDF	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	120.5 [4.74]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-215B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	155.0 [6.10]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-220N</u>	PDF	180.0 [7.09]	141.4 [5.57]	247.7 [9.75]	150.0 [5.91]	13.5 [0.53]	35.0 [1.38]
<u>SV2M-220B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	281.8 [11.09]	184.1 [7.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2M-230N</u>	PDF	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	183.1 [7.21]	13.5 [0.53]	35.0 [1.38]
<u>SV2M-230B</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-245N</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-245B</u>	PDF	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	260.3 [10.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-255N</u>	PDF	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	260.7 [10.26]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-255B</u>	PDF	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	292.7 [11.52]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-275N</u>	PDF	180.0 [7.09]	141.4 [5.57]	454.70 [17.9]	323.0 [12.72]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-275B</u>	PDF	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	357.1 [14.06]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-2BON</u>	PDF	219.9 [8.66]	166.2 [6.54]	487.4 [19.19]	319.0 [12.56]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-2B0B</u>	PDF	219.9 [8.66]	166.2 [6.54]	550.4 [21.67]	382.0 [15.04]	13.5 [0.53]	42.0 [1.63]
<u>SV2H-2FON</u>	PDF	219.9 [8.66]	166.2 [6.54]	566.4 [22.30]	398.0 [15.67]	13.5 [0.53]	55.0 [2.17]
<u>SV2H-2F0B</u>	PDF	219.9 [8.66]	166.2 [6.54]	629.4 [24.78]	461.0 [18.15]	13.5 [0.53]	55.0 [2.17]

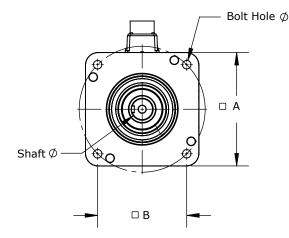
NOTE: Motor cables are approximately 304mm (12") in length.

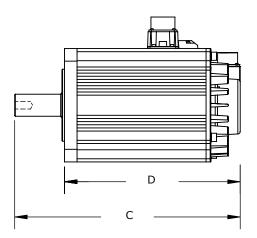
For additional dimensions, see the AutomationDirect website or click on the drawing links.



AC Servo System Dimensions

460V Servo motor dimensions





		SureServo	2 460V Mo	tor Dimens	ions		
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]
<u>SV2L-404N</u>	PDF	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-404B</u>	PDF	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-407N</u>	PDF	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-407B</u>	PDF	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-410N</u>	PDF	100.0 [3.94]	81.3 [3.20]	198.2 [7.81]	153.2 [6.03]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-410B</u>	PDF	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	192.5 [7.58]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415N</u>	PDF	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	167.5 [6.59]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415B</u>	PDF	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	202.0 [7.95]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-420N</u>	PDF	130.0 [5.12]	102.5 [4.04]	242.5 [9.55]	187.5 [7.38]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-420B</u>	PDF	130.0 [5.12]	102.5 [4.04]	271.0 [10.67]	216.0 [8.50]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410N</u>	PDF	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	147.5 [5.81]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410B</u>	PDF	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	183.5 [7.22]	9.0 [0.35]	22.0 [0.87]
<u>SV2H-430N</u>	PDF	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	201.8 [7.94]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-430B</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445N</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445B</u>	PDF	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	279.0 [10.98]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-455N</u>	PDF	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	279.4 [11.00]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-455B</u>	PDF	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	311.4 [12.26]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475N</u>	PDF	180.0 [7.09]	141.4 [5.57]	454.7 [17.90]	341.7 [13.45]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475B</u>	PDF	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	375.8 [14.80]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-4BON</u>	PDF	220.0 [8.66]	166.2 [6.54]	487.4 [19.19]	371.4 [14.62]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-4B0B</u>	PDF	220.0 [8.66]	166.2 [6.54]	550.4 [21.67]	434.4 [17.10]	13.5 [0.53]	42.0 [1.65]
SV2H-4F0N	PDF	220.0 [8.66]	166.2 [6.54]	566.4 [22.30]	450.4 [17.73]	13.5 [0.53]	55.0 [2.17]
SV2H-4F0B	PDF	220.0 [8.66]	166.2 [6.54]	629.4 [24.78]	513.4 [20.21]	13.5 [0.53]	55.0 [2.17]



NOTE: Motor cables are approximately 304mm (12") in length.

or of

For additional dimensions, see the AutomationDirect website or click on the drawing links.

For the latest prices, please check AutomationDirect.com.



AC Servo System Accessories

Accessories

CN1 Accessories

The terminal block module and direct mount feedthrough module allow for I/O connections to a SureServo2 drive.

Option 1:

Select an SV2-CN1-CBL50 cable (3 lengths available) and the DIN rail mount SV2-CN1-RTB50 Remote Terminal Block for access to all 50 of the drive's digital and analog I/O signals.

Option 2:

Select the SV2-CN1-LTB20 Local Terminal Block. The LTB20 can be used in many applications and allows connection to the most frequently-used I/O: High speed line driver pulse inputs (Pulse and Direction, AB Quad, etc.), (5) Digital Inputs, (4) Digital Outputs, and the Z-pulse open collector output.



SV2-CN1-RTB50

Part Number	Price	Description	Cable Length	Drawing	Compatible Drives
<u>SV2-CN1-RTB50</u>	\$58.00	SureServo2 feedthrough module, 50-pole, DIN rail mount	-	PDF	
SV2-CN1-CBL50	\$71.00	SureServo2 CN1 I/O	0.5 m		All
SV2-CN1-CBL50-1	\$75.00	control cable with	1m	- 1	
SV2-CN1-CBL50-2	\$79.00	mating connectors	2m		
<u>SV2-CN1-LTB20</u>	\$43.00	SureServo2 feedthrough module, 20-pole, direct mount	-	PDF	



Communication Modules

SureServo2 drives can also make use of optional communication cards. Both EtherNet/IP and Modbus TCP cards are available. Field upgradeable firmware ensures that the cards can always be kept current.

ModBus TCP

The SV2-CM-MODTCP Modbus TCP card allows the same access to all the drive parameters as the native serial Modbus (RS485).

EtherNet/IP

The SV2-CM-ENETIP Ethernet/IP card allows both Explicit and Implicit (I/O) Messaging. The SureServo2 Pro software allows you to easily generate (with pull-down menus) an EDS file for import into your PLC that contains exactly what you want in your Implicit Message.

Part Number	Price	Description	Drawing	Compatible Drives
<u>SV2-CM-ENETIP</u>	\$107.00	SureServo2 communication module, EtherNet/IP, 1 port, (1) Ethernet (RJ45) port.	<u>PDF</u>	
<u>SV2-CM-MODTCP</u>	\$97.00	SureServo2 communication module, Modbus TCP, 1 port, (1) Ethernet (RJ45) port.	PDF	All SureServo2 drives



SV2-CM-ENETIP or SV2-CM-MODTCP



Accessories, continued

Motor Cables

Use the table to the right to select the correct SV2 motor cables (power, encoder, and brake) for your SureServo2 motor. Note that the largest frame brakemotors require a separate brake cable: 230V motors 5.5–15 kW and 460V motors 11kW–15kW. For smaller brakemotors, the brake wiring is incorporated into the motor power cable.

First find the motor part number in the left column, then reference the required cable part series under the Power, Encoder, and Brake columns. The first two "x" digits in the part numbers below are placeholders to represent length in meters while the 3rd "x" denotes flex (F) or non-flex (N) cabling. Brake vs non-brake cables are represented by a "B" or "N" at the end of the part number. For example, a 20m non-flex non-brake cable would end in 20NN, while a 3m flex-rated brake motor cable would end in 03FB. Note that SV2H series motors (5.5 kW and greater) use a separate cable to power the brake, so use an "N" cable for motor power. Also, if you use a flex-rated power cable (F series) you should use flex-rated encoder and brake power cables. The flex cables may not feel more flexible when compared sideby-side with the non-flex versions, but they are constructed with finer strands of wire and are designed to withstand millions of flex cycles (continuous flexing) without suffering from "cable corkscrew".

Specs and prices for the various cable options in each series can be found in the tables on the following pages.

Example:

You are purchasing an SV2L-201B brake motor and want 10m flex-rated cabling. What cables do you need? The abbreviated motor chart below shows that the SV2L-201B brake motor needs a PB18 series power cable and an E122 series encoder cable. Brake power is supplied through the power cable. The cable charts on subsequent pages enumerate all the various options and show that a 10m, flex, E122 series encoder cable is SV2C-E122-10FN and that a 10m, flex, PB series power cable is SV2C-PB18-10FB.

SureServo	2® Motor	Power Cable	Encoder Cable	Brake Cable			
230V	460V	ruwei Gable	Elicouel Cable	DI ANE CADIE			
<u>SV2L-201N</u> <u>SV2L-202N</u> <u>SV2L-204N</u> <u>SV2L-207N</u>	<u>SV2L-404N</u> <u>SV2L-407N</u>	SV2C-PA18-xxxN	- SV2C-E122-xxxN				
<u>SV2L-201B</u> <u>SV2L-202B</u> <u>SV2L-204B</u> <u>SV2L-207B</u>	<u>SV2L-404B</u> <u>SV2L-407B</u>	SV2C-PB18-xxxB	3V20-L 122-XXXIV				
<u>SV2L-210N</u>	<u>SV2L-410N</u> <u>SV2M-410N</u> <u>SV2L-415N</u> <u>SV2L-420N</u>	SV2C-PC16-xxxN					
<u>SV2L-210B</u>	<u>SV2L-410B</u> <u>SV2M-410B</u> <u>SV2L-415B</u> <u>SV2L-420B</u>	SV2C-PC16-xxxB					
SV2M-210N SV2M-215N	-	SV2C-PC12-xxxN		n/a			
<u>SV2M-210B</u> <u>SV2M-215B</u>	-	SV2C-PC12-xxxB					
SV2M-220N SV2M-230N	<u>SV2H-430N</u>	SV2C-PD12-xxxN					
SV2M-220B SV2M-230B	<u>SV2H-430B</u>	SV2C-PD12-xxxB					
<u>SV2H-245N</u>	<u>SV2H-445N</u> <u>SV2H-455N</u> <u>SV2H-475N</u>	SV2C-PD08-xxxN	SV2C-E222-xxxN				
<u>SV2H-245B</u>	<u>SV2H-445B</u> <u>SV2H-455B</u> <u>SV2H-475B</u>	SV2C-PD08-xxxB					
<u>SV2H-255N</u> <u>SV2H-275N</u> <u>SV2H-2B0N</u>	-	SV2C-PF06-xxxN					
<u>SV2H-255B</u> <u>SV2H-275B</u> <u>SV2H-2B0B</u>	-	SV2C-PF06-xxxN		SV2C-B120-xxxB			
SV2H-2F0N	-	SV2C-PF04-xxxN		n/a			
SV2H-2F0B	-	SV2C-PF04-xxxN		SV2C-B120-xxxB			
-	SV2H-4B0N SV2H-4F0N	SV2C-PF08-xxxN]	n/a			
-	<u>SV2H-4B0B</u> <u>SV2H-4F0B</u>	SV2C-PF08-xxxN		SV2C-B120-xxxB			





Encoder Cables



Separate Brake Cable (for large frame motors (see table))



Accessories, continued

SV2C-E122 Series Encoder Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-E122-03NN	\$60.00	N	3m		PDF		
SV2C-E122-05NN	\$82.00		5m		PDF		
SV2C-E122-10NN	\$130.00		10m		PDF		SV2L-201x SV2L-202x SV2L-204x SV2L-207x
SV2C-E122-20NN	\$213.00		20m		PDF		
SV2C-E122-03FN	\$77.00		3m	22	PDF	SV2C-E1-CON	
SV2C-E122-05FN	\$109.00	v	5m		PDF		SV2L-404x SV2L-407x
SV2C-E122-10FN	\$182.00	ř	10m		PDF		
SV2C-E122-20FN	\$316.00		20m		PDF		

SV2C-E222 Series Encoder Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-E222-03NN	\$130.00		3m		PDF		SV2L-210x SV2L-410x
SV2C-E222-05NN	\$213.00	N	5m		PDF		SV2M-210x SV2M-410x
SV2C-E222-10NN	\$265.00	IN	10m	1 22	PDF		SV2M-215x SV2L-415x SV2M-220x SV2L-420x
SV2C-E222-20NN	\$350.00		20m		PDF	SV2C-E2-CON	SV2M-220X SV2L-420X SV2M-230X SV2H-430X
SV2C-E222-03FN	\$168.00		3m		PDF	<u>5V2C-E2-CON</u>	SV2H-245x SV2H-445x
SV2C-E222-05FN	\$206.00	v	5m		PDF		SV2H-255x SV2H-455x SV2H-275X SV2H-475X
SV2C-E222-10FN	\$317.00] ř	10m]	PDF		SV2H-2B0x SV2H-4B0x
<u>SV2C-E222-20FN</u>	\$453.00		20m	ו	PDF		SV2H-2F0x SV2H-4F0x

SV2C-PA18 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors	
SV2C-PA18-03NN	\$41.00		3m		PDF			
SV2C-PA18-05NN	\$54.00	N	5m	18	PDF			
SV2C-PA18-10NN	\$80.00	N	10m		PDF		SV2L-201N SV2L-202N SV2L-204N SV2L-207N	
SV2C-PA18-20NN	\$128.00		20m		PDF			
<u>SV2C-PA18-03FN</u>	\$57.00		3m	10	PDF	SV2C-PA-CON		
SV2C-PA18-05FN	\$77.00	V	5m		PDF		SV2L-404N SV2L-407N	
SV2C-PA18-10FN	\$124.00	r	10m	n	PDF		0V2L-40/14	
SV2C-PA18-20FN	\$212.00		20m		PDF			



Accessories, continued

SV2C-PB18 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PB18-03NB	\$48.00		3m		PDF		
SV2C-PB18-05NB	\$63.00	N	5m		PDF		SV2L-201B SV2L-202B SV2L-204B SV2L-207B SV2L-207B SV2L-404B SV2L-407B
SV2C-PB18-10NB	\$100.00		10m	10	PDF	<u>SV2C-PB-CON</u>	
SV2C-PB18-20NB	\$163.00		20m		PDF		
SV2C-PB18-03FB	\$72.00		3m	18	PDF		
SV2C-PB18-05FB	\$105.00	v	5m		PDF		
SV2C-PB18-10FB	\$176.00	Ŷ	10m		PDF		
SV2C-PB18-20FB	\$313.00		20m		PDF		

SV2C-PC16 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PC16-03NN	\$140.00		3m		PDF		
SV2C-PC16-05NN	\$166.00	N	5m		PDF		
SV2C-PC16-10NN	\$219.00	N	10m		PDF		SV2L-210N
SV2C-PC16-20NN	\$318.00		20m	16	PDF		SV2L-410N
SV2C-PC16-03FN	\$154.00		3m	10	PDF		SV2M-410N SV2L-415N SV2L-420N
SV2C-PC16-05FN	\$186.00	Y	5m		PDF	<u>SV2C-PC-CON</u>	
SV2C-PC16-10FN	\$261.00	Ť	10m		PDF		
SV2C-PC16-20FN	\$401.00		20m		PDF		
SV2C-PC16-03NB	\$164.00		3m		PDF		
SV2C-PC16-05NB	\$198.00	N	5m		PDF		
SV2C-PC16-10NB	\$274.00	Ν	10m		PDF	-	SV2L-210B
SV2C-PC16-20NB	\$415.00		20m	16	PDF		SV2L-410B
SV2C-PC16-03FB	\$184.00		3m	1 10	PDF		SV2M-410B SV2L-415B
SV2C-PC16-05FB	\$230.00	Y	5m]	PDF	-	SV2L-420B
SV2C-PC16-10FB	\$335.00		10m		PDF		
SV2C-PC16-20FB	\$537.00		20m		PDF		



Accessories, continued

SV2C-PC12 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PC12-03NN	\$192.00		3m		PDF		
SV2C-PC12-05NN	\$251.00	N	5m		PDF		
SV2C-PC12-10NN	\$391.00	IN	10m		PDF		
SV2C-PC12-20NN	\$659.00	Y	20m	12	PDF		SV2M-210N
SV2C-PC12-03FN	\$210.00		3m		PDF		SV2M-215N
SV2C-PC12-05FN	\$279.00		5m		PDF	<u>SV2C-PC-CON</u>	
SV2C-PC12-10FN	\$443.00	T	10m		PDF		
SV2C-PC12-20FN	\$760.00		20m		PDF		
SV2C-PC12-03NB	\$213.00		3m		PDF		
SV2C-PC12-05NB	\$280.00	Ν	5m		PDF		
SV2C-PC12-10NB	\$442.00	IN	10m		PDF	-	
SV2C-PC12-20NB	\$752.00		20m	12	PDF		SV2M-210B
SV2C-PC12-03FB	\$235.00		3m	12	PDF		SV2M-215B
SV2C-PC12-05FB	\$316.00	Y	5m]	PDF	_	
SV2C-PC12-10FB	\$513.00	ř	10m		PDF		
SV2C-PC12-20FB	\$892.00		20m		PDF		

SV2C-PD12 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PD12-03NN	\$175.00		3m		PDF		
SV2C-PD12-05NN	\$223.00	N	5m		PDF		
SV2C-PD12-10NN	\$342.00	IN	10m		PDF		
SV2C-PD12-20NN	\$570.00		20m	12	PDF		SV2M-220N SV2M-230N
SV2C-PD12-03FN	\$188.00		3m	12	PDF		SV2H-430N
SV2C-PD12-05FN	\$246.00	Y	5m	-	PDF	SV2C-PD-CON	
SV2C-PD12-10FN	\$386.00	ř	10m		PDF		
SV2C-PD12-20FN	\$655.00		20m		PDF		
SV2C-PD12-03NB	\$194.00		3m		PDF		
SV2C-PD12-05NB	\$251.00	N	5m		PDF		
SV2C-PD12-10NB	\$386.00	IN	10m		PDF		
SV2C-PD12-20NB	\$649.00		20m	12	PDF		SV2M-220B
SV2C-PD12-03FB	\$212.00		3m	12	PDF		SV2M-230B SV2H-430B
SV2C-PD12-05FB	\$281.00	Y	5m]	PDF		57211 1000
SV2C-PD12-10FB	\$447.00) ř	10m]	PDF		
SV2C-PD12-20FB	\$768.00		20m		PDF		



Accessories, *continued*

SV2C-PD08 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PD08-03NN	\$238.00		3m		PDF		
SV2C-PD08-05NN	\$325.00	N	5m		PDF		
SV2C-PD08-10NN	\$544.00	IN	10m		PDF		SV2H-245N
SV2C-PD08-20NN	\$970.00		20m	8	PDF		SV2H-445N
SV2C-PD08-03FN	\$258.00		3m	0	PDF		SV2H-455N SV2H-475N
SV2C-PD08-05FN	\$360.00	Y	5m		PDF	<u>SV2C-PD-CON</u>	
SV2C-PD08-10FN	\$612.00	ř	10m		PDF		
SV2C-PD08-20FN	\$1,108.00		20m		PDF		
SV2C-PD08-03NB	\$231.00		3m		PDF		SV2H-245B SV2H-445B
SV2C-PD08-05NB	\$326.00		5m		PDF		
SV2C-PD08-10NB	\$559.00	N	10m		PDF		
SV2C-PD08-20NB	\$1,009.00		20m	8	PDF		
SV2C-PD08-03FB	\$272.00		3m	0	PDF		SV2H-455B
SV2C-PD08-05FB	\$383.00	Y	5m]	PDF		SV2H-475B
SV2C-PD08-10FB	\$659.00	Y	10m		PDF		
SV2C-PD08-20FB	\$1,192.00		20m		PDF		

SV2C-PF08 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PF08-03NN	\$241.00		3m		PDF		
SV2C-PF08-05NN	\$297.00	N	5m		PDF		
SV2C-PF08-10NN	\$433.00	IN	10m		PDF	SV2C-PF-CON	SV2H-4B0N SV2H-4B0B SV2H-4F0N SV2H-4F0B
SV2C-PF08-20NN	\$750.00		20m		PDF		
SV2C-PF08-03FN	\$305.00		3m	8	PDF		
SV2C-PF08-05FN	\$401.00	v	5m		PDF		
SV2C-PF08-10FN	\$633.00	r	10m		PDF		
SV2C-PF08-20FN	\$1,148.00		20m		PDF		

SV2C-PF06 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PF06-03NN	\$323.00		3m		PDF		
SV2C-PF06-05NN	\$478.00	N	5m		PDF		
SV2C-PF06-10NN	\$833.00	N	10m		PDF	SV2C-PF-CON	SV2H-255N SV2H-255B SV2H-275N SV2H-275B SV2H-275B SV2H-2B0N SV2H-2B0B
SV2C-PF06-20NN	\$1,507.00		20m		PDF		
SV2C-PF06-03FN	\$376.00		3m	6	PDF		
SV2C-PF06-05FN	\$528.00	v	5m		PDF		
SV2C-PF06-10FN	\$913.00	ř	10m		PDF		
SV2C-PF06-20FN	\$1,660.00		20m		PDF		



Accessories, *continued*

SV2C-PF04 Series Power Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-PF04-03NN	\$382.00		3m		PDF		
SV2C-PF04-05NN	\$539.00	N	5m		PDF	<u>SV2C-PF-CON</u>	SV2H-2F0N SV2H-2F0B
SV2C-PF04-10NN	\$909.00	IN	10m		PDF		
SV2C-PF04-20NN	\$1,652.00		20m		PDF		
SV2C-PF04-03FN	\$434.00		3m	4	PDF		
SV2C-PF04-05FN	\$612.00	v	5m		PDF		
SV2C-PF04-10FN	\$1,064.00	Y	10m		PDF		
SV2C-PF04-20FN	\$1,944.00		20m		PDF		

SV2C-B120 Series Brake Cables

Part Number	Price	Flex Rated	Length	Gauge	Drawing	Connector	Compatible Motors
SV2C-B120-03NB	\$88.00		3m		PDF		
SV2C-B120-05NB	\$102.00	N	5m		PDF		
SV2C-B120-10NB	\$128.00	IN	10m		PDF	- <u>SV2C-B1-CON</u>	SV2H-255B SV2H-275B SV2H-2B0B SV2H-2F0B SV2H-4B0B SV2H-4F0B
SV2C-B120-20NB	\$172.00		20m		PDF		
SV2C-B120-03FB	\$95.00		3m	20	PDF		
SV2C-B120-05FB	\$112.00		5m		PDF		
SV2C-B120-10FB	\$149.00	ľ	10m		PDF		
SV2C-B120-20FB	\$214.00		20m	1	PDF		



Accessories, continued

External Encoder CN5 Cables

CN5 secondary encoder cables can be used to connect an external secondary encoder to a SureServo2 drive. The CN5 uses a wire not present in standard VGA cables - you must use one of these cables, standard HD15 VGA cables will not work.

Part Number	Price	Description	Length	Drawing	Compatible Drives
ZL-HD15M-CBL-2P	\$19.00	ZIPLink communication cable, 15-pin D-sub HD15 male to pigtail, shielded, twisted pair.	2m	PDF	All SV2 drives
ZL-HD15M-CBL-DB15F*	\$20.50	ZIPLink communication cable, 15-pin female D-sub to 15-pin D-sub HD15 male, shielded, twisted pair.	2m	PDF	All 3v2 drives

* ZL-RTB-DB15 is required to use the ZL-HD15M-CBL-DB15F cable

Pin Number	Color	Signal	Function
1	Black/White	Opt_/Z	/Z phase input
2	Blue/White	Opt_/B	/B phase input
3	Blue	Opt_B	B phase input
4	Green	Opt_A	A phase input
5	Green/White	Opt_/A	/A phase input
6	Yellow Yellow/Black	GND	Encoder grounding
7	Red/White	GND	Encoder grounding
8	Red	+5V	Encoder power
9	Black	Opt_Z	Z phase input
10	Orange	Reserved	Reserved
11	Orange/White	Reserved	Reserved
12	Brown	Reserved	Reserved
13	Brown/White	Reserved	Reserved
14	Purple	Reserved	Reserved
15	Purple/White	Reserved	Reserved



ZL-HD15M-CBL-2P







ZL-HD15M-CBL-DB15F

Battery Box

An optional external battery can be used to power SureServo2 encoders. The battery allows the use of Absolute Encoder Mode. This mode will keep track of the motor actual position (regardless of number of turns) even if control power is removed from the drive.

SV2-BBOX-1 attaches to the encoder cable. There is a small connector protruding from each encoder cable several inches from the drive-end connector. This connector plugs into the SV2-BBOX-1.

SV2-BBOX-CBL is not required for most applications. Use this cable to extend the length from the encoder cable's connector to the BBOX. This is used if you do not want the BBOX clamped onto the encoder cable right under the drive.

Part Number	Price	Description	Length	Drawing	Compatible Drives
<u>SV2-BBOX-1</u>	\$22.50	SureServo2 encoder single battery box, for use with all SureServo2 drives. (1) AA ER14505 lithium battery included.	_	<u>PDF</u>	
<u>SV2-BBOX-CBL</u>	\$3.00	SureServo2 battery box cable, mating connectors, 7.8 in/200mm cable length. For use with SureServo2 encoder battery box.	200mm	<u>PDF</u>	All SV2 drives





SV2-BBOX-1 Servo Systems tSRV-141

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Accessories, continued

Serial Comms Connectors

Available serial comms connectors consist of an RS-485 splitter and an RS-485 terminating resistor. These connectors (and the drive's CN3) all use RJ45 connectors.

With these two connectors, you can easily create a multi-drop RS485 connection with minimal manual wiring. For multi-drop systems, use one SV2-CN3-CON-2 per drive. Connect each drive with a standard RJ45 (Ethernet patch) cable. On the last drive in the daisy-chain, plug in an SV2-CN3-TR2 to terminate the network. On the first drive, either strip one end of a patch cable to wire into your controller/PLC or plug into a ZL-RTB-RJ45 breakout board for easy wiring to your controller/PLC.

Part Number	Price	Description	Drawing	Compatible Drives
<u>SV2-CN3-CON-2</u>	\$11.50	SureServo2 splitter, (2) RS-485 (RJ45) to (1) RS-485 (RJ45)	<u>PDF</u>	All SureServo2 Drives
<u>SV2-CN3-TR2</u>	\$5.25	Terminating resistor, 120 ohm, RJ45 8P8C male.	PDF	Drives

Toroid

A toroid (ferrite ring) is available for use with all SureServo2 drives to reduce radiated noise. See the user manual for application information for the SV2-TOR1.

Part Number	Price	Description	Drawing	Compatible Drives
<u>SV2-TOR1</u>	\$13.50	Toroid ring for EMI/RFI filtering (2 per pack)	PDF	All SureServo2 Drives



SV2-CN3-CON-2



SV2-CN3-TR2



SV2-TOR1

Cable Connectors

Use the cable connectors below to build your own motor power, brake, or encoder cable.

Part Number	Price	Description	Drawing	Compatible With
SV2C-PA-CON	\$11.50		PDF	750W or smaller SureServo2 motors w/o brake
SV2C-PB-CON	\$13.50		<u>PDF</u>	750W or smaller SureServo2 motors w/brake
SV2C-PC-CON	\$40.00	SureServo2 motor power connector	PDF	All 1 and 1.5 kW and 460V series 2kW SureServo2 motors
SV2C-PD-CON	\$47.00		PDF	230V series 2 to 4.5 kW and 460V series 3 to 7.5 kW SureServo2 motors
SV2C-PF-CON	\$69.00		PDF	230V series 5.5 to 15kW and 460V series 11 and 15kW SureServo2 motors
SV2C-E1-CON	\$10.00	SureServo2 motor encoder	PDF	750W or smaller SureServo2 motors
SV2C-E2-CON	\$37.00	connector	PDF	1kW and larger SureServo2 motors
<u>SV2C-E3-CON</u>	\$10.00	CN2 encoder cable (connection to drive)	PDF	All SureServo2 drives
SV2C-B1-CON	\$32.00	SureServo2 motor brake connector	PDF	230V series 5.5 to 15kW and 460V series 11 and 15kW SureServo2 motors with brake



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SV2C-PF-CON



Accessories, *continued*

Replacement Connectors

The following replacement connectors can be purchased for use with SureServo2 drives. SV2-CN1-CON and SV2-CN10-STO are standalone connectors, while SV2-CON-KIT is a set of connectors.

Part Number	Price	Description	Drawing	Compatible With
<u>SV2-CN1-CON</u>	\$17.50	Optional 50-pin CN1 I/O connector (solder)	-	All SureServo2 drives
<u>SV2-CON-KIT</u>	\$21.50	SureServo2 replacement connector kit, contains: (1) SV2-CN10-STO connector (2) AC power connectors (1) Power resistor connector (1) Motor power connector (2) Wire insert tools	_	Up to 1.5 kW 230V SureServo2 drives (460V drives use integrated terminals)
<u>SV2-CN10-STO</u>	\$10.00	Replacement SureServo2 STO connector	PDF	All SureServo2 drives







SV2-CN10-STO

SV2-CN1-CON

Replacement Drive Fans

The following replacement fans can be purchased for use with SureServo2 drives. Each fan can be used to replace the fan on a specific 230 and 460 V drive. Please see the table below to find the correct part.

Part Number	Price	Description
<u>SV2-FAN-1</u>	\$15.00	SureServo2 main cooling fan, replacement, 40 x 40 x 15mm, 12 VDC. For use with SureServo2 SV2A-2075 and SV2A-2150 drives. Electrical connector included.
<u>SV2-FAN-2</u>	\$14.00	SureServo2 main cooling fan, replacement, 50 x 50 x 20mm, 12 VDC. For use with SureServo2 SV2A-2200 and SV2A-2300 drives. Electrical connector included.
<u>SV2-FAN-3</u>	\$23.00	SureServo2 main cooling fan, replacement, 50 x 50 x 20mm, 12 VDC. For use with SureServo2 SV2A-4040, SV2A-4075 and SV2A-4150 drives. Electrical connector included.
<u>SV2-FAN-4</u>	\$24.00	SureServo2 main cooling fan, replacement, 60 x 60 x 25mm, 12 VDC. For use with SureServo2 SV2A-2550, SV2A-4300 and SV2A-4550 drives. Electrical connector included.
<u>SV2-FAN-5</u>	\$19.00	SureServo2 main cooling fan, replacement, 60 x 60 x 20mm, 12 VDC. For use with SureServo2 SV2A-2550, SV2A-4200 and SV2A-4550 drives. Electrical connector included.
<u>SV2-FAN-6</u>	\$27.00	SureServo2 main cooling fan, replacement, 70 x 70 x 25mm, 12 VDC. For use with SureServo2 SV2A-2750 and SV2A-4750 drives. Electrical connector included.
<u>SV2-FAN-7</u>	\$49.00	SureServo2 main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with SureServo2 SV2A-2F00 drive. Electrical connector included.
<u>SV2-FAN-8</u>	\$38.00	SureServo2 main cooling fan, replacement, 92 x 92 x 38mm, 12 VDC. For use with SureServo2 SV2A-4F00 drive. Electrical connector included.



SV2-FAN-1

