GS1 Series Introduction



GS1 Series Drives						
Motor Rating	hp	0.25	0.5	1	2	
	kW	0.2	0.4	0.75	1.5	
115V Single-Phase Input / 230V Three-Phase Output			√			
230V Single-Phase Input / 230V Three-Phase Output			√	✓		
230VThree-Phase Input / Output	✓	✓	✓	✓		

Overview

The GS1 series of AC drives is our most affordable and compact inverter, offering V/Hz control with general purpose application features. These drives can be configured using the built-in digital keypad (which also allows you to set the drive speed, start and stop, and monitor specific parameters) or with the standard RS-485 serial communications port. Standard GS1 features include one analog input, four programmable digital inputs and one programmable normally open relay output.

Features

- Simple Volts/Hertz control
- Pulse Width Modulation (PWM)
- 3-10 kHz carrier frequency
- IGBT technology
- 130% starting torque at 5Hz
- 150% rated current for one minute
- Electronic overload protection
- · Stall prevention
- Adjustable accel and decel ramps
- S-curve settings for acceleration and deceleration
- Manual torque boost
- Automatic slip compensation
- DC braking
- Three skip frequencies
- · Trip history
- · Integral keypad and speed potentiometer
- Programmable jog speed
- Three programmable preset speeds
- Four programmable digital inputs
- One programmable analog input
- One programmable relay output
- RS-485 Modbus communications up to 19.2K
- Optional Ethernet communications
- DIN rail or panel mountable
- Two-year warranty
- UL/cUL/CE listed

Accessories

- AC line reactors
- RF filter
- Fuse kits and replacement fuses
- · Ethernet interface
- Four and eight-port RS-485 multi-drop termination board
- Serial communication cables available for creating plug and play RS-232/RS-485 networks with AutomationDirect PLCs. See the comm cable matrix (pg.tGSX-182).
- GSoft drive configuration software
- USB-485M USB to RS-485 PC adapter (see "Communications Products" chapter for detailed information)
- Detailed descriptions and specifications for GS accessories are available in the "GS/ DURApulse Accessories" section.

Typical Applications

- Conveyors
- Fans
- Pumps
- Shop tools

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GS1 Series Specifications

	115V	/230V CLASS GS1 Series			
Model		<u>GS1-20P2</u>	<u>GS1-21P0</u>		
Price		Retired	Retired		
Motor Dating	HP	1/4 hp	1hp		
Motor Rating	kW	0.2 kW	0.7 kW		
Rated Output Capacity (200V) kVA		0.6	1.6		
Rated Input Voltage		Single/three-phase: 200–240 VAC ±10%; 50/60 Hz ±5%			
Rated Output Voltage		Three-phase corresponds to the input voltage			
Rated Input Current (A)		4.9/1.9	9.7/5.1		
Rated Output Current (A)		1.6	4.2		
Watt Loss @ 100% I (W)		18.4	44.6		
Cooling Fan		no	yes		
Weight: kg (lb)		2.20	2.20		
Dimensions (HxWxD) (mm [in])		132.0 x 68.0 x128.1 [5.20 x 2.68 x 5.04]			
		Accessories			
Line Reactor *		LR-1xxPx-xxx (refer to "GS/DURApulse Drives Accessories – Line Reactors" section for exact part #)			
RF Filter		RF220X00A			
Fuse Kit **	Single- Phase**	<u>GS-20P2-FKIT-1P</u>	<u>n/a</u>		
	Three-Phase	GS-20P2-FKIT-3P	<u>n/a</u>		
Replacement Fuses	Single-Phase	GS-20P2-FUSE-1P	<u>GS-21P0-FUSE-1P</u>		
	Three-Phase	GS-20P2-FUSE-3P	<u>n/a</u>		
Ethernet Communications mod Drives (DIN rail mounted)	ule for GS Series	GS-EDRV100			
USB to RS-485 PC Communication Adapter		<u>USB-485M</u>			
RS-485 Communication Distribution Module (for creating plug and play RS-485 networks)		ZL-CDM-RJ12X4 / ZL-CDM-RJ12X10			
RS-485 Serial Cable, GS Drive to DL06/D2-260		GS-485HD15-CBL-2			
RS-485 Serial Cable, GS Drive to ZIPLink CDM Module		<u>GS-485RJ12-CBL-2</u>			
Software		<u>GSOFT</u>			
* GS1-1xxx drives require 115V class ** Single-phase fuse kits and fuses ar					

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GS1 General Specifications

			General Specifications			
			Control Characteristics			
Control System			Sinusoidal Pulse Width Modulation, carrier frequency 3kHz–10kHz			
Rated Output Frequency			1.0 to 400.0 Hz limited to 9999 motor rpm			
Output Freque	ency Resolution		0.1 Hz			
Overload Cap	acity		150% of rated current for 1 minute			
Torque Characteristics			Includes manual torque boost, auto-slip compensation, starting torque 130% @ 5.0Hz			
DC Braking			Operation frequency 60–0Hz, 0–30% rated voltage. Start time 0.0–5.0 seconds. Stop time 0.0–25.0 seconds			
Acceleration/Deceleration Time		 e	0.1 to 600 seconds (can be set individually)			
Voltage/Frequency Pattern			V/F pattern adjustable. Settings available for Constant Torque – low and high starting torque, Variable Torque – low and high starting torque, and user configured			
Stall Preventi	ion Level		20 to 200% of rated current			
			Operation Specification			
Inputs	_	Keypad	Setting by <up> or <down> buttons or potentiometer</down></up>			
	Frequency Setting	External Signal	Potentiometer - $5k\Omega$ 0.5W, 0 to 10 VDC (input impedance $47k\Omega$), 0 to 20 mA / 4 to 20 mA (input impedance 250Ω), Multi-function inputs 1 to 3 (3 steps, JOG, UP/DOWN command), RS485 communication setting			
	Operation	Keypad	Setting by <run>, <stop> buttons</stop></run>			
	Setting	External Signal	D11, D12, D13, D14 can be combined to offer various modes of operation, RS485 communication port			
I	Multi-Function	n Input Signal	Multi-step selection 0 to 3, Jog, Accel/decel inhibit, First/second accel/decel switch, Counter, PLC operation, External base block (N.C., N.O.) selection			
Outputs	Multi-Function	o Output Signal	AC drive operating, Frequency attained, Non zero speed, Base Block, Fault indication, Local/remote indication, PLC operation indication			
Operating Functions		octions	Automatic voltage regulation, S-curve, Over-voltage stall prevention, DC braking, Fault records, Adjustable carried frequency, Starting frequency setting of DC braking, Over-current stall prevention, Momentary power loss restart, Reverse inhibition, Frequency limits, Parameter lock/			
Protective Functions			Overcurrent, overvoltage, undervoltage, electronic thermal motor overload, Overheating, Overload, Self testing			
	Operator Devi	ices	5-key, 4-digit, 7-segment LED, 3 status LEDs, potentiometer			
Operator	Programming		Parameter values for setup and review, fault codes			
Interface	Parameter Monitor		Master Frequency, Output Frequency, Scaled Output Frequency, Output Voltage, DC Bus Voltage, Output Direction, Trip Event Monitor, Trip History Monitor			
	Key Functions	•	RUN/STOP, DISPLAY/RESET, PROGRAM/ENTER, <up>, <down></down></up>			
	Enclosure Rat	ing	Protected chassis, IP20			
Environment	Ambient Operating Temperature		-10° to 40°C (14°F to 104°F) w/o derating			
	Storage Temperature		-20° to 60 °C (-4°F to 140°F) during short-term transportation period)			
	Ambient Humidity		0 to 90% RH (non-condensing)			
	Vibration		9.8 m/s ² (1G), less than 10Hz; 5.88 m/s ² (0.6G) 20 to 50 Hz			
	Installation Lo	ocation	Altitude 1000m or lower above sea level, keep from corrosive gas, liquid and dust			
Options			Programming Software (GSOFT)			

GS1 Specifications - Installation

Understanding the installation requirements for your GS1 drive will help to ensure that it will operate within its environmental and electrical limits.

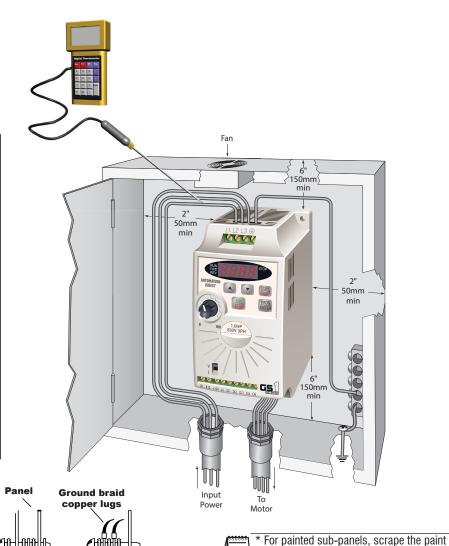
NOTE:

Never use only this catalog for installation instructions or operation of equipment; refer to the user manual, GS1-M.

Environmental	Specifications
Protective Structure ¹	IP20
Ambient Operating Temperature ²	-10 to 40 °C (14 to 104 °F)
Storage Temperature ³	-20 to 60°C (-4 to 140 °F)
Humidity	up to 90% (no condensation)
Vibration ⁴	5.9 m/s ² (0.6g), 10 to 55 Hz
Location	Altitude 1,000 m or less, indoors (no corrosive gases or dust)

- 1: Protective structure is based upon EN60529
- 2: The ambient temperature must be in the range of -10 to 40 °C (14 to 104 °F). If the range will be up to 50 °C (122°F), you will need to set the carrier frequency to 3.0 kHz and derate the output current to 80% or less. See our web site for derating curves.
- 3: The storage temperature refers to the short-term temperature during transport.
- 4: Conforms to the test method specified in JIS CO911 (1984)

Watt Loss Chart			
GS1 Drive Model	At full load		
<u>GS1-20P2</u>	18.4		
GS1-21P0	44.6		





Star

washers



Panel or single point

ground*

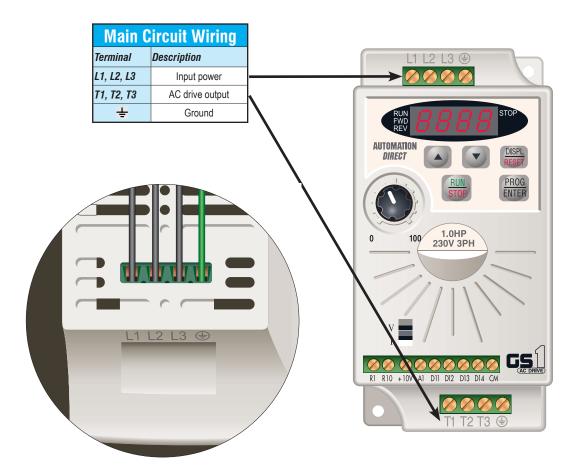
WARNING: AC DRIVES GENERATE A LARGE AMOUNT OF HEAT, WHICH MAY DAMAGE THE AC DRIVE. AUXILIARY COOLING METHODS ARE TYPICALLY REQUIRED IN ORDER TO NOT EXCEED MAXIMUM AMBIENT TEMPERATURES.

tightening them.

from underneath the star washers before

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GS1 Specifications - Terminals



Control Circuit Terminals			
Terminal Symbol	Description		
R10	Relay output 1 normally open		
R1	Relay output 1 common		
DI1	Digital input 1		
DI2	Digital input 2		
DI3	Digital input 3		
DI4	Digital input 4		
AI ¹	Analog input		
+10V	Internal power supply (10 mA @ 10 VDC)		
СМ	Common		

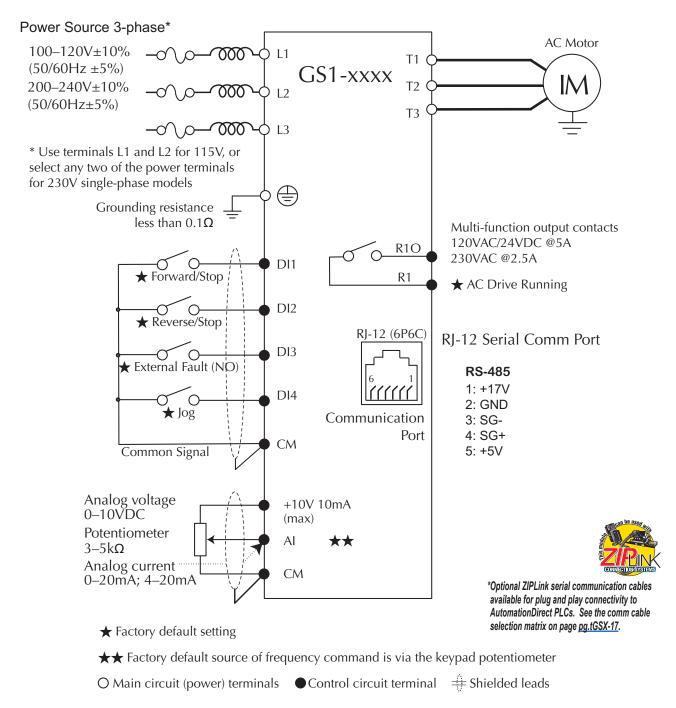
¹ 0 to +10 VDC, 0 to 20 mA, or 4 to 20 mA input represents zero to maximum output frequency.

Note: Use twisted-shielded, twisted-pair or shielded-lead wires for the control signal wiring. It is recommended all signal wiring be run in a separate steel conduit. The shield wire should only be connected at the drive. Do not connect shield wire on both ends.

GS1 Specifications - Basic Wiring Diagram

Note: Users MUST connect wiring according to the circuit diagram shown below. (Refer to user manual GS1-M for additional specific wiring information.)

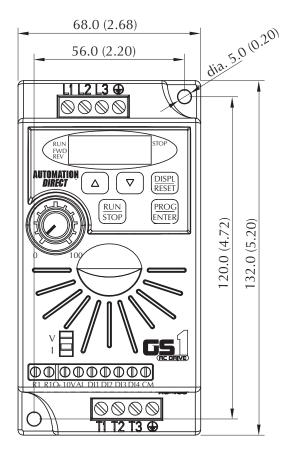
Note: Please refer to the following pages for explanations and information regarding line reactors (pg.tGSX-135) and RF filters (pg.tGSX-171)

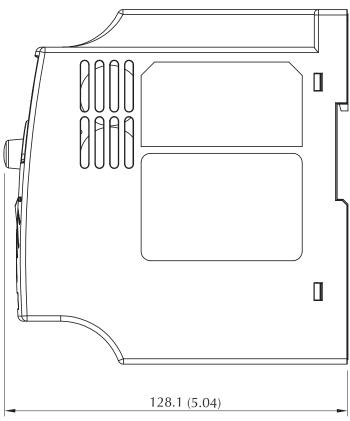


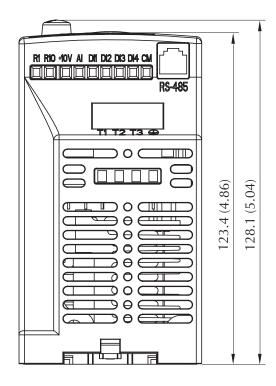


DO NOT PLUG A MODEM OR TELEPHONE INTO THE GS1 RJ-12 SERIAL COMM PORT, OR PERMANENT DAMAGE MAY RESULT. TERMINALS 2 AND 5 SHOULD NOT BE USED AS A POWER SOURCE FOR YOUR COMMUNICATION CONNECTION.

GS1 Specifications - Dimensions







Unit: mm (in)



Wiring Solutions

Wiring Solutions using the **ZIP**Link Wiring System

ZIPLinks eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the ZIPLink System ranging from PLC I/O-to-ZIPLink Connector Modules that are ready for field

termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of *ZIP*Link modules are provided with *ZIP*Link cables. See the following solutions to help determine the best *ZIP*Link system for your application.

Solution 1: DirectLOGIC, CLICK and Productivity I/O Modules to ZIPLink Connector Modules

When looking for quick and easy I/O-to-field termination, a *ZIP*Link connector module used in conjunction with a prewired *ZIP*Link cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.

Using the PLC I/O Modules to *ZIP*Link Connector Modules selector tables located in this section,

- 1. Locate your I/O module/PLC.
- 2. Select a **ZIP**Link Module.
- 3. Select a corresponding **ZIP**Link Cable.



Solution 2: DirectLOGIC, CLICK and Productivity I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the *ZIP*Link Pigtail Cables. *ZIP*Link Pigtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

- 1. Locate your PLC I/O module.
- Select a ZIPLink Pigtail Cable that is compatible with your 3rd party device.



Solution 3: GS Series and DURAPULSE Drives Communication Cables

Need to communicate via Modbus RTU to a drive or a network of drives?

ZIPLink cables are available in a wide range of configurations for connecting to PLCs and *SureServo*, *SureStep*, Stellar Soft Starter and AC drives. Add a **ZIP**Link communications module to quickly and easily set up a multi-device network.

Using the **Drives Communication** selector tables located in this section,

- 1. Locate your Drive and type of communications.
- 2. Select a **ZIP**Link cable and other associated hardware.





Wiring Solutions

Solution 4: Serial Communications Cables

ZIPLink offers communications cables for use with *Direct*LOGIC, CLICK, and Productivity CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25-pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the **Serial Communications Cables** selector table located in this section,

• 1. Locate your connector type 2. Select a cable.



Solution 5: Specialty ZIPLink Modules

For additional application solutions, *ZIP*Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and SureServo 50-pin I/O interface connection.

Using the **ZIPLink Specialty Modules** selector table located in this section,

- 1. Locate the type of application.
- 2. Select a ZIPLink module.



Solution 6: ZIPLink Connector Modules to 3rd Party Devices

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible *ZIP*Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the Universal Connector Modules and Pigtail Cables table located in this section,

- 1. Select module type.
- 2. Select the number of pins.
- 3. Select cable.





PIN Motor Controller Communication

AC Drive / Controller		Communications			ZIPLink Cable		
Controller	Comm Port Type	Network/Protocol	Connects to	Comm Port Type	Cable (2 meter length)	Cable Connectors	Other Hard- ware Required
GS1			BRX MPUs	RS-485, 3-Pin			
			P1 CPUs]		
	RJ12	RS-485 Modbus RTU	P2 CPUs	RS-485	ZL-RJ12-CBL-2P	RJ12 to pigtail	N/A
			P3 CPUs		ZL-1\01Z-ODL-ZI		
			P2-SCM P3-SCM	RS-485, 4-Pin			
			DL06 PLCs	Port 2 (HD15)	GS-485HD15- CBL-2	RJ12 to HD15	
			D2-260, D2-262 CPU	FOIL 2 (LID 13)			
			GS-EDRV100	RJ12	GS-EDRV-CBL-2		
			ZL-CDM-RJ12Xxx *	RJ12	GS-485RJ12- CBL-2	RJ12 to RJ12	
			FA-ISOCON	5-pin connector	GS-ISOCON- CBL-2	RJ12 to 5-pin plug	
			BRX MPUs	RS-232/485, 3-Pin			
			P1 CPUs				
			P2 CPUs	RS-485	ZL-RJ12-CBL-2P	RJ12 to pigtail	
			P3 CPUs		ZL-N012-ODL-21	RJ 12 to pigtali	N/A
			P2-SCM	Ports 1, 2 & 3			
		RS-232 Modbus RTU	P3-SCM	Ports 1 to 4			
		110-202 Wodbus 1110	CLICK PLCs	Port 2 (RJ12)			
			DL05 PLCs	1 0112 (11012)			
			DL06 PLCs		GS-RJ12-CBL-2	RJ12 to RJ12	
			D2-250-1 CPU	Port 2 (HD15)	00-1012-0DL-2	NO 12 10 NO 12	FA-15HD
			D2-260, D2-262 CPU				
200	D MO		D4-450, D4-454 CPU	Port 3 (25-pin)			FA-CABKIT
iS2	RJ12		BRX MPUs	RS-232/485, 3-Pin		RJ12 to pigtail	N/A
			P1 CPUs				
			P2 CPUs	RS-485	ZL-RJ12-CBL-2P		
		RS-485 Modbus RTU	P3 CPUs				
			P2-SCM P3-SCM	RS-485, 4-Pin			
			DL06 PLCs D2-260, D2-262 CPU	Port 2 (HD15)	GS-485HD15- CBL-2	RJ12 to HD15	
			GS-EDRV100	RJ12	GS-EDRV-CBL-2		
			ZL-CDM-RJ12Xxx *	RJ12	GS-485RJ12- CBL-2	RJ12 to RJ12	
			FA-ISOCON	5-pin connector	GS-ISOCON- CBL-2	RJ12 to 5-pin plug	
			BRX MPUs	RS-485, 3-Pin	ZL-RJ12-CBL-2P	RJ12 to pigtail	
	RJ12	RS-485 Modbus RTU	P1 CPUs	RS-485 RS-485, 4-Pin			
			P2 CPUs				
			P3 CPUs				
			P2-SCM				
OuraPulse			P3-SCM		GS-485HD15- CBL-2 RJ12 to HD15		N/A
(GS3)			DL06 PLCs	Port 2 (HD15)		IN/A	
			D2-260, D2-262 CPU				-
			GS-EDRV100	RJ12	GS-EDRV-CBL-2 RJ12 to RJ12		
			ZL-CDM-RJ12Xxx *	RJ12	GS-485RJ12- CBL-2	NUIZ IU NUIZ	
			FA-ISOCON	5-pin Connector	GS-ISOCON- CBL-2	RJ12 to 5-pin plug	

^{*} When using the ZL-CDM-RJ12Xxx ZIPLink Communication Distribution Module, replace the lowercase xx with the number of RJ12 ports, i.e. 4 for four ports or 10 for ten ports. (ex: ZL-CDM-RJ12X4 or ZL-CDM-RJ12X10)