



# IronHorse ACG Series Introduction



IronHorse ACG AC Drives												
Motor Rating	HP	0.5	1.0	2.0	3.0	5.0	7.5	10.0	15.0	20.0	25.0	30.0
	kW	0.4	0.8	1.5	2.2	4.0	5.5	7.5	11.0	15.0	18.5	22.0
230V 1-Phase Input/ 230V 3-Phase Output	✓	✓	✓	✓	✓	✓	✓	✓				
230V 3-Phase Input/ 230V 3-Phase Output	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓		
460V 1-Phase Input/ 460V 3-Phase Output	✓	✓	✓	✓	✓	✓	✓	✓	✓			
460V 3-Phase Input/ 460V 3-Phase Output	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

## Overview

The Ironhorse ACG sensorless vector control AC drives provide all the features needed for a variety of applications in a compact and durable package. The drives include many of the same standard features as our DURAPulse family of drives, including dynamic braking, PID, and RS-485 Modbus communication. All 230VAC and 460VAC drives are fully capable of single-phase input capability (with de-rating) and optional EtherNet/IP and Modbus TCP communication card. The drive supports up to two (2) independent IM motor parameter sets. Ironhorse ACG AC drives offer several different control modes: V/Hz, Slip compensation, and sensorless vector. It even provides Torque limit capability. Ironhorse ACG provides either voltage or current analog input for drive control, one analog output, five digital inputs, and two relay outputs. All of the analog and digital I/O can be configured for a wide variety of input or output functions. One option card port is available for an Ethernet/IP and Modbus TCP communication option card or remote mounted keypad. Durability is enhanced through UL 61800-5-3 conformance and robust military spec design.

## Features

- Broad offering from 1/2 to 30 hp
- 230VAC: three-phase up to 20Hp, single phase up to 10hp
- 460VAC: three phase up to 30HP, single-phase up to 15hp
- Single-phase UL Ratings – 230 or 460 VAC input
- Heavy Load (Constant Torque), Normal Load (Variable Torque) ratings
- Flexible carrier frequency to 15khz
- Output frequency to 400Hz (120Hz sensorless vector)
- Built-in RJ45 port for fast & easy programming.
- Free downloadable software for drive configuration
- Local/Remote control mode selection or digital/comm input with Hand/Off/Auto control
- PCB Conformal Coating
- Meets UL 61800-5-1 standards
- 100kA Short Circuit Current Rating
- Durable MIL217Plus based design
- DC Bus Connection for 15-30 hp drives
- Analog I/O – configurable current/voltage input and 1 output
- 2-Motor Control
- Built-in Dynamic Braking – optional resistors
- KEB Operation (Kinetic Energy Buffering) - for ride through of power loss
- PID Controller – including sleep and wake
- Built-in Potentiometer
- Password protection
- High speed communication interfaces with MODBUS RTU built in, with optional EtherNet/IP and ModbusTCP Communication Card
- DIN rail mounting built in on 5hp and lower for zero stack installation.
- Able to operate at 50°C ambient temperature
- 24 month warranty
- CE, UL, cUL

## Accessories

- EtherNet/IP and ModbusTCP comm card
- AC line reactors
- dV/dT output filters
- EMI filters
- Braking resistors
- Fuses
- Remote Keypad Mount Kit
- VFD Suite drive configuration software

## Typical Applications

Suitable for most applications, including:

- Conveyors
- Fans
- Pumps
- Shop tools
- Mixer
- Crane and Hoist
- Press
- Auger
- Centrifuge
- Waste Water Rake Drive
- X-Y Positioning
- Vibratory Tables
- Synchronous Machine



# IronHorse ACG Series Selection

## Selecting the Proper Drive Rating

Selecting the Proper Drive Rating															
<b>Determine Motor Voltage and Full-Load Amperage (FLA)</b>															
Motor voltage and FLA are located on the nameplate of the motor. <i>NOTE: FLA of motors that have been rewound may be higher than stated.</i>															
<b>Determine Motor Overload Requirements</b>															
Many applications experience temporary overload conditions due to starting requirements or impact loading. Most AC drives are designed to operate at 150% overload for 60 seconds. If the application requires an overload greater than 150% or longer than 60 seconds, the AC drive must be oversized. <i>NOTE: Applications that require replacement of existing motor starters with AC drives may require up to 600% overload.</i>															
<b>Determine Application Type: Heavy Load (HD) or Normal Load (ND)</b>															
This torque requirement has a direct effect on which drive to select. Normal load (or variable torque) applications are generally easier to start; typically fans and pumps. Most other applications outside fans and pumps fall into the heavy load (or constant torque) category (machine control, conveyors, etc.). If you are unsure of the application, assume heavy load.															
<b>Installation Altitude</b>															
AC drives rely on air flow for cooling. ACG drives are designed to operate at 100% capacity at altitudes up to 1000 meters. As the altitude increases, the air becomes less dense. This drop in air density decreases the cooling properties of the air, therefore, the AC drive must be oversized to compensate for the decrease in cooling. <i>NOTE: For use above 1000m, the AC drive must be derated as described below.</i>															
<b>Derate Output Current Based on Altitude Above 1000 Meters</b>															
<ul style="list-style-type: none"> <li>• If the AC drive is installed at an altitude of 0–1000m, follow normal operation restrictions.</li> <li>• From 1000 to 4000m, the rated input voltage and rated output current of the drive must be derated by 1% for every 100m.</li> </ul>															
<p><b>Derating for Altitude</b></p> <table border="1" style="margin: 10px auto;"> <caption>Data for Derating for Altitude</caption> <thead> <tr> <th>Altitude (m)</th> <th>Current Rated Ratio (%)</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>100</td> </tr> <tr> <td>1000</td> <td>100</td> </tr> <tr> <td>2000</td> <td>90</td> </tr> <tr> <td>3000</td> <td>80</td> </tr> <tr> <td>4000</td> <td>70</td> </tr> <tr> <td>5000</td> <td>0</td> </tr> </tbody> </table>		Altitude (m)	Current Rated Ratio (%)	0	100	1000	100	2000	90	3000	80	4000	70	5000	0
Altitude (m)	Current Rated Ratio (%)														
0	100														
1000	100														
2000	90														
3000	80														
4000	70														
5000	0														



# IronHorse ACG Series Selection

## Selecting the Proper Drive Rating

### Derate Output Current Based on Carrier Frequency (if necessary)

#### Carrier Frequency Effects

AC Drives rectify the incoming 50Hz or 60Hz line power resulting in DC power. The DC power is then pulse-width modulated and supplied to the motor by the drive's power electronics. IGBTs invert the DC power, simulating a sine wave at the desired frequency (that's what allows variable speed in AC induction motors). The speed at which the IGBTs are turned ON and OFF is called Carrier Frequency. In ACG drives, the Carrier Frequency can range from 2kHz to 15kHz. Though Carrier Frequency can be adjusted, there are trade-offs between high Carrier Frequencies and low Carrier Frequencies.

#### Benefits of Higher Carrier Frequencies:

- Better efficiency (lower harmonic losses) in the motor
- Lower audible noise

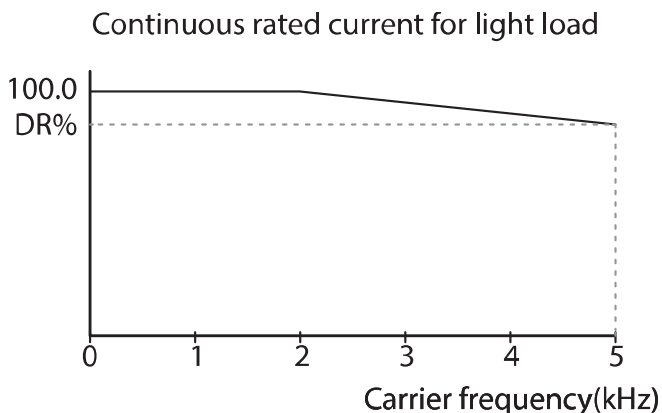
#### Benefits of Lower Carrier Frequencies:

- Better efficiency in the drive
- Lower EMI (electrical noise)
- Reduced reflective wave peak voltage

As a general rule, the Carrier Frequency should be set as low as possible without creating unacceptable audible noise in the motor. Smaller systems can have higher Carrier Frequencies, but larger drives (>20 or 30hp) should not have Carrier Frequencies set higher than 6kHz. Heavy duty applications typically run around 2-4 kHz.

### Derating Tables

Capacity (hp)	Drive Voltage	
	230V DR (%)	460V DR (%)
0.5	88	74
1	88	86
2	88	84
3	94	85
5	96	93
7.5	85	81
10	85	77
15-30	80	80





# IronHorse ACG Series Selection Specifications

ACG 230V Class Specifications; Frame Sizes A-E												
Part Number			ACG-20P5	ACG-21P0	ACG-22P0	ACG-23P0	ACG-25P0	ACG-27P5	ACG-2010	ACG-2015	ACG-2020	
Price			\$164.00	\$173.00	\$184.00	\$192.00	\$234.00	\$366.00	\$414.00	\$876.00	\$997.00	
Frame Size			A			B		C	D		E	
Drawing Link			<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	
Applied Motor	Heavy Load (HD)	hp	0.5	1.0	2.0	3.0	5.0	7.5	10	15	20	
		kW	0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15	
	Normal Load (ND)	hp	1.0	2.0	3.0	5.0	7.5	10	15	20	25	
		kW	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	
Output Rating	Rated Capacity	HD kVA	1.0	1.9	3.0	4.2	6.5	9.1	12.2	17.9	22.9	
		ND kVA	1.2	2.3	3.8	4.6	6.9	11.4	15.2	21.3	26.7	
	Rated Current - 3ph input	HD A	2.5	5.0	8.0	11.0	17.0	24.0	32.0	47	60	
		ND A	3.1	6.0	9.6	12.0	18.0	30.0	40.0	56	70	
	Rated Current - 1ph input (60Hz)	HD A	1.5	2.8	4.6	6.1	9.3	12.8	17.4	26.8	34	
		ND A	2.0	3.6	5.9	6.7	9.8	16.3	22.0	31	38	
	Rated Current - 1ph input (50Hz)	HD A	1.5	2.7	4.5	5.9	9.1	12.4	16.9	26	33.1	
		ND A	1.9	3.5	5.7	6.5	9.5	15.8	21.3	30	36.9	
	Output Frequency	Hz	0-400 Hz (IM Sensorless: 0-120 Hz)									
	Output Voltage	V	3-phase 200-240 V									
	Input Voltage - 3ph input	V	3-phase 200-240 VAC (-15% to +10%)									
	Input Voltage - 1ph input	V	1-phase 240VAC (-5% to +10%)									
Input Frequency - 3ph input	Hz	50-60 Hz (±5%)										
Input Frequency - 1ph input	Hz	60Hz (±5%)										
Rated Current - 1 or 3ph input	HD A	2.2	4.9	8.4	11.8	18.5	25.8	34.9	53.2	68.4		
	ND A	3.0	6.3	10.3	13.1	19.4	32.7	44.2	63.8	79.8		
Weight (lb [kg])		2.29 [1.04]	2.34 [1.06]	3.0 [1.36]	3.09 [1.4]	4.17 [1.89]	6.79 [3.08]	7.08 [3.21]	10.7 [4.84]	16.8 [7.6]		
Cooling Method		Forced Fan										
<ul style="list-style-type: none"> <li>The standard motor capacity is based on a standard 4-pole motor.</li> <li>The standard used for 230V drives is based on a 220V supply voltage.</li> <li>The rated output current is limited based on the carrier frequency set at Cn.4.</li> <li>The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5~5 hp models only).</li> <li>For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.</li> </ul>												



**ACG-20P5**



**ACG-2020**



# IronHorse ACG Series Selection Specifications

ACG 460V Class Specifications; Frame Sizes A-C								
<b>Part Number</b>			<b>ACG-40P5</b>	<b>ACG-41P0</b>	<b>ACG-42P0</b>	<b>ACG-43P0</b>	<b>ACG-45P0</b>	
<b>Price</b>			\$175.00	\$183.00	\$192.00	\$202.00	\$228.00	
<b>Frame Size</b>			A	A	B	B	C	
<b>Drawing Link</b>			<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	
<b>Applied Motor</b>	<b>Heavy Load (HD)</b>	<b>hp</b>	0.5	1.0	2.0	3.0	5.0	
		<b>kW</b>	0.3	0.75	1.5	2.2	4.0	
	<b>Normal Load (ND)</b>	<b>hp</b>	1.0	2.0	3.0	5.0	7.5	
		<b>kW</b>	0.75	1.5	2.2	4.0	5.5	
<b>Output Rating</b>	<b>Rated Capacity</b>	<b>HD</b>	<b>kVA</b>	1.0	1.9	3.0	4.2	6.5
		<b>ND</b>	<b>kVA</b>	1.5	2.4	3.9	5.3	7.6
	<b>Rated Current-3ph input</b>	<b>HD</b>	<b>A</b>	1.3	2.5	4.0	5.5	9.0
		<b>ND</b>	<b>A</b>	2.0	3.1	5.1	6.9	10.0
	<b>Rated Current-1ph input (60Hz)</b>	<b>HD</b>	<b>A</b>	0.7	1.4	2.1	2.8	4.9
		<b>ND</b>	<b>A</b>	1.3	1.9	2.8	3.6	5.4
	<b>Rated Current-1ph input (50Hz)</b>	<b>HD</b>	<b>A</b>	0.7	1.4	2.0	2.7	4.8
		<b>ND</b>	<b>A</b>	1.3	1.8	2.7	3.5	5.2
	<b>Output Frequency</b>		<b>Hz</b>	0-400 Hz (IM Sensorless: 0-120 Hz)				
	<b>Output Voltage</b>		<b>V</b>	3-phase 380-480 V				
<b>Input Voltage-3ph input</b>		<b>V</b>	380-480 VAC (-15% to +10%)					
<b>Input Voltage-1ph input</b>		<b>V</b>	480VAC (-5% to +10%)					
<b>Input Frequency-3ph input</b>		<b>Hz</b>	50-60 Hz (±5%)					
<b>Input Frequency-1ph input</b>		<b>Hz</b>	60Hz (±5%)					
<b>Input Rating</b>	<b>Rated Current -1 or 3ph input</b>	<b>HD</b>	<b>A</b>	1.1	2.4	4.2	5.9	9.8
		<b>ND</b>	<b>A</b>	2.0	3.3	5.5	7.5	10.8
<b>Weight (lb [kg])</b>			2.25 [1.02]	2.34 [1.06]	3.09 [1.4]	3.13 [1.42]	4.23 [1.92]	
<b>Cooling Method</b>			Forced Fan					

- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 460V drives is based on a 440V supply voltage.
- The rated output current is limited based on the carrier frequency set at Cn.4.
- The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5-5 hp models only).
- For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.



**ACG-40P5**



**ACG-43P0**



# IronHorse ACG Series Selection Specifications

ACG 460V Class Specifications; Frame Sizes D-F									
Part Number			<a href="#">ACG-47P5</a>	<a href="#">ACG-4010</a>	<a href="#">ACG-4015</a>	<a href="#">ACG-4020</a>	<a href="#">ACG-4025</a>	<a href="#">ACG-4030</a>	
Price			\$326.00	\$348.00	\$960.00	\$1,043.00	\$1,156.00	\$1,224.00	
Frame Size			D		E		F		
Drawing Link			<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	<a href="#">PDF</a>	
Applied Motor	Heavy Load (HD)	hp	7.5	10	15	20	25	30	
		kW	5.5	7.5	11	15	18.5	22	
	Normal Load (ND)	hp	10	15	20	25	30	40	
		kW	7.5	11	15	18.5	22	30	
Output Rating	Rated Capacity	HD	kVA	9.1	12.2	18.3	23.6	29.7	34.3
		ND	kVA	12.2	17.5	23.6	29.0	34.3	46.5
	Rated Current-3ph input	HD	A	12.0	16.0	24	31	39	45
		ND	A	16.0	23.0	31	38	45	61
	Rated Current-1ph input (60Hz)	HD	A	6.4	8.7	15	18	23	27
		ND	A	8.7	12.6	18	23	27	35
	Rated Current-1ph input (50Hz)	HD	A	6.2	8.5	14.6	17.4	22.3	26.2
		ND	A	8.4	12.2	17.4	22.2	26.1	33.8
	Output Frequency	Hz	0-400 Hz (IM Sensorless: 0-120 Hz)						
	Output Voltage	V	3-phase 380-480 V						
Input Rating	Input Voltage-3ph input	V	380-480 VAC (-15% to +10%)						
	Input Voltage-1ph input	V	480VAC (-5% to +10%)						
	Input Frequency-3ph input	Hz	50-60 Hz (±5%)						
	Input Frequency-1ph input	Hz	60Hz (±5%)						
	Rated Current -1 or 3ph input	HD	A	12.9	17.5	27.2	35.3	44.5	51.9
ND		A	17.5	25.4	35.3	43.3	51.9	70.8	
Weight (lb [kg])			6.79 [3.08]	6.88 [3.12]	10.8 [4.89]	10.8 [4.91]	16.8 [7.63]	16.9 [7.65]	
Cooling Method			Forced Fan						
<ul style="list-style-type: none"> <li>The standard motor capacity is based on a standard 4-pole motor.</li> <li>The standard used for 460V drives is based on a 440V supply voltage.</li> <li>The rated output current is limited based on the carrier frequency set at Cn.4.</li> <li>The output voltage becomes 20~40% lower during no-load operations to protect the drive from the impact of the motor closing and opening (0.5-5 hp models only).</li> <li>For Single Phase Power input, an Input Line Reactor is required. See accessories for the specific line reactor for each drive model.</li> </ul>									



**ACG-47P5**



**ACG-4030**



# IronHorse ACG Series General Specifications

## ACG General Specifications

IronHorse ACG Series General Specifications (All Models)				
Control Characteristics	<b>Control Method</b>		V/F control, Slip Compensation, Sensorless Vector	
	<b>Frequency Settings Power Resolution</b>		Digital command: 0.01 Hz Analog command: 0.06 Hz (60Hz standard)	
	<b>Frequency Accuracy</b>		1% of maximum output frequency	
	<b>V/F Pattern</b>		Linear, square reduction, user V/F	
	<b>Overload Capacity</b>		Heavy load rated current: 150% for 1 minute Normal load rated current: 120% for 1 minute	
	<b>Torque Boost</b>		Manual torque boost, automatic torque boost	
Operation Characteristics	<b>Operation Type</b>		Select key pad, terminal strip, or communication operation	
	<b>Frequency Setting Signal</b>		Analog type: -10~10 V, 0~10 V, 4~20 mA, keypad built-in potentiometer dial Digital type: keypad	
	<b>Main Functions</b>		<ul style="list-style-type: none"> <li>• PID control</li> <li>• 3-wire operation</li> <li>• Frequency limit</li> <li>• Second motor function</li> <li>• Anti-forward and reverse direction rotation</li> <li>• Commercial transition</li> <li>• Speed search</li> <li>• Power braking</li> <li>• Up-down operation</li> </ul> <ul style="list-style-type: none"> <li>• DC braking</li> <li>• Frequency jump</li> <li>• Slip compensation</li> <li>• Automatic restart</li> <li>• Automatic tuning</li> <li>• Energy buffering</li> <li>• Flux braking</li> <li>• Fire mode</li> </ul>	
	Input	<b>Multi-function Terminal (5) P1-P5</b>	Select PNP (Source) or NPN (Sink) mode. Functions can be set according to In.65–In.69 codes and parameter settings.	
			<ul style="list-style-type: none"> <li>• Forward direction operation</li> <li>• Reset</li> <li>• Emergency Stop</li> <li>• Multi-step speed frequency-high/med/low</li> <li>• DC braking during stop</li> <li>• Frequency increase</li> <li>• 3-wire</li> <li>• Select acc/dec/stop</li> </ul>	<ul style="list-style-type: none"> <li>• Reverse run</li> <li>• External trip</li> <li>• Jog operation</li> <li>• Multi-step acc/dec-high/med/low</li> <li>• Second motor selection</li> <li>• Frequency reduction</li> <li>• Fix analog command frequency</li> <li>• Transition from PID to general operation</li> </ul>
		<b>Analog Input (2)</b>	-10 to 10 V, 0~10 V, 4~20 mA, Speed or PID control	
	Output	<b>Multi-function relay terminal (2)</b>	Fault output and drive operation status output	Less than (N.O., N.C.) 250VAC, 1A Less than 30VDC 1A
		<b>Analog Output (1)</b>	0~12 VDC: Select frequency, output current, output voltage, DC terminal voltage and others	
Protection Function Characteristics	<b>Trip</b>		<ul style="list-style-type: none"> <li>• Overcurrent trip</li> <li>• External signal trip</li> <li>• ARM short circuit current trip</li> <li>• Overheat trip</li> <li>• In phase open trip</li> <li>• Ground trip</li> <li>• Motor overheat trip</li> <li>• I/O board link trip</li> <li>• No motor trip</li> <li>• Parameter writing trip</li> <li>• Emergency stop trip</li> <li>• Command loss trip</li> <li>• External memory error</li> <li>• CPU watchdog trip</li> <li>• Motor light load trip</li> </ul> <ul style="list-style-type: none"> <li>• Overvoltage trip</li> <li>• Temperature sensor trip</li> <li>• Drive overheat</li> <li>• Option trip</li> <li>• Out phase open trip</li> <li>• Drive overload trip</li> <li>• Fan trip</li> <li>• Pre-PID operation failure</li> <li>• External break trip</li> <li>• Low voltage trip during operation</li> <li>• Low voltage trip</li> <li>• Analog input error</li> <li>• Motor overload trip</li> <li>• Over-torque trip</li> <li>• Under-torque trip</li> </ul>	
	<b>Alarm</b>		Command loss trip alarm, overload alarm, light load alarm, drive overload alarm, fan operation alarm, resistance braking rate alarm, number of corrections on rotor tuning error, drive pre-overheat alarm, over-torque alarm, under-torque alarm	
	<b>Instantaneous Blackout</b>		Heavy load less than 15ms (normal load less than 8ms): must be within the rated input voltage and rated output range Heavy load more than 15ms (normal load more than 8ms): auto-restart operation	
<b>Communication Card Option</b>		EtherNet/IP and Modbus TCP (ACG-ET2)		
<b>Agency Approvals</b>		UL, CE		





# IronHorse ACG Series General Specifications

## ACG Environmental Specifications

Environmental Conditions for IronHorse ACG Series AC Drives	
<b>Installation Location</b>	Mount the drive on a wall or inside a panel. Not suitable for use in direct sunlight.
<b>Cooling</b>	Forced fan cooling structure Forced cooling type: 1/2–15 hp 230V/1/2–30 hp 460V (excluding some models)
<b>Operating Ambient Temperature</b>	Heavy Load (HD): -10 to 50°C (14 to 122°F) Normal Load (ND): -10 to 40°C (14 to 104°F)
<b>Storage Temperature*</b>	-20° to 65°C (-4 to 149°F)
<b>Relative Humidity</b>	Less than 95% (to avoid condensation)
<b>Air Pressure</b>	70 to 106 kPa
<b>Pollution Level</b>	Pollution level 3 environment: Prevent contact with corrosive gases, inflammable gases, oil stains, dust, and other pollutants.
<b>Altitude</b>	No higher than 3280ft (1000m). From 1000 to 4000m, the rated input voltage and rated output current of the drive must be derated by 1% for every 100m.
<b>Vibration</b>	Less than 9.8 m/sec <sup>2</sup> (1G)
<b>Installation Orientation</b>	Max allowed offset angle = 0 degrees. (Vertical orientation only). Do not install the drive on the floor or mount it sideways against a wall. The drive MUST be installed vertically, on a wall or inside a panel, with its back flat on the mounting surface.

\* The ambient temperature is the temperature measured at a point 2" (5 cm) from the surface of the drive.

## ACG Watt Loss and Efficiency

IronHorse ACG Watt Loss and Efficiency							
Model Number	Voltage	Rated Power (hp) [kW]	Efficiency (%)	Total Losses (W)	Internal Losses (W)	External (Heat) Losses (W)	Heat Losses (Kcal)
<a href="#">ACG-20P5</a>	230	1/2 [0.4]	96.40	18.4	16.8	1.6	1.4
<a href="#">ACG-21P0</a>		1 [0.8]	96.40	36.8	16.8	20.0	17.2
<a href="#">ACG-22P0</a>		2 [1.5]	96.70	64.5	17.4	47.1	40.5
<a href="#">ACG-23P0</a>		3 [2.2]	96.70	94.6	17.4	77.2	66.4
<a href="#">ACG-25P0</a>		5 [4]	96.80	168.0	17.7	150.3	129.2
<a href="#">ACG-27P5</a>		7 [5.5]	96.90	225.5	18.7	206.8	177.8
<a href="#">ACG-2010</a>		10 [7.5]	96.90	307.5	18.7	288.8	248.3
<a href="#">ACG-2015</a>		15 [11]	97.71	362.5	23.8	338.7	291.2
<a href="#">ACG-2020</a>		20 [15]	97.89	466.8	38.2	428.6	368.6
<a href="#">ACG-40P5</a>		460	1/2 [0.4]	96.00	20.0	17.4	2.6
<a href="#">ACG-41P0</a>	1 [0.8]		96.80	33.6	17.4	16.2	14.0
<a href="#">ACG-42P0</a>	2 [1.5]		97.30	55.5	17.7	37.8	32.5
<a href="#">ACG-43P0</a>	3 [2.2]		97.50	77.0	17.7	59.3	51.0
<a href="#">ACG-45P0</a>	5 [4]		97.60	136.0	18.7	117.3	100.8
<a href="#">ACG-47P5</a>	7 [5.5]		97.80	176.0	19.7	156.3	134.4
<a href="#">ACG-4010</a>	10 [7.5]		97.80	240.0	19.7	220.3	189.4
<a href="#">ACG-4015</a>	15 [11]		98.50	274.7	23.8	250.9	215.8
<a href="#">ACG-4020</a>	20 [15]		98.35	397.4	23.8	373.6	321.3
<a href="#">ACG-4025</a>	25 [18.5]		98.55	454.0	38.2	415.8	357.6
<a href="#">ACG-4030</a>	30 [22]	98.65	517.0	38.2	478.8	411.8	

This watt loss and efficiency data were measured under the following test conditions:

- Operation at 60Hz and room temperature
- 100% load
- Carrier Frequency (Default value)

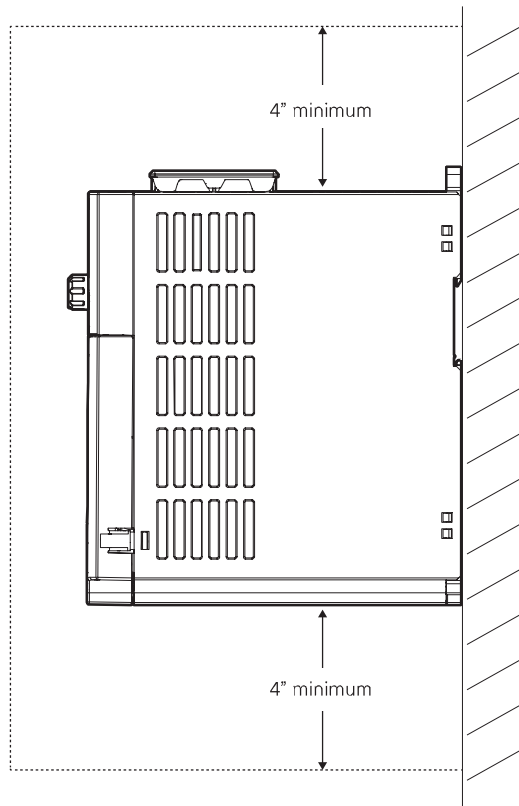
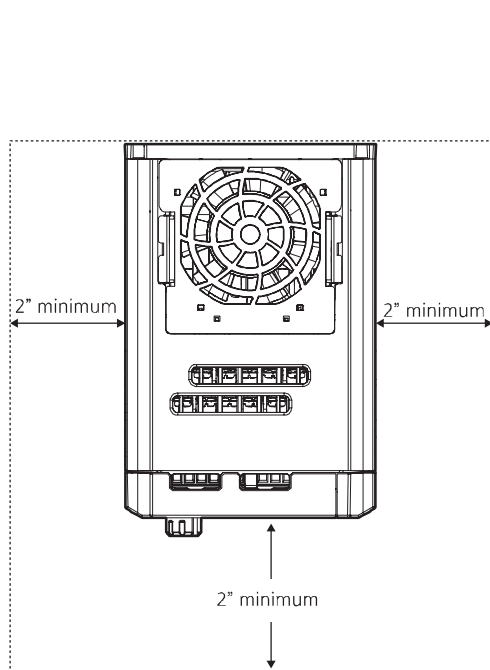
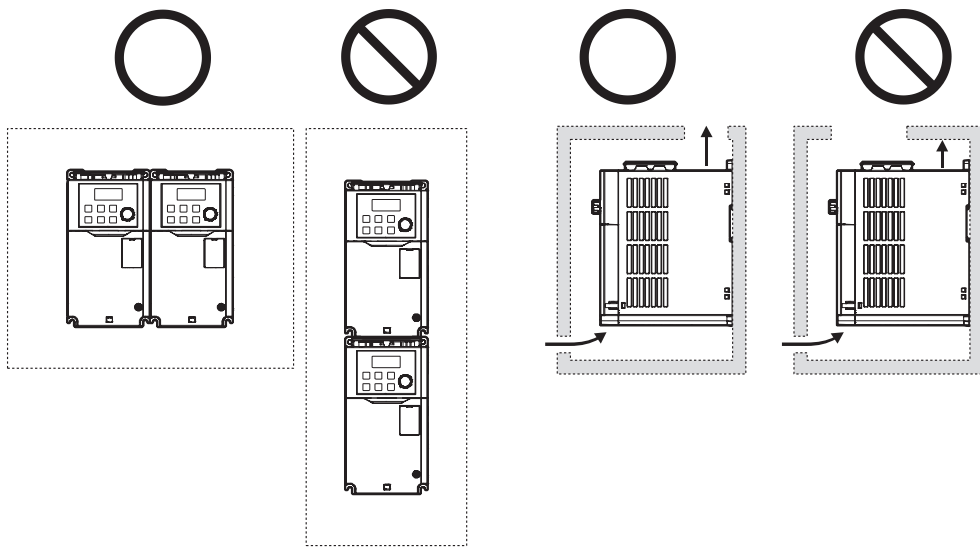




# IronHorse ACG Series Mounting Clearances

## ACG Mounting Clearances

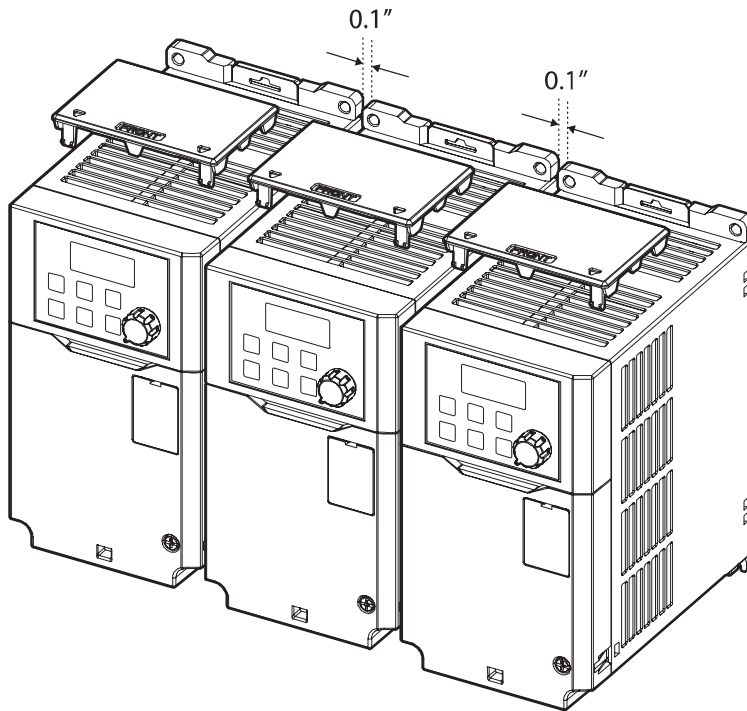
Ensure sufficient air circulation is provided around the drive when it is installed. If the drive is to be installed inside a panel, enclosure, or cabinet rack, carefully consider the position of the drive's cooling fan and the ventilation louver. Cooling fans must be positioned to efficiently transfer the heat generated by the operation of the drive.



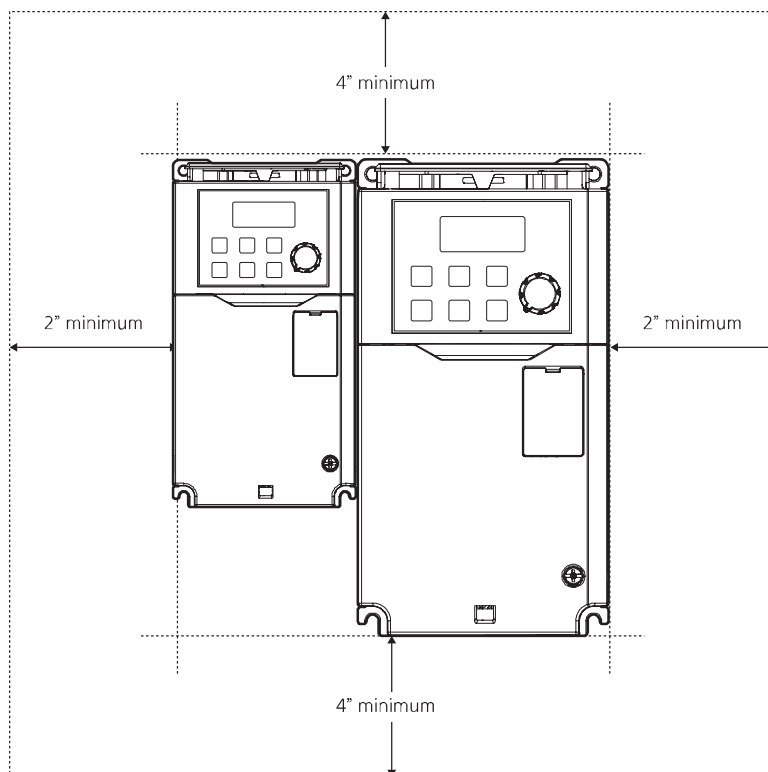


# IronHorse ACG Series Mounting Clearances

If you are installing multiple drives in one location, arrange them side-by-side and remove the top covers. The top covers MUST be removed for side-by-side installations. Use a flat-head screwdriver to remove the top covers.



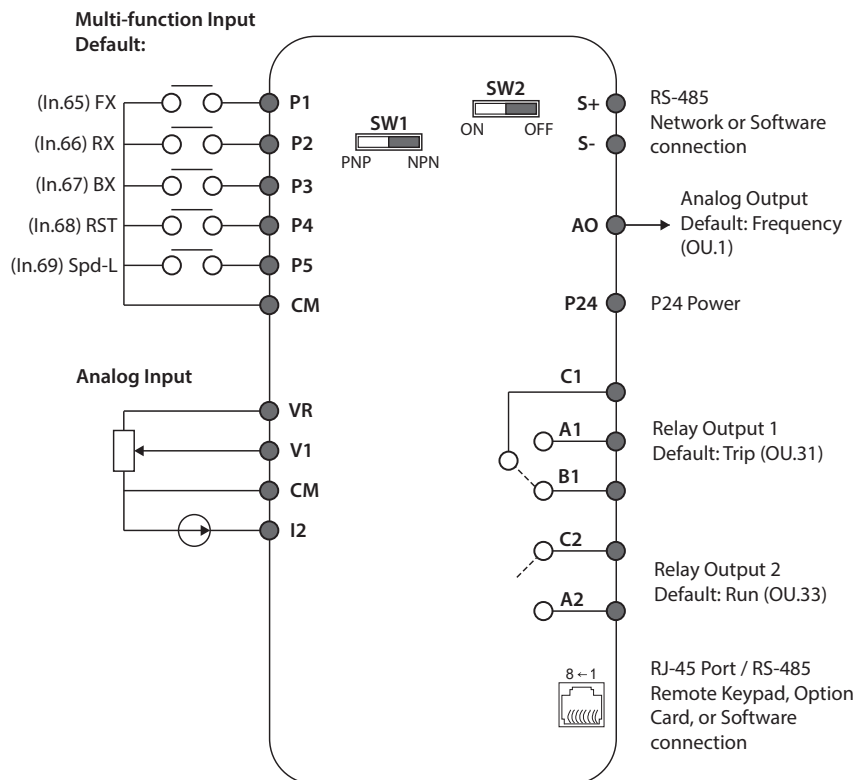
If you are installing multiple drives of different ratings, provide sufficient clearance to meet the clearance specifications of the larger drive.





# IronHorse ACG Series I/O Diagram

## ACG System I/O Diagram



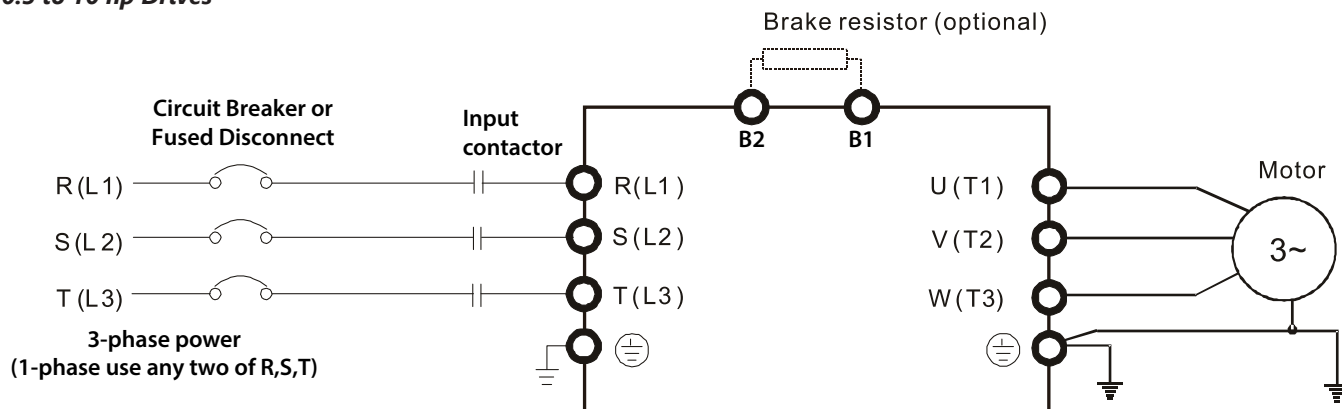
I/O Details			
Function	Label	Name	Description
<b>Multi-function Digital Input Terminal Configuration</b>	P1-P5	Multi-function Input 1-5	Configurable for multi-function input terminals. Factory default terminals and setup are as follows: <ul style="list-style-type: none"> <li>• P1: FX (Forward Run)</li> <li>• P2: RX (Reverse Run)</li> <li>• P3: BX (Block)</li> <li>• P4: RST (Reset)</li> <li>• P5: Speed-L</li> </ul>
	CM	Common Sequence	Common terminal for terminal input, RS-485 communication, and analog terminal inputs and outputs.
<b>Analog Input Configuration</b>	VR	Potentiometer frequency reference input	Used to setup or modify a frequency reference via analog voltage or current input. <ul style="list-style-type: none"> <li>• Maximum Voltage Output: 12V</li> <li>• Maximum Current Output: 100mA</li> <li>• Potentiometer: 1-5kΩ</li> </ul>
	V1	Voltage input for control reference	Used to setup or modify a frequency reference via analog voltage input terminal. <ul style="list-style-type: none"> <li>• Unipolar: 0-10V (12V Max.)</li> <li>• Bipolar: -10-10V (±12V Max.)</li> </ul>
	I2	Voltage/current input for control reference	Used to setup or modify a frequency reference via the I2 terminal. <ul style="list-style-type: none"> <li>• Input current: 4-20mA</li> <li>• Maximum Input current: 20mA</li> <li>• Input resistance: 249Ω</li> </ul>
<b>Analog Output</b>	AO	Voltage/Current Output	Used to send inverter output information to external devices: output frequency, output current, output voltage, or a DC voltage. <ul style="list-style-type: none"> <li>• Output voltage: 0-10V</li> <li>• Maximum output voltage/current: 12V/10mA</li> <li>• Factory default output: Frequency</li> </ul>
<b>Digital Relay Output</b>	24	Internal 24V power source	Maximum output current: 100mA
	A1/C1/B1	Fault signal output 1	Sends out alarm signals when the inverter's safety features are activated (250VAC <1A, 30VDC < 1A). <ul style="list-style-type: none"> <li>• Fault condition: A1 and C1 contacts are connected (B1 and C1 open connection)</li> <li>• Normal operation: B1 and C1 contacts are connected (A1 and C1 open connection)</li> </ul>
	A2/C2	Fault signal output 2	Sends out alarm signals when the inverter's safety features are activated (250VAC <1A, 30VDC < 1A). <ul style="list-style-type: none"> <li>• Fault condition: A2 and C2 contacts are open connection</li> <li>• Normal operation: A2 and C2 contacts are connected</li> </ul>
<b>Communication</b>	S+/S-	RS-485 signal line	Used for network or software connection
	RJ45 Port	RS-485 signals	Remote keypad, option card, or software connection



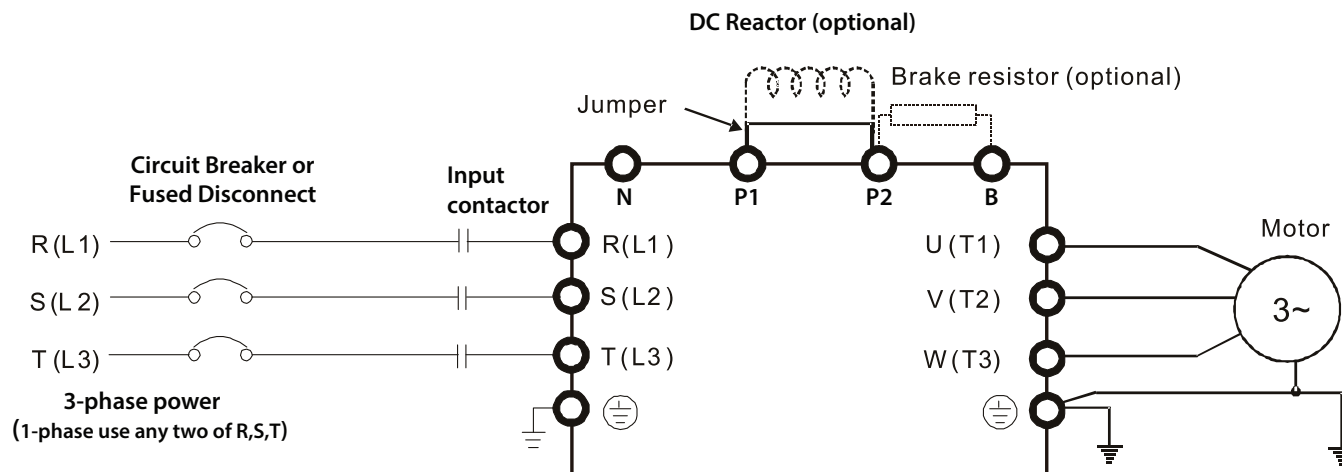
# IronHorse ACG Series Basic Wiring

## Main Circuit Wiring Diagram

### 0.5 to 10 hp Drives



### 15 to 30 hp Drives



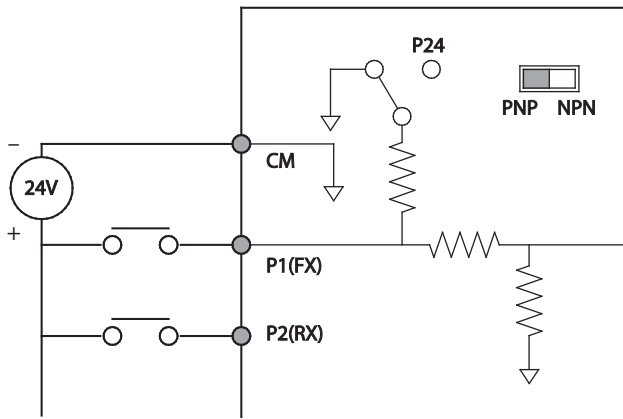
Power Terminal Labels and Descriptions		
Function	Name	Description
R(L1)/S(L2)/T(L3)	AC power input terminal	Mains supply AC power connections.
P2(+)/N(-)	DC input terminal	DC voltage terminals for 15-30 hp drives.
P1(+)/P2(+)	DC reactor terminal	DC reactor wiring connection for 15-30 hp drives. (Remove the short-bar when you use the DC reactor).
B1/B2 (0.5 to 10 hp)	Brake resistor terminals	Brake resistor wiring connection.
P2(+)/B (15 to 30 hp)		
U/V/W	Motor output terminals	3-phase AC motor wiring connections.



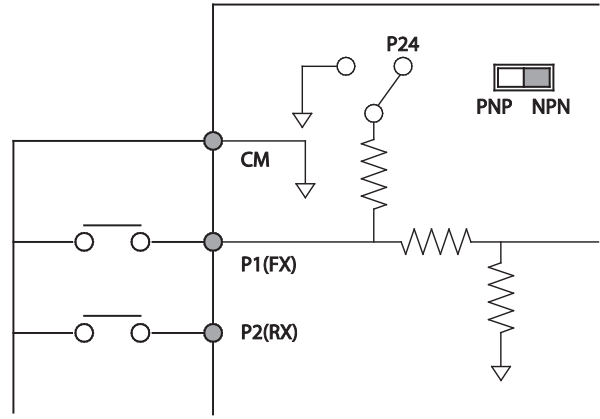
# IronHorse ACG Series Basic Wiring

## Control Circuit Wiring Diagram: Digital Inputs

Select PNP using the PNP/NPN selection switch (SW1). Note that the factory default setting is NPN mode. CM is the common ground terminal for all analog inputs at the terminal, and P24 is 24V internal source. If you are using an external 24V source, build a circuit that connects the external source (-) and the CM terminal.



PNP Mode (Source)



NPN Mode (Sink)

## 2 and 3 Wire Control

2-Wire Control	
	<p>2-wire control consists of maintained run signals. This can be accomplished via toggle switches, relays, jumpers, etc. Default parameters support this operation.</p> <p>P1=Forward Run (Fx) P2=Reverse Run (Rx) CM=Common</p>
3-Wire Control	
	<p>3-Wire control consists of momentary push buttons to run and stop the VFD. The Forward and Reverse buttons are Normally Open while the Stop button is Normally Closed. Set parameter In.67=14 if using P3 (like below) for the Stop button.</p> <p>P1 = Forward Run (Fx) P2 = Reverse Run (Rx) P3 = Stop (3-Wire) CM = CommonFrequency Reference Wiring</p>

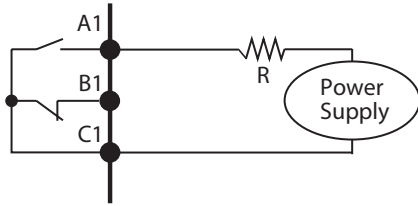


# IronHorse ACG Series Basic Wiring

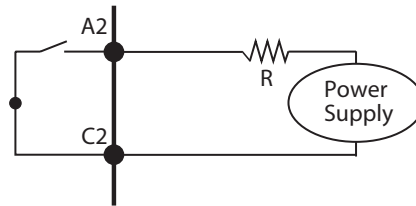
## Digital Output Relay Wiring

*NOTE: Ensure device current does not exceed 1A.*

Relay 1

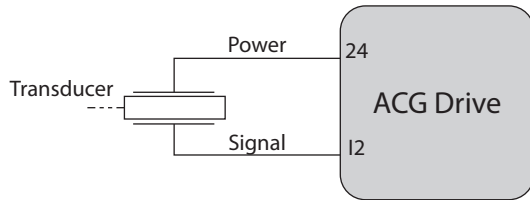


Relay 2

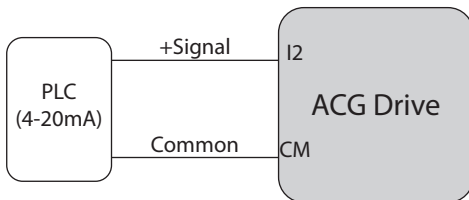


## 4-20mA Analog Input Wiring

**Transducer (4-20mA):** Transducers are typically 4-20mA devices which require a 24VDC power source. For 2-wire transducers connect to the 24VDC and 4-20mA input terminals listed below. Connect the positive lead of the device to the 24V terminal and the signal lead to the analog input terminal (I2).

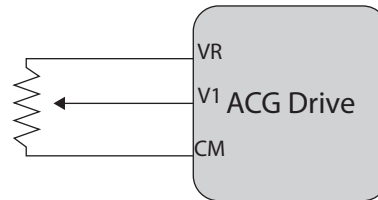


**PLC (4-20mA):** The wiring for connecting a PLC's 4-20mA output to the analog input of a VFD differs slightly from the transducer wiring discussed above. The positive (signal) lead is wired to the corresponding analog input while the negative (common) lead is wired to the drives common. Reference the figure below.

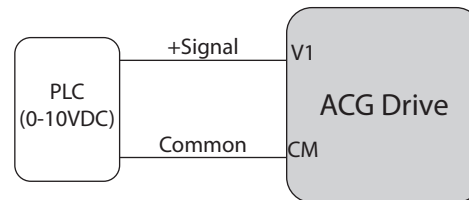


## 0-10VDC Analog Input Wiring

**Speed POT/Rheostat (0-10VDC):** Speed potentiometers have three wires which must be connected to properly vary a 0-10VDC signal. The required terminal connections will vary slightly depending on the drive series. Reference the figure below. The wiper of the speed POT should always be connected to the analog input.

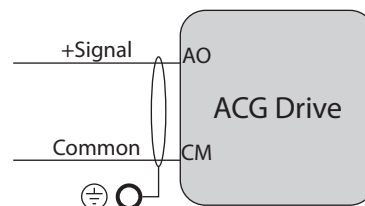


**PLC (0-10VDC):** The wiring for connecting a PLC's 0-10VDC output to the analog input of a VFD differs slightly from the speed POT wiring discussed above. The positive (signal) lead is wired to the corresponding analog input while the negative (common) lead is wired to the drives common. Reference the figure below.



## AO Wiring

Wire the drive analog out as follows:





# IronHorse ACG Series Accessories

## Accessories Available for ACG Drives

<b>ACG Drives Available Software and Accessories</b>	
<i>Accessory</i>	<i>Reference</i>
<b>Ethernet Module: ACG-ET2</b>	<a href="#">ACG Ethernet Module on page tIHA-16</a>
<b>Conduit Boxes: ACG-N1A – ACG-N1F</b>	<a href="#">ACG Conduit Boxes on page tIHA-17</a>
<b>Remote Keypad: ACG-KPD</b>	<a href="#">Remote Keypad on page tIHA-18</a>
<b>Replacement Fans: ACG-FAN-A – ACG-FAN-FR45</b>	<a href="#">Replacement Fans on page tIHA-19</a>
<b>Fuses/Circuit Breakers</b>	<a href="#">Fuses/Circuit Breakers on page tIHA-20</a>
<b>EMI Filters</b>	<a href="#">High Performance EMI Input Filters on page tIHA-21</a>
<b>Braking Resistors</b>	<a href="#">Braking Resistors on page tIHA-23</a>
<b>Line Reactors/Voltage Time Filters</b>	<a href="#">Line Reactors/Voltage Time Filters on page tIHA-22</a>
<b>VFD Suite</b>	<a href="#">VFD Suite on page tIHA-45</a>





# IronHorse ACG Series Accessories

## ACG Ethernet Module

The ACG-ET2 is an option module for connecting any ACG series drive to an ethernet network. The module supports both the EtherNet/IP and Modbus TCP protocols.

ACG Ethernet Module		
Part Number	Price	Description
<b>ACG-ET2</b>	\$105.00	IronHorse ACG series communication module, EtherNet/IP and Modbus TCP, 2 ports, (2) Ethernet (RJ45) and (1) RS-485 (RJ45) port(s). For use with IronHorse ACG series AC drives. Mounting hardware included.



**ACG-ET2**



**Installed on ACG Drive**



# IronHorse ACG Series Accessories

## ACG Conduit Boxes

The ACG conduit boxes allow conversion of the ACG drive to a NEMA1 rating.

ACG Conduit Boxes			
Part Number	Price	Description	Drawing Links
<a href="#"><u>ACG-N1A</u></a>	\$39.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series A frame AC drives. Mounting hardware included.	<a href="#">PDF</a>
<a href="#"><u>ACG-N1B</u></a>	\$40.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series B frame AC drives. Mounting hardware included.	<a href="#">PDF</a>
<a href="#"><u>ACG-N1C</u></a>	\$43.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series C frame AC drives. Mounting hardware included.	<a href="#">PDF</a>
<a href="#"><u>ACG-N1D</u></a>	\$47.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series D frame AC drives. Mounting hardware included.	<a href="#">PDF</a>
<a href="#"><u>ACG-N1E</u></a>	\$69.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series E frame AC drives. Mounting hardware included.	<a href="#">PDF</a>
<a href="#"><u>ACG-N1F</u></a>	\$75.00	IronHorse ACG series conduit box, NEMA 1. For use with ACG series F frame AC drives. Mounting hardware included.	<a href="#">PDF</a>



[ACG-N1A](#)



# IronHorse ACG Series Accessories

## Remote Keypad

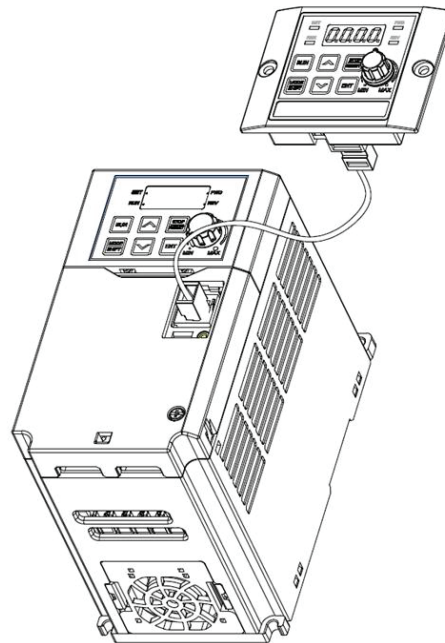
The ACG-KPD keypad allows for remote mounting of the standard keypad functionality for the ACG series drives.

The keypad can be mounted on an external panel or enclosure and connected to the drive by standard ethernet patch cable.

ACG Remote Keypad			
Part Number	Price	Description	Drawing Links
<a href="#">ACG-KPD</a>	\$45.00	IronHorse ACG series remote keypad, for use with IronHorse ACG series AC drives. (1) 16.4ft/5m Ethernet patch cable included.	<a href="#">PDF</a>



[ACG-KPD](#)





# IronHorse ACG Series Accessories

## Replacement Fans

The ACG-FAN-xxxx fans are replacement kits for the ACG drive fan(s) that comes installed with the drive.

ACG Replacement Fans			
Part Number	Price	Description	Drawing Links
<a href="#"><u>ACG-FAN-A</u></a>	\$9.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 1/2hp - 1hp AC drives.	<a href="#"><u>PDF</u></a>
<a href="#"><u>ACG-FAN-BC</u></a>	\$9.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 2hp - 5hp AC drives.	<a href="#"><u>PDF</u></a>
<a href="#"><u>ACG-FAN-D</u></a>	\$20.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 7-1/2hp - 10hp AC drives.	<a href="#"><u>PDF</u></a>
<a href="#"><u>ACG-FAN-E15</u></a>	\$38.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 15hp AC drives.	<a href="#"><u>PDF</u></a>
<a href="#"><u>ACG-FAN-E20F</u></a>	\$50.00	IronHorse ACG series main cooling fan, replacement, 92 x 92 x 38mm, 24 VDC. For use with ACG series 20hp - 30hp AC drives.	<a href="#"><u>PDF</u></a>



[ACG-FAN-A](#)



[ACG-FAN-BC](#)



[ACG-FAN-D](#)



[ACG-FAN-E15](#)



[ACG-FAN-E20F](#)



# IronHorse ACG Series Accessories

## Fuses/Circuit Breakers

Protection devices are essential to prevent damage to your ACG drive and application equipment. Please use the fuse specification chart below to select fuses that are applicable to your ACG drive. Only use UL-certified 600V fuses which comply with your local regulations.

Drive	Drive Voltage	HP (CT)	Fuse Amps (Class H or RK5)	Suggested ADC Class RK5 Fuses	Circuit Breaker	
					Size	Model*
<a href="#">ACG-20P5</a>	200-240	0.5	10	ECSR10	15	UTE100H
<a href="#">ACG-21P0</a>		1	10	ECSR10	15	
<a href="#">ACG-22P0</a>		2	15	ECSR15	15	
<a href="#">ACG-23P0</a>		3	20	ECSR20	20	
<a href="#">ACG-25P0</a>		5	30	ECSR30	30	
<a href="#">ACG-27P5</a>		7.5	50	ECSR50	50	UTS150H
<a href="#">ACG-2010</a>		10	60	ECSR60	60	
<a href="#">ACG-2015</a>		15	80	ECSR80	80	
<a href="#">ACG-2020</a>		20	100	ECSR100	100	
<a href="#">ACG-40P5</a>		380-480	0.5	10	ECSR10	
<a href="#">ACG-41P0</a>	1		10	ECSR10	6.3	
<a href="#">ACG-42P0</a>	2		10	ECSR10	12	
<a href="#">ACG-43P0</a>	3		15	ECSR15	12	
<a href="#">ACG-45P0</a>	5		20	ECSR20	20	
<a href="#">ACG-47P5</a>	7.5		30	ECSR30	32	
<a href="#">ACG-4010</a>	10		35	ECSR35	32	
<a href="#">ACG-4015</a>	15		50	ECSR50	50	
<a href="#">ACG-4020</a>	20		60	ECSR60	60	
<a href="#">ACG-4025</a>	25		70	ECSR70	70	
<a href="#">ACG-4030</a>	30	100	ECSR100	90		

\* Manufactured by LS Electric. Not available at [AutomationDirect.com](#)



**CAUTION: ONLY USE 600V CLASS H OR RK5, UL LISTED INPUT FUSES AND UL LISTED CIRCUIT BREAKERS. SEE THE TABLE ABOVE FOR THE CURRENT RATINGS FOR FUSES AND CIRCUIT BREAKERS.**

**MAXIMUM ALLOWED PROSPECTIVE SHORT-CIRCUIT CURRENT AT THE INPUT POWER CONNECTION IS DEFINED IN IEC 60439-1 AS 100 KA. DEPENDING ON THE SELECTED MCCB, THE ACG SERIES IS SUITABLE FOR USE IN CIRCUITS CAPABLE OF DELIVERING A MAXIMUM OF 100 KA RMS SYMMETRICAL AMPERES AT THE DRIVE'S MAXIMUM RATED VOLTAGE. THE FOLLOWING TABLE SHOWS THE RECOMMENDED MCCB FOR RMS SYMMETRICAL AMPERES.**



# IronHorse ACG Series Accessories

## High Performance EMI Input Filters

The optional accessories below are available for use with the ACG drive. Selection of these accessories is application specific and may improve drive performance. Additional information regarding filter installation and operation is available in the AutomationDirect white paper, "Applied EMI/RFI Techniques."

Drive	Drive Voltage	HP (HD)	Roxburgh Filters Chassis Type 1ph *1	Roxburgh High Performance Filters *2	Roxburgh Max Performance Filters *3
<a href="#">ACG-20P5</a>	200-240	0.5	<a href="#">RES90F03</a>	<a href="#">KMF306A</a>	<a href="#">MIF310</a>
<a href="#">ACG-21P0</a>		1	<a href="#">RES90F10</a>	<a href="#">KMF310A</a>	<a href="#">MIF310</a>
<a href="#">ACG-22P0</a>		2	<a href="#">RES90F16</a>	<a href="#">KMF318A</a>	<a href="#">MIF316</a>
<a href="#">ACG-23P0</a>		3	<a href="#">RES90F16</a>	<a href="#">KMF318A</a>	<a href="#">MIF316</a>
<a href="#">ACG-25P0</a>		5	<a href="#">RES90S20</a>	<a href="#">KMF325A</a>	<a href="#">MIF323</a>
<a href="#">ACG-27P5</a>		7.5	-	<a href="#">KMF336A</a>	<a href="#">MIF350</a>
<a href="#">ACG-2010</a>		10	-	<a href="#">KMF350A</a>	<a href="#">MIF350</a>
<a href="#">ACG-2015</a>		15	-	<a href="#">KMF370A</a>	<a href="#">MIF375</a>
<a href="#">ACG-2020</a>		20	-	<a href="#">KMF3100A</a>	<a href="#">MIF3100</a>
<a href="#">ACG-40P5</a>		380-480	0.5	-	<a href="#">KMF306A</a>
<a href="#">ACG-41P0</a>	1		-	<a href="#">KMF306A</a>	<a href="#">MIF310</a>
<a href="#">ACG-42P0</a>	2		-	<a href="#">KMF306A</a>	<a href="#">MIF310</a>
<a href="#">ACG-43P0</a>	3		-	<a href="#">KMF310A</a>	<a href="#">MIF310</a>
<a href="#">ACG-45P0</a>	5		-	<a href="#">KMF318A</a>	<a href="#">MIF316</a>
<a href="#">ACG-47P5</a>	7.5		-	<a href="#">KMF318A</a>	<a href="#">MIF323</a>
<a href="#">ACG-4010</a>	10		-	<a href="#">KMF336A</a>	<a href="#">MIF330B</a>
<a href="#">ACG-4015</a>	15		-	<a href="#">KMF336A</a>	<a href="#">MIF350</a>
<a href="#">ACG-4020</a>	20		-	<a href="#">KMF350A</a>	<a href="#">MIF350</a>
<a href="#">ACG-4025</a>	25		-	<a href="#">KMF350A</a>	<a href="#">MIF350</a>
<a href="#">ACG-4030</a>	30	-	<a href="#">KMF370A</a>	<a href="#">MIF375</a>	

\*1 -EMI rating for motor cable length: C2 to 75Ft, C1 to 30ft

\*2 -EMI rating for motor cable length: C2 to 150Ft, C1 to 75ft

\*3 -EMI rating for motor cable length: C2 to 300Ft, C1 to 150ft



# IronHorse ACG Series Accessories

## Line Reactors/Voltage Time Filters

Installing an AC Line Reactor on the input side of an AC motor drive can increase line impedance, improve the power factor, reduce input current, increase system capacity, and reduce interference generated from the motor drive.

Installing a load reactor or voltage time filter on the drive's output side can increase the high-frequency impedance to reduce the dV/dT and terminal voltage to protect the motor. Use output filters if the motor cable length exceeds 100ft or any applications where reduced reflected waves is needed.

Line/Load Reactors & AC Output Filters											
Drive	Voltage	HP	Input (Amps)	Output FLA 3ph (Amps)	AC Input Line Reactor		AC Output Load Reactor		AC dVdT Output Filter**		DC reactor values Induct./Current
					3ph	1ph	3ph	1ph	3ph	1ph	
<a href="#">ACG-20P5</a>	200-240	0.5	2.2	2.5	<a href="#">LR2-20P5</a>	<a href="#">LR2-20P2</a>	<a href="#">LR2-20P5</a>	<a href="#">LR2-20P2</a>	<a href="#">VTF-246-CFG</a>	<a href="#">VTF-46-DE</a>	*
<a href="#">ACG-21P0</a>		1	4.9	5.0	<a href="#">LR2-21P0</a>	<a href="#">LR2-21P0</a>	<a href="#">LR2-21P0</a>	<a href="#">LR2-20P5</a>	<a href="#">VTF-24-FH</a>	<a href="#">VTF-246-CFG</a>	
<a href="#">ACG-22P0</a>		2	8.4	8.0	<a href="#">LR-23P0</a>	<a href="#">LR-25P0</a>	<a href="#">LR2-22P0</a>	<a href="#">LR2-22P0</a>	<a href="#">VTF-246-GJJ</a>	<a href="#">VTF-24-FH</a>	
<a href="#">ACG-23P0</a>		3	11.8	11.0	<a href="#">LR-23P0</a>	<a href="#">LR-23P0</a>	<a href="#">LR2-22P0</a>	<a href="#">LR2-22P0</a>	<a href="#">VTF-4-M</a>	<a href="#">VTF-246-GJJ</a>	
<a href="#">ACG-25P0</a>		5	18.5	17.0	<a href="#">LR-25P0</a>	<a href="#">LR-2010</a>	<a href="#">LR-25P0</a>	<a href="#">LR2-22P0</a>	<a href="#">VTF-46-LM</a>	<a href="#">VTF-246-HKL</a>	
<a href="#">ACG-27P5</a>		7.5	25.8	24.0	<a href="#">LR-2010</a>	<a href="#">LR-2015</a>	<a href="#">LR-27P5</a>	<a href="#">LR-25P0</a>	<a href="#">VTF-246-KMN</a>	<a href="#">VTF-24-JL</a>	
<a href="#">ACG-2010</a>		10	34.9	32.0	<a href="#">LR-2015</a>	<a href="#">LR-2020</a>	<a href="#">LR-2010</a>	<a href="#">LR-25P0</a>	<a href="#">VTF-246-LPQ</a>	<a href="#">VTF-46-LM</a>	
<a href="#">ACG-2015</a>		15	53	47	<a href="#">LR-2020</a>	<a href="#">LR-2030</a>	<a href="#">LR-2015</a>	<a href="#">LR-2010</a>	<a href="#">VTF-246-NRS</a>	<a href="#">VTF-46-NP</a>	0.95/61
<a href="#">ACG-2020</a>		20	68	60	<a href="#">LR-2025</a>	<a href="#">LR-2040</a>	<a href="#">LR-2020</a>	<a href="#">LR-2010</a>	<a href="#">VTF-246-PSU</a>	<a href="#">VTF-246-LPQ</a>	0.70/75
<a href="#">ACG-40P5</a>	380-480	0.5	1.1	1.3	<a href="#">LR2-40P5</a>				<a href="#">VTF-46-DE</a>		*
<a href="#">ACG-41P0</a>		1	2.4	2.5	<a href="#">LR2-41P0</a>				<a href="#">VTF-246-CFG</a>		
<a href="#">ACG-42P0</a>		2	4.2	4.0	<a href="#">LR2-42P0</a>				<a href="#">VTF-246-DGH</a>		
<a href="#">ACG-43P0</a>		3	5.9	5.5	<a href="#">LR2-43P0</a>				<a href="#">VTF-24-FH</a>		
<a href="#">ACG-45P0</a>		5	9.8	9.0	<a href="#">LR2-45P0</a>				<a href="#">VTF-46-DE</a>		
<a href="#">ACG-47P5</a>		7.5	12.9	12.0	<a href="#">LR2-47P5</a>				<a href="#">VTF-46-DE</a>		
<a href="#">ACG-4010</a>		10	17.5	16.0	<a href="#">LR-4010</a>				<a href="#">VTF-24-JL</a>		
<a href="#">ACG-4015</a>		15	27	24	<a href="#">LR-4015</a>				<a href="#">VTF-246-KMN</a>		1.90/32
<a href="#">ACG-4020</a>		20	35	31	<a href="#">LR-4020</a>				<a href="#">VTF-246-LPQ</a>		1.40/41
<a href="#">ACG-4025</a>		25	44	39	<a href="#">LR-4025</a>				<a href="#">VTF-246-MQR</a>		1.00/49
<a href="#">ACG-4030</a>		30	51	45	<a href="#">LR-4030</a>				<a href="#">VTF-246-MQR</a>		0.70/64

\* Only drives from 11–22 kW support DC reactors.

\*\* NEMA1 filter versions are available. Use same PN with suffix -N1.





# IronHorse ACG Series Accessories

## Braking Resistors

Dynamic braking absorbs the motor regeneration energy when the motor is decelerated faster than it would if it was allowed to coast to a stop. The regeneration energy is dissipated by braking resistors. All drives have the braking function built-in and do not require a separate dynamic braking unit. The recommended open type or NEMA 1 type brake resistors available at AutomationDirect for each drive model are listed in the table below.

Brake Resistors											
Voltage	Drive	Drive Power (HP)	Drive Braking Capacity-Max Torque			150% Braking Torque @ 5% Duty Cycle					
			Minimum Resistor	Max Total Brake Current (A)	Peak Power (kW)	Open Type Resistors			NEMA1 Resistors with Thermal Switch		
						ADC Part Number	Qty	Total Brake Current (A)	ADC Part Number	Qty	Total Brake Current (A)
230	<a href="#">ACG-20P5</a>	0.5	250.0	1.6	0.6	<a href="#">GS-BR-300W250</a>	1	1.6	<a href="#">BR-N1-240W250</a>	1	1.6
	<a href="#">ACG-21P0</a>	1	150.0	2.6	1.0	<a href="#">GS-BR-400W150</a>	1	2.6	<a href="#">BR-N1-240W150</a>	1	2.6
	<a href="#">ACG-22P0</a>	2	50.0	7.8	3.0	<a href="#">GS-BR-300W070</a>	1	5.6	<a href="#">BR-N1-280W50</a>	1	7.8
	<a href="#">ACG-23P0</a>	3	43.0	9.1	3.5	<a href="#">GS-BR-1K5W043</a>	1	9.1	<a href="#">BR-N1-720W50</a>	1	7.8
	<a href="#">ACG-25P0</a>	5	25.0	15.6	6.1	<a href="#">GS-BR-1K2W015</a>	2S	13.0	<a href="#">BR-N1-800W25</a>	1	15.6
	<a href="#">ACG-27P5</a>	7.5	18.0	21.7	8.5	<a href="#">GS-BR-1K0W020</a>	1	19.5	<a href="#">BR-N1-800W18P0</a>	1	21.7
	<a href="#">ACG-2010</a>	10	14.0	27.9	10.9	<a href="#">GS-BR-1K2W015</a>	1	26.0	<a href="#">BR-N1-1K5W14P0</a>	1	27.9
	<a href="#">ACG-2015</a>	15	8.6	45.3	17.7	<a href="#">GS-BR-1K5W012</a>	1	32.5	<a href="#">BR-N1-2K2W08P6</a>	1	45.3
	<a href="#">ACG-2020</a>	20	8.0	48.8	19.0	<a href="#">GS-BR-1K2W015</a>	2P	52.0	<a href="#">BR-N1-2K2W08P6</a>	1	45.3
460	<a href="#">ACG-40P5</a>	0.5	400.0	2.0	1.5	<a href="#">GS-BR-300W400</a>	1	2.0	<a href="#">BR-N1-250W400</a>	1	2.0
	<a href="#">ACG-41P0</a>	1	400.0	2.0	1.5		1		<a href="#">BR-N1-240W250</a>	1	
	<a href="#">ACG-42P0</a>	2	250.0	3.1	2.4		1		<a href="#">BR-N1-500W200</a>	1	3.9
	<a href="#">ACG-43P0</a>	3	180.0	4.3	3.4	<a href="#">GS-BR-200W360</a>	2P	4.3	<a href="#">BR-N1-720W85</a>	1	9.2
	<a href="#">ACG-45P0</a>	5	85.0	9.2	7.2	<a href="#">GS-BR-300W250</a>	2P	6.2	<a href="#">BR-N1-1K2W75</a>	1	10.4
	<a href="#">ACG-47P5</a>	7.5	75.0	10.4	8.1	<a href="#">GS-BR-1K0W075</a>	1	10.4	<a href="#">BR-N1-1K2W50</a>	1	15.6
	<a href="#">ACG-4010</a>	10	49.0	15.9	12.4	<a href="#">GS-BR-1K5W043</a>	1	18.1	<a href="#">BR-N1-1K5W40</a>	1	19.5
	<a href="#">ACG-4015</a>	15	40.0	19.5	15.2	<a href="#">GS-BR-1K5W043</a>	1	18.1	<a href="#">BR-N1-2K3W26</a>	1	30.0
	<a href="#">ACG-4020</a>	20	22.0	35.5	27.7		2P	36.3	<a href="#">BR-N1-2K8W25</a>	1	31.2
	<a href="#">ACG-4025</a>	25	20.0	39.0	30.4		2P		<a href="#">BR-N1-3K6W20</a>	1	39.0
	<a href="#">ACG-4030</a>	30	20.0	39.0	30.4		2P				

Note: Where noted on resistor quantity, S = series wiring, P = parallel wiring.



# IronHorse AC Series Accessories

## VFD Suite

VFD Suite is the configuration software for the Automation Direct Ironhorse AC family of variable frequency drives, featuring the ACG IP20 series and the ACN Nema4X series. It is designed to allow connection of a personal computer to the drives and perform a variety of functions:

- Create new drive configurations
- Upload/Download drive configurations
- Edit/Compare drive configurations
- Utilize Parameter Wizard for easy configuration
- Archive/Store multiple drive configurations on your PC
- Trend drive operation parameters
- Tune the drive PID loop
- View real time key operating parameters
- Start/Stop drive and switch directions, provided drive is set up for remote operation
- View drive faults
- Program Function blocks for simple control applications (ACN series only, 18 steps maximum)

VFD Suite includes a PDF help file for explanation of the software and features. VFD Suite can be downloaded for free from [Automationdirect.com](http://Automationdirect.com).

## System Requirements

Category	Requirement
<b>Windows</b>	Windows 8/10/11
<b>Processor</b>	1 GHz or higher
<b>RAM</b>	1 GB (32-bit) or 2 GB (64-bit)
<b>HDD</b>	16 GB (32-bit) or 20 GB (64-bit)
<b>Graphics</b>	Graphic card supporting MS DirectX 9



## Communication Cable

(For ACN series drives only)



**ACN-232C**

Communication Cable			
Part Number	Price	Description	Drive Compatibility
<b><u>ACN-232C</u></b>	\$91.00	IronHorse programming/communication cable, 3.2ft/1m cable length, RS-232 (RJ45 8P8C) to USB A. Not compatible with Windows 11 software. Instead use USB-485M PC adapter.	ACN series drives only