# Sure/v-2

### **AC Servo Systems**

#### **Drive features**

- Power:
- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW
- Fully digital with up to 3.1 kHz bandwidth velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the SureServo2 Pro PCbased software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- · Communications include:
- Serial Modbus (native/built-in)
- Optional Modbus TCP card
- Optional Ethernet/IP card (this card can use implicit and explicit messaging. SureServo2 Pro software can generate an EDS file to transfer custom data between PLC and drive)
- · Command options include:
- ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
- Powerful built-in motion controller for position control using 99 preset positions (enter these during development, or send them through the communications options above during runtime)
- Internal sequencing for position/speed

# commands, registration (capture/compare), electronic camming, homing (10 different options), Jumps, and arithmetic statements.

- The 3.1 kHz bandwidth allows for high-level automatic tuning. Several modes of tuning are available including Auto Tune that can estimate the load inertia and fine-tune the system when all the loads are attached.
- Optically isolated digital inputs (10) and outputs (6), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution).
- Other Features:
- Secondary/Auxiliary encoder feedback (for true closed loop control)
- Registration ability
- Analog positioning
- Safe Torque Off (STO) included so no need for large, bulky contactors to disconnect power from the drive in E-stop situations
- Absolute Encoder operation (with optional encoder battery backup)
- Electronic camming (you can define the cam with SureServo2 Pro software or you can import an Excel spreadsheet)
- Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.

#### **Motor features**

- · Low inertia models:
- 100W, 200W, 400W, 750W, 1kW, 1.5 kW, and 2kW
- Speeds up to 6,000 rpm
- · Medium inertia models:
- 1kW, 1.5 kW, 2kW, and 3kW
- Speeds up to 3,000 rpm
- · High inertia models:
  - 3kW, 4.5 kW, 5.5 kW, 7.5 kW, 11kW, and 15kW
- Speeds up to 3,000 rpm
- Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style couplings
- Integrated encoder with 16,777,216 encoder pulses/revolution plus marker pulse (once per revolution)
- Optional 24 VDC spring-set holding brakes (xxxxB series motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for brake motors 230V systems 5.5kW and larger or 460V systems 11kW and larger)
- Motor cables available in standard or flexrated lengths of 3, 5, 10, and 20m
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 20-pin spring clamp terminal block (limited I/O) that mounts directly to the drive

#### SureServo2 tuning technology

The SureServo2 drive closes the loop on current, velocity, and position (depending on control mode selection). The 3.1 kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and five (5) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can easily tune systems with as much as 60:1 inertia mismatch.

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- One Touch Auto Tuning—the drive tunes the motor without any motion (static motor/ system analysis)
- Normal Auto Tuning—the drive tunes the load while an external controller or the drive's internal indexer provides point-to-point moves
- Assisted Tuning–3 modes where the drive tunes the motor while moving. The user can adjust responsiveness while the drive is analyzing the system
- Manual Tuning–20+ parameters are available to give power users the ultimate flexibility to tune their systems.

# SureServo2 Built-in motion controller

While the SureServo2 drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to 99 index moves can be pre-defined and stored in the drive and then selected and executed using digital inputs (inputs as events or inputs used as a multiplexer) or communication (serial Modbus, Modbus TCP, or Ethernet/IP). The index profiles can also be changed while in-process with digital events or via comms. The internal motion can consist of incremental or absolute moves, and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial/Ethernet communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful motion controller inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

# SureServo2 Optional Holding Brake

Each SureServo2 motor rating can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

# SureGear® Precision Gearboxes for Servo motors

Inertia balancing issue in your design?

The SureGear
PGA series
easily mates
to SureServo2
motors. Everything
you need to mount your
SureServo2 motor is included!

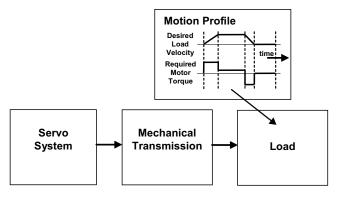
- Four gear ratios available (5, 10, 15, 25:1)
- Mounting hardware included for attaching to SureServo2 motors
- Industry-standard mounting dimensions
- Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty

## **AC Servo Systems**

#### How to select and apply SureServo2 systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo2 system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement. SureServo2 Pro has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.

AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from www. automationdirect.com on the store page for your drive.



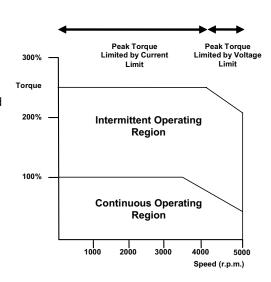
#### 1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system.

In general, applications that need high response or bandwidth will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo2 systems may be tuned manually, fully Automatically, or via a hybrid mode where the software tunes the system with input for system responsiveness from the user.

#### 2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have a SureServo2 system, these values are easily captured and recorded with the Scope feature built into SureServo2 Pro. If you are designing the system, use VisualSizer to define the system and calculate expected inertia and required power.



## **AC Servo Systems**

#### **Application tip - coupling considerations**

The SureServo2 motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider the stiffness, torque rating, and inertia. Higher stiffness

(lb-in/radian) is needed for better response but there is a tradeoff between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo2 **peak** torque requirement of your application.

#### **Available Couplings**

#### Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

### 1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo2 systems can go up to 6,000 rpm for the low inertia motors and up to 3,000 rpm for the medium inertia motors.

Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

### 2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo

system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

### 3. Space limitations and motor orientation

SureServo2 motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.

For more information, refer to the website listed below.

Mechanical Transmission: <u>Timing Belts and Pulleys</u>
Precision Gearboxes

#### Ordering guide instructions

The following four pages are your ordering guide for SureServo2 systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

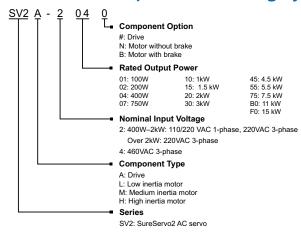
#### Each system needs:

- Motor
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either CN1 cable + RTB breakout board, or an LTB20 breakout board that mounts on the drive)
- For brakemotors 4.5 kW and below, the brake wiring is included in the power cable. For brakemotors 5.5 kw and above, a separate brake cable is required.

A wide variety of optional accessories are also available, such as Ethernet cards, RS485 splitters/terminators, toroids, etc.

You can also use the SureServo2 selector tool on the AutomationDirect.com website to help you configure your system.

### SureServo2 series drives and motors part numbering system



#### Here is what you will need to order a complete servo system:













NOTE: Unit can be programmed via keypad. Optional programming software (free download) and optional programming cable available.



NOTE: If you need a gear box for your configuration, you can do it easily online: http://www.sureservo.com/gearbox/selector





### Torque to SureServo2 System Quick Reference

	230V System Torque								
System Rated Torque (N∙m)	System Maximum Torque (N·m)	Suggested Servo Motor	Required Servo Drive						
0.32	1.12	SV2L-201N or SV2L-201B	<u>SV2A-2040</u>						
0.64	2.24	SV2L-202N or SV2L-202B	SV2A-2040						
1.27	3.96	SV2L-204N or SV2L-204B	SV2A-2040						
2.39	7.86	SV2L-207N or SV2L-207B	SV2A-2075						
3.18	8.12	SV2L-210N or SV2L-210B	SV2A-2150						
4.77	14.32	SV2M-210N or SV2M-210B	SV2A-2150						
7.16	14.88	SV2M-215N or SV2M-215B	SV2A-2150						
9.55	24.54	SV2M-220N or SV2M-220B	SV2A-2200						
17.55	48.29	SV2M-230N or SV2M-230B	SV2A-2300						
28.65	71.62	SV2H-245N or SV2H-245B	SV2A-2550						
35.01	87.53	SV2H-255N or SV2H-255B	SV2A-2550						
47.74	119.36	SV2H-275N or SV2H-275B	SV2A-2750						
70	175	SV2H-2B0N or SV2H-2B0B	SV2A-2F00						
95.4	224.0	SV2H-2F0N or SV2H-2F0B	<u>SV2A-2F00</u>						

	460V System Torque							
System Rated Torque (N·m)	System Maximum Torque (N·m)	Suggested Servo Motor	Required Servo Drive					
1.27	4.45	SV2L-404N or SV2L-404B	<u>SV2A-4040</u>					
2.24	7.58	SV2L-407N or SV2L-407B	<u>SV2A-4075</u>					
3.18	9.54	SV2L-410N or SV2L-410B	<u>SV2A-4150</u>					
4.77	14.32	SV2M-410N or SV2M-410B	SV2A-4150					
7.16	18.1	SV2L-415N or SV2L-415B	<u>SV2A-4150</u>					
9.55	28.65	SV2L-420N or SV2L-420B	<u>SV2A-4200</u>					
19.1	49.38	SV2H-430N or SV2H-430B	<u>SV2A-4300</u>					
28.65	64.61	SV2H-445N or SV2H-445B	SV2A-4550					
35.01	73.48	SV2H-455N or SV2H-455B	SV2A-4550					
47.74	93.71	SV2H-475N or SV2H-475B	<u>SV2A-4750</u>					
70	175	SV2H-4B0N or SV2H-4B0B	<u>SV2A-4F00</u>					
95.4	224.0	SV2H-4F0N or SV2H-4F0B	<u>SV2A-4F00</u>					

www.automationdirect.com Servo Systems tSRV-98



#### SureServo2 AC servo drive, motor, and cable combinations

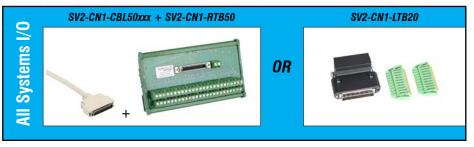
	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		1,12 (350%)	SV2L-201N		SV2C-PA18-xxNN	SV2C-E122-xxNN
Ш	120V	(E+A) Intermittent Region	0V2E-2011V	SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
Syste	1200	0.32 (100%) Continuous Region	SV2L-201B	<u> 3VZA-2040</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
Inertia		1,600 3,000 4,200 Speed (r/min)	<u>3v2L-201D</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
100W Low Inertia System		(350%)	SV2L 201N		SV2C-PA18-xxNN	SV2C-E122-xxNN
100W	2201/	[上 (188%)] (188%)] (188%)	<u>SV2L-201N</u>	CV2A 2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
	230V	0.32 (100%) 0.16 (50%) 	SV2L-201B	SV2A-2040	SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
		(350%)  (E4)  Intermittent Region  Continuous Region	<u>SV2L-202N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
u	120V			SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
200W Low Inertia System	1200		0.404 0000		SV2C-PB18-xxNB	SV2C-E122-xxNN
ertia		1,400 3,000 3,700  Speed (r/min)	<u>SV2L-202B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
Low In		2.24 (350%) 1.90	CVOL 202N		SV2C-PA18-xxNN	SV2C-E122-xxNN
MOO	2201/	الهجار (جورور) الهجار (جورور) الهجار (جورور) الهجار (جورورور) الهجار (جورورورورورورورورورورورورورورورورورورور	<u>SV2L-202N</u>	SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
	230V	0,64 (100%) 0.323 (50%) Continuous Region 3,000 4,300 6,000 Speed (r/min)	SV2L-202B		SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
Noto	"vv" in the cable	nart numbers represents cable length: SV2C-xx	vv-10vv is a 10m cable	•		

SV2C-xxxx-xxNB is a non-flex, brake motor cable

Note: "xx" in the cable part numbers represents cable length. Clark The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFN is a flex-rated, brake motor cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online

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#### SureServo2 AC servo drive, motor, and cable combinations, continued

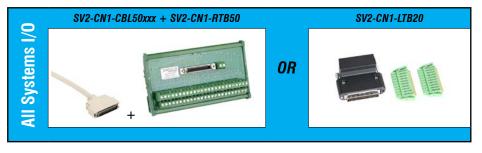
	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			3.96 (312%)	<u>SV2L-204N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N·m)	Intermittent Region		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
		1 (100 <sup>6</sup>	Continuous Region	SV2L-204B	<u></u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,000 2,700 3,600  Speed (r/min)	<u>3V2L-204b</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
400W Low Inertia System		3 (312 3 (274	3.96 2%) 4.48 4%)	<u>SV2L-204N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
Inertia	230V	Torque (N·m)	Intermittent Region			SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low		1 (100	1.27 (100%) 0.65 - Continuous Region	SV2L-204B	<u>3V2A-2040</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
400		(30	3,000 4,400 6,000  Speed (r/min)	<u>5V2L-204B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
		Torque (N·m) 3.(272	4.45	SV2L-404N	- SV2A-4040	SV2C-PA18-xxNN	SV2C-E122-xxNN
	460V		3.45 72%) Intermittent Region	3V2L-404IV		SV2C-PA18-xxFN	SV2C-E122-xxFN
	4000	(10	1.27 00%) 0.65 50%) Continuous Region			SV2C-PB18-xxNB	SV2C-E122-xxNN
	(()) in the cold	3,000 3,900 6,000  Speed (r/min)	SV2L-404B		SV2C-PB18-xxFB	SV2C-E122-xxFN	

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



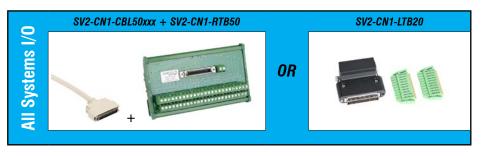
### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		7.8 (3299	16 (t)	<u>SV2L-207N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N·m)	Intermittent Region	<u> </u>	<u>SV2A-2075</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200	2.3 (1009	Continuous Region	SV2L-207B	<u>3V2A-2013</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,300 2,550 3,200  Speed (r/min)	<u>3V2L-20/B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
System		7.84 (329% 6.6: (277% (w-w) 1.194 (100%	9%)		<u>SV2A-2075</u> -	SV2C-PA18-xxNN	SV2C-E122-xxNN
750W Low Inertia System	230V		Intermittent Region	<u>SV2L-207N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low	2300		Continuous Region	SV2L-207B		SV2C-PB18-xxNB	SV2C-E122-xxNN
750			195 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
		(338	58 %) 48	SV2L-407N SV2L-407B		SV2C-PA18-xxNN	SV2C-E122-xxNN
	4001/	Torque (N·m)	Intermittent Region			SV2C-PA18-xxFN	SV2C-E122-xxFN
	460V	2 (100	95		SV2A-4075	SV2C-PB18-xxNB	SV2C-E122-xxNN
		(53	%) Continuous Region 3,200 4,350 6,000  Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
Noto	"vv" in the cable	nort num	bers represents cable length: SV2C-xx	rvy 10vy io o 10m oobl	`		

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



### SureServo2 AC servo drive, motor, and cable combinations, continued

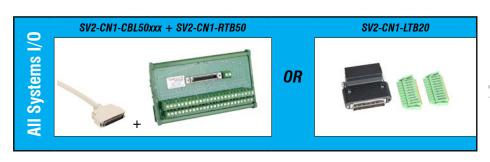
Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
	(E	8.12 (255%)	<u>SV2L-210N</u>		SV2C-PC16-xxNN	SV2C-E222-xxNN
1201/	Torque (N·r	Intermittent Region		SV2A 2150	SV2C-PC16-xxFN	SV2C-E222-xxFN
1200		Continuous Region	SV2L-210B	<u>3VZA-213U</u>	SV2C-PC16-xxNB	SV2C-E222-xxNN
		1,800 2,800 3,500  Speed (r/min)	<u> </u>		SV2C-PC16-xxFB	SV2C-E222-xxFN
		8.12 (255%)	0)/01 0401		SV2C-PC16-xxNN	SV2C-E222-xxNN
230V	ue (N·m)	Intermittent Region	372E-21014	SV2A-2150 SV2C-PC16	SV2C-PC16-xxFN	SV2C-E222-xxFN
	Torq	3.18 (100%) Continuous Region	CV2L 240D		SV2C-PC16-xxNB	SV2C-E222-xxNN
		1.91 3,000 3,300 5,000 Speed (r/min)	<u>5V2L-210B</u>		SV2C-PC16-xxFB	SV2C-E222-xxFN
		9.54 (300%)	SV2L-410N	S	SV2C-PC16-xxNN	SV2C-E222-xxNN
4007		Intermittent Region			SV2C-PC16-xxFN	SV2C-E222-xxFN
46UV		3.18 (100%) 1.91 (60%)	0)/01 4400	SV2A-4150 SV2L-410B	SV2C-PC16-xxNB	SV2C-E222-xxNN
			SV2L-410B		SV2C-PC16-xxFB	SV2C-E222-xxFN
	120V 230V 460V	120V 230V 120V 120V 120V 120V 120V 120V 120V 12	230V  2460V  255%  Continuous Region  Continuous Region  Continuous Region  Speed (r/min)  Continuous Region  Continuous Region  Speed (r/min)  Continuous Region  Speed (r/min)	120V    Sv2L-210N   Sv2L-210N	120V	120V

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector **Online** 



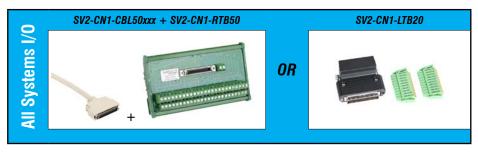
#### SureServo2 AC servo drive, motor, and cable combinations, continued

		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
	,	14.32 (300%)	SV2M-210N		SV2C-PC12-xxNN	SV2C-E222-xxNN
120\/	orque (N·m)	Intermittent Person		SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
1207	-	4.77	SV/2M-210B	<u>51212166</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
		700 1,550 2,000 Speed (r/min)	<u> </u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
	<b>Lordue (N·m)</b> 4.77 (100%)	14,32	<u>SV2M-210N</u>	SV2A-2150	SV2C-PC12-xxNN	SV2C-E222-xxNN
2301/		Intermittent Region			SV2C-PC12-xxFN	SV2C-E222-xxFN
2300		4.77 100%) Continuous Region	SV2M-210B		SV2C-PC12-xxNB	SV2C-E222-xxNN
		3.20 2,000 3,000 Speed (r/min)			SV2C-PC12-xxFB	SV2C-E222-xxFN
	Torque (N·m)	14.32	SV2M-410N		SV2C-PC16-xxNN	SV2C-E222-xxNN
4607		Intermittent Region		SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
4007		4.77 (100%) 3.20 (67%) Continuous Region	SV2M-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
		2,000 3,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN
	120V 230V 460V	120V 230V Land (M·m) Torque (M·m) 460V	230V  (a.77 (100%)  Continuous Region  700 1,550 2,000  Speed (r/min)  Litermittent Region  230V  Continuous Region  3.20 (67%)  Speed (r/min)  Continuous Region  A.77 (100%)  Speed (r/min)  Continuous Region  Continuous Region  Speed (r/min)  Continuous Region  Speed (r/min)	120V	120V   1,477	120V     120V

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



#### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			14.88 (208%)	<u>SV2M-215N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
m:	120V	Torque (N·m)	7.16 (100%)		SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
1.5 kW Medium Inertia System	1200	ř (	Continuous Region	SV2M-215B	<u>3VZA-213U</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
m Inert			1,000 1,400 1,800 Speed (r/min)	<u> </u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
Mediu		Torque (N·m)	14.88 (208%)	<u>SV2M-215N</u>	CV(0A 2450	SV2C-PC12-xxNN	SV2C-E222-xxNN
1.5 KW			Intermittent Region			SV2C-PC12-xxFN	SV2C-E222-xxFN
	230V		7.16 (100%) Continuous Region			SV2C-PC12-xxNB	SV2C-E222-xxNN
			4.60 2.000 2.400 3,000  Speed (r/min)	<u>SV2M-215B</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
ystem		(25 ( <b>E.</b> ( <b>y</b> )	18.1 (253%)	CV/21 445N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V		Intermittent Region	SV2L-415N	SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
1.5 kW Low Inertia System	<del>4</del> 00 <i>V</i>	Torq	7,16 (100%) 4,77 (67%) Continuous Region SV2L-415B  Speed (r/min)		SV2A-415U	SV2C-PC16-xxNB	SV2C-E222-xxNN
				SV2L-415B		SV2C-PC16-xxFB	SV2C-E222-xxFN

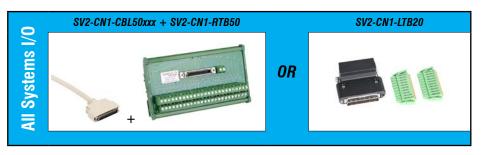
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable. The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





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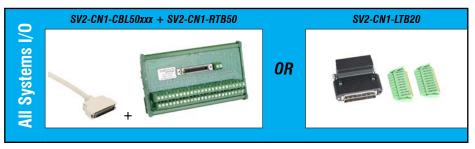
#### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		24.54 (257%)	24.54 257%)	<u>SV2M-220N</u>		SV2C-PD12-xxNN	SV2C-E222-xxNN
m:	120V	Torque (N·m)	mittent Region	OVENI EEDIT	SV2A-2200	SV2C-PD12-xxFN	SV2C-E222-xxFN
2.0 kW Medium Inertia System	1200	9.55 (100%)	Continuous Region	SV2M-220B	3VZA-2200	SV2C-PD12-xxNB	SV2C-E222-xxNN
m Inerti			800 1,500 1,950 Speed (r/min)	<u> 3VZINI-ZZUD</u>		SV2C-PD12-xxFB	SV2C-E222-xxFN
Mediu		24.54 (257%)		SV2M-220N	SV2A-2200	SV2C-PD12-xxNN	SV2C-E222-xxNN
2.0 kW	230V	Joseph (1,00%)	Intermittent Region			SV2C-PD12-xxFN	SV2C-E222-xxFN
		(10070)	Continuous Region	<u>SV2M-220B</u>		SV2C-PD12-xxNB	SV2C-E222-xxNN
		6.40 (67%)	2,000 2,200 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		28.65 (300%)		0.401.4001		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Inte	ermittent Region	SV2L-420N		SV2C-PC16-xxFN	SV2C-E222-xxFN
2.0 kW Low Inertia System	400V	9.55 (100%) (6.40) (67%) Continuous Region Speed (r/min)	01/01 4000	- SV2A-4200	SV2C-PC16-xxNB	SV2C-E222-xxNN	
2.0 KM			5V2L-420B		SV2C-PC16-xxFB	SV2C-E222-xxFN	

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable
SV2C-xxxx-xxNN is a flex-rated, non-brake cable
SV2C-xxxx-xxNB is a non-flex, brake motor cable
SV2C-xxxx-xxNB is a flex-rated, brake motor cable





SureServo2 System Selector Online



### SureServo2 AC servo drive, motor, and cable combinations, continued

n	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
a Systen		48.29 (275%)	CVOM OZONI		SV2C-PD12-xxNN	SV2C-E222-xxNN
3.0 kW Medium Inertia System	230V	Intermittent Region  17.55 (100%)	<u>SV2M-230N</u>	SV/2A 2200	SV2C-PD12-xxFN	SV2C-E222-xxFN
N Mediu	2300	17.55 (100%) 10.00 (57%) 9.55 (54%) Continuous Region	SV2M-230B	SV2A-2300	SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 KI		1,700 1,800 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		49.38 (259%)	01/01/ 4001/	SV2A-4300	SV2C-PD12-xxNN	SV2C-E222-xxNN
nertia S	460V	Intermittent Region	SV2H-430N		SV2C-PD12-xxFN	SV2C-E222-xxFN
3.0 kW High Inertia System	4000	9.00 (47%) Continuous Region  1,500 1,800 3,000  Speed (r/min)	SV2H-430B		SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 KI					SV2C-PD12-xxFB	SV2C-E222-xxFN

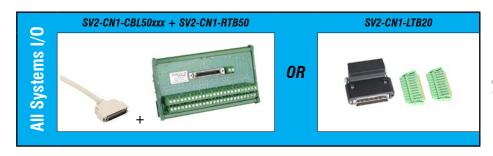
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



#### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		71.62 (250%)	SV2H-245N	01/04/0550	SV2C-PD08-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	<u> </u>		SV2C-PD08-xxFN	SV2C-E222-xxFN
System	2007	28.65 (100%) 14.33 (50%) Continuous Region	<u>SV2H-245B</u>	<u>SV2A-2550</u>	SV2C-PD08-xxNB	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN
4.5 kW High Inertia System		64.61 (226%)	SV2H-445N		SV2C-PD08-xxNN	SV2C-E222-xxNN
4.5	460V	Intermittent Region			SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	14.33 (50%) Continuous Region	SV2H-445B	SV2A-4550	SV2C-PD08-xxNB	SV2C-E222-xxNN
		1,500 1,700 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN

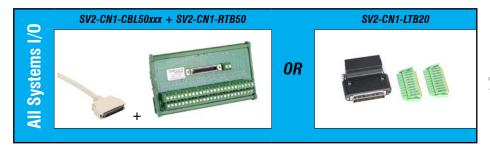
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





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### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		87.53 (250%)	<u>SV2H-255N</u>	SV2A-2550	SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region 35.01 (100%)			SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2300	35.01 (100%) 17.51 (50%) Continuous Region	C//2H 2EED		SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	<u>SV2H-255B</u>		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
5.5 kW High Inertia System		73.48 (210%)	SV2H-455N		SV2C-PD08-xxNN	SV2C-E222-xxNN
5.5	460V	Intermittent Region	3V211-433IV	SV2A-4550	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	19.1 (55%) 17.51 (50%) Continuous Region	SV2H-455B	SI	SV2C-PD08-xxNN	SV2C-E222-xxNN
		1,500 1,900 3,000 Speed (r/min)			SV2C-PD08-xxFN	SV2C-E222-xxFN

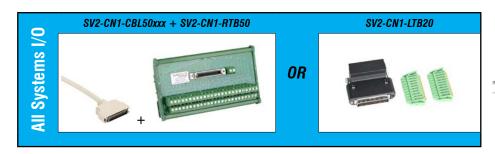
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(	119.36 (250%)	SV2H-275N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Torque (N·m)	Intermittent Region	3V21F213IN	SV2A-2750	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2500	Tor	47.74 (100%) 23.87 (50%) Continuous Region	SV2H-275B	3V2A-2130	SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia			1,500 3,000 Speed (r/min)	<u>3vzn-2/3b</u>		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
7.5 kW High Inertia System			.71	SV2H-475N		SV2C-PD08-xxNN	SV2C-E222-xxNN
7.5	460V	Torque (N·m)	Intermittent Region 47.74 100%	3V2H-4/3N	SV2A-4750	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000		20.0 (42%) Continuous Region	SV2H-475B	3V2N-4730	SV2C-PD08-xxNN	SV2C-E222-xxNN
			1,500 2,000 3,000 Speed (r/min)	37211-4730		SV2C-PD08-xxFN	SV2C-E222-xxFN

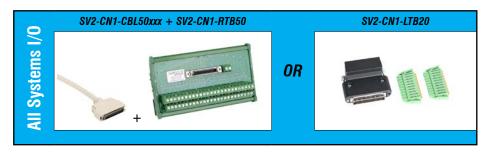
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



#### SureServo2 AC servo drive, motor, and cable combinations, continued

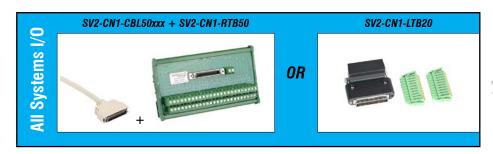
	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(2	175.0 250%)		<u>SV2H-2B0N</u>		SV2C-PF06-xxNN	SV2C-E222-xxNN
	2201/	Torque (N·m)		Intermittent Region	SVZH-ZBUN	0)/04 0500	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	230V 230V	Torqu	70.0 100%) 52.5 (75%)	Continuous Region	SV2H-2B0B	<u>SV2A-2F00</u>	SV2C-PF06-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
11.0 kW High Inertia System				1,500 2,000 Speed (r/min)	<u> </u>		SV2C-PF06-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN
kW High		(2	175.0 250%)		SV2H-4B0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
11.0	460V		70.0	Intermittent Region	5V2H-4BUN	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	400V	. (1	70.0 100%) 52.5 (75%)	Continuous Region	SV2H-4B0B	3V2A-41 00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
				1,500 2,000 Speed (r/min)	37211-4000		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



### SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		224.0 (235%)	<u>SV2H-2F0N</u>		SV2C-PF04-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	SVZH-ZFUN	SV2A-2F00	SV2C-PF04-xxFN	SV2C-E222-xxFN
System	2307	95,4 (100%) 71.6 (75%) Continuous Region	SV2H-2F0B	<u> </u>	SV2C-PF04-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
15.0 kW High Inertia System		1,500 2,000 Speed (r/min)	<u>3V2N-2FUD</u>		SV2C-PF04-xxFB and SV2C-B120-xxFB	SV2C-E222-xxFN
kW High		224.0 (235%)	SV2H-4F0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
15.0	460V	Intermittent Region	37211-41 014	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	400V	95.4 (100%) 71.6 (75%) Continuous Region	SV2H-4F0B	3V2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
		1,500 2,000 Speed (r/min)	37211-41 00		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

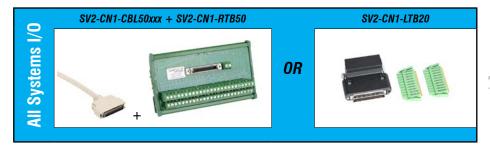
Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable





SureServo2 System Selector Online



#### Servo motor overview

#### 24-bit Encoder Connector

1-foot cable with 9-position connector

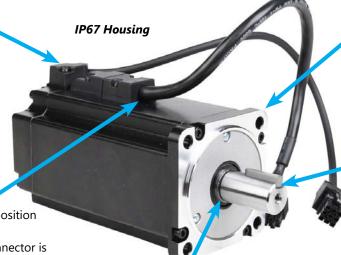
(Motor-mounted connector is IP67, end-of-cable connector is not liquid tight)

#### **750W and** below

**Motor Power and Brake Connector** 

1-foot cable with 6-position connector

(Motor-mounted connector is IP67, end-of-cable connector is not liquid tight)



#### Low Inertia Motors

- 100W 40 mm flange
- 200W 60 mm flange
- 400W 60 mm flange
- 750W 80 mm flange

#### Keyed Shafts

- 100W 8 mm diameter
- 200W 14 mm diameter
- 400W 14 mm diameter
- 750W 19 mm diameter

With Shaft Seal (liquid tight)

> All SureServo2 motors have keyed shafts for use with servo-grade clamp or compression couplings (recommended) or servo-grade keyed couplings.

#### **Motor Power and Brake Connector**

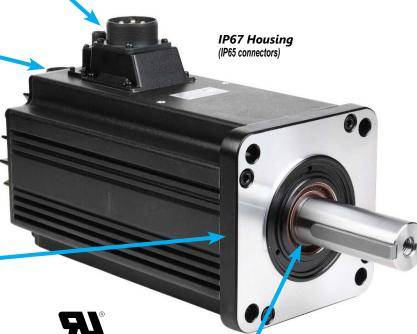
(Liquid tight when using AutomationDirect cables)

#### 24-bit Encoder Connector (Liquid tight when using AutomationDirect cables)

#### 1 kW and above

#### Low, Medium, and High **Inertia Motors**

- Low Inertia Model:
- 1kW 100mm flange
- 1.5 kW 130mm flange
- 2kW 130mm flange
- · Medium Inertia Models:
  - 1kW 130mm flange
- 1.5kW 130mm flange
- 2kW 180mm flange
- 3kW 180mm flange • High Inertia Models:
- 3.0kW 180mm flange
- 4.5kW 180mm flange
- 5.5kW 180mm flange
- 7.5kW 180mm flange
- 11kW 220mm flange
- 15kW 220mm flange



With Shaft Seal (liquid tight)

#### **Keyed Shafts**

- · Low Inertia Model:
  - 1kW 22mm diameter
  - 1.5 kW 22mm diameter
  - 2kW 22mm diameter
- Medium Inertia Models:
  - 1kW 22mm diameter
  - 1.5kW 22mm diameter
- 2kW 35mm diameter
- 3kW 35mm diameter
- · High Inertia Models:
- 3.0kW 35mm diameter
- 4.5kW 35mm diameter
- 5.5kW 42mm diameter
- 7.5kW 42mm diameter
- 11kW 42mm diameter
- 15kW 55mm diameter



### **230V Low Inertia Motor Specifications**

		230V Sur	eServo2	Low Ine	tia Moto	r Specifi	cations			
Model		SV2L-201B	<u>SV2L-202N</u>	SV2L-202B	<u>SV2L-204N</u>	SV2L-204B	<u>SV2L-207N</u>	SV2L-207B	SV2L-210N	SV2L-210B
Price	\$286.00	\$419.00	\$315.00	\$465.00	\$340.00	\$479.00	\$364.00	\$510.00	\$477.00	\$702.00
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
Rated Power [kW]	0.1	0.1	0.2	0.2	0.4	0.4	0.75	0.75	1.0	1.0
Rated Torque [N·m]Note 1	0.32	0.32	0.64	0.64	1.27	1.27	2.39	2.39	3.18	3.18
Max. Torque [N·m]	1.12	1.12	2.24	2.24	3.96	3.96	7.86	7.86	8.12	8.12
Rated Speed [rpm]										L
Max. Speed [rpm]		6000								00
Rated current [Amps] rms	0.9	1.9         0.9         1.45         1.45         2.60         2.60         4.5         4.5								8.04
Max. Instantaneous Current [Amps] rms	3.3	3.3	5.4	5.4	8.56	8.56	15.41	15.41	20.16	20.16
Change of Rated Power [W/s]	16.3	14.90	16.4	14.60	35.8	33.60	37.8	34.40	38.2	30.40
Rotor Inertia [x10-4 kg m2]	0.0627	0.0689	0.25	0.28	0.45	0.48	1.51	1.66	2.65	3.33
Mechanical Time Constant [ms]	1.13	1.24	1.38	1.54	0.94	1.01	0.91	1.00	0.83	1.05
Torque Constant-KT [N-m/A]	0.356	0.356	0.441	0.441	0.488	0.488	0.531	0.531	0.396	0.396
Voltage Constant-KE [mV/ rpm]	13.66	13.66	16.4	16.4	17.2	17.2	18.7	18.7	16.8	16.8
Armature Resistance [Ohm]	8.34	8.34	3.8	3.8	1.68	1.68	0.57	0.57	0.20	0.20
Armature Inductance [mH]	9.85	9.85	8.15	8.15	4.03	4.03	2.2	2.2	1.81	1.81
Electrical Time Constant [ms]	1.18	1.18	2.14	2.14	2.40	2.40	3.86	3.86	9.05	9.05
Insulation Class					Class A (UL),	Class B (CE)				
Insulation Resistance					> 100MΩ	, 500VDC				
Insulation Strength		T			1.8 kVAC,	, 1 second			1	Г
Weight [kg]	0.5	0.8	1.1	1.6	1.4	1.9	2.8	3.6	4.3	4.7
Max. Radial Loading [N]	78	78	245	245	245	245	392	392	490	490
Max. Axial Loading [N]	54	54	74	74	74	74	147	147	98	98
Brake Holding Torque [N·m (min)]Note 2		0.32		1.3		1.3		2.5		8
Brake Power Consumption (at 20°C) [W]	n/a	6.1	n/a	7.2	n/a	7.2	n/a	8	n/a	18.7
Brake Release Time [ms (max)]	II/a	20	11/4	20	11/4	20	11/a	20	II/a	10
Brake Pull-in Time [ms (max)]		35		50		50		60		70
Vibration Grade [μm]					V	15				
Operating Temperature [°C]					0–40 °C (3	32–104 °F)				
Storage Temperature [°C]		-10°C to 80°C (-14°F to 176°F)								
Operating Humidity		20–90% relative humidity (non-condensing)								
Storage Humidity		20–90% relative humidity (non-condensing)								
Vibration Capacity		2.5 G								
IP Rating <sup>3</sup>		IP67 (when using waterproof connectors)  IP65 (when using waterproof connectors)								
Encoder Resolution					24-bit (1677					
Agency Approvals					$_{\mathrm{C}}UR_{\mathrm{U}}$	<sub>IS</sub> , CE				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating termperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.

Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.

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### **230V Medium Inertia Motor Specifications**

	230V	SureServo	2 Medium	Inertia Mo	tor Specifi	cations			
Model	SV2M-210N	SV2M-210B	SV2M-215N	SV2M-215B	SV2M-220N	SV2M-220B	SV2M-230N	SV2M-230B	
Price	\$497.00	\$711.00	\$537.00	\$795.00	\$651.00	\$863.00	\$735.00	\$947.00	
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	
Rated Power [kW]	1.0	1.0	1.5	1.5	2.0	2.0	3.0	3.0	
Rated Torque [N·m]Note 1	4.77	4.77	7.16	7.16	9.55	9.55	17.55	17.55	
Max. Torque [N·m]	14.32	14.32	14.88	14.88	24.54	24.54	48.29	48.29	
Rated Speed [rpm]			20	00			17	00	
Max. Speed [rpm]				30	00				
Rated current [Amps] rms	5.66	5.66	8.33	8.33	12.1	12.1	17.9	17.9	
Max. Instantaneous Current [Amps] rms	19.73	19.73	20.16	20.16	33.66	33.66	55.93	55.93	
Change of Rated Power [W/s]	27.1	24.90	45.8	43.10	26.3	24.10	56.0	53.90	
Rotor Inertia [x10-4 kg m2]	8.41	9.14	11.2	11.9	34.7	37.8	55	57.1	
Mechanical Time Constant [ms]	1.54	1.67	1.12	1.18	1.75	1.90	1.29	1.34	
Torque Constant-KT [N-m/A]	0.843	0.843	0.860	0.860	0.789	0.789	0.980	0.980	
Voltage Constant-KE [mV/ rpm]	31.9	31.9	31.8	31.8	31.4	31.4	35	35	
Armature Resistance [Ohm]	0.47	0.47	0.26	0.26	0.119	0.119	0.077	0.077	
Armature Inductance [mH]	5.99	5.99	4.01	4.01	2.84	2.84	1.27	1.27	
Electrical Time Constant [ms]	12.74	12.74	15.42	15.42	23.87	23.87	16.49	16.49	
Insulation Class				Class A (UL),	Class B (CE)				
Insulation Resistance				> 100MΩ	, 500VDC				
Insulation Strength				1.8 kVAC					
Weight [kg]	7.0	8.4	7.5	8.9	13.5	17.5	18.5	22.5	
Max. Radial Loading [N]			90		11	76	14	70	
Max. Axial Loading [N]		9	8	Г		49	90	Г	
Brake Holding Torque [N·m (min)]Note 2		10		10		25		25	
Brake Power Consumption (at 20°C) [W]	n/a	19	n/a	19	n/a	20.4	n/a	20.4	
Brake Release Time [ms (max)]	11/4	10	11/4	10	11/4	10	11/4	10	
Brake Pull-in Time [ms (max)]		70		70		70		70	
Vibration Grade [µm]	V15								
Operating Temperature [°C]	0-40 °C (32-104 °F)								
Storage Temperature [°C]		-10°C to 80°C (-14°F to 176°F)							
Operating Humidity		20–90% relative humidity (non-condensing)							
Storage Humidity		20–90% relative humidity (non-condensing)							
Vibration Capacity		2.5 G							
IP Rating <sup>3</sup>			IF		aterproof connector	s)			
Encoder Resolution				24-bit (1677	77216 p/rev)				
Agency Approvals				cUR	<sub>IS</sub> , CE				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.

Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.

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#### 230V High Inertia Motor Specifications

	23	BOV Sure	Servo2	High Iner	tia Moto	r Specifi	cations			
Model	SV2H-245N		SV2H-255N	SV2H-255B	SV2H-275N	SV2H-275B	SV2H-2B0N	SV2H-2B0B	SV2H-2F0N	SV2H-2F0B
Price	\$911.00	\$1,415.00	\$1,050.00	\$1,568.00	\$1,273.00	\$1,989.00	\$1,956.00	\$2,682.00	\$2,257.00	\$3,091.00
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
Rated Power [kW]	4.5	4.5	5.5	5.5	7.5	7.5	11	11	15	15
Rated Torque [N·m]Note 1	28.65	28.65	35.01	35.01	47.74	47.74	70	70	95.4	95.4
Max. Torque [N·m]	71.62	71.62	87.53	87.53	119.36	119.36	175	175	224.0	224.0
Rated Speed [rpm]					15	00				
Max. Speed [rpm]			30	00				20	000	
Rated current [Amps] rms	32.5	32.5	40.12	40.12	47.5	47.5	51.1	51.1	67	67
Max. Instantaneous Current [Amps] rms	91.4	91.4	108.0	108.0	127.46	127.46	129.5	129.5	162	162
Change of Rated Power [W/s]	105.6	101.8	122.8	119.3	159.7	156.6	145.0	141.4	201.8	197.1
Rotor Inertia [x10-4 kg m2]	77.75	80.65	99.78	102.70	142.7	145.55	338	346.5	451	461.8
Mechanical Time Constant [ms]	0.93	0.96	0.97	0.99	0.84	0.85	1.38	1.41	1.22	1.25
Torque Constant-KT [N·m/A]	0.878	0.878	0.873	0.873	1.005	1.005	1.370	1.370	1.424	1.424
Voltage Constant-KE [mV/rpm]	32.0	32.0	31.0	31.0	35.5	35.5	49	49	50	50
Armature Resistance [Ohm]	0.032	0.032	0.025	0.025	0.02	0.02	0.0261	0.0261	0.0184	0.0184
Armature Inductance [mH]	0.89	0.89	0.71	0.71	0.6	0.6	0.65	0.65	0.48	0.48
Electrical Time Constant [ms]	27.81	27.81	28.4	28.4	30.0	30.0	24.9	24.9	26.09	26.09
Insulation Class			Class A (UL),	Class B (CE)				Class F (UL),	Class F (CE)	
Insulation Resistance					> 100MΩ					
Insulation Strength					1.8 kVAC,			T	I	I -
Weight [kg]	23.5	29	30.5	36	40.5	46	56.4	68.4	75	87
Max. Radial Loading [N]	14				64				800	
Max. Axial Loading [N]	49	90		58	38 			11	00	
Brake Holding Torque [N·m (min)]Note 2		55.0		55.0		55.0		115		115
Brake Power Consumption (at 20°C) [W]	n/a	19.9	n/a	19.9	n/a	19.9	n/a	28.8	n/a	28.8
Brake Release Time [ms (max)]		10		10		10		10		10
Brake Pull-in Time [ms (max)]		70		70		70		70		70
Vibration Grade [μm]						15				
Operating Temperature [°C]					0–40 °C (3	32–104 °F)				
Storage Temperature [°C]					10°C to 80°C (		·			
Operating Humidity	20–90% relative humidity (non-condensing)									
Storage Humidity	20–90% relative humidity (non-condensing)									
Vibration Capacity	2.5 G									
IP Rating <sup>3</sup>		IP65 (when using specified cables)								
Encoder Resolution					24-bit (1677	. ,				
Agency Approvals					cUR <sub>U</sub>	S, CE				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm,400mm x 400mm x 20mm,550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.

Note 3-All SureServo2 motors are shipped with oil seals installed for IP rating requirements.

### **460V Low Inertia Motor Specifications**

		160V Sur	eServo2	Low Ine	rtia Moto	r Specifi	cations					
Model	SV2L-404N	SV2L-404B	SV2L-407N	SV2L-407B	SV2L-410N	SV2L-410B	<u>SV2L-415N</u>	SV2L-415B	SV2L-420N	SV2L-420B		
Price	\$360.00	\$515.00	\$388.00	\$555.00	\$505.00	\$745.00	\$580.00	\$855.00	\$687.00	\$899.00		
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF		
Rated Power [kW]	0.4	0.4	0.75	0.75	1.0	1.0	1.5	1.5	2.0	2.0		
Rated Torque [N·m]Note 1	1.27	1.27	2.24	2.24	3.18	3.18	7.16	7.16	9.55	9.55		
Max. Torque [N·m]	4.45	4.45	7.58	7.58	9.54	9.54	18.1	18.1	28.65	28.65		
Rated Speed [rpm]	30	00	32	00	30	00		2000				
Max. Speed [rpm]	60	00	60	00	50	00		30	00			
Rated current [Amps] rms	1.43	43 1.43 2.90 2.90 4.36 4.36 5.1 5.1 6.7 6							6.7			
Max. Instantaneous Current [Amps] rms	5.25	5.25	9.70	9.70	13.74	13.74	13.28	13.28	21.35	21.35		
Change of Rated Power [W/s]	35.8	33.6	33.2	30.2	38.2	30.40	45.9	43.10	62.5	57.4		
Rotor Inertia [x10-4 kg m2]	0.45	0.48	1.51	1.66	2.65	3.33	11.18	11.9	14.59	15.88		
Mechanical Time Constant [ms]	1.05	1.12	1.02	1.12	0.81	1.02	1.26	1.34	1.11	1.21		
Torque Constant-KT [N-m/A]	0.888	0.888	0.772	0.772	0.729	0.729	1.404	1.404	1.425	1.425		
Voltage Constant-KE [mV/ rpm]	31.83	31.83	27.83	27.83	29.00	29.00	55.00	55.00	55.00	55.00		
Armature Resistance [Ohm]	6.28	6.28	1.38	1.38	0.617	0.617	0.83	0.83	0.57	0.57		
Armature Inductance [mH]	13.34	13.34	4.78	4.78	6.03	6.03	11.67	11.67	8.29	8.29		
Electrical Time Constant [ms]	2.12	2.12	3.46	3.46	9.77	9.77	14.06	14.06	14.54	14.54		
Insulation Class					Class A (UL),	Class B (CE)						
Insulation Resistance					> 100 MΩ	, 500VDC						
Insulation Strength					2.3 kVA	C, 1 sec						
Weight [kg]	1.4	1.9	2.8	3.6	4.3	4.7	7.5	8.9	7.8	9.2		
Max. Radial Loading [N]	245	245	392	392	490	490	490	490	490	490		
Max. Axial Loading [N]	74	74	147	147	98	98	98	98	98	98		
Brake Holding Torque [N·m (min)]Note 2		1.3		2.5		8		10		10		
Brake Power Consumption (at 20°C) [W]	n/a	7.2	n/a	8	n/a	18.7	n/a	19	n/a	19		
Brake Release Time [ms (max)]	II/a	20	II/a	20	II/a	10	Π/α	10	II/a	10		
Brake Pull-in Time [ms (max)]		50		60		70		70		70		
Vibration Grade [μm]					V	15						
Operating Temperature [°C]					0–40 °C (3							
Storage Temperature [°C]					-10°C to 80°C (							
Operating Humidity	20–90% relative humidity (non-condensing)											
Storage Humidity		20–90% relative humidity (non-condensing)  2.5 G										
Vibration Capacity  IP Rating		sing waterproo			T	ing waterproof		when an oil se	al is fitted to the	e rotating shaft		
Encoder Resolution	Seai is iilleu	to the rotating s	onan (IVI all Oll	ocai IIIUUCI))	24-bit (1677	7216 n/rev)	(IUI all Ull S	cai iiiouei))				
Agency Approvals										,		
нувноу нрргочать					cur <sub>u</sub>	S, CE						

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.

### **460V Medium Inertia Motor Specifications**

460V SureServo2 Me	edium Inertia Motor Sp	ecifications				
Model	<u>SV2M-410N</u>	<u>SV2M-410B</u>				
Price	\$530.00	\$765.00				
Drawing	PDF	PDF				
Rated Power [kW]	1.0	1.0				
Rated Torque [N·m]Note 1	4.77	4.77				
Max. Torque [N·m]	14.32	14.32				
Rated Speed [rpm]	20	000				
Max. Speed [rpm]	30	000				
Rated current [Amps] rms	3.6	3.6				
Max. Instantaneous Current [Amps] rms	11.41	11.41				
Change of Rated Power [W/s]	27.1	24.90				
Rotor Inertia [x10-4 kg m2]	8.41	9.14				
Mechanical Time Constant [ms]	1.85 2.01					
Torque Constant-KT [N-m/A]	1.325 1.325					
Voltage Constant-KE [mV/rpm]	53.20 53.20					
Armature Resistance [Ohm]	1.477	1.477				
Armature Inductance [mH]	17.79	17.79				
Electrical Time Constant [ms]	12.04	12.04				
Insulation Class	Class A (UL),	Class B (CE)				
Insulation Resistance	> 100 MΩ	2, 500VDC				
Insulation Strength	2.3 kVA	C, 1 sec				
Weight [kg]	7.0	8.4				
Max. Radial Loading [N]	49	90				
Max. Axial Loading [N]	9	8				
Brake Holding Torque [N·m (min)]Note 2		10				
Brake Power Consumption (at 20°C) [W]	n/a	19				
Brake Release Time [ms (max)]		10				
Brake Pull-in Time [ms (max)]		70				
Vibration Grade [µm]	V	15				
Operating Temperature [°C]	0–40 °C (3	32–104 °F)				
Storage Temperature [°C]	-10°C to 80°C (	-14°F to 176°F)				
Operating Humidity	ity 20–90% relative humidity (non-condensing)					
Storage Humidity	20–90% relative humidity (non-condensing)					
Vibration Capacity	city 2.5 G					
IP Rating	` ' '	ors and when an oil seal is fitted to the an oil seal model))				
	rotating shaft (for an oil seal model))					
Encoder Resolution	24-bit (1677	77216 p/rev)				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.

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### **460V High Inertia Motor Specifications**

460V	SureServo	2 High Iner	tia Motor Sp	ecification	S					
Model	<u>SV2H-430N</u>	SV2H-430B	<u>SV2H-445N</u>	SV2H-445B	SV2H-455N	SV2H-455B				
Price	\$823.00	\$1,001.00	\$939.00	\$1,456.00	\$1,082.00	\$1,614.00				
Drawing	PDF	PDF	PDF	PDF	PDF	PDF				
Rated Power [kW]	3.0	3.0	4.5	4.5	5.5	5.5				
Rated Torque [N·m]Note 1	19.1	19.1	28.65	28.65	35	35				
Max. Torque [N·m]	49.38	49.38	64.61	64.61	73.48	73.48				
Rated Speed [rpm]			15	00						
Max. Speed [rpm]		3000								
Rated current [Amps] rms	12.2	12.2 12.2 21.9 21.9 23.6 2								
Max. Instantaneous Current [Amps] rms	30.46	30.46	47.5	47.5	47.5	47.5				
Change of Rated Power [W/s]	66.4	63.9	105.6	101.8	122.8	119.3				
Rotor Inertia [x10-4 kg m2]	54.95	57.1	77.75	80.65	99.78	80.65				
Mechanical Time Constant [ms]	1.20	1.24	1.06	1.10	0.84	0.86				
Torque Constant-KT [N·m/A]	1.566	1.566	1.308	1.308	1.483	1.483				
Voltage Constant-KE [mV/rpm]	64.4	64.4	53.00	53.00	58.9	58.9				
Armature Resistance [Ohm]	0.21	0.21	0.09	0.09	0.07	0.07				
Armature Inductance [mH]	4.94	4.94	2.36	2.36	2.20	2.20				
Electrical Time Constant [ms]	23.52	23.52	26.22	26.22	31.43	31.43				
Insulation Class			Class A (UL),	Class B (CE)						
Insulation Resistance			> 100 MΩ	, 500VDC						
Insulation Strength			2.3 kVA	C, 1 sec						
Weight [kg]	18.5	22.5	23.5	29	30.5	36				
Max. Radial Loading [N]		14	70		17	64				
Max. Axial Loading [N]		4:	90		58	88				
Brake Holding Torque [N·m (min)]Note 2		25		55		55				
Brake Power Consumption (at 20°C) [W]		20.4		19.9		19.9				
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10				
Brake Pull-in Time [ms (max)]		70		70		70				
Vibration Grade [µm]			V	15						
Operating Temperature [°C]			0–40 °C (3	32–104 °F)						
Storage Temperature [°C]			-10°C to 80°C (	-14°F to 176°F)						
Operating Humidity		20	0–90% relative humi	dity (non-condensin	ıg)					
Storage Humidity		20–90% relative humidity (non-condensing)								
Vibration Capacity		2.5 G								
IP Rating	IP65 (when using waterproof connectors and when an oil seal is fitted to the rotating shaft (for an oil seal model))									
Encoder Resolution		24-bit (16777216 p/rev)								
Agency Approvals			<sub>C</sub> UR <sub>U</sub>	S, CE						
		Continued on ne	ext page							

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.



### 460V High Inertia Motor Specifications, continued

460V S	ureServo2	High Inerti	a Motor Sp	ecifications	S				
Model	<u>SV2H-475N</u>	SV2H-475B	SV2H-4B0N	SV2H-4B0B	SV2H-4F0N	SV2H-4F0B			
Price	\$1,311.00	\$2,047.00	\$2,014.00	\$2,760.00	\$2,324.00	\$3,182.00			
Drawing	<u>PDF</u>	<u>PDF</u>	<u>PDF</u>	<u>PDF</u>	PDF	<u>PDF</u>			
Rated Power [kW]	7.5	7.5	11	11	15	15			
Rated Torque [N·m]Note 1	47.74	47.74	70	70	95.4	95.4			
Max. Torque [N·m]	93.71	93.71	175	175	224.0	224.0			
Rated Speed [rpm]	15	00		15	500				
Max. Speed [rpm]	30	00		20	000				
Rated current [Amps] rms	28.7	28.7	26.8	26.8	37.5	37.5			
Max. Instantaneous Current [Amps] rms	57.69	57.69	67.7	67.7	95.3	95.3			
Change of Rated Power [W/s]	159.7	156.6	145.0	141.4	201.8	197.1			
Rotor Inertia [x10-4 kg m2]	142.7	145.5	338	346.5	451	461.8			
Mechanical Time Constant [ms]	<b>ns]</b> 0.81 0.83 1.40 1.44 1.21 1								
Torque Constant-KT [N·m/A]	1.663	1.663 1.663 2.612 2.612 2.544							
Voltage Constant-KE [mV/rpm]	66.40	66.40	96.00	96.00	83.90	83.90			
Armature Resistance [Ohm]	0.06	0.06	0.0994	0.0994	0.0545	0.0545			
Armature Inductance [mH]	1.70	1.70	2.51	2.51	1.43	1.43			
Electrical Time Constant [ms]	28.33	28.33	25.25	25.25	26.24	26.24			
Insulation Class	Class A (UL),	Class B (CE)		Class F (UL),	Class F (CE)				
Insulation Resistance			> 100 MΩ	2, 500VDC					
Insulation Strength			2.3 kVA	C, 1 sec					
Weight [kg]	40.5	46	56.4	68.4	75	87			
Max. Radial Loading [N]	17	64		33	300				
Max. Axial Loading [N]	58	38		11	00	1			
Brake Holding Torque [N·m (min)]Note 2		55		115		115			
Brake Power Consumption (at 20°C) [W]		19.9		28.8		28.8			
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10			
Brake Pull-in Time [ms (max)]		70		70		70			
Vibration Grade [µm]			V	15					
Operating Temperature [°C]			0–40 °C (3	32–104 °F)					
Storage Temperature [°C]	-10°C to 80°C (-14°F to 176°F)								
Operating Humidity		20–90% relative humidity (non-condensing)							
Storage Humidity		20	)–90% relative hum	idity (non-condensir	ng)				
Vibration Capacity	2.5 G								
IP Rating	IP65 (when using waterproof connectors and when an oil seal is fitted to the rotating shaft (for an oil seal model))								
Encoder Resolution			24-bit (1677	77216 p/rev)					
Agency Approvals			cUR	<sub>JS</sub> , CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

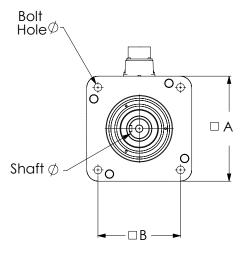
550mm x 550mm x 30mm

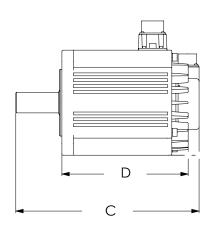
All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.

### **AC Servo System Dimensions**

#### 230V Servo motor dimensions





	SureServo2 230V Motor Dimensions											
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]					
<u>SV2L-201N</u>	<u>PDF</u>	40.0 [1.57]	32.2 [1.27]	110.3 [4.34]	85.3 [3.36]	4.5 [0.18]	8.0 [0.31]					
<u>SV2L-201B</u>	<u>PDF</u>	40.0 [1.57]	32.2 [1.27]	145.1 [5.71]	120.1 [4.73]	4.5 [0.18]	8.0 [0.31]					
<u>SV2L-202N</u>	<u>PDF</u>	60.0 [2.36]	49.5 [1.95]	113.9 [4.49]	84.0 [3.31]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-202B</u>	<u>PDF</u>	60.0 [2.36]	49.5 [1.95]	147.6 [5.81]	117.1 [4.61]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-204N</u>	PDF	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-204B</u>	<u>PDF</u>	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-207N</u>	PDF	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [2.51]	19.0 [0.75]					
<u>SV2L-207B</u>	<u>PDF</u>	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [2.51]	19.0 [0.75]					
<u>SV2L-210N</u>	<u>PDF</u>	100.0 [3.94]	81.3 [3.20]	198.3 [7.81]	110.2 [4.34]	9.0 [0.35]	22.0 [0.87]					
<u>SV2L-210B</u>	<u>PDF</u>	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	149.5 [5.89]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-210N</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	104.5 [4.11]	9.0 [0.35]	22.0 [0.87]					
SV2M-210B	PDF	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	140.5 [5.53]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-215N</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	120.5 [4.74]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-215B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	155.0 [6.10]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-220N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	247.7 [9.75]	150.0 [5.91]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-220B</u>	PDF	180.0 [7.09]	141.4 [5.57]	281.8 [11.09]	184.1 [7.25]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-230N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	183.1 [7.21]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-230B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-245N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-245B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	260.3 [10.25]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-255N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	260.7 [10.26]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-255B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	292.7 [11.52]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-275N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	454.70 [17.9]	323.0 [12.72]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-275B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	357.1 [14.06]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-2B0N</u>	<u>PDF</u>	219.9 [8.66]	166.2 [6.54]	487.4 [19.19]	319.0 [12.56]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-2B0B</u>	<u>PDF</u>	219.9 [8.66]	166.2 [6.54]	550.4 [21.67]	382.0 [15.04]	13.5 [0.53]	42.0 [1.63]					
SV2H-2F0N	<u>PDF</u>	219.9 [8.66]	166.2 [6.54]	566.4 [22.30]	398.0 [15.67]	13.5 [0.53]	55.0 [2.17]					
<u>SV2H-2F0B</u>	<u>PDF</u>	219.9 [8.66]	166.2 [6.54]	629.4 [24.78]	461.0 [18.15]	13.5 [0.53]	55.0 [2.17]					



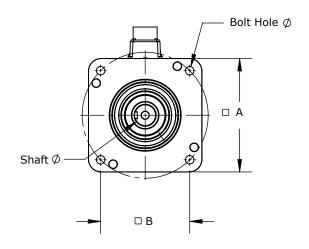
NOTE: Motor cables are approximately 304mm (12") in length.

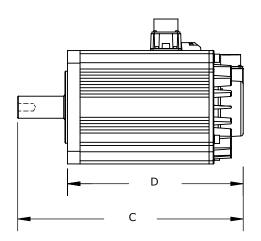


For additional dimensions, see the AutomationDirect website or click on the drawing links.

# **AC Servo System Dimensions**

### **460V Servo motor dimensions**





		SureServo	2 460V Mo	tor Dimens	ions		
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]
<u>SV2L-404N</u>	<u>PDF</u>	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-404B</u>	<u>PDF</u>	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-407N</u>	<u>PDF</u>	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-407B</u>	<u>PDF</u>	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-410N</u>	<u>PDF</u>	100.0 [3.94]	81.3 [3.20]	198.2 [7.81]	153.2 [6.03]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-410B</u>	<u>PDF</u>	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	192.5 [7.58]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415N</u>	PDF	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	167.5 [6.59]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	202.0 [7.95]	9.0 [0.35]	22.0 [0.87]
SV2L-420N	PDF	130.0 [5.12]	102.5 [4.04]	242.5 [9.55]	187.5 [7.38]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-420B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	271.0 [10.67]	216.0 [8.50]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410N</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	147.5 [5.81]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	183.5 [7.22]	9.0 [0.35]	22.0 [0.87]
<u>SV2H-430N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	201.8 [7.94]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-430B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	279.0 [10.98]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-455N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	279.4 [11.00]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-455B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	311.4 [12.26]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475N</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	454.7 [17.90]	341.7 [13.45]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	375.8 [14.80]	13.5 [0.53]	42.0 [1.65]
SV2H-4BON	<u>PDF</u>	220.0 [8.66]	166.2 [6.54]	487.4 [19.19]	371.4 [14.62]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-4B0B</u>	<u>PDF</u>	220.0 [8.66]	166.2 [6.54]	550.4 [21.67]	434.4 [17.10]	13.5 [0.53]	42.0 [1.65]
SV2H-4F0N	<u>PDF</u>	220.0 [8.66]	166.2 [6.54]	566.4 [22.30]	450.4 [17.73]	13.5 [0.53]	55.0 [2.17]
SV2H-4F0B	<u>PDF</u>	220.0 [8.66]	166.2 [6.54]	629.4 [24.78]	513.4 [20.21]	13.5 [0.53]	55.0 [2.17]



NOTE: Motor cables are approximately 304mm (12") in length.



For additional dimensions, see the AutomationDirect website or click on the drawing links.