1-800-633-0405

For the latest prices, please check AutomationDirect.com.

AC Servo Systems



Drive features

• Power:

- 1 phase 110VAC: 100W-2kW
- 1 phase 220VAC: 100W-2kW
- 3 phase 220VAC: 100W-15kW
- 3 phase 460VAC: 400W-15kW
- Fully digital with up to 3.1 kHz bandwidth velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the SureServo2 Pro PCbased software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- Communications include:
- Serial Modbus (native/built-in)
- Optional Modbus TCP card
- Optional Ethernet/IP card (this card can use implicit and explicit messaging. SureServo2 Pro software can generate an EDS file to transfer custom data between PLC and drive)
- · Command options include:
- ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
- Powerful built-in motion controller for position control using 99 preset positions (enter these during development, or send them through the communications options above during runtime)
- Internal sequencing for position/speed

SureServo2 tuning technology

The SureServo2 drive closes the loop on current, velocity, and position (depending on control mode selection). The 3.1 kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and five (5) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can easily tune systems with as much as 60:1 inertia mismatch.

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- One Touch Auto Tuning-the drive tunes the motor without any motion (static motor/ system analysis)
- Normal Auto Tuning-the drive tunes the load while an external controller or the drive's internal indexer provides point-to-point moves
- Assisted Tuning-3 modes where the drive tunes the motor while moving. The user can adjust responsiveness while the drive is analyzing the system
- Manual Tuning-20+ parameters are available to give power users the ultimate flexibility to tune their systems.



commands, registration (capture/compare), electronic camming, homing (10 different options), Jumps, and arithmetic statements.

- The 3.1 kHz bandwidth allows for high-level automatic tuning. Several modes of tuning are available including Auto Tune that can estimate the load inertia and fine-tune the system when all the loads are attached.
- Optically isolated digital inputs (10) and outputs (6), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution).
- Other Features:
 - Secondary/Auxiliary encoder feedback (for true closed loop control)
 - Registration ability
 - Analog positioning
 - Safe Torque Off (STO) included so no need for large, bulky contactors to disconnect power from the drive in E-stop situations
 - Absolute Encoder operation (with optional encoder battery backup)
 - Electronic camming (you can define the cam with SureServo2 Pro software or you can import an Excel spreadsheet)
 - Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.

SureServo2 Built-in motion controller

While the SureServo2 drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to 99 index moves can be pre-defined and stored in the drive and then selected and executed using digital inputs (inputs as events or inputs used as a multiplexer) or communication (serial Modbus, Modbus TCP, or Ethernet/IP). The index profiles can also be changed while in-process with digital events or via comms. The internal motion can consist of incremental or absolute moves, and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial/Ethernet communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful motion controller inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion

Motor features

- · Low inertia models:
 - 100W, 200W, 400W, 750W, 1kW, 1.5 kW, and 2kW
- Speeds up to 6,000 rpm • Medium inertia models:
- 1kW, 1.5 kW, 2kW, and 3kW
- Speeds up to 3,000 rpm
- · High inertia models:
- 3kW, 4.5 kW, 5.5 kW, 7.5 kW, 11kW, and 15kW
- Speeds up to 3,000 rpm
- Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style couplings
- Integrated encoder with 16,777,216 encoder pulses/revolution plus marker pulse (once per revolution)
- Optional 24 VDC spring-set holding brakes (xxxxB series motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for brake motors 230V systems 5.5kW and larger or 460V systems 11kW and larger)
- · Motor cables available in standard or flexrated lengths of 3, 5, 10, and 20m
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 20-pin spring clamp terminal block (limited I/O) that mounts directly to the drive

SureServo2 **Optional Holding Brake**

Each SureServo2 motor rating can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

SureGear[®] Precision Gearboxes for Servo motors

Inertia balancing issue in your design?



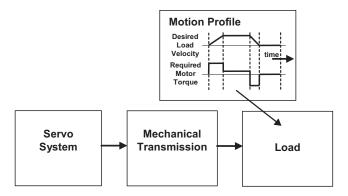
- Four gear ratios available (5, 10, 15, 25:1)
- Mounting hardware included for attaching to SureServo2 motors
- Industry-standard mounting dimensions
- · Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty



AC Servo Systems

How to select and apply SureServo2 systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo2 system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement. SureServo2 Pro has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.



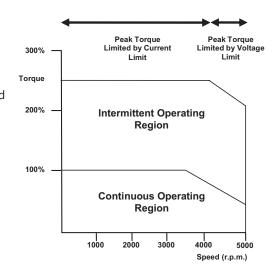
1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system. AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from www. automationdirect.com on the store page for your drive.

In general, applications that need high response or bandwidth will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo2 systems may be tuned manually, fully Automatically, or via a hybrid mode where the software tunes the system with input for system responsiveness from the user.

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have a SureServo2 system, these values are easily captured and recorded with the Scope feature built into SureServo2 Pro. If you are designing the system, use VisualSizer to define the system and calculate expected inertia and required power.





AC Servo Systems

Application tip - coupling considerations

The SureServo2 motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider the stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a tradeoff between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo2 **peak** torque requirement of your application.

Available Couplings

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo2 systems can go up to 6,000 rpm for the low inertia motors and up to 3,000 rpm for the medium inertia motors.

Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo

system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

SureServo2 motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.

For more information, refer to the website listed below.

Mechanical Transmission: <u>Timing Belts and Pulleys</u> <u>Precision Gearboxes</u>

Ordering guide instructions

The following four pages are your ordering guide for SureServo2 systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

Each system needs:

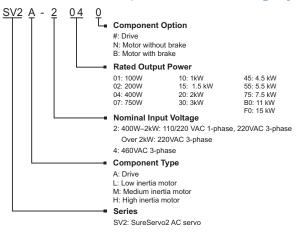
- MotorDrive
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either CN1 cable + RTB breakout board, or an LTB20 breakout board that mounts on the drive)
- For brakemotors 4.5 kW and below, the brake wiring is included in the power cable. For brakemotors 5.5 kw and above, a separate brake cable is required.

A wide variety of optional accessories are also available, such as Ethernet cards, RS485 splitters/terminators, toroids, etc.

You can also use the SureServo2 selector tool on the AutomationDirect.com website to help you configure your system.



SureServo2 series drives and motors part numbering system



Here is what you will need to order a complete servo system:



NOTE: Unit can be programmed via keypad. Optional programming software (free download) and optional programming cable available.

NOTE: If you need a gear box for your configuration, you can do it easily online: http://www.sureservo.com/gearbox/selector





Torque to SureServo2 System Quick Reference

	230V System Torque								
System Rated Torque (N·m)	System Maximum Torque (N∙m)	Suggested Servo Motor	Required Servo Drive						
0.32	1.12	SV2L-201N or SV2L-201B	<u>SV2A-2040</u>						
0.64	2.24	SV2L-202N or SV2L-202B	<u>SV2A-2040</u>						
1.27	3.96	SV2L-204N or SV2L-204B	<u>SV2A-2040</u>						
2.39	7.86	SV2L-207N or SV2L-207B	<u>SV2A-2075</u>						
3.18	8.12	SV2L-210N or SV2L-210B	<u>SV2A-2150</u>						
4.77	14.32	SV2M-210N or SV2M-210B	<u>SV2A-2150</u>						
7.16	14.88	SV2M-215N or SV2M-215B	<u>SV2A-2150</u>						
9.55	24.54	SV2M-220N or SV2M-220B	<u>SV2A-2200</u>						
17.55	48.29	SV2M-230N or SV2M-230B	<u>SV2A-2300</u>						
28.65	71.62	SV2H-245N or SV2H-245B	<u>SV2A-2550</u>						
35.01	87.53	SV2H-255N or SV2H-255B	<u>SV2A-2550</u>						
47.74	119.36	SV2H-275N or SV2H-275B	<u>SV2A-2750</u>						
70	175	SV2H-2B0N or SV2H-2B0B	SV2A-2F00						
95.4	224.0	SV2H-2F0N or SV2H-2F0B	<u>SV2A-2F00</u>						

	460V System Torque							
System Rated Torque (N∙m)	System Maximum Torque (N∙m)	Suggested Servo Motor	Required Servo Drive					
1.27	4.45	<u>SV2L-404N</u> or <u>SV2L-404B</u>	<u>SV2A-4040</u>					
2.24	7.58	<u>SV2L-407N</u> or <u>SV2L-407B</u>	<u>SV2A-4075</u>					
3.18	9.54	<u>SV2L-410N</u> or <u>SV2L-410B</u>	<u>SV2A-4150</u>					
4.77	14.32	<u>SV2M-410N</u> or <u>SV2M-410B</u>	<u>SV2A-4150</u>					
7.16	18.1	<u>SV2L-415N</u> or <u>SV2L-415B</u>	<u>SV2A-4150</u>					
9.55	28.65	<u>SV2L-420N</u> or <u>SV2L-420B</u>	<u>SV2A-4200</u>					
19.1	49.38	SV2H-430N or SV2H-430B	<u>SV2A-4300</u>					
28.65	64.61	<u>SV2H-445N</u> or <u>SV2H-445B</u>	SV2A-4550					
35.01	73.48	<u>SV2H-455N</u> or <u>SV2H-455B</u>	<u>SV2A-4550</u>					
47.74	93.71	<u>SV2H-475N</u> or <u>SV2H-475B</u>	<u>SV2A-4750</u>					
70	175	<u>SV2H-4B0N</u> or <u>SV2H-4B0B</u>	SV2A-4F00					
95.4	224.0	SV2H-4F0N or SV2H-4F0B	SV2A-4F00					



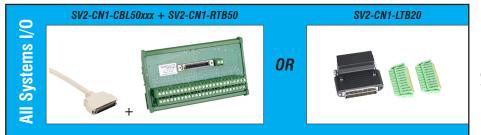
SureServo2 AC servo drive, motor, and cable combinations

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(350%) F	<u>SV2L-201N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
em	120V	EF, and a second secon		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
100W Low Inertia System	1200	0.32 (100%) Continuous Region	<u>SV2L-201B</u>	012112040	SV2C-PB18-xxNB	SV2C-E122-xxNN
Inertia		1,600 3,000 4,200 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
/ Low		1.12	SV/2L-201N	<u>SV2A-2040</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
100M	230V	(188%) 0.60 0.50 0.22 (188%) 0.32 (100%) 0.16 (50%) Continuous Region 3,000 4,800 6,000 Speed (r/min)	<u>SV2L-201N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
			<u>SV2L-201B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
					SV2C-PB18-xxFB	SV2C-E122-xxFN
	120V	(350%)	<u>SV2L-202N</u>	<u>SV2A-2040</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
n		E about the second sec			SV2C-PA18-xxFN	SV2C-E122-xxFN
Syster		0.64 (100%) Continuous Region			SV2C-PB18-xxNB	SV2C-E122-xxNN
ertia		1,400 3,000 3,700 Speed (r/min)	<u>SV2L-202B</u>		SV2C-PB18-xxFB	SV2C-E122-xxFN
200W Low Inertia System		224 (350%)	SV2L-202N		SV2C-PA18-xxNN	SV2C-E122-xxNN
MOO	230V	1.90 (297%) (E: 2010) (297%) Intermittent Region	<u>3v2L-20211</u>	- <u>SV2A-2040</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
2	230V	0.64 (100%) 0.32 Continuous Region	<u>SV2L-202B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
		(50%) 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

SV2C-xxxx-xxNB is a non-flex, brake motor cable

The final two digits indicate flex rating and motor brake compatibility: SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







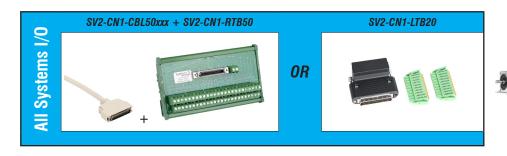
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(m-N	3.96 (312%)	<u>SV2L-204N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2040</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200		1.27 (100%) Continuous Region	<u>SV2L-204B</u>	<u>372A-2040</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,000 2,700 3,600 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
System			3.96 (312%) 3.48 2724%)	SV2L-204N		SV2C-PA18-xxNN	SV2C-E122-xxNN
400W Low Inertia System	230V	Torque (N-m)	Intermittent Region		SV2A-2040	SV2C-PA18-xxFN	SV2C-E122-xxFN
N LOW	2300	Tor	1.27 (100%) 0.65 Continuous Region	<u>SV2L-204B</u>	<u></u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
400			(50%) 3,000 4,400 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
			4.45 (350%)			SV2C-PA18-xxNN	SV2C-E122-xxNN
	1001	Torque (N-m)	3.45 (272%) Intermittent Region	SV2L-404N	SV2A-4040	SV2C-PA18-xxFN	SV2C-E122-xxFN
	460V	ToT	1.27 (100%) 0.65 (50%) Continuous Region	SV2L-404B		SV2C-PB18-xxNB	SV2C-E122-xxNN
			(50%) Continuous Region 3,000 3,900 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







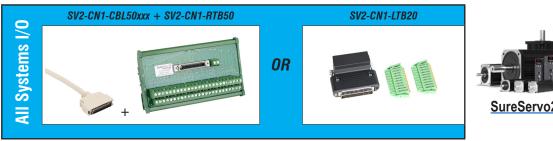
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		2	7.86 (329%)	<u>SV2L-207N</u>		SV2C-PA18-xxNN	SV2C-E122-xxNN
	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2075</u>	SV2C-PA18-xxFN	SV2C-E122-xxFN
	1200		2.39 (100%) Continuous Region	<u>SV2L-207B</u>	<u>572A-2075</u>	SV2C-PB18-xxNB	SV2C-E122-xxNN
			1,300 2,550 3,200			SV2C-PB18-xxFB	SV2C-E122-xxFN
System		Torque (N-m)	7.86 (329%) 6.63	SV2L-207N	<u>SV2A-2075</u>	SV2C-PA18-xxNN	SV2C-E122-xxNN
750W Low Inertia System	230V		(277%) Intermittent Region	<u>3V2L-207N</u>		SV2C-PA18-xxFN	SV2C-E122-xxFN
W Low		Torq	2.39 (100%) Continuous Region	<u>SV2L-207B</u>		SV2C-PB18-xxNB	SV2C-E122-xxNN
750			1.195 (50%) 3,000 4,300 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN
			7.58 (338%) 6.48	SV2L-407N		SV2C-PA18-xxNN	SV2C-E122-xxNN
	460V	Torque (N-m)	(289%) Intermittent Region	3V2L-40/N	- SV2A-4075	SV2C-PA18-xxFN	SV2C-E122-xxFN
	4007	Tor	2.24 (100%) 1.195 (53%)	SV2L-407B		SV2C-PB18-xxNB	SV2C-E122-xxNN
			(53%) Continuous Region 3,200 4,350 6,000 Speed (r/min)			SV2C-PB18-xxFB	SV2C-E122-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





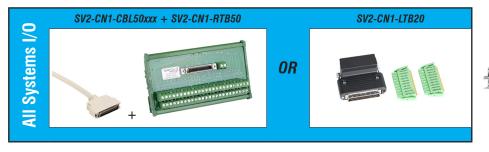
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		(4	8.12 (255%)		SV2L-210N		SV2C-PC16-xxNN	SV2C-E222-xxNN
	120V	Torque (N-m)		Intermittent Region		01/04 0450	SV2C-PC16-xxFN	SV2C-E222-xxFN
	1200		3.18 (100%)	Continuous Region	SV2L-210B	<u>SV2A-2150</u>	SV2C-PC16-xxNB	SV2C-E222-xxNN
1			L	1,800 2,800 3,500	0721-2100		SV2C-PC16-xxFB	SV2C-E222-xxFN
Systen	230V		8.12 (255%)		<u>SV2L-210N</u>	— <u>SV2A-2150</u>	SV2C-PC16-xxNN	SV2C-E222-xxNN
1.0 kW Low Inertia System		Torque (N-m)		Intermittent Region			SV2C-PC16-xxFN	SV2C-E222-xxFN
W Low		Torq	3.18 (100%)	Continuous Region	<u>SV2L-210B</u>		SV2C-PC16-xxNB	SV2C-E222-xxNN
1.0 k			1.91 (60%)	3,000 3,300 5,000 Speed (r/min)	0721-2100		SV2C-PC16-xxFB	SV2C-E222-xxFN
			9.54 (300%)				SV2C-PC16-xxNN	SV2C-E222-xxNN
	460V	Torque (N·m)		Intermittent Region	SV2L-410N	SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
	4007	þ	3.18 (100%) 1.91 (60%)	Continuous Region	SV2L-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
				3,000 5,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







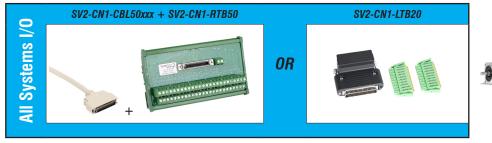
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		14.32 (300%)		<u>SV2M-210N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
	120V	Torque (N-m)		<u> </u>	SV2A-2150	SV2C-PC12-xxFN	SV2C-E222-xxFN
	1200	₽ 4.77 (100%)	Intermittent Region Continuous Region	CV/2M 240D	<u>372A-2130</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
ша			700 1,550 2,000 Speed (r/min)	<u>SV2M-210B</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
1.0 kW Medium Inertia System		14,32 (300%)		SV2M-210N	<u>SV2A-2150</u>	SV2C-PC12-xxNN	SV2C-E222-xxNN
m Inert	230V	Torque (N·m)	Intermittent Region	<u>5721014</u>		SV2C-PC12-xxFN	SV2C-E222-xxFN
Mediu		4.77 (100%)	Continuous Region	<u>SV2M-210B</u>		SV2C-PC12-xxNB	SV2C-E222-xxNN
1.0 KW		3.20 (67%)	2,000 3,000 Speed (r/min)			SV2C-PC12-xxFB	SV2C-E222-xxFN
		14.32 (300%)		SV2M-410N		SV2C-PC16-xxNN	SV2C-E222-xxNN
	1001	Torque (N-m)	Intermittent Region		SV2A-4150	SV2C-PC16-xxFN	SV2C-E222-xxFN
	460V	2 (100%) 3.20 (67%)	Continuous Region	SV2M-410B		SV2C-PC16-xxNB	SV2C-E222-xxNN
			2,000 3,000 Speed (r/min)			SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







SureServo2 AC servo drive, motor, and cable combinations, continued

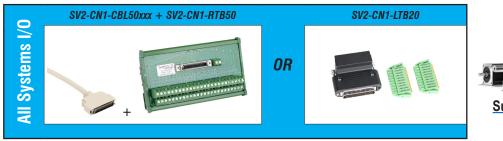
	Input Voltage			Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
			14.88 (208%)		<u>SV2M-215N</u>		SV2C-PC12-xxNN	SV2C-E222-xxNN
m	120V	Torque (N-m)	7.16 (100%)	Intermittent Region	<u>57219721514</u>	<u>SV2A-2150</u>	SV2C-PC12-xxFN	SV2C-E222-xxFN
1.5 kW Medium Inertia System	1200	Ĕ.	(100%)	Continuous Region	<u>SV2M-215B</u>	<u>372A-2130</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN
n Inerti				1,000 1,400 1,800 Speed (r/min)	<u>372M-2130</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
Mediur		Torque (N:m)	14.88 (208%)	7.16	SV2M-215N		SV2C-PC12-xxNN	SV2C-E222-xxNN
1.5 kW	230V		716			01/04 0450	SV2C-PC12-xxFN	SV2C-E222-xxFN
			Continuous Region		<u>SV2A-2150</u>	SV2C-PC12-xxNB	SV2C-E222-xxNN	
			4.60 (67%)	2,000 2,400 3,000 Speed (r/min)	<u>SV2M-215B</u>		SV2C-PC12-xxFB	SV2C-E222-xxFN
ystem			18.1 (253%)	18.1 (253%)	SV2L-415N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Torque (N·m)		Intermittent Region	5V2L-415IV		SV2C-PC16-xxFN	SV2C-E222-xxFN
1.5 kW Low Inertia System	7007	Тог	5 7.16 (100%) 4.77 (67%) Continuous Region		SV2A-4150	SV2C-PC16-xxNB	SV2C-E222-xxNN	
1.5 kV				2,000 3,000 Speed (r/min)	SV2L-415B		SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility: SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable

SV2C-xxxx-xxNB is a non-flex, brake motor cable

SV2C-xxxx-xxFB is a flex-rated, brake motor cable







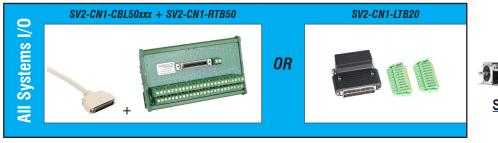
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		24. (257	24.54 (257%)	SV2M-220N		SV2C-PD12-xxNN	SV2C-E222-xxNN
m	120V	Torque (N-m)	Intermittent Region		<u>SV2A-2200</u>	SV2C-PD12-xxFN	SV2C-E222-xxFN
a Syste	1200	بے ب (100	55 %) Continuous Region	<u>SV2M-220B</u>	<u>372A-2200</u>	SV2C-PD12-xxNB	SV2C-E222-xxNN
2.0 kW Medium Inertia System			800 1,500 1,950 Speed (r/min)	37210-2200		SV2C-PD12-xxFB	SV2C-E222-xxFN
Mediu		24 (257	.54	SV2M-220N		SV2C-PD12-xxNN	SV2C-E222-xxNN
2.0 kW	230V	Forque (N-m)	Intermittent Region	<u>3vzm-zzon</u>		SV2C-PD12-xxFN	SV2C-E222-xxFN
		9 100 (100	Continuous Region	<u>SV2M-220B</u>	<u>SV2A-2200</u>	SV2C-PD12-xxNB	SV2C-E222-xxNN
		6 (67	.40 %6) 2,000 2,200 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		28.65 (300%)		SV2L-420N		SV2C-PC16-xxNN	SV2C-E222-xxNN
nertia S	460V	Torque (N-m)	Intermittent Region	0721-42014	SV2L-420N SV2A-4200	SV2C-PC16-xxFN	SV2C-E222-xxFN
2.0 kW Low Inertia System	4007	9.55 (100%) 6.40 (67%)	9.55 (100%) 6.40 (67%) Continuous Region 2,000 3,000 Speed (r/min)	SV/21 420P		SV2C-PC16-xxNB	SV2C-E222-xxNN
2.0 KN				SV2L-420B		SV2C-PC16-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable SV2C-xxxx-xxFN is a flex-rated, non-brake cable SV2C-xxxx-xxFB is a flex-rated, brake motor cable







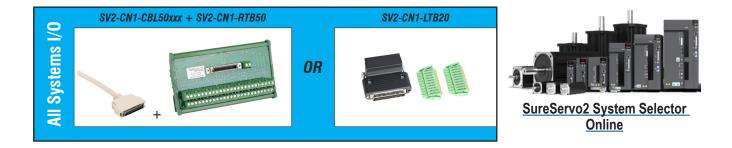
SureServo2 AC servo drive, motor, and cable combinations, continued

u	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
a Syster		48.29	SV2M-230N		SV2C-PD12-xxNN	SV2C-E222-xxNN
m Inerti	2201/	Intermittent Region	<u>37210-23010</u>	<u>SV2A-2300</u>	SV2C-PD12-xxFN	SV2C-E222-xxFN
3.0 kW Medium Inertia System	230V	b 17.55 (100%) 10.00 (57%) 9.55 (54%) € Continuous Region			SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 K		1,700 1,800 3,000 Speed (r/min)	<u>SV2M-230B</u>		SV2C-PD12-xxFB	SV2C-E222-xxFN
ystem		49.38	SV2H-430N	- SV2A-4300	SV2C-PD12-xxNN	SV2C-E222-xxNN
3.0 kW High Inertia System		Intermittent Region			SV2C-PD12-xxFN	SV2C-E222-xxFN
N High I	460V	9.00 (47%) Continuous Region			SV2C-PD12-xxNB	SV2C-E222-xxNN
3.0 K	3.0 KV	1,500 1,800 3,000 Speed (r/min)			SV2C-PD12-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





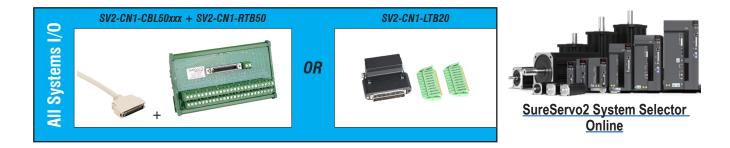
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		71.62 (250%)	SV2H-245N		SV2C-PD08-xxNN	SV2C-E222-xxNN
	230V	(E. ž) and the second	<u>57511-24514</u>	<u>SV2A-2550</u>	SV2C-PD08-xxFN	SV2C-E222-xxFN
System	2007	28.65 (100%) 14.33 (50%) Continuous Region	SV2H-245B		SV2C-PD08-xxNB	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	<u>3V2I1-243D</u>		SV2C-PD08-xxFB	SV2C-E222-xxFN
4.5 kW High Inertia System		64.61 (226%)		- SV2A-4550	SV2C-PD08-xxNN	SV2C-E222-xxNN
4.5	460V	Intermittent Region	SV2H-445N		SV2C-PD08-xxFN	SV2C-E222-xxFN
	4007	← (100%) 14.33 (50%) Continuous Region	SV2H-445B		SV2C-PD08-xxNB	SV2C-E222-xxNN
		1,500 1,700 3,000 Speed (r/min)			SV2C-PD08-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage	Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		87.53 (250%)	SV2H-255N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	230V	Intermittent Region	<u></u>		SV2C-PF06-xxFN	SV2C-E222-xxFN
System	2300	b (100%) 17.51 (50%) Continuous Region	SV2H-255B	<u>SV2A-2550</u>	SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia		1,500 3,000 Speed (r/min)	<u>37211-2336</u>		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
5.5 kW High Inertia System		73.48		SV2A-4550	SV2C-PD08-xxNN	SV2C-E222-xxNN
5.2	460V	E Intermittent Region	SV2H-455N		SV2C-PD08-xxFN	SV2C-E222-xxFN
	4007	19.1 (55%) 17.51 (50%)	SV2H-455B		SV2C-PD08-xxNN	SV2C-E222-xxNN
		1,500 1,900 3,000 Speed (r/min)			SV2C-PD08-xxFN	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





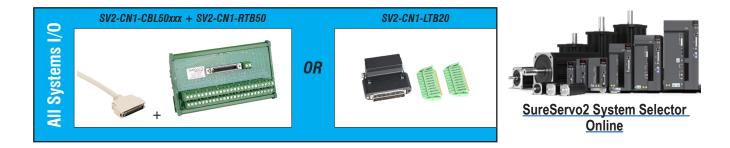
SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		119. (250	36	SV2H-275N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	2201/	Torque (N-m)	Intermittent Region	<u>3vz1+z/3N</u>	- <u>SV2A-2750</u>	SV2C-PF06-xxFN	SV2C-E222-xxFN
System	7.5 kW High Inertia System	(100	47.74 (100%) 23.87 (50%) Continuous Region	SV2H-275B	<u>3VZA-2730</u>	SV2C-PF06-xxNN and SV2C-B120-xxxx	SV2C-E222-xxNN
Inertia			1,500 3,000 Speed (r/min)	37211-2730		SV2C-PF06-xxFN and SV2C-B120-xxxx	SV2C-E222-xxFN
kW High		93.7 (1969		SV2H-475N		SV2C-PD08-xxNN	SV2C-E222-xxNN
7.5	460V	Lordue (N-m)	Intermittent Region	3V211-473N	SV2A-4750	SV2C-PD08-xxFN	SV2C-E222-xxFN
	4000	20. (42%		SV2H-475B	072744700	SV2C-PD08-xxNN	SV2C-E222-xxNN
			1,500 2,000 3,000 Speed (r/min)	0.1141.00		SV2C-PD08-xxFN	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		17 (250	5.0	SV2H-2B0N		SV2C-PF06-xxNN	SV2C-E222-xxNN
	71.0 kW High Inertia System	Torque (N-m)	Intermittent Region	<u>37211-2000</u>	01/04 0500	SV2C-PF06-xxFN	SV2C-E222-xxFN
System			25-	SV2H-2B0B	<u>SV2A-2F00</u>	SV2C-PF06-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
h Inertia			1,500 2,000 Speed (r/min)	<u>3721-2000</u>		SV2C-PF06-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN
kW Hig		17 (250	5.0	SV2H-4B0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
11.0	(j) ant		Intermittent Region	37211-4001	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	460V	- (100	2.5	SV2H-4B0B	SV2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
			1,500 2,000 Speed (r/min)	3ν2Π-4ΒυΒ		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable





SureServo2 AC servo drive, motor, and cable combinations, continued

	Input Voltage		Torque Chart	SureServo2 Motor	SureServo2 Drive	Power Cable*	Encoder Cable*
		22 (235	14.0	SV2H-2F0N		SV2C-PF04-xxNN	SV2C-E222-xxNN
	230V	Torque (N-m)	Intermittent Region	<u>3vzn-zrun</u>	SV2A-2F00	SV2C-PF04-xxFN	SV2C-E222-xxFN
System	2300	. (100	75.4 0966) 1.6 5969) Continuous Region	SV2H-2F0B	<u>SV2A-2F00</u>	SV2C-PF04-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
15.0 kW High Inertia System			1,500 2,000 Speed (r/min)	<u>3v2n-2rub</u>		SV2C-PF04-xxFB and SV2C-B120-xxFB	SV2C-E222-xxFN
kW Higl		224 (235	4.0	SV2H-4F0N		SV2C-PF08-xxNN	SV2C-E222-xxNN
15.0		Torque (N·m)	95.4	3v2n-4run	SV2A-4F00	SV2C-PF08-xxFN	SV2C-E222-xxFN
	460V	(100) (100) (75%	%)		SV2A-4F00	SV2C-PF08-xxNN and SV2C-B120-xxNB	SV2C-E222-xxNN
			1,500 2,000 Speed (r/min)	SV2H-4F0B		SV2C-PF08-xxFN and SV2C-B120-xxFB	SV2C-E222-xxFN

Note: "xx" in the cable part numbers represents cable length: SV2C-xxxx-10xx is a 10m cable.

The final two digits indicate flex rating and motor brake compatibility:

SV2C-xxxx-xxNN is a non-flex, non-brake motor cable SV2C-xxxx-xxNB is a non-flex, brake motor cable

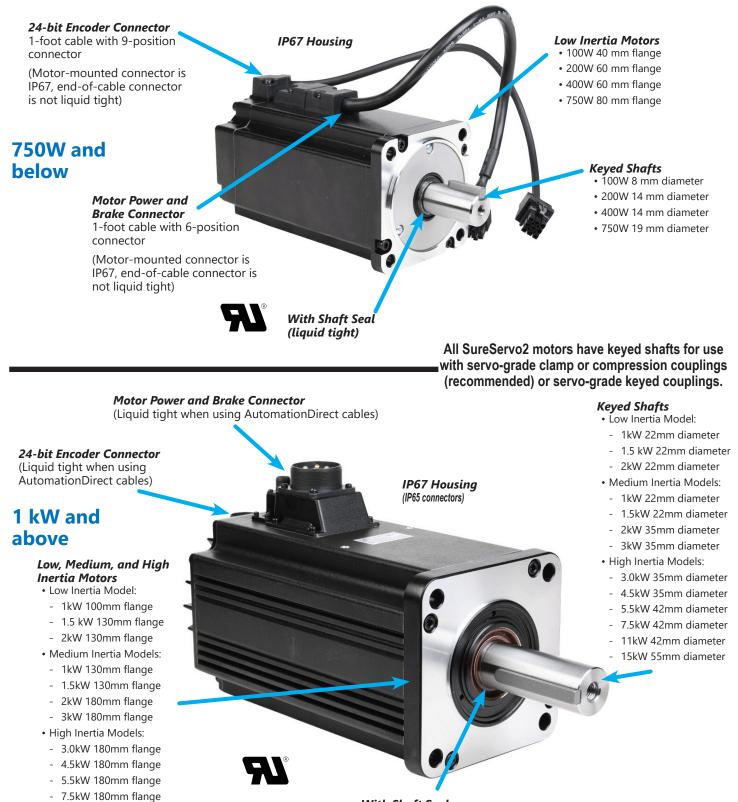


For the latest prices, please check AutomationDirect.com.



AC Servo Motor Specifications

Servo motor overview



With Shaft Seal (liquid tight)

- 11kW 220mm flange



230V Low Inertia Motor Specifications

		230V Sur	eServo2	Low Iner	tia Moto	r Specifi	cations			
Model	SV2L-201N	SV2L-201B	SV2L-202N	SV2L-202B	SV2L-204N	SV2L-204B	SV2L-207N	SV2L-207B	SV2L-210N	SV2L-210B
Price	\$286.00	\$419.00	\$315.00	\$465.00	\$340.00	\$479.00	\$364.00	\$510.00	\$477.00	\$702.00
Drawing	#200.00 PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
Rated Power [kW]	0.1	0.1	0.2	0.2	0.4	0.4	0.75	0.75	1.0	1.0
Rated Torque [N·m]Note 1	0.32	0.32	0.64	0.64	1.27	1.27	2.39	2.39	3.18	3.18
Max. Torque (N·m)	1.12	1.12	2.24	2.24	3.96	3.96	7.86	7.86	8.12	8.12
Rated Speed [rpm]					30	00				
Max. Speed [rpm]		6000 5000								
Rated current [Amps] rms	0.9	0.9	1.45	1.45	2.60	2.60	4.5	4.5	8.04	8.04
Max. Instantaneous Current [Amps] rms	3.3	3.3	5.4	5.4	8.56	8.56	15.41	15.41	20.16	20.16
Change of Rated Power [W/s]	16.3	14.90	16.4	14.60	35.8	33.60	37.8	34.40	38.2	30.40
Rotor Inertia [x10-4 kg m2]	0.0627	0.0689	0.25	0.28	0.45	0.48	1.51	1.66	2.65	3.33
Mechanical Time Constant [ms]	1.13	1.24	1.38	1.54	0.94	1.01	0.91	1.00	0.83	1.05
Torque Constant-KT [N-m/A]	0.356	0.356	0.441	0.441	0.488	0.488	0.531	0.531	0.396	0.396
/Voltage Constant-KE [mV rpm]	13.66	13.66	16.4	16.4	17.2	17.2	18.7	18.7	16.8	16.8
Armature Resistance [Ohm]	8.34	8.34	3.8	3.8	1.68	1.68	0.57	0.57	0.20	0.20
Armature Inductance [mH]	9.85	9.85	8.15	8.15	4.03	4.03	2.2	2.2	1.81	1.81
Electrical Time Constant [ms]	1.18	1.18	2.14	2.14	2.40	2.40	3.86	3.86	9.05	9.05
Insulation Class					Class A (UL),	Class B (CE)				
Insulation Resistance						, 500VDC				
Insulation Strength						, 1 second		1	1	
Weight [kg]	0.5	0.8	1.1	1.6	1.4	1.9	2.8	3.6	4.3	4.7
Max. Radial Loading [N]	78	78	245	245	245	245	392	392	490	490
Max. Axial Loading [N]	54	54	74	74	74	74	147	147	98	98
Brake Holding Torque [N·m (min)]Note 2		0.32		1.3		1.3		2.5	-	8
Brake Power Consumption (at 20°C) [W]	n/a	6.1	n/a	7.2	n/a	7.2	n/a	8	n/a	18.7
Brake Release Time [ms (max)]		20		20		20		20		10
Brake Pull-in Time [ms (max)]		35		50		50		60		70
Vibration Grade [µm]						15				
Operating Temperature [°C]		0-40 °C (32-104 °F)								
Storage Temperature [°C]		-10°C to 80°C (-14°F to 176°F)								
Operating Humidity		20–90% relative humidity (non-condensing)								
Storage Humidity		20–90% relative humidity (non-condensing) 2.5 G								
Vibration Capacity		IDEE (when using untergrant								
IP Rating ³		IP67 (when using waterproof connectors) IP65 (when using waterproof connectors)								
Encoder Resolution					(7216 p/rev)				
Agency Approvals					cURU	_{IS} , CE				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating termperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



230V Medium Inertia Motor Specifications

					tor Specifi			-		
Model	<u>SV2M-210N</u>	<u>SV2M-210B</u>	<u>SV2M-215N</u>	<u>SV2M-215B</u>	<u>SV2M-220N</u>	<u>SV2M-220B</u>	<u>SV2M-230N</u>	<u>SV2M-230B</u>		
Price	\$497.00	\$711.00	\$537.00	\$795.00	\$651.00	\$863.00	\$735.00	\$947.00		
Drawing	<u>PDF</u>	PDF	PDF	<u>PDF</u>	PDF	PDF	PDF	PDF		
Rated Power [kW]	1.0	1.0	1.5	1.5	2.0	2.0	3.0	3.0		
Rated Torque [N·m]Note 1	4.77	4.77	7.16	7.16	9.55	9.55	17.55	17.55		
Max. Torque [N·m]	14.32	14.32	14.88	14.88	24.54	24.54	48.29	48.29		
Rated Speed [rpm]		2000								
Max. Speed [rpm]		3000								
Rated current [Amps] rms	5.66	5.66	8.33	8.33	12.1	12.1	17.9	17.9		
Max. Instantaneous Current [Amps] rms	19.73	19.73	20.16	20.16	33.66	33.66	55.93	55.93		
Change of Rated Power [W/s]	27.1	24.90	45.8	43.10	26.3	24.10	56.0	53.90		
Rotor Inertia [x10-4 kg m2]	8.41	9.14	11.2	11.9	34.7	37.8	55	57.1		
Mechanical Time Constant [ms]	1.54	1.67	1.12	1.18	1.75	1.90	1.29	1.34		
Torque Constant-KT [N-m/A]	0.843	0.843	0.860	0.860	0.789	0.789	0.980	0.980		
Voltage Constant-KE [mV/ rpm]	31.9	31.9	31.8	31.8	31.4	31.4	35	35		
Armature Resistance [Ohm]	0.47	0.47	0.26	0.26	0.119	0.119	0.077	0.077		
Armature Inductance [mH]	5.99	5.99	4.01	4.01	2.84	2.84	1.27	1.27		
Electrical Time Constant [ms]	12.74	12.74	15.42	15.42	23.87	23.87	16.49	16.49		
Insulation Class				Class A (UL),	Class B (CE)					
Insulation Resistance				> 100MΩ	, 500VDC					
Insulation Strength				1.8 kVAC	1 second					
Weight [kg]	7.0	8.4	7.5	8.9	13.5	17.5	18.5	22.5		
Max. Radial Loading [N]		49	90		11	76	14	70		
Max. Axial Loading [N]		g	8			49	90			
Brake Holding Torque [N·m (min)]Note 2		10		10		25		25		
Brake Power Consumption (at 20°C) [W]	n/a	19	n/a	19	n/a	20.4	n/a	20.4		
Brake Release Time [ms (max)]	11/d	10	11/a	10	11/a	10	n/a	10		
Brake Pull-in Time [ms (max)]		70		70		70		70		
Vibration Grade [µm]				V	15					
Operating Temperature [°C]				0–40 °C (3	32–104 °F)					
Storage Temperature [°C]	-10°C to 80°C (-14°F to 176°F)									
Operating Humidity		20–90% relative humidity (non-condensing)								
Storage Humidity		20–90% relative humidity (non-condensing)								
Vibration Capacity		2.5 G								
IP Rating ³			IF	65 (when using wa	aterproof connector	s)				
Encoder Resolution				24-bit (1677	7216 p/rev)					
Agency Approvals					_{IS} , CE		-			

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



230V High Inertia Motor Specifications

	2	30V Sure	Servo2	High Ine	rtia Moto	r Specifi	cations						
Model	<u>SV2H-245N</u>	<u>SV2H-245B</u>	<u>SV2H-255N</u>	<u>SV2H-255B</u>	<u>SV2H-275N</u>	<u>SV2H-275B</u>	SV2H-2BON	SV2H-2B0B	SV2H-2FON	SV2H-2F0B			
Price	\$911.00	\$1,415.00	\$1,050.00	\$1,568.00	\$1,273.00	\$1,989.00	\$1,956.00	\$2,682.00	\$2,257.00	\$3,091.00			
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF			
Rated Power [kW]	4.5	4.5	5.5	5.5	7.5	7.5	11	11	15	15			
Rated Torque [N·m]Note 1	28.65	28.65	35.01	35.01	47.74	47.74	70	70	95.4	95.4			
Max. Torque [N·m]	71.62	71.62	87.53	87.53	119.36	119.36	175	175	224.0	224.0			
Rated Speed [rpm]					15	00							
Max. Speed [rpm]		r	30	00	1	1	2000						
Rated current [Amps] rms	32.5	32.5	40.12	40.12	47.5	47.5	51.1	51.1	67	67			
Max. Instantaneous Current [Amps] rms	91.4	91.4	108.0	108.0	127.46	127.46	129.5	129.5	162	162			
Change of Rated Power [W/s]	105.6	101.8	122.8	119.3	159.7	156.6	145.0	141.4	201.8	197.1			
Rotor Inertia [x10-4 kg m2]	77.75	80.65	99.78	102.70	142.7	145.55	338	346.5	451	461.8			
Mechanical Time Constant [ms]	0.93	0.96	0.97	0.99	0.84	0.85	1.38	1.41	1.22	1.25			
Torque Constant-KT [N·m/A]	0.878	0.878	0.873	0.873	1.005	1.005	1.370	1.370	1.424	1.424			
Voltage Constant-KE [mV/rpm]	32.0	32.0	31.0	31.0	35.5	35.5	49	49	50	50			
Armature Resistance [Ohm]	0.032	0.032	0.025	0.025	0.02	0.02	0.0261	0.0261	0.0184	0.0184			
Armature Inductance [mH]	0.89	0.89	0.71	0.71	0.6	0.6	0.65	0.65	0.48	0.48			
Electrical Time Constant [ms]	27.81	27.81	28.4	28.4	30.0	30.0	24.9	24.9	26.09	26.09			
Insulation Class			Class A (UL),	Class B (CE)				Class F (UL),	Class F (CE)				
Insulation Resistance				-	> 100MΩ	, 500VDC							
Insulation Strength			1	1	1.8 kVAC	1 second	1	1		1			
Weight [kg]	23.5	29	30.5	36	40.5	46	56.4	68.4	75	87			
Max. Radial Loading [N]	14	-			/64				800				
Max. Axial Loading [N]	49	90		5	88			11	00				
Brake Holding Torque [N·m (min)]Note 2		55.0		55.0	-	55.0	-	115		115			
Brake Power Consumption (at 20°C) [W]	n/a	19.9	n/a	19.9	n/a	19.9	n/a	28.8	n/a	28.8			
Brake Release Time [ms (max)]	Th G	10		10		10	, ind	10		10			
Brake Pull-in Time [ms (max)]		70		70		70		70		70			
Vibration Grade [µm]					V	15							
Operating Temperature [°C]		0-40 °C (32-104 °F)											
Storage Temperature [°C]		-10°C to 80°C (-14°F to 176°F)											
Operating Humidity	20–90% relative humidity (non-condensing)												
Storage Humidity		20–90% relative humidity (non-condensing)											
Vibration Capacity		2.5 G											
IP Rating ³				IP	65 (when using		es)						
Encoder Resolution					24-bit (1677	7216 p/rev)							
Agency Approvals					CURU	_{IS} , CE							

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm,400mm x 400mm x 20mm,550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability) Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake. Note 3–All SureServo2 motors are shipped with oil seals installed for IP rating requirements.



460V Low Inertia Motor Specifications

	4	460V Sur	eServo2	Low Ine	rtia Moto	r Specifi	cations			
Model	<u>SV2L-404N</u>	<u>SV2L-404B</u>	<u>SV2L-407N</u>	<u>SV2L-407B</u>	<u>SV2L-410N</u>	<u>SV2L-410B</u>	<u>SV2L-415N</u>	<u>SV2L-415B</u>	<u>SV2L-420N</u>	<u>SV2L-420B</u>
Price	\$360.00	\$515.00	\$388.00	\$555.00	\$505.00	\$745.00	\$580.00	\$855.00	\$687.00	\$899.00
Drawing	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
Rated Power [kW]	0.4	0.4	0.75	0.75	1.0	1.0	1.5	1.5	2.0	2.0
Rated Torque [N·m]Note 1	1.27	1.27	2.24	2.24	3.18	3.18	7.16	7.16	9.55	9.55
Max. Torque [N·m]	4.45	4.45	7.58	7.58	9.54	9.54	18.1	18.1	28.65	28.65
Rated Speed [rpm]	30	3000 3200 3000 2000								
Max. Speed [rpm]	60	6000 6000 5000 3000								
Rated current [Amps] rms	1.43	1.43 2.90 2.90 4.36 4.36 5.1 5.1 6.7								6.7
Max. Instantaneous Current [Amps] rms	5.25	5.25	9.70	9.70	13.74	13.74	13.28	13.28	21.35	21.35
Change of Rated Power [W/s]	35.8	33.6	33.2	30.2	38.2	30.40	45.9	43.10	62.5	57.4
Rotor Inertia [x10-4 kg m2]	0.45	0.48	1.51	1.66	2.65	3.33	11.18	11.9	14.59	15.88
Mechanical Time Constant [ms]	1.05	1.12	1.02	1.12	0.81	1.02	1.26	1.34	1.11	1.21
Torque Constant-KT [N-m/A]	0.888	0.888	0.772	0.772	0.729	0.729	1.404	1.404	1.425	1.425
/Voltage Constant-KE [mV/ rpm]	31.83	31.83	27.83	27.83	29.00	29.00	55.00	55.00	55.00	55.00
Armature Resistance [Ohm]	6.28	6.28	1.38	1.38	0.617	0.617	0.83	0.83	0.57	0.57
Armature Inductance [mH]	13.34	13.34	4.78	4.78	6.03	6.03	11.67	11.67	8.29	8.29
Electrical Time Constant [ms]	2.12	2.12	3.46	3.46	9.77	9.77	14.06	14.06	14.54	14.54
Insulation Class		1	1		Class A (UL),	Class B (CE)			1	
Insulation Resistance					> 100 MΩ	, 500VDC				
Insulation Strength					2.3 kVA	C, 1 sec				
Weight [kg]	1.4	1.9	2.8	3.6	4.3	4.7	7.5	8.9	7.8	9.2
Max. Radial Loading [N]	245	245	392	392	490	490	490	490	490	490
Max. Axial Loading [N]	74	74	147	147	98	98	98	98	98	98
Brake Holding Torque [N∙m (min)]Note 2		1.3		2.5		8		10		10
Brake Power Consumption (at 20°C) [W]	n/a	7.2	n/a	8	n/a	18.7	n/a	19	n/a	19
Brake Release Time [ms (max)]	11/a	20	11/a	20	11/a	10	11/a	10	11/a	10
Brake Pull-in Time [ms (max)]		50		60		70		70		70
Vibration Grade [µm]					V	15				
Operating Temperature [°C]					0–40 °C (3					
Storage Temperature [°C]					-10°C to 80°C (/			
Operating Humidity					% relative humi					
Storage Humidity				20–90	% relative humi		ensing)			
Vibration Capacity		2.5 G								
IP Rating		67 (when using waterproof connectors and when an oil eal is fitted to the rotating shaft (for an oil seal model)) IP65 (when using waterproof connectors and when an oil seal is fitted to the rotating shaft (for an oil seal model))								
Encoder Resolution					24-bit (1677					
Agency Approvals					CURU	_{IS} , CE				

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability). Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.



460V Medium Inertia Motor Specifications

Madal	01/01/ 4100	01/01/ 4100			
Model	<u>SV2M-410N</u>	<u>SV2M-410B</u>			
Price	\$530.00	\$765.00			
Drawing	PDF	PDF			
Rated Power [kW]	1.0	1.0			
Rated Torque [N·m]Note 1	4.77	4.77			
Max. Torque [N·m]	14.32	14.32			
Rated Speed [rpm]	2000	-			
Max. Speed [rpm]	3000				
Rated current [Amps] rms	3.6	3.6			
Max. Instantaneous Current [Amps] rms	11.41	11.41			
Change of Rated Power [W/s]	27.1	24.90			
Rotor Inertia [x10-4 kg m2]	8.41	9.14			
Mechanical Time Constant [ms]	1.85	2.01			
Torque Constant-KT [N-m/A]	1.325	1.325			
Voltage Constant-KE [mV/rpm]	53.20	53.20			
Armature Resistance [Ohm]	1.477	1.477			
Armature Inductance [mH]	17.79	17.79			
Electrical Time Constant [ms]	12.04	12.04			
Insulation Class	Class A (UL), C	Class B (CE)			
Insulation Resistance	> 100 MΩ,	500VDC			
Insulation Strength	2.3 kVAC,	1 sec			
Weight [kg]	7.0	8.4			
Max. Radial Loading [N]	490				
Max. Axial Loading [N]	98				
Brake Holding Torque [N·m (min)]Note 2		10			
Brake Power Consumption (at 20°C) [W]	n/a	19			
Brake Release Time [ms (max)]		10			
Brake Pull-in Time [ms (max)]		70			
Vibration Grade [µm]	V15	j			
Operating Temperature [°C]	0–40 °C (32	–104 °F)			
Storage Temperature [°C]	-10°C to 80°C (-1	4°F to 176°F)			
Operating Humidity	20–90% relative humidi	ty (non-condensing)			
Storage Humidity	<i>idity</i> 20–90% relative humidity (non-condensing)				
Vibration Capacity	2.5 G				
IP Rating	IP65 (when using waterproof connectors and when an oil seal is fitted to th rotating shaft (for an oil seal model))				
Encoder Resolution	24-bit (16777)	216 p/rev)			
Agency Approvals cUR _{US} , CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use for deceleration or as a dynamic brake.



460V High Inertia Motor Specifications

460V	SureServo	2 High Iner	tia Motor S	pecification	S			
Model	<u>SV2H-430N</u>	<u>SV2H-430B</u>	<u>SV2H-445N</u>	<u>SV2H-445B</u>	<u>SV2H-455N</u>	<u>SV2H-455B</u>		
Price	\$823.00	\$1,001.00	\$939.00	\$1,456.00	\$1,082.00	\$1,614.00		
Drawing	PDF	PDF	PDF	PDF	PDF	PDF		
Rated Power [kW]	3.0	3.0	4.5	4.5	5.5	5.5		
Rated Torque [N·m]Note 1	19.1	19.1	28.65	28.65	35	35		
Max. Torque [N·m]	49.38	49.38	64.61	64.61	73.48	73.48		
Rated Speed [rpm]			15	00				
Max. Speed [rpm]			30	00				
Rated current [Amps] rms	12.2	12.2	21.9	21.9	23.6	23.6		
Max. Instantaneous Current [Amps] rms	30.46	30.46	47.5	47.5	47.5	47.5		
Change of Rated Power [W/s]	66.4	63.9	105.6	101.8	122.8	119.3		
Rotor Inertia [x10-4 kg m2]	54.95	57.1	77.75	80.65	99.78	80.65		
Mechanical Time Constant [ms]	1.20	1.24	1.06	1.10	0.84	0.86		
Torque Constant-KT [N·m/A]	1.566	1.566	1.308	1.308	1.483	1.483		
Voltage Constant-KE [mV/rpm]	64.4	64.4	53.00	53.00	58.9	58.9		
Armature Resistance [Ohm]	0.21	0.21	0.09	0.09	0.07	0.07		
Armature Inductance [mH]	4.94	4.94	2.36	2.36	2.20	2.20		
Electrical Time Constant [ms]	23.52	23.52	26.22	26.22	31.43	31.43		
Insulation Class			Class A (UL),	Class B (CE)				
Insulation Resistance			> 100 MΩ	, 500VDC				
Insulation Strength			2.3 kVA	C, 1 sec				
Weight [kg]	18.5	22.5	23.5	29	30.5	36		
Max. Radial Loading [N]		14	70		17	64		
Max. Axial Loading [N]		4	90		58	38		
Brake Holding Torque [N·m (min)]Note 2		25		55		55		
Brake Power Consumption (at 20°C) [W]		20.4		19.9		19.9		
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10		
Brake Pull-in Time [ms (max)]		70		70		70		
Vibration Grade [µm]			V	15				
Operating Temperature [°C]			0–40 °C (3	32–104 °F)				
Storage Temperature [°C]	-10°C to 80°C (-14°F to 176°F)							
Operating Humidity	20–90% relative humidity (non-condensing)							
Storage Humidity		20	0–90% relative hum	dity (non-condensin	g)			
Vibration Capacity			2.5	5 G				
IP Rating	IP65 (when using	g waterproof connec	ctors and when an o	il seal is fitted to the	rotating shaft (for a	n oil seal model))		
Encoder Resolution			24-bit (1677	7216 p/rev)				
Agency Approvals			_c UR _L	_{IS} , CE				
		Continued on ne						

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

550mm x 550mm x 30mm

All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

Note 2-The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.



460V High Inertia Motor Specifications, continued

460V S	ureServo2	High Inerti	a Motor Sp	ecifications	3				
Model	<u>SV2H-475N</u>	<u>SV2H-475B</u>	SV2H-4BON	<u>SV2H-4B0B</u>	SV2H-4F0N	SV2H-4F0B			
Price	\$1,311.00	\$2,047.00	\$2,014.00	\$2,760.00	\$2,324.00	\$3,182.00			
Drawing	PDF	PDF	PDF	PDF	PDF	PDF			
Rated Power [kW]	7.5	7.5	11	11	15	15			
Rated Torque [N·m]Note 1	47.74	47.74	70	70	95.4	95.4			
Max. Torque [N·m]	93.71	93.71	175	175	224.0	224.0			
Rated Speed [rpm]	15	00		15	00				
Max. Speed [rpm]	30	00		20	00				
Rated current [Amps] rms	28.7	28.7	26.8	26.8	37.5	37.5			
Max. Instantaneous Current [Amps] rms	57.69	57.69	67.7	67.7	95.3	95.3			
Change of Rated Power [W/s]	159.7	156.6	145.0	145.0 141.4 201.8 19					
Rotor Inertia [x10-4 kg m2]	142.7	145.5	338	38 346.5 451					
Mechanical Time Constant [ms]	0.81	0.83	3 1.40 1.44 1.21 1						
Torque Constant-KT [N·m/A]	1.663	1.663	3 2.612 2.612 2.544 2.5						
Voltage Constant-KE [mV/rpm]	66.40	66.40	96.00	96.00	83.90	83.90			
Armature Resistance [Ohm]	0.06	0.06	0.0994	0.0994	0.0545	0.0545			
Armature Inductance [mH]	1.70	1.70	2.51	2.51	1.43	1.43			
Electrical Time Constant [ms]	28.33	28.33	25.25	25.25	26.24	26.24			
Insulation Class	Class A (UL),	Class B (CE)		Class F (UL),	Class F (CE)				
Insulation Resistance			> 100 MΩ	, 500VDC					
Insulation Strength			2.3 kVA	C, 1 sec					
Weight [kg]	40.5	46	56.4	68.4	75	87			
Max. Radial Loading [N]	17	-		33	00				
Max. Axial Loading [N]	58	38		11	00				
Brake Holding Torque [N·m (min)]Note 2		55		115		115			
Brake Power Consumption (at 20°C) [W]		19.9		28.8		28.8			
Brake Release Time [ms (max)]	n/a	10	n/a	10	n/a	10			
Brake Pull-in Time [ms (max)]		70		70		70			
Vibration Grade [µm]			V	15					
Operating Temperature [°C]			0–40 °C (3	82–104 °F)					
Storage Temperature [°C]	-10°C to 80°C (-14°F to 176°F)								
Operating Humidity		20)–90% relative humi	dity (non-condensir	g)				
Storage Humidity		20)–90% relative humi	dity (non-condensir	g)				
Vibration Capacity	2.5 G								
IP Rating	IP65 (when using waterproof connectors and when an oil seal is fitted to the rotating shaft (for an oil seal model))								
Encoder Resolution			24-bit (1677	7216 p/rev)					
Agency Approvals			cURU	_S , CE					

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions:

300mm x 300mm x 12mm

400mm x 400mm x 20mm

550mm x 550mm x 30mm

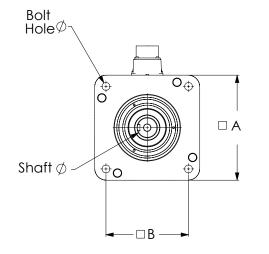
All made from aluminum (or mounted to equipment with an equivalent heat sinking capability)

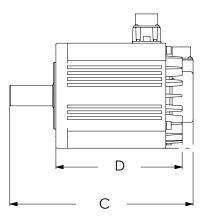
Note 2–The built-in servo motor brake is only for holding the load in a stopped state. Do not use it for deceleration or as a dynamic brake.



AC Servo System Dimensions

230V Servo motor dimensions





	SureServo2 230V Motor Dimensions											
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]					
<u>SV2L-201N</u>	PDF	40.0 [1.57]	32.2 [1.27]	110.3 [4.34]	85.3 [3.36]	4.5 [0.18]	8.0 [0.31]					
<u>SV2L-201B</u>	PDF	40.0 [1.57]	32.2 [1.27]	145.1 [5.71]	120.1 [4.73]	4.5 [0.18]	8.0 [0.31]					
<u>SV2L-202N</u>	PDF	60.0 [2.36]	49.5 [1.95]	113.9 [4.49]	84.0 [3.31]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-202B</u>	PDF	60.0 [2.36]	49.5 [1.95]	147.6 [5.81]	117.1 [4.61]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-204N</u>	PDF	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-204B</u>	PDF	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]					
<u>SV2L-207N</u>	PDF	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [2.51]	19.0 [0.75]					
<u>SV2L-207B</u>	PDF	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [2.51]	19.0 [0.75]					
<u>SV2L-210N</u>	PDF	100.0 [3.94]	81.3 [3.20]	198.3 [7.81]	110.2 [4.34]	9.0 [0.35]	22.0 [0.87]					
<u>SV2L-210B</u>	PDF	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	149.5 [5.89]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-210N</u>	PDF	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	104.5 [4.11]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-210B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	140.5 [5.53]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-215N</u>	PDF	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	120.5 [4.74]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-215B</u>	<u>PDF</u>	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	155.0 [6.10]	9.0 [0.35]	22.0 [0.87]					
<u>SV2M-220N</u>	PDF	180.0 [7.09]	141.4 [5.57]	247.7 [9.75]	150.0 [5.91]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-220B</u>	<u>PDF</u>	180.0 [7.09]	141.4 [5.57]	281.8 [11.09]	184.1 [7.25]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-230N</u>	PDF	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	183.1 [7.21]	13.5 [0.53]	35.0 [1.38]					
<u>SV2M-230B</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-245N</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	216.3 [8.52]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-245B</u>	PDF	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	260.3 [10.25]	13.5 [0.53]	35.0 [1.38]					
<u>SV2H-255N</u>	PDF	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	260.7 [10.26]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-255B</u>	PDF	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	292.7 [11.52]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-275N</u>	PDF	180.0 [7.09]	141.4 [5.57]	454.70 [17.9]	323.0 [12.72]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-275B</u>	PDF	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	357.1 [14.06]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-2BON</u>	PDF	219.9 [8.66]	166.2 [6.54]	487.4 [19.19]	319.0 [12.56]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-2B0B</u>	PDF	219.9 [8.66]	166.2 [6.54]	550.4 [21.67]	382.0 [15.04]	13.5 [0.53]	42.0 [1.63]					
<u>SV2H-2FON</u>	PDF	219.9 [8.66]	166.2 [6.54]	566.4 [22.30]	398.0 [15.67]	13.5 [0.53]	55.0 [2.17]					
<u>SV2H-2F0B</u>	PDF	219.9 [8.66]	166.2 [6.54]	629.4 [24.78]	461.0 [18.15]	13.5 [0.53]	55.0 [2.17]					

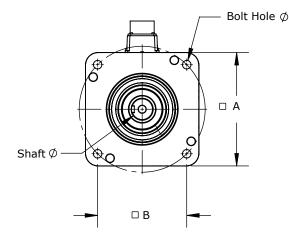
NOTE: Motor cables are approximately 304mm (12") in length.

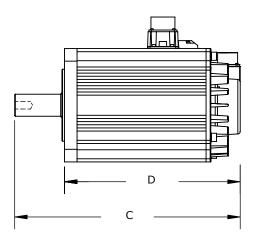
For additional dimensions, see the AutomationDirect website or click on the drawing links.



AC Servo System Dimensions

460V Servo motor dimensions





		SureServo	2 460V Mo	tor Dimens	ions		
Model	Drawing Link	A mm [inches]	B mm [inches]	C mm [inches]	D mm [inches]	Bolt Hole Ø mm [inches]	Shaft Ø mm [inches]
<u>SV2L-404N</u>	PDF	60.0 [2.36]	49.5 [1.95]	136.0 [5.35]	106.0 [4.17]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-404B</u>	PDF	60.0 [2.36]	49.5 [1.95]	169.7 [6.68]	139.7 [5.50]	5.5 [0.22]	14.0 [0.55]
<u>SV2L-407N</u>	PDF	80.0 [3.15]	63.6 [2.51]	155.8 [6.13]	115.8 [4.56]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-407B</u>	PDF	80.0 [3.15]	63.6 [2.51]	193.2 [7.61]	153.2 [6.03]	6.6 [0.26]	19.0 [0.75]
<u>SV2L-410N</u>	PDF	100.0 [3.94]	81.3 [3.20]	198.2 [7.81]	153.2 [6.03]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-410B</u>	PDF	100.0 [3.94]	81.3 [3.20]	237.5 [9.35]	192.5 [7.58]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415N</u>	PDF	130.0 [5.12]	102.5 [4.04]	222.5 [8.76]	167.5 [6.59]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-415B</u>	PDF	130.0 [5.12]	102.5 [4.04]	257.0 [10.12]	202.0 [7.95]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-420N</u>	PDF	130.0 [5.12]	102.5 [4.04]	242.5 [9.55]	187.5 [7.38]	9.0 [0.35]	22.0 [0.87]
<u>SV2L-420B</u>	PDF	130.0 [5.12]	102.5 [4.04]	271.0 [10.67]	216.0 [8.50]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410N</u>	PDF	130.0 [5.12]	102.5 [4.04]	202.5 [7.97]	147.5 [5.81]	9.0 [0.35]	22.0 [0.87]
<u>SV2M-410B</u>	PDF	130.0 [5.12]	102.5 [4.04]	238.5 [9.39]	183.5 [7.22]	9.0 [0.35]	22.0 [0.87]
<u>SV2H-430N</u>	PDF	180.0 [7.09]	141.4 [5.57]	280.8 [11.06]	201.8 [7.94]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-430B</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445N</u>	PDF	180.0 [7.09]	141.4 [5.57]	314.0 [12.36]	235.0 [9.25]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-445B</u>	PDF	180.0 [7.09]	141.4 [5.57]	358.0 [14.09]	279.0 [10.98]	13.5 [0.53]	35.0 [1.38]
<u>SV2H-455N</u>	PDF	180.0 [7.09]	141.4 [5.57]	392.4 [15.45]	279.4 [11.00]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-455B</u>	PDF	180.0 [7.09]	141.4 [5.57]	424.4 [16.71]	311.4 [12.26]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475N</u>	PDF	180.0 [7.09]	141.4 [5.57]	454.7 [17.90]	341.7 [13.45]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-475B</u>	PDF	180.0 [7.09]	141.4 [5.57]	488.8 [19.24]	375.8 [14.80]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-4BON</u>	PDF	220.0 [8.66]	166.2 [6.54]	487.4 [19.19]	371.4 [14.62]	13.5 [0.53]	42.0 [1.65]
<u>SV2H-4B0B</u>	PDF	220.0 [8.66]	166.2 [6.54]	550.4 [21.67]	434.4 [17.10]	13.5 [0.53]	42.0 [1.65]
SV2H-4F0N	PDF	220.0 [8.66]	166.2 [6.54]	566.4 [22.30]	450.4 [17.73]	13.5 [0.53]	55.0 [2.17]
SV2H-4F0B	PDF	220.0 [8.66]	166.2 [6.54]	629.4 [24.78]	513.4 [20.21]	13.5 [0.53]	55.0 [2.17]



NOTE: Motor cables are approximately 304mm (12") in length.

or

For additional dimensions, see the AutomationDirect website or click on the drawing links.