

# **IronHorse ACG Series Introduction**



	IronHorse ACG AC Drives											
Motor Poting	HP	0.5	1.0	2.0	3.0	5.0	7.5	10.0	15.0	20.0	25.0	30.0
Motor Rating	kW	0.4	0.8	1.5	2.2	4.0	5.5	7.5	11.0	15.0	18.5	22.0
230V 1-Phase Inpu 230V 3-Phase Out		✓	✓	✓	✓	✓	✓	✓				
230V 3-Phase Inpu 230V 3-Phase Out		✓	✓	✓	✓	✓	✓	✓	✓	✓		
460V 1-Phase Inpu 460V 3-Phase Out		✓	✓	✓	✓	✓	✓	✓	✓			
460V 3-Phase Inpu 460V 3-Phase Out		<b>√</b>	✓	✓	<b>✓</b>	✓	✓	✓	✓	<b>√</b>	<b>~</b>	✓

#### **Overview**

The Ironhorse ACG sensorless vector control AC drives provide all the features needed for a variety of applications in a compact and durable package. The drives include many of the same standard features as our DURAPulse family of drives, including dynamic braking, PID, and RS-485 Modbus communication. All 230VAC and 460VAC drives are fully capable of single-phase input capability (with derating) and optional EtherNet/IP and Modbus TCP communication card. The drive supports up to two (2) independent IM motor parameter sets. Ironhorse ACG AC drives offer several different control modes: V/Hz, Slip compensation, and sensorless vector. It even provides Torque limit capability. Ironhorse ACG provides either voltage or current analog input for drive control, one analog output, five digital inputs, and two relay outputs. All of the analog and digital I/O can be configured for a wide variety of input or output functions. One option card port is available for an Ethernet/IP and Modbus TCP communication option card or remote mounted keypad. Durability is enhanced through UL 61800-5-3 conformance and robust military spec design.

#### **Features**

- Broad offering from 1/2 to 30 hp
- 230VAC: three-phase up to 20Hp, single phase up to 10hp
- 460VAC: three phase up to 30HP, singlephase up to 15hp
- Single-phase UL Ratings 230 or 460 VAC input
- Heavy Load (Constant Torque), Normal Load (Variable Torque) ratings
- Flexible carrier frequency to 15khz
- Output frequency to 400Hz (120Hz sensorless vector)
- Built-in RJ45 port for fast & easy programming.
- Free downloadable software for drive configuration
- Local/Remote control mode selection or digital/comm input with Hand/Off/Auto control
- PCB Conformal Coating
- Meets UL 61800-5-1 standards
- 100kA Short Circuit Current Rating
- Durable MIL217Plus based design
- DC Bus Connection for 15-30 hp drives
- Analog I/O configurable current/voltage input and 1 output
- · 2-Motor Control

- Built-in Dynamic Braking optional resistors
- KEB Operation (Kinetic Energy Buffering) for ride through of power loss
- PID Controller including sleep and wake
- Built-in Potentiometer
- · Password protection
- High speed communication interfaces with MODBUS RTU built in, with optional EtherNet/IP and ModbusTCP Communication Card
- DIN rail mounting built in on 5hp and lower for zero stack installation.
- Able to operate at 50°C ambient temperature
- 24 month warranty
- CE, UL, cUL

#### **Accessories**

- EtherNet/IP and ModbusTCP comm card
- AC line reactors
- dV/dT output filters
- EMI filters
- · Braking resistors
- Fuses
- Remote Keypad Mount Kit
- VFD Suite drive configuration software

## **Typical Applications**

Suitable for most applications, including:

- Conveyors
- Fans
- Pumps
- Shop tools
- Mixer
- Crane and Hoist
- Press
- Auger
- Centrifuge
- Waste Water Rake Drive
- X-Y Positioning
- Vibratory Tables
- · Synchronous Machine



# IronHorse ACG Series Selection

## **Selecting the Proper Drive Rating**

#### Selecting the Proper Drive Rating

#### Determine Motor Voltage and Full-Load Amperage (FLA)

Motor voltage and FLA are located on the nameplate of the motor.

NOTE: FLA of motors that have been rewound may be higher than stated.

#### **Determine Motor Overload Requirements**

Many applications experience temporary overload conditions due to starting requirements or impact loading. Most AC drives are designed to operate at 150% overload for 60 seconds. If the application requires an overload greater than 150% or longer than 60 seconds, the AC drive must be oversized.

NOTE: Applications that require replacement of existing motor starters with AC drives may require up to 600% overload.

#### Determine Application Type: Heavy Load (HD) or Normal Load (ND)

This torque requirement has a direct effect on which drive to select. Normal load (or variable torque) applications are generally easier to start; typically fans and pumps. Most other applications outside fans and pumps fall into the heavy load (or constant torque) category (machine control, conveyors, etc.). If you are unsure of the application, assume heavy load.

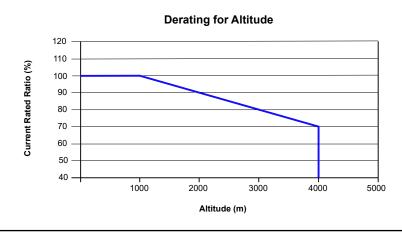
#### Installation Altitude

AC drives rely on air flow for cooling. ACG drives are designed to operate at 100% capacity at altitudes up to 1000 meters. As the altitude increases, the air becomes less dense. This drop in air density decreases the cooling properties of the air, therefore, the AC drive must be oversized to compensate for the decrease in cooling.

NOTE: For use above 1000m, the AC drive must be derated as described below.

#### Derate Output Current Based on Altitude Above 1000 Meters

- If the AC drive is installed at an altitude of 0–1000m, follow normal operation restrictions.
- From 1000 to 4000m, the rated input voltage and rated output current of the drive must be derated by 1% for every 100m.





# **IronHorse ACG Series Selection**

## **Selecting the Proper Drive Rating**

#### Derate Output Current Based on Carrier Frequency (if necessary)

#### Carrier Frequency Effects

AC Drives rectify the incoming 50Hz or 60Hz line power resulting in DC power. The DC power is then pulse-width modulated and supplied to the motor by the drive's power electronics. IGBTs invert the DC power, simulating a sine wave at the desired frequency (that's what allows variable speed in AC induction motors). The speed at which the IGBTs are turned ON and OFF is called Carrier Frequency. In ACG drives, the Carrier Frequency can range from 2kHz to 15kHz. Though Carrier Frequency can be adjusted, there are trade-offs between high Carrier Frequencies and low Carrier Frequencies.

#### Benefits of Higher Carrier Frequencies:

- · Better efficiency (lower harmonic losses) in the motor
- · Lower audible noise

#### **Benefits of Lower Carrier Frequencies:**

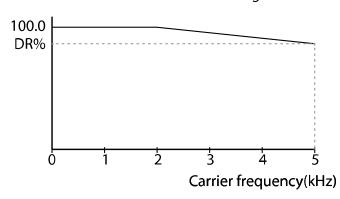
- · Better efficiency in the drive
- · Lower EMI (electrical noise)
- Reduced reflective wave peak voltage

As a general rule, the Carrier Frequency should be set as low as possible without creating unacceptable audible noise in the motor. Smaller systems can have higher Carrier Frequencies, but larger drives (>20 or 30hp) should not have Carrier Frequencies set higher than 6kHz. Heavy duty applications typically run around 2–4 kHz.

#### **Derating Tables**

	Drive V	/oltage
Capacity (hp)	230V DR (%)	460V DR (%)
0.5	88	74
1	88	86
2	88	84
3	94	85
5	96	93
7.5	85	81
10	85	77
15–30	80	80

#### Continuous rated current for light load





# **IronHorse ACG Series Selection Specifications**

				ACG <u>230</u>	V Class	Specifica	tions; Fr	ame Size	es A–F			
Par	t Number			ACG-20P5	ACG-21P0	ACG-22P0	ACG-23P0	ACG-25P0	ACG-27P5	ACG-2010	ACG-2015	ACG-2020
Pric	се			\$164.00	\$173.00	\$184.00	\$192.00	\$234.00	\$366.00	\$414.00	\$876.00	\$997.00
Fra	me Size			,	A	E	3	С	[	)	E	F
Dra	wing Link			PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF	PDF
_	Heavy Load (HD	1	hp	0.5	1.0	2.0	3.0	5.0	7.5	10	15	20
Moto	neavy Luau (nu	)	kW	0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15
Applied Motor	Normal Load (N	וח	hp	1.0	2.0	3.0	5.0	7.5	10	15	20	25
Арр	NOTHIAI LUAU (N	U)	kW	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5
	Rated	HD	kVA	1.0	1.9	3.0	4.2	6.5	9.1	12.2	17.9	22.9
	Capacity	ND	kVA	1.2	2.3	3.8	4.6	6.9	11.4	15.2	21.3	26.7
	Rated Current-3ph	HD	A	2.5	5.0	8.0	11.0	17.0	24.0	32.0	47	60
	input	ND	A	3.1	6.0	9.6	12.0	18.0	30.0	40.0	56	70
	Rated Current -1ph input	HD	A	1.5	2.8	4.6	6.1	9.3	12.8	17.4	26.8	34
	(60Hz)	ND	A	2.0	3.6	5.9	6.7	9.8	16.3	22.0	31	38
_	Rated Current -1ph input	HD	A	1.5	2.7	4.5	5.9	9.1	12.4	16.9	26	33.1
ating	(50Hz)	ND	A	1.9	3.5	5.7	6.5	9.5	15.8	21.3	30	36.9
Output Rating	Output Frequen	су	Hz				0-400 Hz (	(IM Sensorless:	0-120 Hz)			
Out	Output Voltage		V				3-	phase 200-240	V			
	Input Voltage-3	ph input	V		3-phase 200-240 VAC (-15% to +10%)							
	Input Voltage-1	ph input	V				1-phase	240VAC (-5%	to +10%)			
	Input Frequency—3ph input Hz							50-60 Hz (±5%	)			
Rating	Input Frequency–1ph input		Hz					60Hz (±5%)				
ıt Ra	Rated Current -1 or 3ph	HD	A	2.2	4.9	8.4	11.8	18.5	25.8	34.9	53.2	68.4
Input	input	ND	A	3.0	6.3	10.3	13.1	19.4	32.7	44.2	63.8	79.8
We	ight (lb [kg])			2.29 [1.04]	2.34 [1.06]	3.0 [1.36]	3.09 [1.4]	4.17 [1.89]	6.79 [3.08]	7.08 [3.21]	10.7 [4.84]	16.8 [7.6]
Cod	Cooling Method Forced Fan											

- The standard motor capacity is based on a standard 4-pole motor. The standard used for 230V drives is based on a 220V supply voltage.
- The rated output current is limited based on the carrier frequency set at Cn.4.

  The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5–5 hp models only).
- For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.



ACG-20P5



ACG-2020



# **IronHorse ACG Series Selection Specifications**

		A	CG <u>460</u> '	<u>V</u> Class Spec	ifications; Fra	me Sizes A–C		
Part I	Number			ACG-40P5	<u>ACG-41P0</u>	ACG-42P0	<u>ACG-43P0</u>	<u>ACG-45P0</u>
Price				\$175.00	\$183.00	\$192.00	\$202.00	\$228.00
Frame Size A A B B					В	С		
Drawi	ng Link			<u>PDF</u>	PDF	PDF	PDF	PDF
	Heavy Load (HD)		hp	0.5	1.0	2.0	3.0	5.0
Moto	neavy Load (HD)		kW	0.3	0.75	1.5	2.2	4.0
Applied Motor	Normal Load (ND)		hp	1.0	2.0	3.0	5.0	7.5
Арр	Normal Load (ND)		kW	0.75	1.5	2.2	4.0	5.5
	Dated Consoits	HD	kVA	1.0	1.9	3.0	4.2	6.5
	Rated Capacity	ND	kVA	1.5	2.4	3.9	5.3	7.6
	Rated Current-3ph	HD	A	1.3	2.5	4.0	5.5	9.0
	input	ND	А	2.0	3.1	5.1	6.9	10.0
	Rated Current	HD	A	0.7	1.4	2.1	2.8	4.9
	–1ph input (60Hz)	ND	A	1.3	1.9	2.8	3.6	5.4
	Rated Current	HD	A	0.7	1.4	2.0	2.7	4.8
ating	–1ph input (50Hz)	ND	A	1.3	1.8	2.7	3.5	5.2
Output Rating	Output Frequency		Hz		0-400	Hz (IM Sensorless: 0-12	20 Hz)	
Out	Output Voltage		V			3-phase 380-480 V		
	Input Voltage-3ph ii	nput	V		38	0-480 VAC (-15% to +10	%)	
	Input Voltage-1ph ii	nput	V			480VAC (-5% to +10%)		
Input Frequency—3ph input Hz						50-60 Hz (±5%)		
ting	Input Frequency–1ph input Hz					60Hz (±5%)		
Input Rating	Rated Current –1	HD	A	1.1	2.4	4.2	5.9	9.8
lub	or 3ph input	ND	A	2.0	3.3	5.5	7.5	10.8
Weigh	t (lb [kg])			2.25 [1.02]	2.34 [1.06]	3.09 [1.4]	3.13 [ 1.42]	4.23 [1.92]
Coolin	g Method					Forced Fan		

- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 460V drives is based on a 440V supply voltage.
- The rated output current is limited based on the carrier frequency set at Cn.4.
- The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5–5 hp models only).
- For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.



ACG-40P5



ACG-43P0



# **IronHorse ACG Series Selection Specifications**

		A	CG <u>460</u>	<u>V</u> Class Spo	ecifications	Frame Size	es D–F			
Part I	Number			ACG-47P5	ACG-4010	ACG-4015	ACG-4020	ACG-4025	ACG-4030	
Price				\$326.00	\$348.00	\$960.00	\$1,043.00	\$1,156.00	\$1,224.00	
Frame	e Size			D E F						
Drawi	ing Link			PDF PDF PDF PDF PDF					PDF	
B Heavy Load (HD)		hp	7.5	10	15	20	25	30		
Applied Motor	Incavy Luau (IID)		kW	5.5	7.5	11	15	18.5	22	
lied	Normal Load (ND)		hp	10	15	20	25	30	40	
Арр	Normai Loau (ND)		kW	7.5	11	15	18.5	22	30	
	Rated Capacity	HD	kVA	9.1	12.2	18.3	23.6	29.7	34.3	
	nateu Capacity	ND	kVA	12.2	17.5	23.6	29.0	34.3	46.5	
	Rated Current-3ph	HD	A	12.0	16.0	24	31	39	45	
	input	ND	A	16.0	23.0	31	38	45	61	
	Rated Current	HD	A	6.4	8.7	15	18	23	27	
	-1ph input (60Hz)	ND	A	8.7	12.6	18	23	27	35	
_	Rated Current	HD	A	6.2	8.5	14.6	17.4	22.3	26.2	
Output Rating	-1ph input (50Hz)	ND	A	8.4	8.4 12.2 17.4 22.2 26.1 33.					
out F	Output Frequency		Hz			0-400 Hz (IM Sen	sorless: 0-120 Hz)			
Out	Output Voltage		V			3-phase 3	380-480 V			
	Input Voltage-3ph i	nput	V			380-480 VAC (	-15% to +10%)			
	Input Voltage-1ph i	nput	V			480VAC (-5	% to +10%)			
	Input Frequency-3p	h input	Hz			50-60 H	z (±5%)			
ting	Input Frequency-1p	h input	Hz			60Hz	(±5%)			
Input Rating	Rated Current -1	HD	A	12.9	17.5	27.2	35.3	44.5	51.9	
lub	or 3ph input	ND	A	17.5	25.4	35.3	43.3	51.9	70.8	
Weigh	nt (lb [kg])			6.79 [3.08]	6.88 [3.12]	10.8 [4.89]	10.8 [4.91]	16.8 [7.63]	16.9 [7.65]	
Coolin	Cooling Method Forced Fan					Force				

- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 460V drives is based on a 440V supply voltage.
- The rated output current is limited based on the carrier frequency set at Cn.4.
- The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5–5 hp models only). For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.



ACG-47P5



ACG-4030 **Ironhorse AC Drives** 



# **IronHorse ACG Series General Specifications**

## **ACG General Specifications**

	Control Meti	hod	V/F control, Slip Compensation, Sensorless Vector				
ristics		ettings Power	Digital command: 0.01 Hz Analog command: 0.06 Hz (60Hz standard)				
acte	Frequency A	ccuracy	1% of maximum output frequency				
Char	V/F Pattern		Linear, square reduction, user V/F				
Control Characteristics	Overload Ca	pacity	Heavy load rated current: 150% for 1 minute Normal load rated current: 120% for 1 minute				
_	Torque Boos	t	Manual torque boost, automatic torque boost				
	Operation Ty	уре	Select key pad, terminal strip, or communication op	peration			
	Frequency S	Cetting Signal	Analog type: -10~10 V, 0~10 V, 4~20 mA, keypad b Digital type: keypad	ouilt-in potentiometer dial			
Operation Characteristics	Main Functions		PID control  - 3-wire operation  Frequency limit  Second motor function  Anti-forward and reverse direction rotation  Commercial transition  Speed search  Power braking  - Up-down operation	DC braking Frequency jump Slip compensation Automatic restart Automatic tuning Energy buffering Flux braking Fire mode			
			Select PNP (Source) or NPN (Sink) mode. Functions can be set according to In.65–In.69 codes and parameter sett				
	Multi-function Terminal (5) P1-P5		Forward direction operation     Reset     Emergency Stop     Multi-step speed frequency-high/med/low     DC braking during stop     Frequency increase     3-wire     Select acc/dec/stop	Reverse run External trip Jog operation Multi-step acc/dec-high/med/low Second motor selection Frequency reduction Fix analog command frequency Transition from PID to general operation			
		Analog Input (2)	-10 to 10 V, 0-10 V, 4-20 mA, Speed or PID control	ol .			
	Output	Multi-function relay terminal (2)	Fault output and drive operation status output	Less than (N.O., N.C.) 250VAC, 1A Less than 30VDC 1A			
	,	Analog Output (1)	0-12 VDC: Select frequency, output current, output	voltage, DC terminal voltage and others			
Protection Function Characteristics	Trip		Overcurrent trip  External signal trip  ARM short circuit current trip  Overheat trip  In phase open trip  Ground trip  Motor overheat trip  I/O board link trip  No motor trip  Parameter writing trip  Emergency stop trip  Command loss trip  External memory error  CPU watchdog trip  Motor light load trip	Overvoltage trip Temperature sensor trip Drive overheat Option trip Out phase open trip Drive overload trip Fan trip Pre-PID operation failure External break trip Low voltage trip during operation Low voltage trip Analog input error Motor overload trip Over-torque trip Under-torque trip			
Pro	Alarm			d alarm, drive overload alarm, fan operation alarm, resistance braking rror, drive pre-overheat alarm, over-torque alarm, under-torque alarm			
	Instantaneo	us Blackout	Heavy load less than 15ms (normal load less than theavy load more than 15ms (normal load more than	8ms): must be within the rated input voltage and rated output range n 8ms): auto-restart operation			
	unication Card		EtherNet/IP and Modbus TCP (ACG-ET2)				



# **IronHorse ACG Series General Specifications**

## **ACG Environmental Specifications**

Envir	onmental Conditions for IronHorse ACG Series AC Drives
Installation Location	Mount the drive on a wall or inside a panel. Not suitable for use in direct sunlight.
Cooling	Forced fan cooling structure Forced cooling type: 1/2–15 hp 230V/1/2–30 hp 460V (excluding some models)
Operating Ambient Temperature	Heavy Load (HD): -10 to 50°C (14 to 122°F) Normal Load (ND): -10 to 40°C (14 to 104°F)
Storage Temperature*	-20° to 65°C (-4 to 149°F)
Relative Humidity	Less than 95% (to avoid condensation)
Air Pressure	70 to 106 kPa
Pollution Level	Pollution level 3 environment: Prevent contact with corrosive gases, inflammable gases, oil stains, dust, and other pollutants.
Altitude	No higher than 3280ft (1000m). From 1000 to 4000m, the rated input voltage and rated output current of the drive must be derated by 1% for every 100m.
Vibration	Less than 9.8 m/sec <sup>2</sup> (1G)
Installation Orientation	Max allowed offset angle = 0 degrees. (Vertical orientation only).  Do not install the drive on the floor or mount it sideways against a wall. The drive MUST be installed vertically, on a wall or inside a panel, with its back flat on the mounting surface.

<sup>\*</sup> The ambient temperature is the temperature measured at a point 2" (5 cm) from the surface of the drive.

## **ACG Watt Loss and Efficiency**

		IronHor	se ACG Wa	tt Loss and	<b>Efficiency</b>		
Model Number	Voltage	Rated Power (hp) [kW]	Efficiency (%)	Total Losses (W)	Internal Losses (W)	External (Heat) Losses (W)	Heat Losses (Kcal)
ACG-20P5		1/2 [0.4]	96.40	18.4	16.8	1.6	1.4
ACG-21P0		1 [0.8]	96.40	36.8	16.8	20.0	17.2
ACG-22P0		2 [1.5]	96.70	64.5	17.4	47.1	40.5
ACG-23P0		3 [2.2]	96.70	94.6	17.4	77.2	66.4
ACG-25P0	230	5 [4]	96.80	168.0	17.7	150.3	129.2
ACG-27P5		7 [5.5]	96.90	225.5	18.7	206.8	177.8
ACG-2010		10 [7.5]	96.90	307.5	18.7	288.8	248.3
ACG-2015		15 [11]	97.71	362.5	23.8	338.7	291.2
ACG-2020		20 [15]	97.89	466.8	38.2	428.6	368.6
ACG-40P5		1/2 [0.4]	96.00	20.0	17.4	2.6	2.3
ACG-41P0		1 [0.8]	96.80	33.6	17.4	16.2	14.0
ACG-42P0		2 [1.5]	97.30	55.5	17.7	37.8	32.5
ACG-43P0		3 [2.2]	97.50	77.0	17.7	59.3	51.0
ACG-45P0		5 [4]	97.60	136.0	18.7	117.3	100.8
ACG-47P5	460	7 [5.5]	97.80	176.0	19.7	156.3	134.4
ACG-4010		10 [7.5]	97.80	240.0	19.7	220.3	189.4
ACG-4015		15 [11]	98.50	274.7	23.8	250.9	215.8
ACG-4020		20 [15]	98.35	397.4	23.8	373.6	321.3
ACG-4025		25 [18.5]	98.55	454.0	38.2	415.8	357.6
ACG-4030		30 [22]	98.65	517.0	38.2	478.8	411.8

This watt loss and efficiency data were measured under the following test conditions:

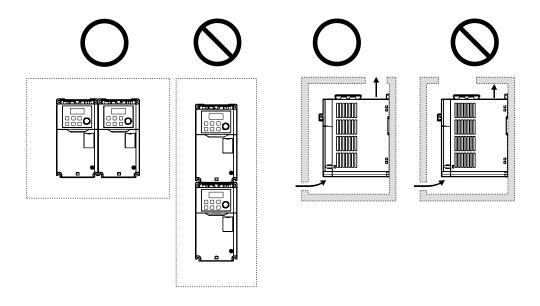
- · Operation at 60Hz and room temperature
- 100% load
- Carrier Frequency (Default value)

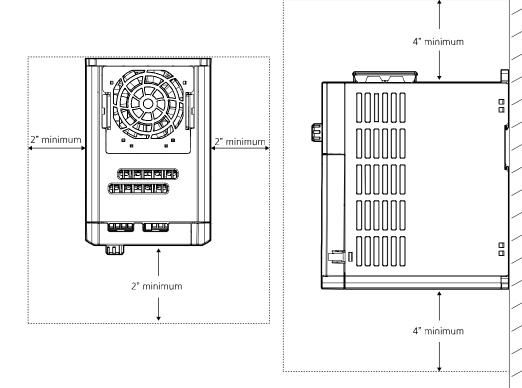


# **IronHorse ACG Series Mounting Clearances**

## **ACG Mounting Clearances**

Ensure sufficient air circulation is provided around the drive when it is installed. If the drive is to be installed inside a panel, enclosure, or cabinet rack, carefully consider the position of the drive's cooling fan and the ventilation louver. Cooling fans must be positioned to efficiently transfer the heat generated by the operation of the drive.

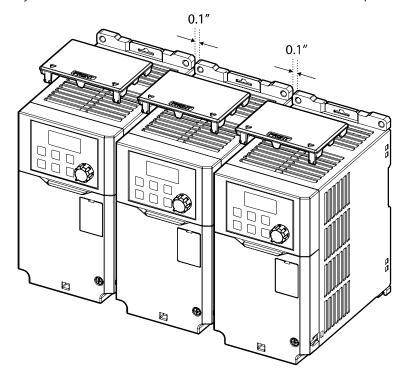




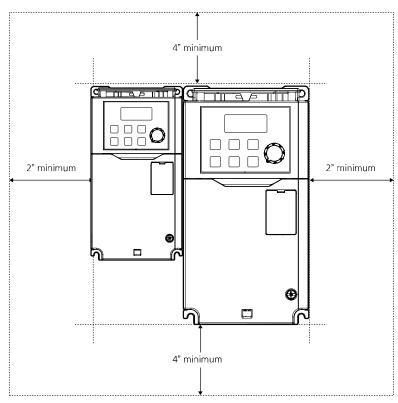


# **IronHorse ACG Series Mounting Clearances**

If you are installing multiple drives in one location, arrange them side-by-side and remove the top covers. The top covers MUST be removed for side-by-side installations. Use a flat-head screwdriver to remove the top covers.



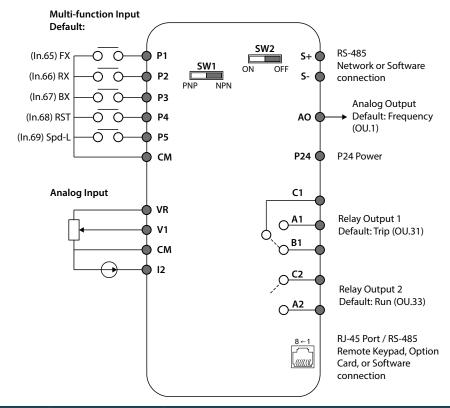
If you are installing multiple drives of different ratings, provide sufficient clearance to meet the clearance specifications of the larger drive.





# IronHorse ACG Series I/O Diagram

# ACG System I/O Diagram

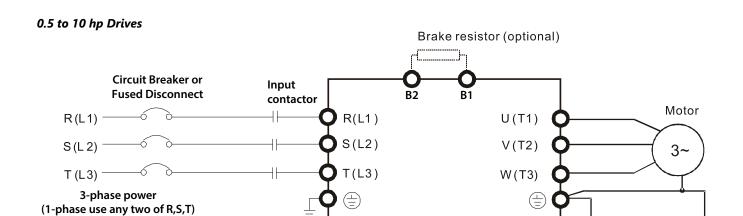


			I/O Details
Function	Label	Name	Description
Multi-function Digital Input Terminal Configuration	P1–P5	Multi-function Input 1-5	Configurable for multi-function input terminals. Factory default terminals and setup are as follows:  • P1: FX (Forward Run)  • P2: RX (Reverse Run)  • P3: BX (Block)  • P4: RST (Reset)  • P5: Speed-L
	CM	Common Sequence	Common terminal for terminal input, RS-485 communication, and analog terminal inputs and outputs.
	VR	Potentiometer frequency reference input	Used to setup or modify a frequency reference via analog voltage or current input.  • Maximum Voltage Output: 12V  • Maximum Current Output: 100mA  • Potentiometer: 1–5kΩ
Analog Input Configuration	V1	Voltage input for control reference	Used to setup or modify a frequency reference via analog voltage input terminal.  • Unipolar: 0–10V (12V Max.)  • Bipolar: -10–10V (±12V Max.)
	12	Voltage/current input for control reference	Used to setup or modify a frequency reference via the I2 terminal.  Input current: 4–20mA  Maximum Input current: 20mA  Input resistance: 249Ω
Analog Output	AO	Voltage/Current Output	Used to send inverter output information to external devices: output frequency, output current, output voltage, or a DC voltage.  • Output voltage: 0–10V  • Maximum output voltage/current: 12V/10mA  • Factory default output: Frequency
	24	Internal 24V power source	Maximum output current: 100mA
Digital Relay Output	A1/C1/B1	Fault signal output 1	Sends out alarm signals when the inverter's safety features are activated (250VAC <1A, 30VDC < 1A).  • Fault condition: A1 and C1 contacts are connected (B1 and C1 open connection)  • Normal operation: B1 and C1 contacts are connected (A1 and C1 open connection)
	A2/C2	Fault signal output 2	Sends out alarm signals when the inverter's safety features are activated (250VAC <1A, 30VDC < 1A).  • Fault condition: A2 and C2 contacts are open connection  • Normal operation: A2 and C2 contacts are connected
Communication	S+/S-	RS-485 signal line	Used for network or software connection
Communication	RJ45 Port	RS-485 signals	Remaote keypad, option card, or software connection

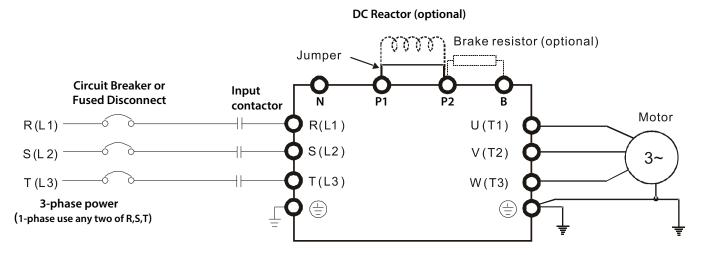


# **IronHorse ACG Series Basic Wiring**

## **Main Circuit Wiring Diagram**



#### 15 to 30 hp Drives



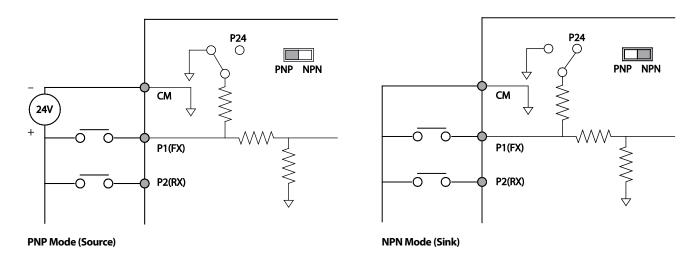
	Power Terminal Labels and Descriptions						
Function	Name	Description					
R(L1)/S(L2)/T(L3)	AC power input terminal	Mains supply AC power connections.					
P2(+)/N(-)	DC input terminal	DC voltage terminals for 15-30 hp drives.					
P1(+)/P2(+)	DC reactor terminal	DC reactor wiring connection for 15-30 hp drives. (Remove the short-bar when you use the DC reactor).					
B1/B2 (0.5 to 10 hp)	Brake resistor	Darle saide side a side a side					
P2(+)/B (15 to 30 hp)	terminals	Brake resistor wiring connection.					
U/V/W	Motor output terminals	3-phase AC motor wiring connections.					



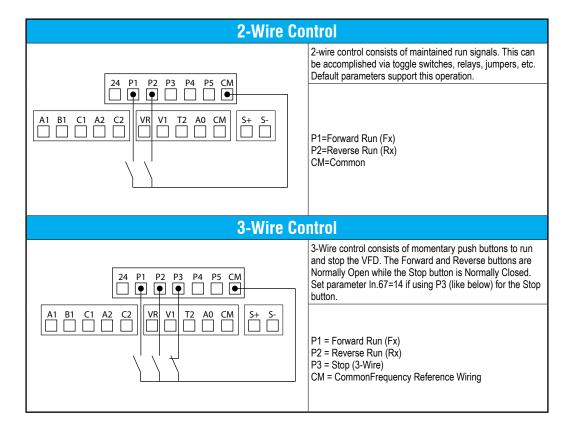
# **IronHorse ACG Series Basic Wiring**

## **Control Circuit Wiring Diagram: Digital Inputs**

Select PNP using the PNP/NPN selection switch (SW1). Note that the factory default setting is NPN mode. CM is the common ground terminal for all analog inputs at the terminal, and P24 is 24V internal source. If you are using an external 24V source, build a circuit that connects the external source (-) and the CM terminal.



#### 2 and 3 Wire Control

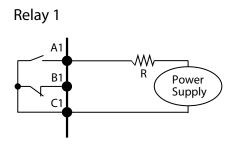


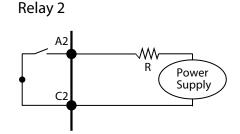


# **IronHorse ACG Series Basic Wiring**

## **Digital Output Relay Wiring**

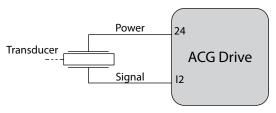
NOTE: Ensure device current does not exceed 1A.



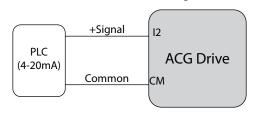


## 4-20mA Analog Input Wiring

**Transducer (4-20mA)**: Transducers are typically 4-20mA devices which require a 24VDC power source. For 2-wire transducers connect to the 24VDC and 4-20mA input terminals listed below. Connect the positive lead of the device to the 24V terminal and the signal lead to the analog input terminal (I2).

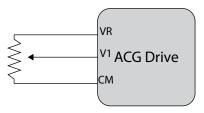


**PLC (4-20mA)**: The wiring for connecting a PLC's 4-20mA output to the analog input of a VFD differs slightly from the transducer wiring discussed above. The positive (signal) lead is wired to the corresponding analog input while the negative (common) lead is wired to the drives common. Reference the figure below.

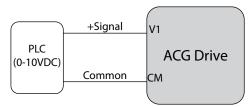


## 0-10VDC Analog Input Wiring

**Speed POT/Rheostat (0-10VDC)**: Speed potentiometers have three wires which must be connected to properly vary a 0-10VDC signal. The required terminal connections will vary slightly depending on the drive series. Reference the figure below. The wiper of the speed POT should always be connected to the analog input.

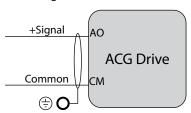


**PLC (0-10VDC)**: The wiring for connecting a PLC's 0-10VDC output to the analog input of a VFD differs slightly from the speed POT wiring discussed above. The positive (signal) lead is wired to the corresponding analog input while the negative (common) lead is wired to the drives common. Reference the figure below.



## **AO Wiring**

Wire the drive analog out as follows:





### **Accessories Available for ACG Drives**

ACG Drives Available Software and Accessories						
Accessory	Reference					
Ethernet Module: ACG-ET2	ACG Ethernet Module on page tIHA-16					
Conduit Boxes: ACG-N1A – ACG-N1F	ACG Conduit Boxes on page tlHA-17					
Remote Keypad: ACG-KPD	Remote Keypad on page tIHA-18					
Replacement Fans: ACG-FAN-A – ACG-FAN-FR45	Replacement Fans on page tIHA-19					
Fuses/Circuit Breakers	Fuses/Circuit Breakers on page tlHA-20					
EMI Filters	High Performance EMI Input Filters on page tlHA-21					
Braking Resistors	Braking Resistors on page tIHA-23					
Line Reactors/Voltage Time Filters	Line Reactors/Voltage Time Filters on page tIHA-22					
VFD Suite	VFD Suite on page tlHA-47					



### **ACG Ethernet Module**

The ACG-ET2 is an option module for connecting any ACG series drive to an ethernet network. The module supports both the EtherNet/IP and Modbus TCP protocols.

	ACG Ethernet Module							
Part Number	Price	Description						
ACG-ET2	\$105.00	IronHorse ACG series communication module, EtherNet/IP and Modbus TCP, 2 ports, (2) Ethernet (RJ45) and (1) RS-485 (RJ45) port(s). For use with IronHorse ACG series AC drives. Mounting hardware included.						



ACG-ET2





### **ACG Conduit Boxes**

The ACG conduit boxes allow conversion of the ACG drive to a NEMA1 rating.

ACG Conduit Boxes							
Part Number	Price	Description	Drawing Links				
ACG-N1A	\$39.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series A frame AC drives.  Mounting hardware included.	PDF				
ACG-N1B	\$40.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series B frame AC drives.  Mounting hardware included.	PDF				
ACG-N1C	\$43.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series C frame AC drives.  Mounting hardware included.	PDF				
ACG-N1D	\$47.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series D frame AC drives.  Mounting hardware included.	PDF				
ACG-N1E	\$69.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series E frame AC drives.  Mounting hardware included.	PDF				
ACG-N1F	\$75.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series F frame AC drives.  Mounting hardware included.	PDF				



ACG-N1A



## Remote Keypad

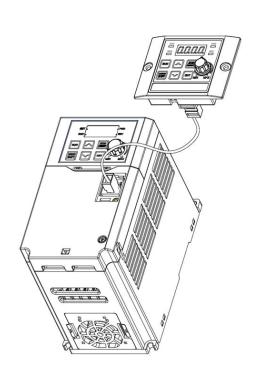
The ACG-KPD keypad allows for remote mounting of the standard keypad functionality for the ACG series drives.

The keypad can be mounted on an external panel or enclosure and connected to the drive by standard ethernet patch cable.

	ACG Remote Keypad						
Part Number	Price	Description	Drawing Links				
ACG-KPD	\$45.00	IronHorse ACG series remote keypad, for use with IronHorse ACG series AC drives. (1) 16.4ft/5m Ethernet patch cable included.	PDF				



**ACG-KPD** 





## **Replacement Fans**

The ACG-FAN-xxxx fans are replacement kits for the ACG drive fan(s) that comes installed with the drive.

ACG Replacement Fans								
Part Number	Price	Description	Drawing Links					
ACG-FAN-A	\$9.00	IronHorse ACG series main cooling fan, replacement, 40 x 40 x 15mm, 24 VDC. For use with ACG series 1/2hp - 1hp AC drives.	<u>PDF</u>					
ACG-FAN-BC	IronHorse ACG series main cooling fan, replacement, 60 x 60 x 25mm, 24 VDC. For use with ACG series 2hp - 5hp AC drives.							
ACG-FAN-D	\$20.00	IronHorse ACG series main cooling fan, replacement, 60 x 60 x 25mm, 24 VDC. For use with ACG series 7-1/2hp - 10hp AC drives.	PDF					
ACG-FAN-E15	\$38.00	IronHorse ACG series main cooling fan, replacement, 80 x 80 x 25mm, 24 VDC. For use with ACG series 15hp AC drives.	PDF					
ACG-FAN-E20F	\$50.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 20hp - 30hp AC drives.	<u>PDF</u>					



**ACG-FAN-A** 



**ACG-FAN-BC** 







ACG-FAN-E20F

www.automationdirect.com Ironho



### **Fuses/Circuit Breakers**

Protection devices are essential to prevent damage to your ACG drive and application equipment. Please use the fuse specification chart below to select fuses that are applicable to your ACG drive. Only use UL-certified 600V fuses which comply with your local regulations.

Drive	Drive Voltage	HP (CT)	Fuse Amps (Class H or	Suggested ADC Class	Circuit Breaker		
DIIVE	Dilve vollage	III (CI)	RK5)	RK5 Fuses	Size	Model*	
ACG-20P5		0.5	10	ECSR10	15		
ACG-21P0		1	10	ECSR10	15		
ACG-22P0		2	15	ECSR15	15	UTE100H	
ACG-23P0		3	20	ECSR20	20		
ACG-25P0	200-240	5	30	ECSR30	30		
ACG-27P5	]	7.5	50	ECSR50	50		
ACG-2010		10	60	ECSR60	60	LITOAFOLI	
ACG-2015		15	80	ECSR80	80	UTS150H	
ACG-2020		20	100	ECSR100	100		
ACG-40P5		0.5	10	ECSR10	3.2		
ACG-41P0		1	10	ECSR10	6.3		
ACG-42P0		2	10	ECSR10	12		
ACG-43P0		3	15	ECSR15	12		
ACG-45P0		5	20	ECSR20	20		
ACG-47P5	380-480	7.5	30	ECSR30	32	UTS150L	
ACG-4010		10	35	ECSR35	32		
ACG-4015		15	50	ECSR50	50		
ACG-4020		20	60	ECSR60	60		
ACG-4025		25	70	ECSR70	70		
ACG-4030		30	100	ECSR100	90		

<sup>\*</sup> Manufactured by LS Electric. Not available at AutomationDirect.com

CAUTION: ONLY USE 600V CLASS H OR RK5, UL LISTED INPUT FUSES AND UL LISTED CIRCUIT BREAKERS. SEE THE TABLE ABOVE FOR THE CURRENT RATINGS FOR FUSES AND CIRCUIT BREAKERS.



MAXIMUM ALLOWED PROSPECTIVE SHORT-CIRCUIT CURRENT AT THE INPUT POWER CONNECTION IS DEFINED IN IEC 60439-1 AS 100 KA. DEPENDING ON THE SELECTED MCCB, THE ACG SERIES IS SUITABLE FOR USE IN CIRCUITS CAPABLE OF DELIVERING A MAXIMUM OF 100 KA RMS SYMMETRICAL AMPERES AT THE DRIVE'S MAXIMUM RATED VOLTAGE. THE FOLLOWING TABLE SHOWS THE RECOMMENDED MCCB FOR RMS SYMMETRICAL AMPERES.



## **High Performance EMI Input Filters**

The optional accessories below are available for use with the ACG drive. Selection of these accessories is application specific and may improve drive performance. Additional information regarding filter installation and operation is available in the AutomationDirect white paper, "Applied EMI/RFI Techniques."

Drive	Drive Voltage	HP (HD)	Roxburgh Filters Chassis Type 1ph *1	Roxburgh High Performance Filters *2	Roxburgh Max Performance Filters *3
ACG-20P5		0.5	RES90F03	KMF306A	MIF310
ACG-21P0		1	RES90F10	<u>KMF310A</u>	MIF310
ACG-22P0		2	RES90F16	KMF318A	MIF316
ACG-23P0		3	RES90F16	KMF318A	MIF316
ACG-25P0	200-240	5	RES90S20	KMF325A	MIF323
ACG-27P5		7.5	-	KMF336A	MIF350
ACG-2010		10	-	KMF350A	MIF350
ACG-2015		15	-	<u>KMF370A</u>	<u>MIF375</u>
ACG-2020		20	1	KMF3100A	MIF3100
ACG-40P5		0.5	1	<u>KMF306A</u>	MIF310
ACG-41P0		1	1	<u>KMF306A</u>	MIF310
ACG-42P0		2	-	<u>KMF306A</u>	<u>MIF310</u>
ACG-43P0		3	-	<u>KMF310A</u>	MIF310
ACG-45P0		5	-	<u>KMF318A</u>	<u>MIF316</u>
ACG-47P5	380-480	7.5	1	<u>KMF318A</u>	MIF323
ACG-4010		10	1	<u>KMF336A</u>	MIF330B
ACG-4015		15	-	<u>KMF336A</u>	MIF350
ACG-4020		20	-	<u>KMF350A</u>	MIF350
ACG-4025		25	-	<u>KMF350A</u>	MIF350
ACG-4030		30	-	KMF370A	MIF375

<sup>\*1 -</sup>EMI rating for motor cable length: C2 to 75Ft, C1 to 30ft

<sup>\*2 -</sup>EMI rating for motor cable length: C2 to 150Ft, C1 to 75ft

<sup>\*3 -</sup>EMI rating for motor cable length: C2 to 300Ft, C1 to 150ft



## **Line Reactors/Voltage Time Filters**

Installing an AC Line Reactor on the input side of an AC motor drive can increase line impedance, improve the power factor, reduce input current, increase system capacity, and reduce interference generated from the motor drive.

Installing a load reactor or voltage time filter on the drive's output side can increase the high-frequency impedance to reduce the dV/dT and terminal voltage to protect the motor. Use output filters if the motor cable length exceeds 100ft or any applications where reduced reflected waves is needed.

				ine/Lo	ad Rea	ctors &	AC Outp	ut Filter:	S				
				Output	AC Input Line Reactor		AC Output Load Reactor		AC dVdT Output Filter**		DC reactor		
Drive	Drive Voltage	Voltage HP	oltage HP	HP	(Amps)	FLA 3ph (Amps)	3ph	1ph	3ph	1ph	3ph	1ph	values Induct./ Current
ACG-20P5		0.5	2.2	2.5	LR2-20P5	LR2-20P2	LR2-20P5	LR2-20P2	<u>VTF-246-CFG</u>	VTF-46-DE			
ACG-21P0		1	4.9	5.0	LR2-21P0	LR2-21P0	LR2-21P0	LR2-20P5	<u>VTF-24-FH</u>	<u>VTF-246-CFG</u>			
ACG-22P0		2	8.4	8.0	LR-23P0	LR-25P0	LR2-22P0	LR2-22P0	VTF-246-GJJ	<u>VTF-24-FH</u>			
ACG-23P0		3	11.8	11.0	LR-23P0	LR-23P0	LR2-22P0	LR2-22P0	<u>VTF-4-M</u>	VTF-246-GJJ	*		
ACG-25P0	200-240	5	18.5	17.0	LR-25P0	LR-2010	LR-25P0	LR2-22P0	<u>VTF-46-LM</u>	VTF-246-HKL	J		
ACG-27P5		7.5	25.8	24.0	LR-2010	LR-2015	LR-27P5	LR-25P0	VTF-246-KMN	VTF-24-JL	_		
ACG-2010		10	34.9	32.0	LR-2015	LR-2020	LR-2010	LR-25P0	VTF-246-LPQ	VTF-46-LM			
ACG-2015		15	53	47	LR-2020	LR-2030	LR-2015	LR-2010	VTF-246-NRS	VTF-46-NP	0.95/61		
ACG-2020		20	68	60	LR-2025	LR-2040	LR-2020	LR-2010	<u>VTF-246-PSU</u>	VTF-246-LPQ	0.70/75		
ACG-40P5		0.5	1.1	1.3		LR2-	40P5		VTF-4	<u>16-DE</u>			
ACG-41P0		1	2.4	2.5		LR2-	41P0		<u>VTF-24</u>	<u>l6-CFG</u>	_		
ACG-42P0		2	4.2	4.0		LR2-	42P0		<u>VTF-24</u>	6-DGH			
ACG-43P0		3	5.9	5.5		LR2-	43P0		VTF-2	<u>24-FH</u>	*		
ACG-45P0		5	9.8	9.0		LR2-	45P0		VTF-4	16-DE			
ACG-47P5	380-480	80-480 7.5 12.9 12.0 <u>LR2-47P5</u>			VTF-46-DE								
ACG-4010		10	17.5	16.0		LR-	<u>4010</u>		VTF-	24-JL			
ACG-4015		15	27	24		LR-	<u>4015</u>		<u>VTF-24</u>	6-KMN	1.90/32		
ACG-4020		20	35	31	LR-4020 VTF-246-LPQ		16-LPQ	1.40/41					
ACG-4025		25	44	39		LR-	<u>4025</u>		<u>VTF-24</u>	6-MQR	1.00/49		
ACG-4030		30	51	45		LR-	4030		<u>VTF-24</u>	0.70/64			

<sup>\*</sup> Only drives from 11-22 kW support DC reactors.

<sup>\*\*</sup> NEMA1 filter versions are available. Use same PN with suffix -N1.



## **Braking Resistors**

Dynamic braking absorbs the motor regeneration energy when the motor is decelerated faster than it would if it was allowed to coast to a stop. The regeneration energy is dissipated by braking resistors. All drives have the braking function built-in and do not require a separate dynamic braking unit. The recommended open type or NEMA 1 type brake resistors available at AutomationDirect for each drive model are listed in the table below.

	Brake Resistors												
			Drive Braki	ng Capacity-M	ax Torque	150% Braking Torque @ 5% Duty Cycle							
Voltage	Drive	Drive Power	8.07 - 7	Max Total	Peak	Open Type I	Resis	tors	NEMA1 Resistors with Thermal Switch				
Voltage	Dilve	(HP)	Minimum Resistor	Brake Current (A)	Power (kW)	ADC Part Number	Qty	Total Brake Current (A)	ADC Part Number	Qty	Total Brake Current (A)		
	ACG-20P5	0.5	250.0	1.6	0.6	GS-BR-300W250	1	1.6	BR-N1-240W250	1	1.6		
	ACG-21P0	1	150.0	2.6	1.0	GS-BR-400W150	1	2.6	BR-N1-240W150	1	2.6		
	ACG-22P0	2	50.0	7.8	3.0	GS-BR-300W070	1	5.6	BR-N1-280W50	1	7.8		
	ACG-23P0	3	43.0	9.1	3.5	GS-BR-1K5W043	1	9.1	<u>BR-N1-720W50</u>	1	7.8		
230	ACG-25P0	5	25.0	15.6	6.1	GS-BR-1K2W015	2S	13.0	BR-N1-800W25	1	15.6		
	ACG-27P5	7.5	18.0	21.7	8.5	<u>GS-BR-1K0W020</u>	1	19.5	BR-N1-800W18P0	1	21.7		
	ACG-2010	10	14.0	27.9	10.9	GS-BR-1K2W015	1	26.0	BR-N1-1K5W14P0	1	27.9		
	ACG-2015	15	8.6	45.3	17.7	GS-BR-1K5W012	1	32.5	BR-N1-2K2W08P6	1	45.3		
	ACG-2020	20	8.0	48.8	19.0	GS-BR-1K2W015	2P	52.0	BR-N1-2K2W08P6	1	45.3		
	ACG-40P5	0.5	400.0	2.0	1.5		1		BR-N1-250W400	1	2.0		
	ACG-41P0	1	400.0	2.0	1.5	GS-BR-300W400	1	2.0	<u>DN-N1-230W400</u>	1	2.0		
	ACG-42P0	2	250.0	3.1	2.4		1		BR-N1-240W250	1	3.1		
	ACG-43P0	3	180.0	4.3	3.4	GS-BR-200W360	2P	4.3	BR-N1-500W200	1	3.9		
	ACG-45P0	5	85.0	9.2	7.2	GS-BR-300W250	2P	6.2	BR-N1-720W85	1	9.2		
460	ACG-47P5	7.5	75.0	10.4	8.1	<u>GS-BR-1K0W075</u>	1	10.4	<u>BR-N1-1K2W75</u>	1	10.4		
	ACG-4010	10	49.0	15.9	12.4	GS-BR-1K5W043	1	18.1	BR-N1-1K2W50	1	15.6		
	ACG-4015	15	40.0	19.5	15.2		1	18.1	BR-N1-1K5W40	1	19.5		
	ACG-4020	20	22.0	35.5	27.7	GS-BR-1K5W043	2P		BR-N1-2K3W26	1	30.0		
	ACG-4025	25	20.0	39.0	30.4	<u>us-dn-1k5W043</u>	2P	36.3	BR-N1-2K8W25	1	31.2		
	ACG-4030	30	20.0	39.0	30.4		2P		<u>BR-N1-3K6W20</u>	1	39.0		

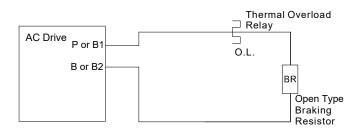
Note: Where noted on resistor quantity, S = series wiring, P = parallel wiring.

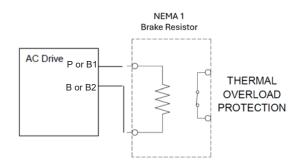


## **Brake Wiring**

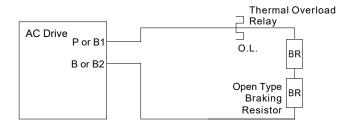
Use your drive's braking component selection table to determine the appropriate brake resistor model and configuration for your drive. Refer to the diagrams below for examples on how to wire each possible configuration.

#### Drive + 1 Resistor or NEMA1 Resistor:

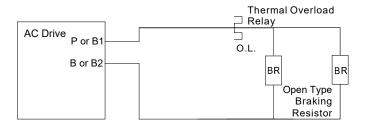




#### Drive + 2 Series Resistors



#### **Drive + 2 Parallel Resistors**





#### **VFD Suite**

VFD Suite is the configuration software for the Automation Direct Ironhorse AC family of variable frequency drives, featuring the ACG IP20 series and the ACN Nema4X series. It is designed to allow connection of a personal computer to the drives and perform a variety of functions:

- Create new drive configurations
- Upload/Download drive configurations
- Edit/Compare drive configurations
- Utilize Parameter Wizard for easy configuration
- Archive/Store multiple drive configurations on your PC
- Trend drive operation parameters
- Tune the drive PID loop
- View real time key operating parameters
- Start/Stop drive and switch directions, provided drive is set up for remote operation
- View drive faults
- Program Function blocks for simple control applications (ACN series only, 18 steps maximum)

VFD Suite includes a PDF help file for explanation of the software and features. VFD Suite can be downloaded for free from Automationdirect.com.

### **System Requirements**

Category	Requirement
Windows	Windows 8/10/11
Processor	1 GHz or higher
RAM	1 GB (32-bit) or 2 GB (64-bit)
HDD	16 GB (32-bit) or 20 GB (64-bit)
Graphics	Graphic card supporting MS DirectX 9



#### **Communication Cable**

(For ACN series drives only)



**ACN-232C** 

Communication Cable						
Part Number	Drive Compatibility					
<u>ACN-232C</u>	\$91.00	IronHorse programming/communication cable, 3.2ft/1m cable length, RS-232 (RJ45 8P8C) to USB A. For use with IronHorse ACN series drives.	ACN series drives only			