

Drive features

- Power: 100W-7.5 kW three-phase 230VAC/460VAC 100W-2.2 kW single-phase 230VAC capable
- Fully digital control with up to 1kHz velocity loop response
- Easy setup and diagnostics with DriveCM PC-based software
- Field upgradeable firmware ensures the drive can always be upgraded to the latest operating system
- Command options include:
 - ± 10V torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector)
- Internal Indexer for position/speed-based moves include the option for simple registration correction. 64 individual move statements can be configured in the drive. Each Index contains its own distance, speed, accel, decel, and dwell parameters. These indexes can be set up through DriveCM software or modified in real-time with serial communication (PLC, HMI, etc.). The indexes can be initiated via Digital Inputs or through serial comms.
- The 1 kHz bandwidth allows for high-level automatic tuning. Several modes of tuning are available including Off-Line Auto Tuning (the drive initiates its own move commands while Auto tuning), On-Line Auto Tuning (an external controller sends the move commands while the drive Auto tunes), and Manual Tuning (all tuning values are adjusted by the user).
- (16) Optically isolated digital inputs and (8) general purpose (user configurable) outputs, analog inputs for speed and torque control (2), and line driver and open collector output for encoder (with scalable resolution). Two configurable analog outputs for monitoring various servo parameters (actual speed, torque, current, position, etc.)
- Advanced Scope feature that can monitor a variety of command and status signals, including output speed, torque, power, etc.







Motor features

- Low and Medium inertia motors available:
- Low: 100W, 200W, 400W, 750W, 900W, 1kW, and 1.5 kW; @5000rpm
- Medium: 1.6 kW, 2.2 kW, 3.5 kW, 5.5 kW, and 7.5 kW; @3000rpm
- · Permanent magnet 3-phase synchronous motor
- Keyed drive shafts support clamp-on style couplings or key-style
- Integrated multi-turn absolute encoder with 19-bit resolution (524,288 pulses per revolution)
- Optional 24 VDC spring-set holding brakes (AMK2 and DMK2 motors)
- Standard hook-up cables for motor power, encoder, and brake (separate brake cable for FBL/FCL brake motors)
- Motor cables available in standard or flex-rated lengths of 3, 5, 10, and
- Standard 50-pin DIN-rail mounted break-out kit for the drive's CN1 connector (with screw terminal connections), or 50-pin cables with flying leads

Note: These parts available for sale to North American locations only.

Tuning Technology

The L7P drive closes the loop on current, velocity, and position (depending on control mode selection). The 1kHz bandwidth in the drive assures precise speed and current control and easy tuning. Proportional gain, integral gain and compensation, feed forward compensation, command low pass filter, and four (4) notch filters for resonance suppression are available. Auto Tuning has been greatly improved and can tune motors up to 20:1 inertia mismatch.

There is an inertia estimation function that analyzes the motor and load to measure how much inertia is coupled to the motor.

The drive has several tuning methods available:

- Online Auto Tuning-the drive can either tune the load live while an external controller moves the load to different positions or using the drive's internal tuning motion profile.
- Offline Auto Tuning-the drive tunes the load using the drive's internal tuning motion profile.
- Manual Tuning–all parameters are available to give power users the ultimate flexibility to tune their systems.

Built-in Indexer

While the L7P drives can accept traditional commands from host controllers, they can also provide their own internal motion control. 64 point-to-point position moves can be configured in the drive. These moves can be populated through the DriveCM configuration software or they can be written to by a PLC through the drive's RS422/485 serial port. The moves can be initiated by digital inputs or by serial commands and include the ability to handle simple registration, and can be sequenced internally with delays in between the moves or moves can be linked together so they are processed one after the other.

Multi-axis systems can be controlled via digital inputs, or serial communication. The motion can be commanded from a powerful external controller that sends out high speed pulses to each drive, or the motion can be initiated by a low-level controller (the simplest CLICK PLC) since each drive has a powerful indexer inside. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

Optional Holding Brake

Each L7P motor can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

LS Electric MSS Series In-**Line Planetary Precision** Gearboxes for Servo Motors

Need more torque from the motor? Have an inertia balancing issue in your design? The LS Electric MSS series gearboxes easily mate to FBL/FCL/FE/FF motors. Everything you need for mounting is included!

- Three gear ratios available (5:1, 10:1, 20:1*)
- Mounting hardware included for attaching to FBL/FCL/FE/FF motors.
- · Industry-standard mounting dimensions
- Thread-in mounting style
- Very low backlash: 7 arc-min single stage (5:1 and 10:1 ratios), 9 arc-min two-stage (20:1
- 1-year warranty
- * The available gearbox ratios for the 7.5 kW motors are 5:1, 10:1, and 15:1, but the featuers are otherwise equivalent.





L7P Series AC Servo Systems

Servo drive overview

LED Display

The 5-digit display is used to indicate servo status and alarm.

DC Bus Charge LED

Visual indication of the drive's DC bus voltage level. Do not work on the drive until the Charge LED is

DIPswitch #2

 120Ω terminating resistor for the RS422/RS485 network (use at the end of a multi-drop network

Connector

4-pin analog monitoring connector (two +/- 10V analog outputs). See L7P-CON-F and L7P-CON-G for optional connectors

Rotary DIPswitch (0-15)

Sets RS422/485 comms station ID. Switch #3 adds 16 to the Node ID (so total addressable Node IDs = 0-31)

USB Connector

Used by Drive CM software for servo configuration. Connect with a standard USB A to USB mini-B cable (SV2-PGM-USB15, MOSAIC-CSU, or

Firmware Upgrade: Use DriveCM software or attach a USB thumb drive with the new FW and update using USB On the Go (no PC required). See the UM for details.

RJ45 Connectors

Serial Modbus RS422 (compatible with RS485 PLCs). Use standard ethernet cables (not crossover cables) to connect multiple drives in a serial network.

CN1 I/O Signal Connector

50-pin CN1 connector for drive I/O. Signals include high speed pulse inputs, 16 digital inputs, 8 digital outputs, 2 analog inputs (voltage and torque), and scalable encoder output.

Encoder Connector

14-pin CN2 connector for the motor encoder. LS Encoder cables available in 3, 5, 10, and 20 meter lengths in standard and flexing cables.

Motor Power Terminal

Incoming single or three phase 200-230 VAC or three phase 380-480 VAC, model dependent. (-15% to+10%, 50/60Hz)

Regenerative Resistor **Terminal**

Connection for optional external braking resistor

Control Power Terminal

Incoming single phase 200-230 VAC (or 380-480 VAC for "PB" models)(-15% to +10%, 50/60Hz)

Motor Output Terminal

Output power to the servo motor. LS motor power cables available in 3, 5, 10, and 20 meter lengths in standard and flexing cables.

Model Number

Clearly displayed on bottom of drive face for easy identification.

The LS Electric L7P servo drives are fully digital and include over 300 parameters to configure the drive for almost any application. For convenience, the parameters are grouped into several categories including:

- · Basic parameters
- · Gain parameters
- · I/O parameters
- · Velocity parameters
- Misc. parameters
- · Monitor parameters
- · Index parameters

All parameters have commonly used default values which allow you to operate the L7P drive "out-of-the-box". The drive auto-detects the

LS servo motor (through the serial encoder) and sets up the default gains and limits based on the connected motor.

The drive can still be easily configured to your specific application, however. The Drive CM configuration software has a built-in Setup Wizard that will guide you through all the basic setup parameters. So, whether you want to use high speed pulse input, analog velocity, analog torque, or the powerful internal indexer for a control mode (or any multi-mode combination of these modes), the Setup Wizard will quickly and easily get your application started - from setting up the I/O to determining the appropriate homing sequence.

After configuration is complete, the Auto Tune features of the drive will get your application tuned for optimal responsiveness and performance.





LSELECTRIC L7P/iX7NH AC Servo Systems

Servo motor overview

Encoder Connector

9-pin watertight connector for the 19-bit serial encoder. The encoder transmits motor/encoder identification information to the drive at power-up and it sends position feedback during operation.

FBL/FCL **Series** Motor

Motor Power Connector

4-pin watertight connector for motor power (U, V, W, and ground) r Flus

Brake Power Connector

motor is set in motion.

IP67 Housing

2-pin watertight connector available on FBL/FCL brake motors only. The 24VDC brake is located between the motor coils and the encoder. Motors ending in AMK2 and DMK2 have brakes. The brakes must have 24VDC applied to them before the

Low Inertia Motors

Low inertia designs (AMK series) result in high responsiveness at high speeds for lighter loads.

- 100-100W motors available
- 60 and 80 mm flanges

Keyed Shafts

FBL and FCL motors are supplied with extra-large keyways, and slightly oversized keys which may need to be "fitted" into the keyway for performance and longevity. Clamp or compression couplings (without key) are recommended.

• 100W 14mm diameter shaft

• 200W 14mm diameter shaft

• 400W 14mm diameter shaft

• 750W 19mm diameter shaft

• 1000W 19mm diameter shaft

All LS Electric FBL/FCL/FE/FF motors have keyed shafts for use with servo-grade clamp or compression couplings (recommended) or servo-grade keyed couplings. Some sanding/filing of the key may be required before pressing into the keyway. Do not modify the shaft/keyway.

Encoder Connector

17-pin watertight connector for the 19-bit serial encoder. The encoder transmits motor/encoder identification information to the drive at power-up and it sends position feedback during operation.

FE/FF **Series** Motor

Motor Power Connector

4-pin watertight connector for motor power (U, V, W, and ground). For brake models, also supports brake wiring.



Low and Medium Inertia Motors

Low inertia designs (AMK series) result in high responsiveness at high speeds for lighter loads.

• 1500W motors with 130mm flanges available

Medium inertia designs (DMK series) result in high responsiveness at moderate speeds for heavier

• 1600-7500W motors available

130 and 180 mm flanges

Keyed Shafts

FE and FF motors are supplied with extra-large keyways, and slightly oversized keys which may need to be "fitted" into the keyway for performance and longevity. Clamp or compression couplings (without key) are recommended.

• 900W 19mm diameter shaft

• 1500W 19mm diameter shaft

• 1600W 22mm diameter shaft

• 2200W 24mm diameter shaft

• 3500W 35mm diameter shaft

• 5500W 35mm diameter shaft

• 7500W 42mm diameter shaft



SELECTRIC LS Electric AC Servo Systems

Drive Software

Drive CM Configuration Software

Drive CM is an optional free downloadable configuration software package for LS Electric servo drives. A PC may be directly connected to the servo drive via any standard USB-A to USB mini-B cable (SV2-PGM-USB15 or SV2-PGM-USB30 recommended).

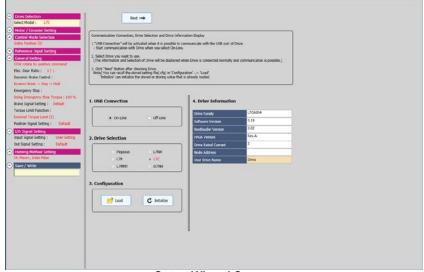
Features

- Easy-to-use setup wizard guides you through the most common setup functions.
- Digital I/O / Jog Control allows the user to operate the servo system from the PC. This allows the servo to perform some basic motion and check the I/O during startup.
- Parameter Object editor for setting up all drive parameters.
- Tune and check the servo response in real-time using the scope feature.
- Upload and download the drive configuration. Save the drive configuration as a file for backup or future use.
- Edit the drive configuration.
- · View all drive faults.
- View drive variable trends in real-time.
- (L7P/L7C series only) Set up 64 internal Indexes (point-to-point moves) that can be triggered by digital inputs or serial communications. Indexes can repeat and can initiate another Index when one move completes.

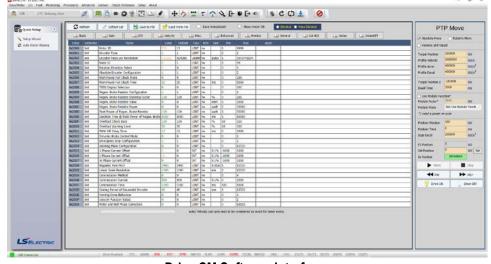
Download

Download the Drive CM software from Automation Direct's LS Electric support page:

https://support.automationdirect.com/products/lselectric.html



Setup Wizard Screen



Drive CM Software Interface

Parameter Object Editor

The Drive CM configuration tool logically organizes all servo drive object parameters for viewing and editing using the Object Dictionary screen. Each parameter has a factory default that usually allows the servo to run "out-ofthe-box".

The parameters can be easily changed with available setting ranges displayed. Tuning modes and parameters can also be changed using Drive CM. After the parameters have been defined, the complete setup can be stored and archived. Drive configurations can be uploaded, edited, saved, and downloaded as often as necessary.

Using the Drive CM software you can also configure and commission your drive without having to be connected to the master controller.



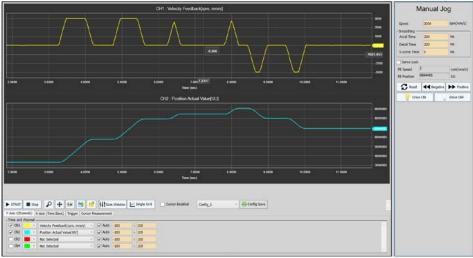
LS ELECTRIC LS Electric AC Servo Systems

Drive Software, continued

Digital I/O, Jog Control, and Scope

The Digital I/O / Jog Control screen allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.

Drive CM also includes a powerful scope function that allows the user to have as many as four channels of data displayed simultaneously. Each channel has a drop-down table to select the data to be displayed. The scope has the ability to save traces to a file and load those traces for offline review/analysis. This function is a valuable tool for tuning LS Electric servo drives.



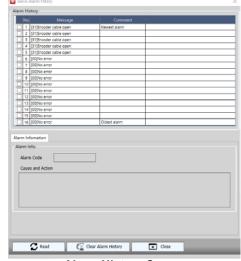
Jog Control / Scope Screen



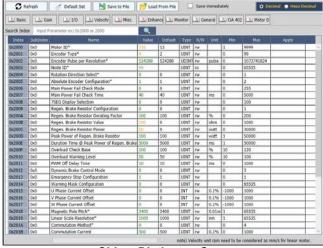
General Setup Screen



Indexer Setting Screen (L7P/L7C series only)



Alarm History Screen

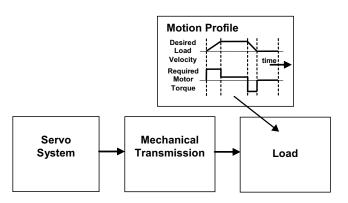


Object Dictionary Screen



How to select and apply L7P systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque servo system that most closely matches these parameters for the system being replaced. In a new application, these parameters should be determined through calculation and/or



measurement. The Drive CM software has the ability to measure the load (reflected) inertia and accurately measure the motor torque output.

AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from https://support.automationdirect.com/products/lselectric.html.

1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system.

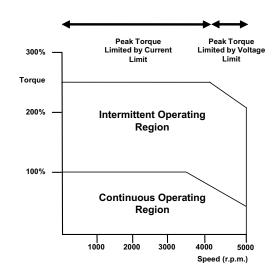
In general, applications that need high response or bandwidth

will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. L7P Auto Tuning will still tune a system with very high response, up to 20:1 inertia mismatch. Higher system ratios can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. The L7P servo systems may be tuned automatically by the software/drive or manually by the user.

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torque-speed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed or torque). If you have an L7P system, these values are easily captured and recorded with the Scope feature built into the Drive CM software. If you are designing the system from scratch, use VisualSizer to define the system and calculate expected inertia and required power.

Compare the application's Continuous and Intermittent torque requirements to the torque-speed curves found in Chapter 16 of the L7P User Manual or in the system torque charts found on "L7P AC servo drive, motor, and cable combinations" on page tMNC-228.





LTP Series AC Servo Systems

Application tip coupling considerations

The LS Electric FBL/FCL motors have keyed shafts that can be used with keyed couplings or with clamp-on or compression style couplings. For standard keyed couplings, the servo key must be "fitted" into the keyway for optimum performance and longevity. Some minor filing and pressing of the key may be required. "Servo-grade" clamp-on or compression style couplings

are usually the best choice when you consider stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a trade-off between stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the servo's **peak** torque requirement of your application.

Click here for <u>Available Couplings</u>

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common ways to translate the rotary motion of the servo motor into linear motion of the load. Matched gearboxes are available from LS Electric that will work with the LS servo motors. Each gearbox is selected to accept the 300% maximum available torque that could be generated by the motor. Gearboxes are available in 5.1, 10:1, and 20:1 ratios. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

1. Reduction of reflected load inertia

As a general rule, keep the reflected load inertia as low as possible while using the full range of servo speed. The LS Electric motors can rotate at a rated speed of 2000 or 3000 rpm (rated torque at rated speed). Their max speed (slightly less available torque) is 3000 or 5000 rpm. See the speed-torque curves for more information.

Example: A gearbox reduces the motor's required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

Here is a link to our Timing Belts and **Pulleys**

Ordering guide instructions

The following four pages are your ordering guide for LS Electric L7P servo systems. Each system has a torque-speed curve included for reference. This is the fundamental information that you need to select the servo motor and matching drive for your application.

Each system needs:

- Motor
- Drive
- Motor Power Cable
- Motor Encoder Cable
- I/O connections (either a 50-pin CN1 cable+terminals kit or a 50-pin flying lead cable(user provides terminal blocks))
- FBL/FCL brake motors require a brake cable. FE/ FF brake motors have brake wiring included in the power cable.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

LS Electric servo motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned.

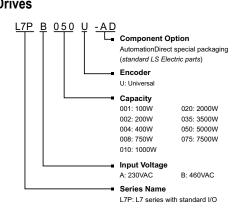


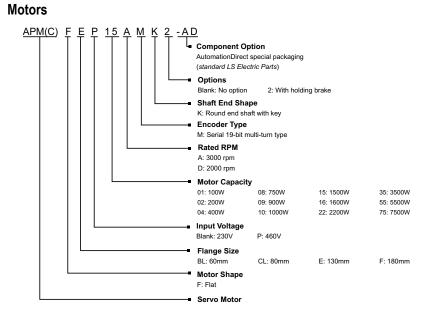
| 22. | | LS Electric M | ISS Planetary In-Lii | ne Gearboxes | |
|------------------|-------------------|---------------|----------------------|-------------------|--|
| Motor | Brake Motor | 5:1 Gearbox | 10:1 Gearbox | 20:1 Gearbox | |
| APMC-FBL01AMK-AD | APMC-FBL01AMK2-AD | | | | |
| APMC-FBL02AMK-AD | APMC-FBL02AMK2-AD | 96200004 | <u>96200005</u> | <u>96200103</u> | |
| APMC-FBL04AMK-AD | APMC-FBL04AMK2-AD | | | | |
| APMC-FCL08AMK-AD | APMC-FCL08AMK2-AD | 0000007 | 0000000 | | |
| APMC-FCL10AMK-AD | APMC-FCL10AMK2-AD | 96200007 | 96200008 | <u>96200257</u> | |
| APM-FEP09AMK-AD | APM-FEP09AMK2-AD | | | | |
| APM-FE15AMK-AD | APM-FE15AMK2-AD | 96200373 | <u>96200378</u> | 96200393 | |
| APM-FEP15AMK-AD | APM-FEP15AMK2-AD | | | | |
| APM-FE16DMK-AD | APM-FE16DMK2-AD | | | 96200479 | |
| APM-FEP16DMK-AD | APM-FEP16DMK2-AD | 96200459 | <u>96200464</u> | | |
| APM-FE22DMK-AD | APM-FE22DMK2-AD | | | | |
| APM-FEP22DMK-AD | APM-FEP22DMK2-AD | 96200010 | <u>96200011</u> | <u>96200445</u> | |
| APM-FF35DMK-AD | APM-FF35DMK2-AD | | | | |
| APM-FFP35DMK-AD | APM-FFP35DMK2-AD | | | | |
| APM-FF55DMK-AD | APM-FF55DMK2-AD | 96200013 | <u>96200014</u> | <u>96200701</u> | |
| APM-FFP55DMK-AD | APM-FFP55DMK2-AD | | | | |
| APM-FF75DMK-AD | APM-FF75DMK2-AD | | | 96200862 | |
| APM-FFP75DMK-AD | APM-FFP75DMK2-AD | 96200016 | <u>96200017</u> | (15:1 gear ratio) | |



LTP Series AC Servo Systems

L7P series drives and motors part numbering system





Example of what you will need to build a complete servo system:





NOTE: Unit can be programmed via keypad. Optional programming software (free download). Use a standard USB-A to USB miniB cable for connectivity (SV2-PGM-USB15, MOSAIC-CSU, or equivalent)



NOTE: If you need a gear box for your configuration, reference the gearbox chart on the previous page. Ratios of 5:1, 10:1, and 20:1 are available for each motor.



Torque to L7P System Quick Reference

| Input Voltage | System Rated Torque (N·m) | System Maximum Torque (N·m) | Suggested Servo Motor | Required Servo Drive | |
|------------------|---------------------------------|-----------------------------------|--------------------------|-------------------------|--|
| | 0.32 | 0.96 | APMC-FBL01AMK-AD | | |
| | 0.32 | 0.96 | APMC-FBL01AMK2-AD | | |
| | 0.04 | 4.04 | APMC-FBL02AMK-AD | 1.7DA00411.AD | |
| | 0.64 | 1.91 | APMC-FBL02AMK2-AD | <u>L7PA004U-AD</u> | |
| | 1.27 | 3.82 | APMC-FBL04AMK-AD | | |
| | 1.27 | 3.02 | APMC-FBL04AMK2-AD | | |
| | 2.20 | 7.16 | APMC-FCL08AMK-AD | | |
| | 2.39 | 7.16 | APMC-FCL08AMK2-AD | 1.7DA04011.AD* | |
| | 2.40 | 0.55 | APMC-FCL10AMK-AD | <u>L7PA010U-AD</u> * | |
| | 3.10 | 9.55 | APMC-FCL10AMK2-AD | | |
| 2001/4.0 | 4 77 | 44.00 | APM-FE15AMK-AD | | |
| 230VAC | 4.77 | 14.32 | APM-FE15AMK2-AD | | |
| | 7.00 | 00.00 | APM-FE16DMK-AD | 1.7D400011.4D | |
| | 7.63 | 22.92 | APM-FE16DMK2-AD | L7PA020U-AD | |
| | | | APM-FE22DMK-AD | 1 | |
| | 10.5 | 31.51 | APM-FE22DMK2-AD | | |
| | 16.7 | 50.4 | APM-FF35DMK-AD | . = 5.00 = 11.45 | |
| | | 50.1 | APM-FF35DMK2-AD | L7PA035U-AD | |
| | | 26.25 78.76 | APM-FF55DMK-AD | | |
| | 26.25 | | APM-FF55DMK2-AD | <u>L7PA050U-AD</u> | |
| | 05.04 | | | . = 0.0== 0 | |
| | 35.81 | 89.53 | APM-FF75DMK2-AD | L7PA075U-AD | |
| | | | APM-FEP09AMK-AD | _ | |
| | 2.86 | 8.59 | APM-FEP09AMK2-AD | <u>L7PB010U-AD</u> | |
| | | 44.00 | APM-FEP15AMK-AD | | |
| | 4.77 | 14.32 | APM-FEP15AMK2-AD | | |
| | | | APM-FEP16DMK-AD | | |
| | 7.64 | 22.92 | APM-FEP16DMK2-AD | <u>L7PB020U-AD</u> | |
| | | | APM-FEP22DMK-AD | | |
| 460VAC | 10.5 | 31.51 | APM-FEP22DMK2-AD | | |
| | | | APM-FFP35DMK-AD | | |
| | 16.71 | 50.13 | APM-FFP35DMK2-AD | <u>L7PB035U-AD</u> | |
| | 00 | 0= | APM-FFP55DMK-AD | 1=DD0= | |
| | 26.26 | 65.65 | APM-FFP55DMK2-AD | <u>L7PB050U-AD</u> | |
| | | | APM-FFP75DMK-AD | <u>L7PB075U-AD</u> | |
| | 35.81 | 89.52 | APM-FFP75DMK2-AD | | |

^{* 1}kW motors only: For single-phase supply, derate motor max torque to 200% or upsize the drive to L7PA020U-AD for max motor torque. ** 2.2 kW motors only: For single-phase supply, upsize the drive to L7PA035U-AD for max motor torque.

www.automationdirect.com

Motion Control



L7P AC servo drive, motor, and cable combinations

xx = Cable length in meters BN/EN/PN = Standard cable (not continuous flex) BF/EF/PF = Flex-rated cable

AMK/DMK motors = no brake AMK2/DMK2 motors = mechanical holding brake

230V FBL/FCL Motor Systems

| Туре | System Torque Chart | L7P Drive | APM/APMC Motor | Power Cable | Encoder Cable | Brake Cable | I/O Cable and Breakout | |
|-------------------------|--|--------------------|------------------------|--------------------------------|------------------------------------|------------------|---------------------------|--|
| System | Torque (N.m) 1,00 0,80 0,60 Instantaneous Operation Range 0,40 0,20 Continuous Operating Range 0 1000 2000 3000 4000 5000 | | APMC-FBL01AMK-AD | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | n/a | | |
| ' Low Inertia | | <u>L7PA004U-AD</u> | | APCS-PFxxLS-AD APCS-PNxxLS-AD | APCS-EFxxxES1-AD APCS-ENxxxES1-AD | APCS-BNxxQS-AD | | |
| 100M | Range 0 1000 2000 3000 4000 5000 Speed [RPM] | | APMC-FBL01AMK2-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | APCS-BFxxQS-AD | | |
| tem | Torque (N.m) | | APMC-FBL02AMK-AD | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | n/a | | |
| 200W Low Inertia System | 1.60 1.20 Instantaneous Operation Range | L7PA004U-AD | AFWIC-FBLUZAWIN-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | II/a | | |
| W Low In | 0.40 Continuous Operating Range | <u>L7PA004U-AD</u> | APMC-FBL02AMK2-AD | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | APCS-BNxxQS-AD | | |
| 200 | 0 1000 2000 3000 4000 5000 Speed [RPM] | | AI WO I DESZAWIKZ AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | APCS-BFxxQS-AD | APC-VSCN1Txx-AD | |
| m ₆ | Torque (N.m) | | | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | | or APC-CN10xA-AD | |
| 400W Low Inertia System | 3.20 Instantaneous 2.40 Operation Range | 7000411 40 | APMC-FBL04AMK-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | n/a AD | | |
| W Low In | 1,60 0,80 Continuous Operating Range | L7PA004U-AD | L7PA004U-AD | APMC-FBL04AMK2-AD | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | APCS-BNxxQS-AD | |
| 400 | 0 1000 2000 3000 4000 5000 Speed [RPM] | | AFWIC-I DLU4AWIKZ-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | APCS-BFxxQS-AD | | |
| ma ma | Torque (N.m) | | | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | | | |
| ertia Syst | 6.40 Instantaneous Operation | 7040404 40 | APMC-FCL08AMK-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | n/a | | |
| W Low In | | L7PA010U-AD | APMC-FCL08AMK2-AD | APCS-PNxxLS-AD | APCS-ENxxxES1-AD | APCS-BNxxQS-AD | | |
| 750 | | | ALINIO-I GLUOAIVINZ-AD | APCS-PFxxLS-AD | APCS-EFxxxES1-AD | APCS-BFxxQS-AD | | |

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Motion Control



L7P AC servo drive, motor, and cable combinations, continued

xx = Cable length in meters BN, EN, or PN = Standard cable (not continuous flex) BF, EF, or PF = Flex-rated cable

AMK/DMK motors = no brake AMK2/DMK2 motors = mechanical holding brake

| Туре | System Torque Chart | L7P Drive | APMC Motor | Power Cable | Encoder Cable | Brake Cable | I/O Cable and Breakout | |
|------------|---|-------------|-----------------------------------|------------------|------------------|-----------------|---------------------------|--|
| System | 6,00 Instantaneous Operation Range 4,00 2,00 Continuous Operating Range | | ADMO FOL 10AMIZ AD | APCS-PNxxxLS-AD | APCS-ENxxxES1-AD | 2/2 | | |
| nertia Sys | | | APMC-FCL10AMK-AD APCS-PFxxxLS-AD | APCS-EFxxxES1-AD | n/a | APC-VSCN1Txx-AD | | |
| ≥ | | L7PA010U-AD | ADMC FCI 10AMK2 AD | APCS-PNxxxLS-AD | APCS-ENxxxES1-AD | APCS-BNxxQS-AD | or APC-CN10xA-AD | |
| 1.0k | 0 1000 2000 3000 4000 5000 Speed [RPM] | | APMC-FCL10AMK2-AD | APCS-PFxxxLS-AD | APCS-EFxxxES1-AD | APCS-BFxxQS-AD | | |
| | | | | | | | | |

^{*} Note - For single-phase supply, derate motor max torque to 200%, or upsize the drive to L7PA020U-AD for the torque curves in the graph.

230V FE Motor Systems

| Туре | System Torque Chart | L7P Drive | APM/APMC Motor | Power Cable** | Encoder Cable | I/O Cable and Breakout | |
|------------------------------|---|--------------------------------|-----------------------|---------------------------------|------------------|------------------------|--|
| stem | Torque (N.m) | | APM-FE15AMK-AD | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | | |
| 1.5 kW Low Inertia System | 9.0 Instantaneous Operation Range | L7PA020U-AD*** | APM-FE IDAMK-AD | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | | |
| W Low II | 3.0 Continuous Operating Range | L/PAUZUU-AD | APM-FE15AMK2-AD | APCS-PNxxNB-AD APCS-ENxxxDS1-AD | | | |
| 1.5 k | 0 1000 2000 3000 4000 5000 Speed [RPM] | | AFIVITI E IJANINZ-AD | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | | |
| ш | Torque (N.m) | | | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | | |
| Syste | 25,0 | APM-FE16DMK-AD L7PA020U-AD*** | APM-FE16DMK-AD | APM-FE16DMK-AD | APCS-PNXXHS-AD | APCS-ENXXXDS1-AD | |
| Inertia | 20.0 15.0 Instantaneous Operation Range | | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | APC-VSCN1Txx-AD | | |
| 1.6 kW Medium Inertia System | 5.0 Continuous Operating Range | | APM-FE16DMK2-AD | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | or APC-CN10xA-AD | |
| 1.6 KW | 0 1000 2000 3000 Speed [RPM] | | AFIVI-FE TODIVINZ-AD | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | | |
| rstem | Torque (N.m) | | | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | | |
| 2.2 kW Medium Inertia System | 28.0 21.0 Instantaneous Operation Range 7.0 Continuous Operating Range | 1.7D400011.4D*** | APM-FE22DMK-AD | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | | |
| / Medium | | L7PA020U-AD*** | APM-FE22DMK2-AD | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | | |
| 2.2 KM | 0 1000 2000 3000 Speed [RPM] | | AI IVI-I LZZDIVINZ-AD | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | | |

^{**} Note - Power cables with "B" in the part number are combination power/brake cables, providing power for both the motor and the brake. A brake cable is not required.
*** Note - For single-phase supply, upsize the drive to L7PA035U-AD for the torque curves in the graph.



L7P AC servo drive, motor, and cable combinations, continued

xx = Cable length in meters BN, EN, or PN = Standard cable (not continuous flex) BF, EF, or PF = Flex-rated cable

AMK/DMK motors = no brake AMK2/DMK2 motors = mechanical holding brake

230V FF Motor Systems

| System Torque Chart | L7P Drive | APM/APMC Motor | Power Cable* | Encoder Cable | I/O Cable and Breakout | |
|---|---|--|--|--|--|--|
| Torque (N.m) | | ADM EESEDMY AD | APCS-PNxxIS-AD | APCS-ENxxxDS1-AD | | |
| 40.0 Instantaneous Operation Range | Ι 7ΡΔ Λ 35Ι Ι-ΔΠ | AFW-FF33DWK-AD | APCS-PFxxIS-AD | APCS-EFxxxDS1-AD | | |
| 10.0 Continuous Operating Range | <u>ETT A0000-AD</u> | APM-FE35DMK2-AD | APCS-PNxxPB-AD | APCS-ENxxxDS1-AD | | |
| Speed [RPM] | | AL WITH GODINICE AD | APCS-PFxxPB-AD | APCS-EFxxxDS1-AD | | |
| Torque (N.m) | | ADM EESEDMK AD | APCS-PNxxJS-AD | APCS-ENxxxDS1-AD | | |
| Torque (N.m) 80.0 60.0 Instantaneous Operation Range 40.0 20.0 Continuous Operating Range 0 1000 2000 3000 Speed [RPM] | 1.7DA05011.AD | APCS-PFxxJS-AD | | APCS-EFxxxDS1-AD | APC-VSCN1Txx-AD | |
| 20.0 Continuous Operating Range | L/FA0300-AD | | APCS-PNxxLB-AD | APCS-ENxxxDS1-AD | or APC-CN10xA-AD | |
| 0 1000 2000 3000 Speed [RPM] | | AL WITH GODINICE AND | APCS-PFxxLB-AD | APCS-EFxxxDS1-AD | | |
| Torque (N.m) | | | APCS-PNxxJS2-AD | APCS-ENxxxDS1-AD | | |
| 80.0 Instantaneous Operation Range | Instantaneous Operation Range L7PA075U-AD Continuous Operating Range | APM-FF/5DMK-AD | APCS-PFxxJS2-AD | APCS-EFxxxDS1-AD | | |
| 20.0 Continuous Operating Range | | ΔPM_FE75DMK2_ΔD | APCS-PNxxLB2-AD | APCS-ENxxxDS1-AD | | |
| 0 1000 2000 3000 Speed [RPM] | | ALIVELLI JUNINZ-AU | APCS-PFxxLB2-AD APCS-EFxxxDS1-AD | | | |
| | Torque (N.m) 50.0 40.0 30.0 20.0 10.0 Continuous Operating Range 1000 2000 3000 Speed [RPM] Torque (N.m) 80.0 60.0 Range 1000 2000 3000 Speed [RPM] Torque (N.m) 100.0 Speed [RPM] Torque (N.m) 100.0 Speed [RPM] Continuous Operating Range 1000 2000 3000 Speed [RPM] | Torque (N.m) 50.0 40.0 30.0 20.0 10.0 Continuous Operating Range 1000 2000 3000 Speed [RPM] Torque (N.m) 80.0 60.0 Range 1000 2000 3000 Speed [RPM] L7PA035U-AD L7PA050U-AD Torque (N.m) 100.0 Speed [RPM] Torque (N.m) 100.0 Speed [RPM] L7PA050U-AD L7PA075U-AD L7PA075U-AD L7PA075U-AD | Torque (N.m) 50.0 40.0 10.0 Range 1000 Speed [RPM] APM-FF35DMK-AD APM-FF35DMK2-AD APM-FF35DMK2-AD APM-FF35DMK2-AD APM-FF55DMK-AD APM-FF75DMK-AD APM-FF75DMK-AD APM-FF75DMK-AD APM-FF75DMK-AD APM-FF75DMK-AD APM-FF75DMK-AD | Torque (N.m) APM-FF35DMK-AD APCS-PNxxIS-AD APCS-PNxxIS-AD APCS-PNxxIS-AD APCS-PNxxPB-AD APCS-PNxxPB-AD APCS-PNxxPB-AD APCS-PNxxPB-AD APCS-PNxxJS-AD APCS-PNxxJS-AD | Torque (N.m) APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PFxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-PNxxIS-AD APCS-ENxxxDS1-AD APCS-ENxxxDS1-AD | |

*Note - Power cables with "B" in the part number are combination power/brake cables, providing power for both the motor and the brake. A brake cable is not required.



L7P AC servo drive, motor, and cable combinations, continued

xx = Cable length in meters BN, EN, or PN = Standard cable (not continuous flex) BF, EF, or PF = Flex-rated cable

AMK/DMK motors = no brake AMK2/DMK2 motors = mechanical holding brake

460V FEP Motor Systems

| Туре | System Torque Chart | L7P Drive | APM/APMC Motor | Power Cable* | Encoder Cable | I/O Cable and Breakout |
|------------------------------|--|-----------------------|----------------------------------|----------------|------------------|------------------------|
| tem | Torque (N.m) | | APM-FEP09AMK-AD | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | |
| ertia Sys | 8.0 6.0 Instantaneous Operation Range | L7PB010U-AD | <u> </u> | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | |
| 1kW Low Inertia System | 4.0 2.0 Continuous Operating Range | EN BOTOG-AB | APM-FEP09AMK2-AD | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | |
| 1KV | 0 1000 2000 3000 4000 5000 Speed [RPM] | | ALIVITIEL OSAWINZ-AD | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | |
| <i>u</i> | Torque (N.m) | | | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | |
| ia Syste | 12.0 | | APM-FEP15AMK-AD | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | |
| 1.5 kW Low Inertia System | 8.0 Instantaneous Operation Range 4.0 | <u>L7PB020U-AD</u> | | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | |
| 1.5 kW L | 4.0 Continuous Operating Range 0 1000 2000 3000 4000 5000 | | APM-FEP15AMK2-AD APCS-PFxxNB-AD | | APCS-EFxxxDS1-AD | |
| | Speed [RPM] | | | APCS-PFXXNB-AD | APCS-EFXXXDS1-AD | APC-VSCN1Txx-AD or |
| System | Torque (N.m) | | APM-FEP16DMK-AD | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | APC-CN10xA-AD |
| Inertia S | 18.0 Instantaneous Operation Range | 1.7DD00011.4D | AFINH LE TODIVIN-AD | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | |
| 1.6 KW Medium Inertia System | 6.0 Continuous Operating Range | L7PB020U-AD | ADM FED4CDM/C AD | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | |
| 1.6 KW | 0 1000 2000 3000 Speed [RPM] | | APM-FEP16DMK2-AD | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | |
| lem . | Torque (N.m) | | | APCS-PNxxHS-AD | APCS-ENxxxDS1-AD | |
| ırtia Sysi | 24.0 Instantaneous Operation | stantaneous Operation | | APCS-PFxxHS-AD | APCS-EFxxxDS1-AD | |
| lium Ine | Torque (N.m) 32,0 24,0 16,0 16,0 8,0 Continuous Operating Range 0 1000 2000 3000 Speed [RPM] | L7PB020U-AD | | | | |
| кW Мес | | | APM-FEP22DMK2-AD | APCS-PNxxNB-AD | APCS-ENxxxDS1-AD | |
| 2.2 | | | | APCS-PFxxNB-AD | APCS-EFxxxDS1-AD | |

*Note - Power cables ending in "B-AD" are combination power/brake cables, and provide power for both the motor and the brake. A separate brake cable is not required.



L7P AC servo drive, motor, and cable combinations, continued

xx = Cable length in meters BN, EN, or PN = Standard cable (not continuous flex) BF, EF, or PF = Flex-rated cable

AMK/DMK motors = no brake AMK2/DMK2 motors = mechanical holding brake

460V FFP Motor Systems

| Туре | System Torque Chart | L7P Drive | APM/APMC Motor | Power Cable* | Encoder Cable | I/O Cable and Breakout |
|------------------------------|---|-------------|---------------------------------|-------------------|------------------|--|
| System | Torque (N.m) | | ADM FEDSEDMIC AD | APCS-PNxxIS-AD | APCS-ENxxxDS1-AD | |
| 3.5 kW Medium Inertia System | 40.0 Instantaneous 30.0 Operation Range | LZDD025LLAD | APM-FFP35DMK-AD | APCS-PFxxIS-AD | APCS-EFxxxDS1-AD | |
| 'Medium | 20,0 10,0 Continuous Operating Range | L7PB035U-AD | APM-FFP35DMK2-AD | APCS-PNxxPB-AD | APCS-ENxxxDS1-AD | |
| 3.5 KW | 0 1000 2000 3000 Speed [RPM] | | AFIVI-I I F33DIVINZ-AD | APCS-PFxxPB-AD | APCS-EFxxxDS1-AD | |
| rstem | Torque (N.m) | | | APCS-PFxxJS1-AD** | APCS-ENxxxDS1-AD | |
| 5.5 kW Medium Inertia System | 56.0 Instantaneous Operation Range | L7PB050U-AD | APM-FFP55DMK-AD APCS-PFxxJS1-/ | APCS-PFxxJS1-AD | APCS-EFxxxDS1-AD | APC-VSCN1Txx-AD or APC-CN10xA-AD |
| ' Medium | 28.0 14.0 Continuous Operating Range | | | APCS-PFxxLB1-AD** | APCS-ENxxxDS1-AD | |
| 5.5 KW | 0 1000 2000 3000 Speed [RPM] | | APM-FFP55DMK2-AD | APCS-PFxxLB1-AD | APCS-EFxxxDS1-AD | |
| tem | Torque (N.m) | | | APCS-PFxxJS1-AD** | APCS-ENxxxDS1-AD | |
| nertia Sys | 90.0 72.0 Instantaneous Operation Range | | APM-FFP75DMK-AD | APCS-PFxxJS1-AD | APCS-EFxxxDS1-AD | - |
| 7.5 kW Medium Inertia System | 36.0 18.0 Continuous Operating Range | L7PB075U-AD | | APCS-PFxxLB1-AD** | APCS-ENxxxDS1-AD | |
| 7.5 KW | 0 1000 2000 3000 Speed [RPM] | | APM-FFP75DMK2-AD | APCS-PFxxLB1-AD | APCS-EFxxxDS1-AD | 1 |

*Note - Power cables ending in "B-AD" or "B1-AD" are combination power/brake cables, and provide power for both the motor and the brake. A separate brake cable is not

^{** -} Non-flex power cable not available for some motors, use the flex cable for both flex and non-flex applications.



L7P Servo drive specifications

| | | | L | 7P Serv | o Drive | Specifi | cations | | | | | |
|--|---------------------------------|--|--|-----------------|----------------|------------------------------|------------------------------|------------------------|---------------------------------|----------------|------------------|-----------------|
| | Model | L7PA004U-AD | L7PA010U-AD | L7PA020U-AD | L7PA035U-AD | L7PA050U-AD | L7PA075U-AD | L7PB010U-AD | L7PB020U-AD | L7PB035U-AD | L7PB050U-AD | L7PB075U-AD |
| | Price | \$393.00 | \$493.00 | \$700.00 | \$743.00 | \$1,155.00 | \$1,700.00 | \$545.00 | \$734.00 | \$760.00 | \$1,155.00 | \$1,364.00 |
| | Drawing | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF |
| | Input Power | 1 | Three phase 200–230 VAC (-15 to +10%), 50–60Hz** Three phase 380–480 VAC (-15 to +10%), 50–60Hz** | | | | | | to +10%), 50 | –60Hz | | |
| Ja | Rated Current [Amps] | 3.0 | 6.75 | 13.5 | 16.7 | 32.0 | 39.4 | 3.7 | 8 | 10.1 | 17.6 | 22.8 |
| Power | Peak Current [Amps] | 9.0 | 20.25 | 40.5 | 50.1 | 90.9 | 98.5 | 11.1 | 24 | 30.3 | 47.25 | 67 |
| | Inrush Current | 35A @ 2 | 230VAC | 55A @ : | 230VAC | 66A @ 230VAC | 82A @ 230VAC | 6 | 8A @ 480VA | .C | 114A @ 480VAC | 56A @ 480VAC |
| ę, | Speed Control Range | | | | | М | aximum 1:50 | 00 | | | | |
| Control Performance | Frequency Response | | | | Maximum | 1KHz or abov | re (when usin | g 19-Bit Seria | al Encoder) | | | |
| rfori | Speed Variation Ratio | | ± 0.0 | 1 % or lower (| when load ch | nanges betwe | en 0 and 100 |)%), ± 0.1 % | or lower (tem | perature 25± | :10°C) | |
| ol Pe | Accel/Decel Time | | | Straight or S-c | urve acceler | ation/decelera | ation (0–10,00 | 00 ms) and 0- | –1000 ms, ur | nit configurab | le | |
| ontr | Input Frequency | | | | 11 | Mpps, line driv | ver / 200kpps | , open collect | tor | | | |
|) | Input Pulse Type | | Pulse and direction, CW+CCW, A/B Phase (quadrature) | | | | | | | | | |
| | Recommended Breaker (UL 489) | 15 C trip | 5A curve | 30 C trip |)A curve | 40A B trip curve | 50A B trip curve | 10A B trip curve | ip 20A 3 B trip curve B trip | | OA curve | |
| | Recommended Fuse*** | 15A | 20A | 40A | 70A | 125A | 150A | 15A | 25A | 35A | 50A | 65A |
| | SCCR Rating*** | | | | | | 5kA | | | | | |
| | Specification | | ANSI/TIA/ | EIA - 422 star | ndard specific | cations - conn | ects to PLCs | with RS485 | ports (Click, I | P-Series, Do- | More, etc.) | |
| | Protocol | | | | | N | MODBUS-RTI | J | | | | |
| ~ | Synchro Method | | | | | , | Asynchronous | 3 | | | | |
| RS-422 | Power Consumption | | | | | 1 | 00mA or belo | W | | | | |
| B | Transmission Speed (bps) | | | | 9,600 / 19,2 | 00 / 38,400 / | 57,600 (can l | oe configured | I at [0x3002] | | | |
| | Distance | | | | | 2 | 00m maximu | m | | | | |
| | Terminating Resistance | | | | | DIP S/W #2 | 2 (On/Off), Bu | ilt-In 120Ω | | | | |
| Digital I/O Specifications | Digital Input | DIP S/W #2 (On/Off), Built-In 120Ω Input voltage range: 12–24 VDC Total 16 input channels (configurable) 34 different selectable functions for assignment. (*SV_ON, *POT, *NOT, *A-RST, *START, *STOP, *REGT, *EMG, *HOME, *HSTART, *ISEL0, *ISEL1, *ISEL3, *ISEL4, *ISEL5, PCON, GAIN2, P_CL, N_CL, MODE, PAUSE, ABSRQ, JSTART, JDIR, PCLR, AOVR, SPD1/LVSF1, SPD2/LVSF2, SPD3, PROBE1, PROBE2) | | | | | | | | | | |
| Service rating: 24VDC ± 10%, 120mA 8 output channels are configurable 19 different selectable functions for assignment (*ALARM±, *READY±, *BRAKE±, *INPOS1±, *ORG±, *EOS±, *TGON±, *TLMT,± VLMT±, INSPD±, ZSPD±, IOUT1±, IOUT2±, IOUT3±, IOUT4±, IOUT5±) | | | | | | ZSPD±, WAF | RN±, INPOS2 | ±, IOUT0±, | | | | |
| Analog 1/0 | Analog Input | | | | | log speed inp torque comn | | | | | | |
| Ana | Analog Output | | | | 15 fund | tion outputs | 2 channels can be selecti | vely allocated | d ± 10V | | | |
| | | | | C | ontinued or | next page | | | | | | |

* Basic allocation signal.

^{**} See Single-phase power input section on the following page for single phase considerations.
*** Use class CC or High Speed J (JHL series) current limiting fuses to prevent nuisance tripping and to increase panel SCCR rating.



L7P Servo drive specifications, continued

| | L7P Servo Drive Specifications, continued | | | | | | |
|-----------------------|---|--|--|--|--|--|--|
| | | Continued from | previous page | | | | |
| | Model | L7PA004U-AD | All Other L7P Series Drives | | | | |
| ation | Connect | Fi | Configuration/Monitor: PC irmware Update: PC or USB On the Go (no PC needed) | | | | |
| USB Communication | Communication Standard | | USB 2.0 full speed (applies standard) | | | | |
| Сош | Specification | | PC, USB 2.0 full speed (applies standard) | | | | |
| | Mechanical Brake | Standard built-in b | rake (activated when the servo alarm goes off or when the servo is OFF) | | | | |
| uo | Regenerative Braking | Default built-in, external installation possible | | | | | |
| Internal Function | Display Function | 7-segment display (5 digits) | | | | | |
| nal F | Self-setting Function | Drive node address can be set using rotary switch and DIP switch #3 (available Nodes = 0–31) | | | | | |
| Inter | Additional Function | | Gain tuning, alarm history, JOG operation, homing | | | | |
| | Protection Function | Excessive current/cur | rent limit/voltage/speed, overload, overheating, low voltage, encoder failure, position following failure, current sensing failure | | | | |
| ant | Operating Temperature | | 0-50 °C [32-122 °F] | | | | |
| ironme | Storage Temperature | | -20 to -70°C [-4 to 158 °F] | | | | |
| n Env. | Operating Humidity | | Below 80% relative humidity | | | | |
| Operation Environment | Storage Humidity | I | Below 90% relative humidity (avoid dew-condensation) | | | | |
| Op | Environment | Indoor, avoid corrosive, inflammable gas, or liquid and electrically conductive dust | | | | | |
| | Approvals | _C UR _{US} (E479434), CE | _C UL _{US} (E479434), CE | | | | |

Single-phase Power Input

Although designed with 3-phase AC input power in mind, some L7P systems are capable of supporting single-phase AC input power. With three phase AC supply, the L7P motor/drive combination supplies 300% rated maximum motor torque (see the Instantaneous Operation Range in the torque-speed charts above). With single phase AC supply some ratings will have limited maximum/intermittent torque, and/or the next larger drive size will be required.

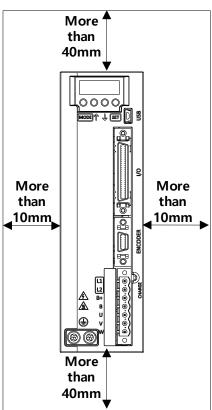
| Drive Derating for 230V Single-phase Usage | | | | | | |
|--|--|--|--|--|--|--|
| 3-phase Motor/Drive Rating | Drive to use with Single- phase Input | Motor Torque Derating for Single-phase Input | | | | |
| 100W/200W/400W | L7PA004U-AD | Single phase and three phase input both produce 300% max torque. No derating required. | | | | |
| 750W | L7PA010U-AD | Single phase and three phase input both produce 300% max torque. No derating required. | | | | |
| 1kW | L7PA010U-AD or L7PA020U-AD | 2kW drive produces 300% max torque. The 1kW drive can be used, but the motor can only provide 200% max torque. | | | | |
| 1.5 kW/1.6 kW | L7PA035U-AD | 3.5 kW drive produces 200% max torque | | | | |
| 2.2 kW | 211710000712 | 3.5 kW drive produces 150% max torque | | | | |
| 3.5 kW and up | n/a | No single phase capability | | | | |



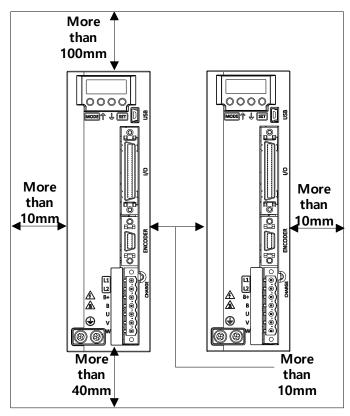
L7P Drive Standard Installation

L7P Drive Installation Spacing

Single Drive



Multiple Drives



L7P Drive Installation Concerns:

- Install external regenerative resistors so that any heat generated does not affect the drive.
- · Vertical installation only. For proper heat dissipation, ensure the back of the drive makes good contact with the subpanel.
- Protect the drive from metal chips and other falling debris during control panel assembly.
- Make sure that oil, water, or metal dust do not enter the drive.
- Protect the control panel by using an air purge system when installing it in any area where there are harmful gases or dust.

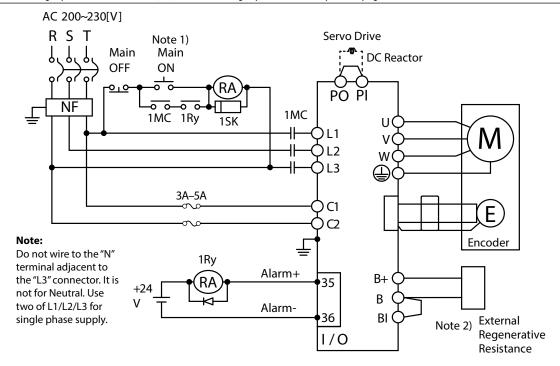


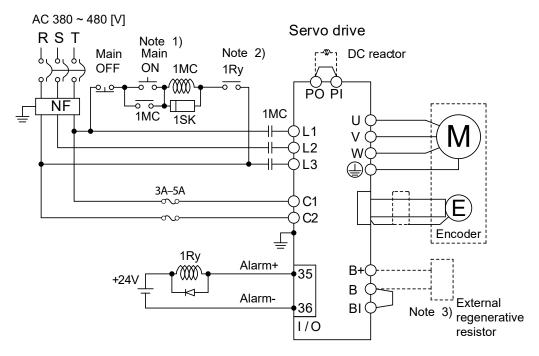
L7P Drive Wiring

L7P Power Supply Wiring



NOTE: Single phase can use 2 of R, S, or T. See "Single-phase Power Input" on page tMNC-264 for more information.







NOTE 1: About 1–2 seconds are required from main power supply to alarm signal output. Hold the main power on for 2 seconds until the alarm circuit ("1Ry") will latch main power ON.



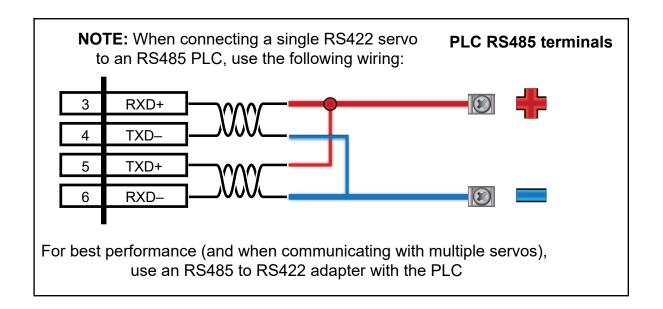
NOTES 2 & 3: Remove the jumper for the inertnal resistor between B and BI, and connect the external resistor to the B+ and B pins. If an external regen resistor is required, see the available regen resistors under the Motion Control category at AutomationDirect.com (APCS-140R50-AD, APCS-300R30-AD, etc.).

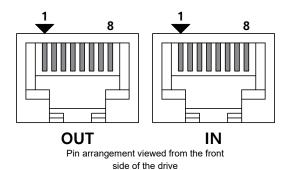


LTP Series AC Servo Systems

L7P Drive Wiring, continued

Connect the L7P RS422 port to a PLC with an RS485 port:







| Pin arra | ngement | viewed | from | the |
|----------|---------|--------|------|-----|
| | conne | ector | | |

| Pin # | Pin Function |
|-------|--------------|
| 1 | Not used |
| 2 | Not used |
| 3 | RXD+ |
| 4 | TXD- |
| 5 | TXD+ |
| 6 | RXD- |
| 7 | Not used |
| 8 | Not used |



NOTE: When connecting multiple drives, use a standard RJ45 ethernet patch cable (not a crossover cable) for the serial network. On the last drive only, set DIP switch #2 = 0N (120 Ohm terminating resistor).



LSELECTRIC L7P/iX7NH AC Servo Systems

60-80 mm Frame Motor Specifications

| | L7 | 7P/iX7NH | 60-80 | mm Fran | ne Moto | Specific | cations | | | |
|---|------------------|------------------|------------------|-----------------|--------------------------|-------------------|-------------------|-------------------|-------------------|-------------------|
| Model | APMC-FBL01AMK-AD | APMC-FBL02AMK-AD | APMC-FBL04AMK-AD | APMC-FCL08AMKAD | APMC-FCL10AMKAD | APMC-FBL01AMK2-AD | APMC-FBL02AMK2-AD | APMC-FBL04AMK2-AD | APMC-FCL08AMK2-AD | APMC-FCL10AMK2-AD |
| Price | \$273.00 | \$318.00 | \$329.00 | \$404.00 | \$449.00 | \$490.00 | \$515.00 | \$525.00 | \$604.00 | \$640.00 |
| Drawing | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | <u>PDF</u> |
| Input Voltage | | | | | 230 | VAC | | | | |
| Drive Compatibility | | | | | L7P and iX | 7NH drives | | | | |
| Integrated Brake | | | No | | | | | Yes | | |
| Flange Size (mm) | | 60 | | 8 | 0 | | 60 | | 8 | 0 |
| Rated Power [kW] | 0.1 | 0.2 | 0.4 | 0.75 | 1 | 0.1 | 0.2 | 0.4 | 0.75 | 1 |
| Rated Torque [N·m]Note 1 | 0.32 | 0.64 | 1.27 | 2.39 | 3.18 | 0.32 | 0.64 | 1.27 | 2.39 | 3.18 |
| Max. Torque [N·m] | 0.96 | 1.91 | 3.82 | 7.16 | 9.55 | 0.96 | 1.91 | 3.82 | 7.16 | 9.55 |
| Rated Speed [rpm] | | 3000 | | | | | | | | |
| Max. Speed [rpm] | | | | | 50 | 000 | | | | |
| Mechanical Time Constant [ms] | 0.926 | 0.518 | 0.374 | 0.609 | 0.492 | 0.926 | 0.518 | 0.374 | 0.609 | 0.492 |
| Rated current [Amps] rms | 0.95 | 1.45 | 2.6 | 5.02 | 5.83 | 0.95 | 1.45 | 2.6 | 5.02 | 5.83 |
| Max. Instantaneous Current [Amps] rms | 2.85 | 4.35 | 7.8 | 15.07 | 17.5 | 2.85 | 4.35 | 7.8 | 15.07 | 17.5 |
| Rated Power Rate [kW/s] | 11.09 | 27.6 | 27.07 | 45.09 | 62.08 | 11.09 | 27.6 | 27.07 | 45.09 | 62.08 |
| Electrical Time Constant [ms] | 2.416 | 3.488 | 4.271 | 5.774 | 6.919 | 2.416 | 3.488 | 4.271 | 5.774 | 6.919 |
| Insulation Class | | | | | Class BE | (CE, UL) | | | | |
| Insulation Resistance | | | | | | 500VDC | | | | |
| Insulation Strength | | | I | | 1.8 kVAC | , 1 second | | | l | |
| Rotor Inertia [x10 ⁻⁴ kg m ²] | 0.091 | 0.147 | 0.248 | 1.264 | 1.632 | 0.091 | 0.147 | 0.248 | 1.264 | 1.632 |
| Allowable Load Inertia Ratio | 20 | times motor ine | ertia | 15 times m | otor inertia | 20 | times motor ine | ertia | 15 times m | notor inertia |
| Max Radial Loading [N] | | 206 | | 25 | 55 | | 206 | | 2 | 55 |
| Max Axial Loading [N] | | 69 | | 9 | 8 | | 69 | | 9 | 8 |
| Vibration Grade [µm] | | | | | V | 15 | | - | 1 | |
| Vibration Capacity | | | | | 19.6 m/s ² or | lower (2.5G) | | | | |
| Speed/Position Detector | | | | Se | rial multi-turn b | uilt-in type (19- | bit) | - | - | |
| Weight [kg] | 0.56 | 0.74 | 1.06 | 2.68 | 3.3 | 1.28 | 1.46 | 1.78 | 3.45 | 4.07 |

Note 1-The rated torque is the continuous permissible torque between the 0° C and 40° C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: $250 \text{mm} \times 250 \text{mm} \times 60 \text{mm}$ made from aluminum (or mounted to equipment with an equivalent heat sinking capability).



L7P/iX7NH AC Servo Systems

130mm Frame Motor Specifications

| | | | L7P/iX | 7NH 1 | 30mm | Frame | Moto | r Spec | ificatio | ons | | | | | |
|---|----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|------------------|------------------|------------------|------------------|--|
| Model | APM-FE15AMK-AD | APM-FE16DMK-AD | APM-FE22DMK-AD | APM-FE15AMK2-AD | APM-FE16DMK2-AD | APM-FE22DMK2-AD | APM-FEP09AMK-AD | APM-FEP15AMK-AD | APM-FEP16DMK-AD | APM-FEP22DMK-AD | APM-FEP09AMK2-AD | APM-FEP15AMK2-AD | APM-FEP16DMK2-AD | APM-FEP22DMK2-AD | |
| Price | \$644.00 | \$690.00 | \$745.00 | \$845.00 | \$893.00 | \$955.00 | \$590.00 | \$646.00 | \$698.00 | \$753.00 | \$793.00 | \$878.00 | \$930.00 | \$962.00 | |
| Drawing | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | <u>PDF</u> | |
| Input Voltage | | | 230 | VAC | | | | | | 460 | VAC | | | | |
| Drive Compatibility | | | L7P and iX | 7NH drives | | | | | | L7P | drives | | | | |
| Integrated Brake | | No | | | Yes | | | N | 0 | | | Y | es | | |
| Flange Size (mm) | | | | | | | 13 | 30 | | | | | | | |
| Rated Power [kW] | 1.5 | 1.6 | 2.2 | 1.5 | 1.6 | 2.2 | 0.9 | 1.5 | 1.6 | 2.2 | 0.9 | 1.5 | 1.6 | 2.2 | |
| Rated Torque [N·m] | 4.77 | 7.63 | 10.5 | 4.77 | 7.63 | 10.5 | 2.86 | 4.77 | 7.64 | 10.5 | 2.86 | 4.77 | 7.64 | 10.5 | |
| Max. Torque [N·m] | 14.32 | 22.92 | 31.51 | 14.32 | 22.92 | 31.51 | 8.59 | 14.32 | 22.92 | 31.51 | 8.59 | 14.32 | 22.92 | 31.51 | |
| Rated Speed [rpm] | 3000 | 20 | 00 | 3000 | 20 | 00 | 30 | 00 | 2000 | | | 3000 | | 2000 | |
| Max. Speed [rpm] | 5000 | 30 | 00 | 5000 | 30 | 00 | 50 | 5000 3000 | | 00 | 5000 | | 30 | 000 | |
| Mechanical Time Constant [ms] | 1.520 | 1.278 | 1.176 | 1.520 | 1.278 | 1.176 | 2.428 | 1.609 | 1.337 | 1.261 | 2.428 | 1.609 | 1.337 | 1.261 | |
| Rated current [Amps] rms | 9.15 | 10.98 | 12.97 | 9.15 | 10.98 | 12.97 | 3.47 | 6.68 | 4.97 | 6.8 | 3.47 | 6.68 | 4.97 | 6.8 | |
| Max. Instantaneous Current [Amps] rms | 27.45 | 32.94 | 38.91 | 27.45 | 32.94 | 38.91 | 10.4 | 20.03 | 14.92 | 20.4 | 10.4 | 20.03 | 14.92 | 20.4 | |
| Rated Power Rate [kW/s] | 22.38 | 39.89 | 57.9 | 22.38 | 39.89 | 57.9 | 14.5 | 22.4 | 39.92 | 57.95 | 14.5 | 22.4 | 39.92 | 57.95 | |
| Electrical Time Constant [ms] | 9.819 | 10.352 | 11.284 | 9.819 | 10.352 | 11.284 | 7.763 | 9.761 | 10.656 | 10.623 | 7.763 | 9.761 | 10.656 | 10.623 | |
| Insulation Class | | | | | | | E | 3 | | | | | | | |
| Insulation Resistance | | | | | | | 101 | ΜΩ | | | | | | | |
| Insulation Strength | | | 1.8 kVAC | 1 second | | | | | | 2.2 kVAC | , 1 second | | | | |
| Rotor Inertia [x10 ⁻⁴ kg m ²] | 10.18 | 14.62 | 19.43 | 10.18 | 14.62 | 19.43 | 5.659 | 10.179 | 14.619 | 19.04 | 5.659 | 10.179 | 14.619 | 19.04 | |
| Allowable Load Inertia Ratio | | | | | | | 10 times m | otor inertia | | | | | | | |
| Max Radial Loading [N] | | | | | | | 72 | 25 | | | | | | | |
| Max Axial Loading [N] | | | | | | | 36 | 62 | | | | | | | |
| Vibration Grade [µm] | 15 | | | | | | | | | | | | | | |
| Vibration Capacity | 5G | | | | | | | | | | | | | | |
| Speed/Position Detector | | | | | | | Serial typ | e (19-bit) | | | | | | | |
| Weight [kg] | 6.7 | 8.5 | 10.1 | 8.28 | 10.02 | 11.59 | 5.04 | 6.7 | 8.5 | 10.1 | 6.58 | 8.28 | 10.02 | 11.59 | |

Note 1–The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

LSELECTRIC L7P/iX7NH AC Servo Systems

180mm Frame Motor Specifications

| | | L7P/i | X7NH 1 | 80mm | Frame | Motor | Specific | cations | | | | |
|---|----------------|----------------|----------------|------------------|------------------|-----------------|-----------------|-----------------|-----------------|------------------|------------------|------------------|
| Model | APM-FF35DMK-AD | APM-FF55DMK-AD | APM-FF75DMK-AD | APIN-FF35DMK2-AD | APIN-FF55DMK2-AD | APM-FF75DMK2-AD | APM-FFP35DMK-AD | APM-FFP55DMK-AD | APM-FFP75DMK-AD | APM-FFP35DMK2-AD | APM-FFP55DMK2-AD | APM-FFP75DMK2-AD |
| Price | \$999.00 | \$1,240.00 | \$1,499.00 | \$1,297.00 | \$1,562.00 | \$1,827.00 | \$1,035.00 | \$1,235.00 | \$1,510.00 | \$1,358.00 | \$1,557.00 | \$1,830.00 |
| Drawing | <u>PDF</u> | PDF | <u>PDF</u> | PDF | <u>PDF</u> | PDF | PDF | <u>PDF</u> | PDF | PDF | <u>PDF</u> | PDF |
| Input Voltag e | | | 230 | VAC | | | | | 460' | VAC | | |
| Drive Compatibility | | L7P and iX | 7NH drives | | | | | L7P o | drives | | | |
| Integrated Brake | | No | | | Yes | | | No | | | Yes | |
| Flange Size (mm) | | | | | | | 30 | | | | | |
| Rated Power [kW] | 3.5 | 5.5 | 7.5 | 3.5 | 5.5 | 7.5 | 3.5 | 5.5 | 7.5 | 3.5 | 5.5 | 7.5 |
| Rated Torque [N·m]Note 1 | 16.7 | 26.25 | 35.81 | 16.7 | 26.25 | 35.81 | 16.71 | 26.26 | 35.81 | 16.71 | 26.26 | 35.81 |
| Max. Torque [N·m] | 50.1 | 78.76 | 89.53 | 50.1 | 78.76 | 89.53 | 50.13 | 65.65 | 89.52 | 50.13 | 65.65 | 89.52 |
| Rated Speed [rpm] | | | | | | 20 | 00 | | | | | |
| Max. Speed [rpm] | | | | | | 30 | 00 | | 1 | | | |
| Mechanical Time Constant [ms] | 1.222 | 0.829 | 0.723 | 1.222 | 0.829 | 0.723 | 1.058 | 0.847 | 0.764 | 1.058 | 0.847 | 0.764 |
| Rated current [Amps] rms | 16.48 | 28.78 | 32.95 | 16.48 | 28.78 | 32.95 | 9.09 | 14.70 | 18.97 | 9.09 | 14.70 | 18.97 |
| Max. Instantaneous Current [Amps] rms | 49.44 | 86.34 | 82.38 | 49.44 | 86.34 | 82.38 | 27.26 | 36.75 | 47.42 | 27.26 | 36.75 | 47.42 |
| Rated Power Rate [kW/s] | 59.89 | 93.27 | 120.15 | 59.89 | 93.27 | 120.15 | 59.98 | 93.38 | 120.15 | 59.98 | 93.38 | 120.15 |
| Electrical Time Constant [ms] | 15.021 | 19.086 | 20.567 | 15.021 | 19.086 | 20.567 | 14.452 | 23.484 | 20.351 | 14.452 | 23.484 | 20.351 |
| Insulation Class | | | | | | E | 3 | | | | | |
| Insulation Resistance | | | | | | 101 | ΜΩ | | | | | |
| Insulation Strength | | T | 1.8 kVAC | 1 second | 1 | 1 | | T | 2.2 kVAC, | 1 second | 1 | 1 |
| Rotor Inertia [x10 ⁻⁴ kg m ²] | 46.56 | 73.85 | 106.7 | 46.56 | 73.85 | 106.7 | 46.56 | 73.85 | 106.73 | 46.56 | 73.85 | 106.73 |
| Allowable Load Inertia Ratio | | | | | | 5 times m | otor inertia | | | | | |
| Max Radial Loading [N] | | | | | | 15 | 48 | | | | | |
| Max Axial Loading [N] | | | | | | 5′ | 19 | | | | | |
| Vibration Grade [µm] | | | | | | 1 | 5 | | | | | |
| Vibration Capacity | | | | | | 5 | G | | | | | |
| Speed/Position Detector | | | | | | Serial typ | e (19-bit) | | | | | |
| Weight [kg] | 17.4 | 25.2 | 34 | 24.6 | 32.4 | 39 | 17.4 | 25.2 | 34 | 24.6 | 32.4 | 39 |

Note 1-The rated torque is the continuous permissible torque between the 0°C and 40°C operating temperature which is suitable for a servo motor mounted with the following heat sink dimensions: 250mm x 250mm x 6mm made from aluminum (or mounted to equipment with an equivalent heat sinking capability).

tMNC-271

L7P/iX7NH AC Servo Systems

Environmental Specifications

| | L7P/iX7NH Motor Environmental Specifications | | | | | | | | | | |
|-----------------------|--|---|---------------|--|--|--|--|--|--|--|--|
| Model Series | APMC-FBL/FCL Motors | FE/FEP Motors | FF/FFP Motors | | | | | | | | |
| IP Rating | Fully closed self-cooling IP67 ¹ | Fully closed self-cooling IP67 ¹ Fully closed self-cooling IP65 ¹ | | | | | | | | | |
| Rated Time | | Continuous | | | | | | | | | |
| Operating Temperature | 0 to 40 °C [32 to 104 °F] | | | | | | | | | | |
| Storage Temperature | -10 to 60 °C [14 to 140 °F] | | | | | | | | | | |
| Operating Humidity | | Below 80% RH | | | | | | | | | |
| Storage Humidity | | Below 90% RH (non condensing) | | | | | | | | | |
| Atmosphere | Avoid o | direct sunlight and corrosive/flammable gas o | r liquid | | | | | | | | |
| E/V | | Elevation/vibration 49m/s ² (5G) | | | | | | | | | |
| Agency Approvals | | _C UR _{US} (E255738), CE | | | | | | | | | |

Note 1 - Shaft connection not included. The IP rating for attached reducers/gearboxes is not guaranteed. Cables may not qualify marked IP rating if bent beyond designated specifications. Use suggested cables for maintaining IP rating.

www.automationdirect.com Motion Control



L7C/L7P Series AC Servo Systems

Accessories

CN1 Accessories

For L7x series drives, two methods are available for creating I/O connections.

Option 1:

Terminal blocks + cables:

- APC-VSCN1T-AD
- APC-VSCN1T01-AD
- APC-VSCN1T02-AD

APC-VSCN1T terminals ship with a universal labeling strip (A1-A25, B1-B25). A labeling template with designations specifically for the L7x drive can be downloaded from any of the drive pages or the terminal block page (www.automationdirect.com/pn/apc-vscn1t-ad).



APC-VSCN1T-AD

Option 2:

Flying lead cables:

- APC-CN101A-AD
- APC-CN102A-AD
- APC-CN103A-AD



APC-CN101A-AD



NOTE: For L7C drives, do not use APC-VSCN1T(xx)-AD feedthrough terminal block if using PLC/Drive serial communication. Communication errors may occur due to disconnects in cable shields. Use APC-CN10xA-AD flying lead cables.

| Part Number | Price | Description | Cable Length | Drawing | Compatible Drives | | |
|-----------------|---------|---|-------------------|---------|------------------------|--|--|
| APC-VSCN1T-AD | \$75.00 | LO Electric ONA feedalle contra | 0.5 m [1.6 ft] | PDF | | | |
| APC-VSCN1T01-AD | \$84.00 | LS Electric CN1 feedthrough terminal block, 50-pole, DIN rail mount | 1.0 m [3.2 ft] | PDF | All L7C and L7P drives | | |
| APC-VSCN1T02-AD | \$92.00 | Tall Mount | 2.0 m [6.5 ft] | PDF | | | |
| APC-CN101A-AD | \$46.00 | | 1.0 m [3.2 ft] | PDF | All L/C and L/F drives | | |
| APC-CN102A-AD | \$50.00 | LS Electric control cable, 50- pin connector to pigtail. | 2.0 m [6.5 ft] | PDF | | | |
| APC-CN103A-AD | \$55.00 | | 3.0 m [9.8 ft] | PDF | | | |

Accessories

L7P Terminal Assignment Table



CAUTION: This terminal assignment table is for use with L7P drives ONLY. Using this table with non-L7P series drives could damage your equipment as terminal assignments are different for each drive series.

APC-VSCN1T-AD

| 1 | | |
|-------|-------|------------------------------------|
| (A1) | 2 | |
| 3 | (B1) | |
| (A2) | 4 | 1 4 |
| 5 | (B2) | |
| (A3) | 6 | |
| 7 | (B3) | |
| (A4) | 8 | |
| 9 | (B4) | |
| (A5) | 10 | |
| 11 | (B5) | |
| (A6) | 12 | |
| 13 | (B6) | |
| (A7) | 14 | |
| 15 | (B7) | |
| (A8) | 16 | |
| 17 | (B8) | |
| (A9) | 18 | |
| 19 | (B9) | |
| (A10) | 20 | |
| 21 | (B10) | |
| (A11) | 22 | |
| 23 | (B11) | |
| (A12) | 24 | |
| 25 | (B12) | |
| (A13) | 26 | |
| 27 | (B13) | |
| (A14) | 28 | _ |
| 29 | (B14) | |
| (A15) | 30 | |
| 31 | (B15) | |
| (A16) | 32 | _ |
| 33 | (B16) | _ |
| (A17) | 34 | |
| 35 | (B17) | |
| (A18) | 36 | |
| 37 | (B18) | |
| (A19) | 38 | |
| 39 | (B19) | |
| (A20) | 40 | |
| 41 | (B20) | |
| (A21) | 42 | |
| 43 | (B21) | |
| (A22) | 44 | |
| 45 | (B22) | |
| (A23) | 46 | |
| 47 | (B23) | |
| (A24) | 48 | |
| 49 | (B24) | $(\downarrow\downarrow\downarrow)$ |
| (A25) | 50 | |
| | (B25) | |
| | | |
| | | |

You can download a printable terminal label at https://www.automationdirect.com/pn/APC-VSCN1T-AD

| | L7P Driv | e Termina | Assign | ments | |
|----------|--------------------------|-------------------------|---------------|-----------------|----------------------|
| Terminal | Drive I/O Pin/ Wire # | Description | Wire Color | Stripe Color | Number of Stripes |
| A1 | 1 | AO | Orange | Black | 1 |
| B1 | 2 | /AO | Orange | Red | 1 |
| A2 | 3 | ВО | Orange | Black | 2 |
| B2 | 4 | /BO | Orange | Red | 2 |
| A3 | 5 | ZO | Orange | Black | 3 |
| В3 | 6 | /ZO | Orange | Red | 3 |
| A4 | 7 | A-TLMT | Orange | Black | 4 |
| B4 | 8 | AGND | Orange | Red | 4 |
| A5 | 9 | A-OVR | Orange | Black | 5 |
| B5 | 10 | AGND | Orange | Red | 5 |
| A6 | 11 | +24V | Yellow | Black | 1 |
| B6 | 12 | DI-1 | Yellow | Red | 1 |
| A7 | 13 | DI-2 | Yellow | Black | 2 |
| В7 | 14 | DI-3 | Yellow | Red | 2 |
| A8 | 15 | DI-4 | Yellow | Black | 3 |
| B8 | 16 | DI-5 | Yellow | Red | 3 |
| A9 | 17 | DI-6 | Yellow | Black | 4 |
| В9 | 18 | DI-7 | Yellow | Red | 4 |
| A10 | 19 | DI-8 | Yellow | Black | 5 |
| B10 | 20 | N/C | Yellow | Red | 5 |
| A11 | 21 | +24v | Gray | Black | 1 |
| B11 | 22 | DI-9 | Gray | Red | 1 |
| A12 | 23 | DI-10 | Gray | Black | 2 |
| B12 | 24 | DI-11 | Gray | Red | 2 |
| A13 | 25 | DI-12 | Gray | Black | 3 |
| B13 | 26 | DI-13 | Gray | Red | 3 |
| A14 | 27 | DI-14 | Gray | Black | 4 |
| B14 | 28 | DI-15 | Gray | Red | 4 |
| A15 | 29 | DI-16 | Gray | Black | 5 |
| B15 | 30 | PULCOM 24V pwr input | Gray | Red | 5 |
| A16 | 31 | PF+ | White | Black | 1 |
| B16 | 32 | PF- | White | Red | 1 |
| A17 | 33 | PR+ | White | Black | 2 |
| B17 | 34 | PR- | White | Red | 2 |
| A18 | 35 | DO-1+ | White | Black | 3 |
| B18 | 36 | DO-1- | White | Red | 3 |
| A19 | 37 | DO-2+ | White | Black | 4 |
| B19 | 38 | DO-2- | White | Red | 4 |
| A20 | 39 | DO-3+ | White | Black | 5 |
| B20 | 40 | DO-3- | White | Red | 5 |
| A21 | 41 | DO-4+ | Pink | Black | 1 |
| B21 | 42 | DO-4- | Pink | Red | 1 |
| A22 | 43 | DO-5+ | Pink | Black | 2 |
| B22 | 44 | DO-5- | Pink | Red | 2 |
| A23 | 45 | DO-6+ | Pink | Black | 3 |
| B23 | 46 | DO-6- | Pink | Red | 3 |
| A24 | 47 | DO-7+ | Pink | Black | 4 |
| B24 | 48 | DO-7- | Pink | Red | 4 |
| A25 | 49 | DO-8+ | Pink | Black | 5 |
| B25 | 50 | DO-8- | Pink | Red | 5 |



LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH System Motor Encoder Cables

| Part Number | Price | Flex Rated | Length | Gauge | Drawing | Compatible Motors |
|-----------------|----------|---------------|---------------|--------|------------|--|
| APCS-EN03ES-AD | \$48.00 | | 3m [9.8 ft] | | PDF | |
| APCS-EN05ES-AD | \$58.00 | N | 5m [16.4 ft] | | <u>PDF</u> | |
| APCS-EN10ES-AD | \$67.00 | IN | 10m [32.8 ft] | | PDF | ADMCt ith |
| APCS-EN20ES-AD | \$79.00 | | 20m [65.6 ft] | 24AWG | PDF | APMC motors with 17-bit incremental |
| APCS-EF03ES-AD | \$70.00 | | 3m [9.8 ft] | 24AVVG | PDF | encoders (AYK/AYK2 motors) |
| APCS-EF05ES-AD | \$83.00 | Υ | 5m [16.4 ft] | | PDF | (ATRATIVE IIIO(013) |
| APCS-EF10ES-AD | \$116.00 | ı | 10m [32.8 ft] | | PDF | |
| APCS-EF20ES-AD | \$188.00 | | 20m [65.6 ft] | | PDF | |
| APCS-EN03ES1-AD | \$79.00 | | 3m [9.8 ft] | | <u>PDF</u> | FBL/FCL series motors with 19-bit encoders |
| APCS-EN05ES1-AD | \$83.00 | N | 5m [16.4 ft] | | PDF | |
| APCS-EN10ES1-AD | \$96.00 | IN | 10m [32.8 ft] | | <u>PDF</u> | |
| APCS-EN20ES1-AD | \$120.00 | | 20m [65.6 ft] | | PDF | |
| APCS-EF03ES1-AD | \$99.00 | | 3m [9.8 ft] | | <u>PDF</u> | |
| APCS-EF05ES1-AD | \$117.00 | Υ | 5m [16.4 ft] | | PDF | |
| APCS-EF10ES1-AD | \$159.00 | ' | 10m [32.8 ft] | | PDF | |
| APCS-EF20ES1-AD | \$244.00 | | 20m [65.6 ft] | 24AWG | PDF | |
| APCS-EN03DS1-AD | \$83.00 | | 3m [9.8 ft] | Z4AVVG | PDF | |
| APCS-EN05DS1-AD | \$88.00 | N | 5m [16.4 ft] | | PDF | |
| APCS-EN10DS1-AD | \$99.00 | IN | 10m [32.8 ft] | | PDF | |
| APCS-EN20DS1-AD | \$123.00 | | 20m [65.6 ft] | | PDF | APM-FE/APM-FF |
| APCS-EF03DS1-AD | \$104.00 | | 3m [9.8 ft] | | PDF | series motors |
| APCS-EF05DS1-AD | \$120.00 | Υ | 5m [16.4 ft] | | PDF | |
| APCS-EF10DS1-AD | \$159.00 | ī | 10m [32.8 ft] | | PDF | |
| APCS-EF20DS1-AD | \$246.00 | | 20m [65.6 ft] | | PDF | |



APCS-EN series encoder cable



APCS-ENxxxES1 series encoder cable



L7P/iX7NH System Encoder Accessories

| Part Number | Price | Description | Compatible Drives |
|----------------|---------|--|---|
| APC-EF00BS-AD | \$20.00 | 17-pin motor encoder connector. | APM-FE and APM- FF series motors |
| APCS-BATT36-AD | \$36.00 | Encoder battery. One (1) AA ER6V lithium battery with extended leads and an encoder cable connector. | All LS Electric motors with 19-bit encoders |

APC-EF00BS-AD



APCS-BATT36-AD



LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH System Motor Brake Power Cables

| Part Number | Price | Flex Rated | Length | Gauge | Drawing | Compatible Motors | |
|-----------------------|----------|---------------|---------------|-------|------------|--|--|
| <u>APCS-BN03QS-AD</u> | \$52.00 | | 3m [9.8 ft] | | PDF | | |
| APCS-BN05QS-AD | \$55.00 | N | 5m [16.4 ft] | | <u>PDF</u> | | |
| APCS-BN10QS-AD | \$61.00 | | 10m [32.8 ft] | 18AWG | PDF | APMC FBL/FCL brake motors (100W – 1kW) | |
| APCS-BN20QS-AD | \$74.00 | | 20m [65.6 ft] | | PDF | | |
| APCS-BF03QS-AD | \$58.00 | | 3m [9.8 ft] | IOAWG | <u>PDF</u> | | |
| APCS-BF05QS-AD | \$63.00 | | 5m [16.4 ft] | | PDF | | |
| APCS-BF10QS-AD | \$79.00 | Y | 10m [32.8 ft] | | PDF | | |
| APCS-BF20QS-AD | \$108.00 | | 20m [65.6 ft] | | <u>PDF</u> | | |



APCS-BN series brake cable



L7P System Non-Brake Motor Power Cables

| L7P System No | п-вгаке і | | 0 | | | |
|------------------------|-----------|---------------|---------------|--------|----------------|--|
| Part Number | Price | Flex Rated | Length | Gauge | Drawing | Compatible Motors |
| APCS-PN03LS-AD | \$42.00 | | 3m [9.8 ft] | | PDF | |
| APCS-PN05LS-AD | \$46.00 | N | 5m [16.4 ft] | | PDF | |
| <u>APCS-PN10LS-AD</u> | \$57.00 | IN . | 10m [32.8 ft] | | PDF | |
| <u>APCS-PN20LS-AD</u> | \$80.00 | | 20m [65.6 ft] | 18AWG | <u>PDF</u> | FBL/FCL series |
| <u>APCS-PF03LS-AD</u> | \$53.00 | | 3m [9.8 ft] | TOAWG | PDF | motors |
| <u>APCS-PF05LS-AD</u> | \$62.00 | Υ | 5m [16.4 ft] | | PDF | |
| APCS-PF10LS-AD | \$90.00 | ' [| 10m [32.8 ft] | | PDF | |
| <u>APCS-PF20LS-AD</u> | \$145.00 | | 20m [65.6 ft] | | PDF | |
| <u>apcs-pno3hs-ad</u> | \$45.00 | | 3m [9.8 ft] | | PDF | |
| APCS-PN05HS-AD | \$54.00 | N | 5m [16.4 ft] | | PDF | |
| APCS-PN10HS-AD | \$76.00 | IN | 10m [32.8 ft] | | PDF | |
| APCS-PN20HS-AD | \$119.00 | | 20m [65.6 ft] | | PDF | APM-FE series |
| APCS-PF03HS-AD | \$62.00 | | 3m [9.8 ft] | | PDF | motors without brake |
| APCS-PF05HS-AD | \$80.00 | Υ | 5m [16.4 ft] | | PDF | |
| APCS-PF10HS-AD | \$127.00 | Ť | 10m [32.8 ft] | | PDF | |
| APCS-PF20HS-AD | \$222.00 | | 20m [65.6 ft] | 14AWG | PDF | |
| APCS-PN03IS-AD | \$61.00 | | 3m [9.8 ft] | 14AVVG | PDF | 230VAC APM-FF35D and 460VAC APM- FFP35D motors without brakes |
| APCS-PN05IS-AD | \$77.00 | N. | 5m [16.4 ft] | | PDF | |
| APCS-PN10IS-AD | \$119.00 | N - | 10m [32.8 ft] | | PDF | |
| APCS-PN20IS-AD | \$199.00 | | 20m [65.6 ft] | | PDF | |
| APCS-PF03IS-AD | \$77.00 | | 3m [9.8 ft] | | PDF | |
| APCS-PF05IS-AD | \$103.00 | Y | 5m [16.4 ft] | | PDF | without brakes |
| APCS-PF10IS-AD | \$169.00 | ĭ | 10m [32.8 ft] | | PDF | |
| APCS-PF20IS-AD | \$305.00 | | 20m [65.6 ft] | | PDF | <u> </u> |
| APCS-PN03JS-AD | \$68.00 | | 3m [9.8 ft] | | PDF | |
| <u>APCS-PN05JS-AD</u> | \$90.00 | N | 5m [16.4 ft] | | PDF | |
| <u>APCS-PN10JS-AD</u> | \$139.00 | IN | 10m [32.8 ft] | | PDF | |
| <u>APCS-PN20JS-AD</u> | \$258.00 | | 20m [65.6 ft] | 10AWG | <u>PDF</u> | 230VAC APM-FF55D |
| <u>APCS-PF03JS-AD</u> | \$97.00 | | 3m [9.8 ft] | IUAWG | PDF | motors without brake |
| APCS-PF05JS-AD | \$137.00 | Υ | 5m [16.4 ft] | | PDF | |
| APCS-PF10JS-AD | \$237.00 | ' | 10m [32.8 ft] | | PDF | |
| APCS-PF20JS-AD | \$440.00 | | 20m [65.6 ft] | | PDF | |
| APCS-PF03JS1-AD | \$82.00 | | 3m [9.8 ft] | | PDF | 460VAC APM- |
| APCS-PF05JS1-AD | \$111.00 | Υ | 5m [16.4 ft] | 12AWG | PDF | FFP55D and APM- |
| APCS-PF10JS1-AD | \$186.00 | ľ | 10m [32.8 ft] | IZAWG | <u>PDF</u> | FFP75D motors without brakes |
| APCS-PF20JS1-AD | \$339.00 | | 20m [65.6 ft] | | PDF | without brakes |
| APCS-PN03JS2-AD | \$117.00 | | 3m [9.8 ft] | | <u>PDF</u> | |
| <u>APCS-PN05JS2-AD</u> | \$163.00 | N | 5m [16.4 ft] | | <u>PDF</u> |] |
| APCS-PN10JS2-AD | \$276.00 | IN | 10m [32.8 ft] | | PDF | |
| APCS-PN20JS2-AD | \$499.00 | | 20m [65.6 ft] | 8AWG | PDF | 230VAC APM-FF75D |
| APCS-PF03JS2-AD | \$169.00 | | 3m [9.8 ft] | JOANNO | PDF | motors without brake |
| APCS-PF05JS2-AD | \$247.00 | Υ | 5m [16.4 ft] | | PDF |] |
| APCS-PF10JS2-AD | \$439.00 | ' | 10m [32.8 ft] | | <u>PDF</u> | |
| APCS-PF20JS2-AD | \$824.00 | | 20m [65.6 ft] | | PDF | |

NOTE: These parts available for sale to North American locations only



APCS-PxxLS series power cable



APCS-PxxHS series power cable



APCS-PxxIS series power cable



APCS-PxxJS series power cable



Accessories, continued

L7P System Brake Motor Power Cables

| Part Number | Price | Flex Rated | Length | Gauge | Drawing | Compatible Motors | | |
|---|----------|---------------|---------------|--------|------------|--------------------------------------|--|--|
| Note: For FBL/FCL 100W–1kW motors with brake, use the power cables on page tMNC-234 (APCS-PxxxLS-AD) AND spearate brake cable APCS-BxxxQS-AD from page tMNC-232. This is for FBL/FCL motors only. FE and FF motors have brake wiring incorporated into the power cable (below). | | | | | | | | |
| APCS-PN03NB-AD | \$49.00 | | 3m [9.8 ft] | | PDF | | | |
| APCS-PN05NB-AD | \$58.00 | | 5m [16.4 ft] | | PDF | | | |
| APCS-PN10NB-AD | \$84.00 | N | 10m [32.8 ft] | | PDF | | | |
| APCS-PN20NB-AD | \$137.00 | | 20m [65.6 ft] | | PDF | 230VAC and 460 | | |
| APCS-PF03NB-AD | \$71.00 | | 3m [9.8 ft] | | PDF | VAC APM-FE series motors with brakes | | |
| APCS-PF05NB-AD | \$95.00 | ., | 5m [16.4 ft] | | PDF | | | |
| APCS-PF10NB-AD | \$153.00 | Y | 10m [32.8 ft] | | PDF | | | |
| APCS-PF20NB-AD | \$274.00 | | 20m [65.6 ft] | | PDF | | | |
| APCS-PN03PB-AD | \$69.00 | | 3m [9.8 ft] | 14AWG | PDF | | | |
| APCS-PN05PB-AD | \$87.00 | ., | 5m [16.4 ft] | | PDF | | | |
| APCS-PN10PB-AD | \$133.00 | N | 10m [32.8 ft] | | <u>PDF</u> | 230VAC APM-FF35D and 460VAC APM- | | |
| APCS-PN20PB-AD | \$229.00 | | 20m [65.6 ft] | | PDF | | | |
| APCS-PF03PB-AD | \$88.00 | | 3m [9.8 ft] | | PDF | FFP35D motors with brakes | | |
| APCS-PF05PB-AD | \$120.00 | · · | 5m [16.4 ft] | | PDF | | | |
| APCS-PF10PB-AD | \$198.00 | Y | 10m [32.8 ft] | | PDF | | | |
| APCS-PF20PB-AD | \$359.00 | | 20m [65.6 ft] | | PDF | | | |
| APCS-PN03LB-AD | \$77.00 | | 3m [9.8 ft] | | PDF | | | |
| APCS-PN05LB-AD | \$99.00 | N. | 5m [16.4 ft] | | PDF | l | | |
| APCS-PN10LB-AD | \$153.00 | N | 10m [32.8 ft] | | PDF | 230VAC APM-FF55D | | |
| APCS-PN20LB-AD | \$265.00 | | 20m [65.6 ft] | 0.000 | PDF | | | |
| APCS-PF03LB-AD | \$114.00 | | 3m [9.8 ft] | 8AWG | PDF | motors with brake | | |
| APCS-PF05LB-AD | \$160.00 | V | 5m [16.4 ft] | | PDF | | | |
| APCS-PF10LB-AD | \$275.00 | Y | 10m [32.8 ft] | | PDF | | | |
| APCS-PF20LB-AD | \$510.00 | | 20m [65.6 ft] | | PDF | | | |
| APCS-PF03LB1-AD | \$95.00 | | 3m [9.8 ft] | | PDF | 400) (4.0.4.0) | | |
| APCS-PF05LB1-AD | \$130.00 | V | 5m [16.4 ft] | 10000 | PDF | 460VAC APM- FFP55D and APM- | | |
| APCS-PF10LB1-AD | \$220.00 | Y | 10m [32.8 ft] | 12AWG | PDF | FFP75D motors with | | |
| APCS-PF20LB1-AD | \$400.00 | | 20m [65.6 ft] | | PDF | brakes | | |
| APCS-PN03LB2-AD | \$130.00 | | 3m [9.8 ft] | | PDF | | | |
| APCS-PN05LB2-AD | \$177.00 | N. | 5m [16.4 ft] | | PDF | | | |
| APCS-PN10LB2-AD | \$300.00 | N | 10m [32.8 ft] | | PDF | | | |
| APCS-PN20LB2-AD | \$540.00 | | 20m [65.6 ft] | 901010 | PDF | 230VAC APM-FF75D | | |
| APCS-PF03LB2-AD | \$187.00 | | 3m [9.8 ft] | 8AWG | PDF | motors with brake | | |
| APCS-PF05LB2-AD | \$272.00 | \ <u>'</u> | 5m [16.4 ft] | | PDF | | | |
| APCS-PF10LB2-AD | \$479.00 | Y | 10m [32.8 ft] | | PDF | 1 | | |
| APCS-PF20LB2-AD | \$906.00 | | 20m [65.6 ft] | | PDF | | | |



APCS-PxxNB series power cable



APCS-PxxPB series power cable



APCS-PxxLB series power cable

LS Drive System Accessories

Accessories, continued

LS Drive System Replacement Connectors

| Part Number | Price | Description | Compatible Drives | Image |
|----------------------|---------|---|--|---------------------------------------|
| <u>5452573</u> | \$6.50 | AutomationDirect replacement drive power connector. | All L7C drives | A HAMANA |
| APC-CN1NNA-AD | \$17.50 | LS solder-type CN1 50-pin Electric I/O connector. | All L7C and L7P series drives | |
| <u>APC-CN2NNA-AD</u> | \$15.00 | LS Electric I/O connector, replacement, 20-pin. | All iX7NH series drives | |
| APC-CN3NNA-AD | \$17.50 | LS Electric solder-type CN2 14-pin drive encoder connector. | All L7C, L7P, and iX7NH series drives | |
| <u>APCS-CN6K-AD</u> | \$19.00 | LS Electric STO connector, replacement, 6-pin. For use with all LS Electric iX7 series drives. | All iX7NH series drives | 0 1 |
| <u>IX7-CON-A</u> | \$19.00 | AutomationDirect drive power connector, replacement, 11-pin. Note: Do not wire to pin 4 (the "-" terminal). | iX7NH series drives, 400W, 750W, and 1kW | |
| <u>IX7-CON-B</u> | \$19.00 | AutomationDirect drive power connector for motor power, replacement, 4-pin. | iX7NH series drives, 400W, 750W, and 1kW | |
| <u>IX7-CON-C</u> | \$9.00 | AutomationDirect drive power connector release, replacement. | iX7NH series drives, 400W, 750W, and 1kW | 000 |
| <u>IX7-CON-D</u> | \$19.00 | AutomationDirect drive power connector for motor power, replacement, 4-pin | iX7NH series drives, 2kW and 3.5 kW | 100 |
| <u>IX7-CON-E</u> | \$19.00 | AutomationDirect drive control power connector, replacement, 5-pin. | iX7NH series drives, 2kW and 3.5 kW | |
| <u>IX7-CON-F</u> | \$19.00 | AutomationDirect drive main power connector, replacement, 6-pin. | iX7NH series drives, 2kW and 3.5 kW | 10-200d |
| L7P-CON-A | \$15.00 | Replacement 11-pin drive power connector. Do not wire to pin 4 (the "N" terminal) | L7PA series 230VAC 400W and 1kW drives | San Marian |
| L7P-CON-B | \$8.00 | Replacement 3-pin drive power connector. | L7PA series 230VAC 400W and 1kW drives | S S S S S S S S S S S S S S S S S S S |
| | | Continued on nex | t page | |

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Motion Control

LS Drive System Accessories

Accessories, continued

LS Drive System Replacement Connectors, continued

| Part Number | Price | Description | Compatible Drives | Image |
|------------------|---------|--|---|--|
| <u>L7P-CON-C</u> | \$20.00 | Replacement 11-pin drive power connector. | L7PB series 460VAC 1kW drives, all L7P series 2kW and 3.5 kW drives | The state of the s |
| <u>L7P-CON-D</u> | \$7.50 | Replacement 3-pin drive power connector. | L7PB series 460VAC 1kW drives, all L7P series 2kW and 3.5 kW drives | |
| <u>L7P-CON-E</u> | \$0.50 | Drive analog monitor crimp pins (24-48 AWG), package of 5. | All L7P and iX7NH drives. Requires L7P-CON-F | ALLA |
| L7P-CON-F | \$2.00 | Drive analog monitor 4-pin crimp connector. | All L7P and iX7NH drives. Requires L7P-CON-E | |
| <u>L7P-CON-G</u> | \$2.00 | Drive analog monitor 4-pin IDC connector (26AWG). | All L7P and iX7NH series drives | |



LS Electric AC Servo Systems

Accessories, continued

L7C/L7P/iX7NH System Braking Resistors

Use external braking resistors to provide additional regenerative capacity and to dissipate heat away from the servo drive.

| Part Number | Price | Description | Drawing | Compatible Drive Series | Compatible Drive Models |
|------------------------|---------|---|------------|---|--|
| <u>APCS-140R50-AD</u> | \$18.50 | LS Electric 140W 30Ω encapsulated braking resistor | <u>PDF</u> | All 400W LS drives | L7CA004U-AD L7PA004U-AD IX7NHA004U-AD |
| <u>APCS-300R30-AD</u> | \$24.00 | LS Electric 300W 30Ω encapsulated braking resistor | PDF | All 230VAC 750W and 1kW LS drives | L7CA010U-AD L7PA010U-AD IX7NHA008U-AD IX7NHA010U-AD |
| <u>APC-600R30-AD</u> | \$42.00 | LS Electric 600W 30Ω encapsulated braking resistor. | <u>PDF</u> | All 230VAC 2.2 kW and 3.5 kW LS drives | L7PA020U-AD L7PA035U-AD IX7NHA020U-AD IX7NHA035U-AD |
| APC-600R28-AD | \$64.00 | LS Electric 600W 28Ω encapsulated braking resistor. | <u>PDF</u> | All 230VAC 5.5 kW and 7.5 kW LS drives | L7PA050U-AD L7PA075U-AD |
| APCS-300R82-AD | \$16.00 | LS Electric 300W 82Ω encapsulated braking resistor. | <u>PDF</u> | All 460VAC 1kW LS drives | L7PB010U-AD |
| <u>APCS-600R140-AD</u> | \$42.00 | LS Electric 600W 140Ω encapsulated braking resistor. | <u>PDF</u> | Alternate resistor for 460VAC 2.2 kW and 3.5 kW LS drives | Alternate resistor for L7PB020U-AD L7PB035U-AD |
| APCS-600R75-AD | \$42.00 | LS Electric 600W 75 Ω encapsulated braking resistor. | PDF | All 460VAC 2.2, 3.5, 5.5, and 7.5 kW LS drives | L7PB020U-AD L7PB035U-AD L7PB050U-AD L7PB075U-AD |



NOTE: 600W resistors require customer-supplied M5-.8 bolts and cable lugs for connection.



APCS-140R50-AD



LECTRIC LS Electric AC Servo Systems

Accessories, continued

NOTE: These parts available for sale to North American locations only

L7C/L7P/iX7NH/PHOX System Planetary Gearboxes

Precision planetary gearboxes can increase the torque output of servo systems while reducing the reflected load inertia for higher response. Gearboxes offer high stiffness, high efficiency, and very quiet operation. Input motor shaft clamp, oversized output shaft key, and mounting hardware are included for mating to LS Electric motors.

Features.

- Maintenance free (no need to replace lubrication)
- IP65
- Operating temperature range of -10°C to +90°C [14°F to 194°F]
- Uses VIGO Grease RE #0



MSS Series Planetary Gearbox

| MSS Series Planetary Gearbox Specfications | | | | | | | | | | |
|--|---|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|
| Model | 96200004 | 96200005 | 96200103 | 96200007 | 96200008 | 96200257 | 96200373 | 96200378 | 96200393 | 96200459 |
| Manufacturer Part Number | MSS0601A- 005KS- B3110103C14 | MSS0601A- 010KS- B3110103C14 | MSS0902B- 020KS- B3110103C14 | MSS0901A- 005KS- C3110103C19 | MSS0901A- 010KS- C3110103C19 | MSS1152B- 020KS- C3110103C19 | MSS0901A- 005KS- C4120103C19 | MSS0901A- 010KS- C4120103C19 | MSS1152B- 020KS- C4120103C19 | MSS1151A- 005KS- D3110103C22 |
| Compatible Motors | APMC-FBL series 100, 200, 300, and 400 W motors | | | APMC FCL | series 750W and | 1kW motors | APM-FE seri | APM-FE series 1.6 kW motors | | |
| Price | \$288.00 | \$296.00 | \$528.00 | \$387.00 | \$387.00 | \$762.00 | \$350.00 | \$350.00 | \$699.00 | \$499.00 |
| Drawing | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF |
| Ratio | 5:1 | 10:1 | 20:1 | 5:1 | 10:1 | 20:1 | 5:1 | 10:1 | 20:1 | 5:1 |
| Nominal Output Torque | 54 N·m | 42 N·m | 143 N·m | 160 N·m | 121 N·m | 295 N·m | 160 N·m | 121 N·m | 295 N·m | 332 N·m |
| Inertia | 0.13 kg/cm ² | 0.13 kg/cm ² | 0.13 kg/cm ² | 0.48 kg/cm ² | 0.44 kg/cm ² | 0.48 kg/cm ² | 0.48 kg/cm ² | 0.44 kg/cm ² | 0.48 kg/cm ² | 2.81 kg/cm ² |
| Output Shaft Diameter | 16mm | 16mm | 22mm | 22mm | 22mm | 32mm | 22mm | 22mm | 32mm | 32mm |
| Stage | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 |
| Frame | 60mm | 60mm | 90mm | 90mm | 90mm | 115mm | 90mm | 90mm | 115mm | 115mm |
| Nominal Input Speed (rpm) | 5,000 | 5,000 | 4,000 | 4,000 | 4,000 | 4,000 | 4,000 | 4,000 | 4,000 | 4,000 |
| Max Input Speed (rpm) | 10,000 | 10,000 | 8,000 | 8,000 | 8,000 | 8,000 | 8,000 | 8,000 | 8,000 | 8,000 |
| Emergency Stop Torque | | | | | 3 times nomina | al output torque | | | | |
| Noise (dB) | ≤54 | ≤54 | ≤56 | ≤56 | ≤56 | ≤59 | ≤56 | ≤56 | ≤59 | ≤59 |
| Efficiency (%) | ≥97 | ≥97 | ≥94 | ≥97 | ≥97 | ≥94 | ≥97 | ≥97 | ≥94 | ≥97 |
| Backlash (Arcmin) | ≤7 | ≤7 | ≤9 | ≤7 | ≤7 | ≤9 | ≤7 | ≤7 | ≤9 | ≤7 |
| Max Radial Load (N) | 1,280 | 1,280 | 3,200 | 3,200 | 3,200 | 6,800 | 3,200 | 3,200 | 6,800 | 6,800 |
| Max Axial Load (N) | 690 | 690 | 1,600 | 1,600 | 1,600 | 3,400 | 1,600 | 1,600 | 3,400 | 3,400 |
| Service Life (Hours) | 20,000 (10,000 under continuous operation) | | | | | | | | | |
| | Continued on next page | | | | | | | | | |

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Motion Control

LS ELECTRIC LS Electric AC Servo Systems

Accessories, continued

| MSS Series Planetary Gearbox Specfications | | | | | | | | | | | |
|--|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|--|------------------------------------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|
| Model | 96200464 | 96200479 | 96200010 | 96200011 | 96200445 | 96200013 | 96200014 | 96200701 | 96200016 | 96200017 | 96200862 |
| Manufacturer Part Number | MSS1151A- 010KS- D3110103C22 | MSS1422B- 020KS- D3110103C22 | MSS1151A- 005KS- D3110103C24 | MSS1151A- 010KS- D3110103C24 | MSS1422B- 020KS- D3110103C24 | MSS1421A- 005KS- E3110103C35 | MSS1421A- 010KS- E3110103C35 | MSS1802B- 020KS- E3110103C35 | MSS1801A- 005KS- F3110103C42 | MSS1801A- 010KS- F3110103C42 | MSS1802A- 015KS- F3110103C42 |
| Compatible Motors | APM-FE series 1.6 kW motors | | APM-FE series 2.2 kW motors | | | APM-FF series 3.5 kW and 5.5 kW motors | | | APM-FF series 7.5 kW motors | | |
| Price | \$499.00 | \$1,030.00 | \$499.00 | \$499.00 | \$1,030.00 | \$770.00 | \$770.00 | \$1,850.00 | \$1,480.00 | \$1,480.00 | \$1,850.00 |
| Drawing | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF | PDF |
| Ratio | 10:1 | 20:1 | 5:1 | 10:1 | 20:1 | 5:1 | 10:1 | 20:1 | 5:1 | 10:1 | 15:1 |
| Nominal Output Torque | 262 N·m | 295 N·m | 332 N·m | 262 N·m | 295 N·m | 634 N·m | 500 N·m | 1060 N·m | 1195 N·m | 960 N·m | 897 N·m |
| Inertia | 2.59 kg/cm ² | 2.81 kg/cm ² | 2.81 kg/cm ² | 2.59 kg/cm ² | 2.81 kg/cm ² | 7.52 kg/cm ² | 7.05 kg/cm ² | 7.52 kg/cm ² | 24.29 kg/cm ² | 23.51 kg/cm ² | 24.29 kg/cm ² |
| Output Shaft Diameter | 32mm | 40mm | 32mm | 32mm | 40mm | 40mm | 40mm | 55mm | 55mm | 55mm | 55mm |
| Stage | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 2 |
| Frame | 115mm | 142mm | 115mm | 115mm | 142mm | 142mm | 142mm | 180mm | 180mm | 180mm | 180mm |
| Nominal Input Speed (rpm) | 4,000 | 3,000 | 4,000 | 4,000 | 3,000 | 3,000 | 3,000 | 3,000 | 3,000 | 3,000 | 3,000 |
| Max Input Speed (rpm) | 8,000 | 6,000 | 8,000 | 8,000 | 6,000 | 6,000 | 6,000 | 6,000 | 6,000 | 6,000 | 6,000 |
| Emergency Stop Torque | | | | | 3 times | nominal output | t torque | | | | |
| Noise (dB) | ≤59 | ≤62 | ≤59 | ≤59 | ≤62 | ≤62 | ≤62 | ≤64 | ≤64 | ≤64 | ≤64 |
| Efficiency (%) | ≥97 | ≥94 | ≥97 | ≥97 | ≥94 | ≥97 | ≥97 | ≥94 | ≥97 | ≥97 | ≥94 |
| Backlash (Arcmin) | ≤7 | ≤9 | ≤7 | ≤7 | ≤9 | ≤7 | ≤7 | ≤9 | ≤7 | ≤7 | ≤9 |
| Max Radial Load (N) | 6,800 | 9,300 | 6,800 | 6,800 | 9,300 | 9,300 | 9,300 | 15,100 | 15,100 | 15,100 | 15,100 |
| Max Axial Load (N) | 3,400 | 4,500 | 3,400 | 3,400 | 4,500 | 4,500 | 4,500 | 7,500 | 7,500 | 7,500 | 7,500 |
| Service Life (Hours) | | | | | 20,000 (10,00 | 0 under continu | ious operation) | | | | |