GS20X AC Drives Installation Instructions

NEMA 4X Sensorless Vector Control Variable Frequency Micro-drive

5014120404 - 202204

- *Please read this instruction sheet thoroughly before installation and retain for later reference.*
- *To ensure the safety of operators and equipment, only qualified personnel familiar with AC drives should install, wire, program, and operate the GS20X drive. Always read this instruction sheet thoroughly before using the GS20X drive, especially the WARNING, DANGER and CAUTION notes. If you have any questions, please contact AutomationDirect.*

PLEASE READ PRIOR TO INSTALLATION FOR SAFETY

DANGER	• *The ground terminal of the GS20X drive must be grounded correctly. The grounding method must comply with the laws of the country where the GS20X drive is to be installed.* • *After power has been turned off, the capacitors in the GS20X drive may retain a charge for several minutes. To prevent personal injury, visually verify that the "CHARGE" LED has turned off. Then measure to confirm that the DC bus voltage level between terminals (+1) and (-) is less than 25VDC before touching any terminals. (Capacitor discharge will take at least 5 minutes for most GS20X models)* • *The CMOS ICs on the internal circuit boards of the GS20X drive are sensitive to static electricity. Please DO NOT touch the circuit boards with your bare hands before taking anti-static measures. Never disassemble the internal components or circuits.* • *If wiring changes must be made, turn off power to the GS20X drive before making those changes. Allow the internal DC bus capacitors in the GS20X drive sufficient time to discharge prior to making changes in power or control wiring. Failure to do so may result in short circuit and fire. To ensure personal safety, allow DC bus voltage to discharge to a safe level before making wiring changes to the GS20X drive.* • *DO NOT install the GS20X drive in locations subject to high temperature, direct sunlight, or flammable materials.*
WARNING	• *Never apply power to the output terminals U/T1, V/T2, W/T3 of the GS20X drive. If a fault occurs during operation of the GS20X drive, refer to the fault code descriptions and corrective actions to reset the fault before attempting to operate the GS20X drive.* • *DO NOT use Hi-pot test for internal components. The semi-conductors in the GS20X drive are easily damaged by high voltage.*
CAUTION	• *Long motor lead lengths may result in reflective wave due to impedance mismatch between the motor cable and the motor. Reflective wave may damage the insulation of the motor. To avoid the possibility of reflective wave damage, use an inverter-rated motor with an insulation rating of 1600 volts. A load reactor installed between the GS20X drive and motor will help to mitigate reflective wave.* • *Nominal supply voltage to the GS20X drive should be less than or equal to 120/240/480 volts AC depending on GS20X model.* • *Nominal supply current capacity should be less than or equal to 100kA for all GS20X models.* • *The GS20X drive must be installed in a clean, well-ventilated and dry location, free from corrosive gases or liquids.* • *The GS20X drive must be stored within an ambient temperature range from –40°C to +85°C, and relative humidity range of 0% to 90% without condensation.* • *Do not apply AC power to the GS20X drive with the front cover removed. Following a fault of the GS20X drive, wait 5 seconds before pressing the RESET key.* • *To improve power factor, install a line reactor ahead of the GS20X drive. Do not install power correction capacitors in the main AC supply circuit to the GS20X drive to prevent drive faults due to over-current.*

Minimum Wiring

- *AC input power to R/L1, S/L2, T/L3 (for single-phase input, use two of the terminals) (For applicability of 1-phase input power, please refer to Chapter 1 of the DURApulse GS20X AC Drives User Manual at AutomationDirect.com.)*
- *Ground from the power supply*
- *Drive power to the motor (U, V, W on T1, T2, T3) (For use with 3-phase motors only!)*
- *Ground to the motor*
- *STO1 and STO2 (both must be wired through appropriate N.C. safety-rated contacts to DCM or the factory-installed jumpers must be left in place)*

With this minimal wiring, the drive can be operated via the keypad to test the motor and drive installation. See the "Parameter Set Up" (page 4) section to configure the drive for keypad operation.

Recommended Safety Wiring

We strongly recommend that customers use the STO safety feature.

The Safe Torque Off (STO) function turns off the power supplied to the motor through the hardware, so that the motor cannot produce torque. This method of removing power from the motor is considered an emergency stop, also known as "coast to stop."

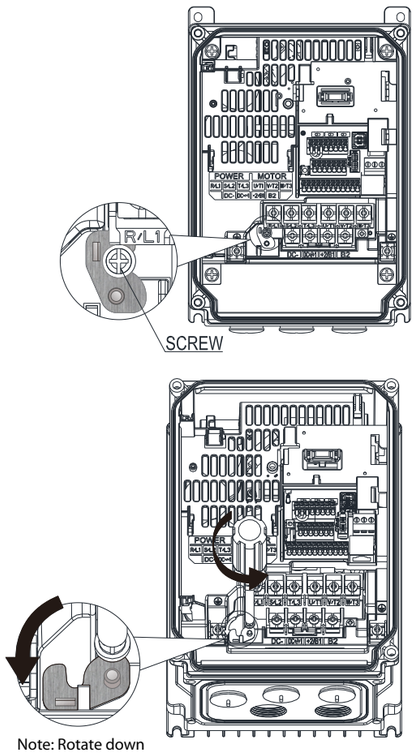
To use this feature, disconnect the appropriate factory-installed jumpers and wire a safety relay or safety PLC as shown. The E-Stop pushbutton should be wired through a safety relay or PLC to meet Category 3 safety requirements. See User Manual Appendix E for wiring the GS20X with STO.

Wiring Diagrams

RFI Jumper Removal

If the power distribution system supplying the GS20X AC drive is a floating (IT) or an asymmetric ground system, the RFI jumper must be removed.
Removing the RFI jumper uncouples the internal RFI capacitor (filter capacitor) between the GS20X drive frame and circuitry to avoid damaging those circuits and (according to IEC 61800-3) to reduce ground leakage current.

GS20X Frame A through C



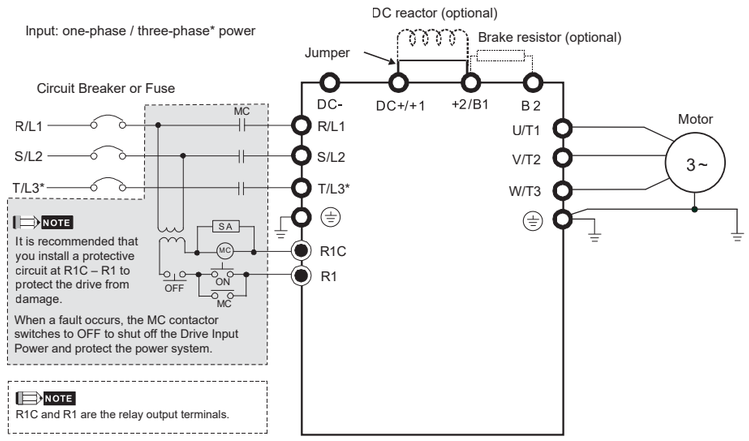
Note: Rotate down

Main Wiring (Power Circuit)

For main (power) wiring terminal specifications, Please refer to "Specifications for Wiring Terminals – Main-Circuit Terminals" (page 2).

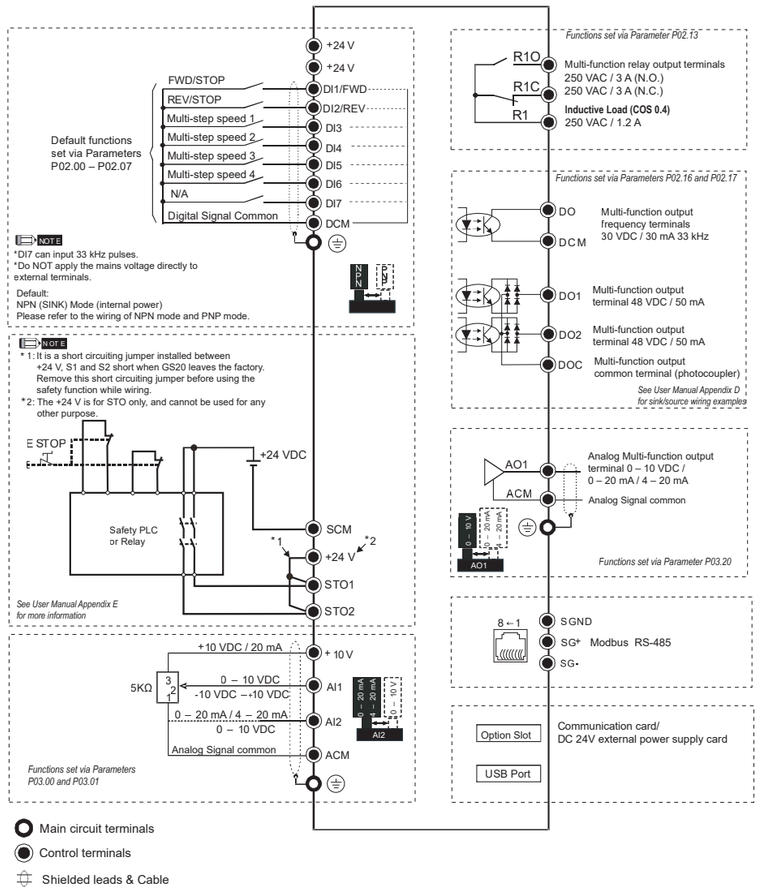
GS20X all Frames

*(Note that 1-phase drives do not have a T/L3 terminal. 120V drives do not have DC-, DC+ terminals.)

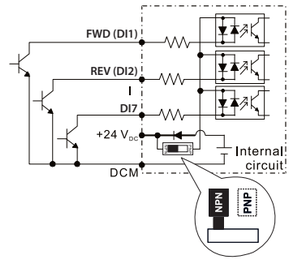


GS20X Control Terminal Wiring

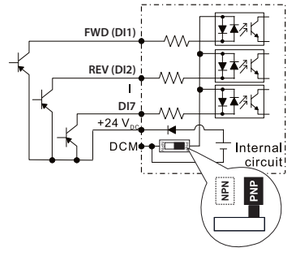
See page 2 for Start/Stop wiring options.



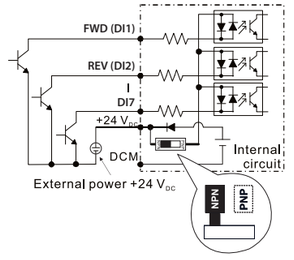
① Sink Mode with internal power (+24 V_{DC})



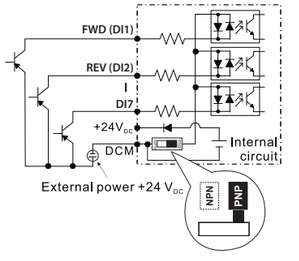
② Source Mode with internal power (+24 V_{DC})

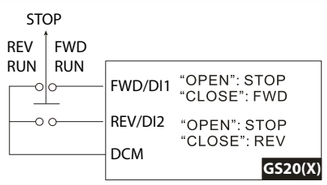
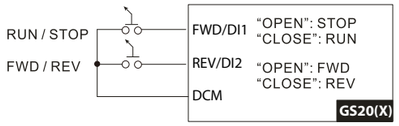
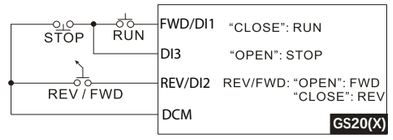


③ Sink Mode with external power



④ Source Mode with external power

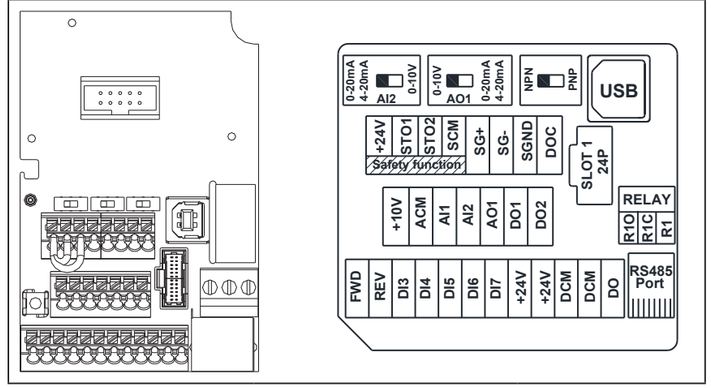


P02.00	External Terminal Control Circuits
Setting value: 1 Two-wire operation control FWD / STOP REV / STOP	
Setting value: 2 Two-wire operation control RUN / STOP FWD / REV	
Setting value: 3 Three-wire operation control	

SPECIFICATIONS FOR WIRING TERMINALS – CONTROL CIRCUIT

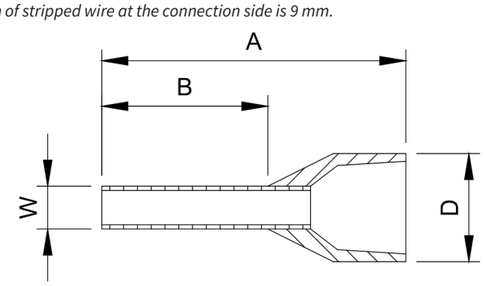
GS20X-xxxx All Models; All Frame Sizes

Terminal	Wire Gauge	Torque
Control	24–18 AWG [0.21–0.82 mm²]	n/a (spring terminals)
Relay	24–16 AWG [0.21–1.31 mm²]	5kg·cm [4.3 lb·in]



WIRING PRECAUTIONS

1) *The factory default condition is +24 V/ S1/ S2 shorted by jumper, as shown in the block 1 of the figure above. Refer to the wiring chapter of the User Manual for more details.*
2) *The +24 V power supply for safety function is only for STO use and cannot be used for other purposes.*
3) *The RELAY terminal uses the PCB terminal block:*
   - *Tighten the wiring with a 3.5 mm width and 0.6 mm thickness slotted screwdriver.*
   - *The ideal length of stripped wire at the connection side is 6–7 mm.*
   - *When wiring bare wires, make sure they are perfectly arranged to go through the wiring holes.*
4) *The control circuit terminal uses a spring clamp terminal block:*
   - *Tighten the wiring with a 2.5 mm width and 0.4 mm thickness slotted screwdriver.*
   - *The ideal length of stripped wire at the connection side is 9 mm.*



RECOMMENDED MODELS OR DIMENSIONS FOR FERRULE TERMINALS

Wire Gauge	Manufacturer	Model Name	A (MAX)	B (MAX)	D (MAX)	W (MAX)
0.25 mm2 [24 AWG]	PHOENIX CONTACT	AI 0,25- 8 YE	12.5	8	2.6	1.1
0.34 mm2 [22 AWG]	PHOENIX CONTACT	AI 0,34- 8 TQ	12.5	8	3.3	1.3
0.5 mm2 [20 AWG]	PHOENIX CONTACT	AI 0,5 - 8 WH	14	8	3.5	1.4
	Z+F	V30AE000006	14	8	2.6	1.15

SPECIFICATIONS FOR WIRING TERMINALS – MAIN-CIRCUIT TERMINALS

Notes:

- *If you install at Ta 40°C above environment, please use copper wire with a 600V voltage rating and temperature resistance of 90°C or higher.*
- *For UL compliant installation, you must:*
  1) *Use 75°C temperature resistant copper wire or better. Do not reduce wire gauge when using higher temperature wire.*
  2) *Use the specific ring lug part listed in the table below.*
  3) *Use crimp tool KST2000D-1322 or IZUMI 5N18 for 22−8 AWG wire, or IZUMI 9H-60 for 6−4 AWG wire.*

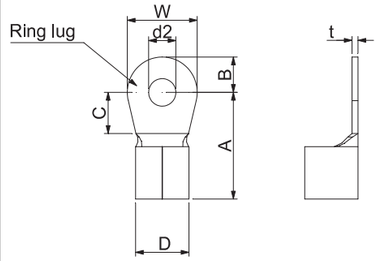


Figure 1.

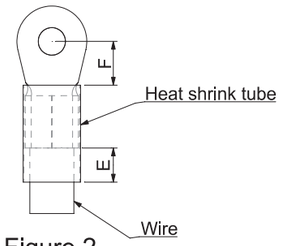


Figure 2.

Drive Models		Max Wire Gauge	Min Wire Gauge	Screw Size	Torque (±10%)	Ring Lug Dimensions (mm)
Frame A	***GS21X-20P5***	14AWG [2.5 mm²]	14AWG [2.5 mm²]	M3.5	9 kg-cm [7.8 lb-in.] [0.88 N·m]	
	GS21X-21P0		16AWG [1.5 mm²]			
	GS23X-20P5		18AWG [0.75 mm²]			
	GS23X-40P5					
	GS23X-41P0					
	GS21X-21P0	12AWG [4mm²]	12AWG [4mm²]	M4	15 kg-cm [13.0 lb-in.] [1.47 N·m	
	GS21X-22P0		14AWG [2.5 mm²]			
	GS23X-42P0		16AWG [1.5 mm²]			
	GS21X-22P0	10AWG [6 mm²]	10AWG [6 mm²]	M4	20 kg-cm [17.4 lb-in.] [1.96 N·m]	
	GS23X-43P0		14AWG [2.5 mm²]			
Frame B	***GS21X-23P0***	8AWG [10 mm²]	8AWG [10 mm²]	M4	20 kg-cm [17.4 lb-in.] [1.96 N·m]	
	GS23X-25P0					
	GS23X-23P0		10AWG [6 mm²]			
	GS23X-45P0		12AWG [4mm²]			

Dim.	Value	Min/ Max
A	14-18 AWG: 11.1 10-12 AWG: 12.1	Max
B	4.0	Max
C	14-18 AWG: 6.3 10-12 AWG: 6.1	Min
D	16-18 AWG: 3.4 14AWG: 4.1 10-12 AWG: 5.6	Max
d2	4.3	Min
E	13.0	Min
F	16-18 AWG: 4.5 10-14 AWG: 5.5	Min
W	14-18 AWG: 6.6 10-12 AWG: 7.2	Max
t	14-18 AWG: 0.8 10-12 AWG: 1	Max

Dimension	Value	Min/Max
A	17.8	Max
B	5.0	Max
C	6.1	Min
D	7.2	Max
d2	4.3	Min
E	13.0	Min
F	5.5	Min
W	8.0	Max
t	1.2	Max

SPECIFICATIONS FOR WIRING TERMINALS – MAIN-CIRCUIT TERMINALS (CONTINUED)

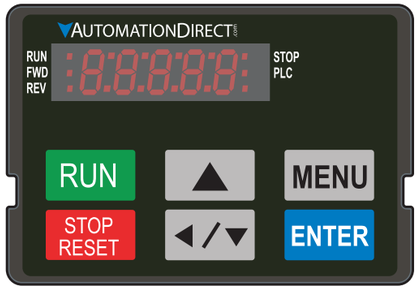
Drive Models		Max Wire Gauge	Min Wire Gauge	Screw Size	Torque (±10%)	Ring Lug Dimensions (mm)
Frame C	***GS23X-27P5***	8AWG [10 mm²]	8AWG [10 mm²]	M4	20 kg-cm [17,4 lb-in.] [1.96 N·m]	
	GS23X-4010					
	GS23X-47P5		10AWG [6 mm²]			

Dimension	Value	Min/Max
A	17.8	Max
B	5.0	Max
C	6.1	Min
D	7.2	Max
d2	4.3	Min
E	13.0	Min
F	5.5	Min
W	8.0	Max
t	1.2	Max

Digital Keypad Functions and Indications

Description of the functions of the keys and indicators of the GS20X AC Drive Keypad.

NOTE: Drive default is AUTO mode. There is no indication from the keypad of the mode. Local mode can be set with I/O configuration or GS4-KPD only.



Descriptions of Keypad Functions	
RUN	**RUN Key** • Valid only when the source of operation command is from the keypad. • RUN can be pressed even when drive is in process of stopping. • When in "LOCAL" mode, RUN is valid only when the source of operation command is from the keypad (drive default is Auto mode, Local mode can be set with I/O or GS4-KPD only).
STOP RESET	**STOP/RESET Key** *This key has the highest processing priority in any situation.* • When the drive receives a STOP command, whether or not the drive is in operation or stop status, the drive will execute a "STOP" command. • The RESET key can be used to reset the drive after a fault occurs. For those faults that can't be reset by the RESET key, see the fault records after pressing MENU key for details. *NOTE: The ability to STOP the drive from the keypad is effective ONLY if the drive is configured to RUN and/or STOP from the keypad. Keypad STOP can be disabled by parameter 00.32, Digital Keypad STOP Function.*
ENTER	**ENTER Key** Press ENTER to go to the next menu level or accept parameter entry. If it is the last level, then press ENTER to execute the command.
MENU	**MENU Key** Press MENU to return to the Main Menu or cycle through the available menu options.
▲	**Direction: Up** Press to make the value set on the current menu/parameter higher.
◀/▼	**Direction: Left/Down** • Press to make the value set on the current menu/parameter lower. • In the menu/text selection mode, the arrows are used for item selection. Long press the MENU key to use the left direction function.

Descriptions of LED Functions	
RUN	**Steady ON**: Drive is running. **Blinking**: Drive is stopping or in base block. **Steady OFF**: Drive is not running.
FWD	**Steady ON**: Drive is operating in Forward mode. **Blinking**: Drive is changing direction. **Steady OFF**: Drive is operating in Reverse mode.
REV	**Steady ON**: Drive is operating in Reverse mode. **Blinking**: Drive is changing direction. **Steady OFF**: Drive is operating in Forward mode.
STOP	**Steady ON**: Drive is stopped or in the process of stopping. **Blinking**: Drive is in standby (run but does not output). **Steady OFF**: Drive is not currently executing an operational (STOP) command. *NOTE: The ability to STOP the drive from the keypad is effective ONLY if the drive is configured to RUN and/or STOP from the keypad. Keypad STOP can be disabled by parameter 00.32, Digital Keypad STOP Function.*
PLC	**Steady ON**: PLC STOP (PLC 2) initiated. **Blinking**: PLC Run (PLC1) inititated. **Steady OFF**: No PLC functions implemented (PLC 0).

Keypad Navigation Example

Instruction	*Press Key*	*Display Will Show*	
First menu to display after power up.	n/a	Displays the present frequency setting of the drive	
Press MENU once from startup.	MENU	Displays the actual output frequency of the motor	
Press MENU twice from startup.	MENU	Displays user defined output	
Press MENU three times from startup.	MENU	Displays output current	
Press MENU four times from startup. Displays Frd if the drive is currently configured for Forward operation. Press the UP or DOWN key to change to Reverse. Press ENTER to confirm the change.	MENU, UP/ DOWN ENTER	Displays the Forward command if configured for Forward operation.	
		Displays the Reverse command if configured for Reverse operation.	
Enable the counter by setting parameter 00.04 to 1. See the user manual for full instructions on using the counter.	MENU	Displays the counter value	
After selecting the desired menu option, press ENTER to bring up the parameter number (Format XX.YY). Use the UP and DOWN arrow keys to change the parameter number as needed, then press ENTER to adjust the parameter value.	ENTER, UP/ DOWN, ENTER	Displays the parameter number	
From the parameter number screen, press ENTER to bring up the current value of the selected parameter. Use the UP and DOWN arrows to adjust the value. Press ENTER again to confirm the choice.	ENTER, UP/ DOWN	Displays the value of the selected parameter	
Once a desired parameter value has been set using the UP and DOWN arrow keys, press ENTER to save the choice and display End message.	ENTER	End message. Displays when data has been accepted and stored	
Displays when data is not accepted or the value exceeded	n/a	Error message.	
Scroll sequentially through the suggested parameters (listed on page 4), and set those parameters as needed for your application. Consult User Manual for additional parameters. After changing all of the applicable parameters, press "MENU" key repeatedly to return to the Menu screen.			

GS20X Fault Codes

See Chapter 6 of the User Manual for more details.

Fault Codes	
0: No Error 1: Overcurrent during Accel (ocA) 2: Overcurrent during Decel (ocd) 3: Overcurrent during constant speed (ocn) 4: Ground Fault (GFF) 6: Overcurrent during Stop (ocS) 7: Overvoltage during Accel (ovA) 8: Overvoltage during Decel (ovd) 9: Overvoltage during constant speed (ovn) 10: Overvoltage during Stop (ovS) 11: Low voltage during Accel (LvA) 12: Low voltage during Decel (Lvd) 13: Low voltage during constant speed (Lvn) 14: Low voltage during Stop (LvS) 15: Input phase loss (OrP) 16: IGBT Overheat 1 (oH1) 18: Thermister 1 open (tH1o) 21: Drive over-load (oL) 22: Electronics thermal relay protection 1 (EoL1) 23: Electronics thermal relay protection 2 (EoL2) 24: Motor Overheat-PTC (oH3) 26: Over Torque 1 (ot1) 27: Over Torque 2 (ot2) 28: Under current (uc) 31: Memory read-out error (cF2) 33: U phase current sensor detection error (cd1) 34: V phase current sensor detection error (cd2) 35: W phase current sensor detection error (cd3) 36: Clamp current detection error (Hd0) 37: Over-current detection error (Hd1) 40: Auto tuning error (AuE) 41: PID Feedback loss (AFE) 42: PG feedback error (PGF1) 43: PG feedback loss (PGF2) 44: PRG feedback stall (PGF3) 45: PG slip error (PGF4) 48: Analog current input loss (ACE) 49: External Fault input (EF) 50: Emergency Stop (EF1) 51: External Base Block (bb) 52: Password Error (Pcod)	54: Communication Error (CE1) 55: Communication Error (CE2) 56: Communication Error (CE3) 57: Communication Error (CE4) 58: PC Communication Time Out (CE10) 61: Y-Delta connection Error (ydc) 62: Decel Energy Backup Error (dEb) 63: Slip Error (oSL) 72: Channel 1 (S1~SCM) safety loop error (SrL1) 76: Safety Torque Off (SrO) 77: Channel 2 (S2~SCM) safety loop error (SrL2) 78: Internal loop error (SrL3) 79: U Phase over current before run (Aoc) 80: V Phase over current before run (boc) 81: W Phase over current before run (coc) 82: U Phase output phase loss (oPL1) 83: V Phase output phase loss (oPL2) 84: W Phase output phase loss (oPL3) 87: Drive over load in low frequency (oL3) 89: Initial rotor position detection error (roPd) 121: Internal communication error (CP20) 123: Internal communication error (CP22) 124: Internal communication error (CP30) 126: Internal communication error (CP32) 127: Software version error (CP33) 128: Over-torque 3 (ot3) 129: Over-torque 4 (ot4) 134: Electronics thermal relay 3 protection (EoL3) 135: Electronics thermal relay 4 protection (EoL4) 140: GFF detected when power on (Hd6) 141: GFF occurs before run (b4GFF) 142: Auto tuning error 1 (DC test stage) (AUE1) 143: Auto tuning error 2 (High frequency test stage) (AUE2) 144: Auto tuning error 3 (Rotary test stage) (AUE3)

Introduction – How To Get Started

AutomationDirect.com would like to thank you for your purchase of the Durapulse GS20X AC drive. The GS20X drive is a state-of-the-art, full-featured AC drive. The Quick-Start Guide below will introduce you to many of the GS20X drive features and help you configure the GS20X drive in a minimum amount of time.

STO (Safe Torque Off) / Emergency Stop

The GS20X drive offers Safe Torque Off (STO) functionality, instead of a standard Emergency Stop circuit. STO provides the ability to immediately turn off the output of the GS20X drive in the event of an emergency, without the need for an emergency stop contactor between the drive and motor.

Please see the Control-Circuit Wiring diagrams (page 1) for how to wire the STO circuit. From the factory, the GS20X STO terminals are jumpered and the STO circuitry of the drive is bypassed. STO is recommended for personnel safety.

After wiring the drive (*but before applying power*), the first thing you should do is press the E-stop button (or otherwise break the safety circuit) and verify that the circuit between the STO1/STO2 terminals and the STO +24V terminal is not connected. If these circuits are open, the STO feature will stop all power from going to the motor and there will be no danger of unexpected movement when you power up the drive.

Powering Up the GS20X Drive

Apply AC line power to the GS20X drive, but don't engage the safety circuit yet (keep the E-stop PB pushed in).

Starting, Stopping, and Controlling the Speed of the GS20X Drive

Out of the box GS20X drives are set to use the keypad buttons to RUN and STOP the drive and vary the drive speed. The drive can also be configured to run from potentiometers, external pushbuttons, Ethernet communication, etc.

Do not attempt to run the motor yet. Certain parameters (especially the motor protection parameters) must be set first.

Configure the Drive

The tables below list those parameters typically used in most applications. You can navigate to any of these parameters through the keypad. (Refer to page 3 for information and instructions for using the Digital Keypad.)

All applications need to configure the parameters in the "Quick Configuration" table. At minimum, you MUST configure these motor parameters before operating the drive:

- *01.02 Motor1 Max Output Voltage (this will typically be either 230V or 460V)*
- *05.01 Motor1 Rated Amps (depends on the motor)*
- *01.01 Motor1 Max Output Frequency (this will typically be 50Hz or 60Hz)*

The main configuration parameters required to get your drive up and running are included in this guide. For more advanced configuration options, please see the User Manual. Your application will dictate which parameters need to be configured. It is NOT necessary to configure every parameter listed in the tables in the User Manual, use only those you need.

Parameter Groups

Group Number	Group Category
00	Drive Config
01	Basic Config
02	Digital I/O Config
03	Analog I/O Config
04	Multi-Step Speed Config
05	Motor Config
06	Protection Config
07	Special Parameters
08	PID Config
09	Communications Config
10	Speed Control Config
11	Advanced Config
13	Macro Config
14	Protection (2) Config

After configuring the minimum settings, you can now engage the safety circuit. The RUN and STOP/RESET buttons should Start and Stop the drive. To adjust the output frequency, press the MENU button repeatedly until the "Fxx" appears for "Frequency Setpoint". Use the Up and Down arrow buttons to adjust the frequency, the press ENTER to confirm. Press ENTER again to return to the main menu.

Parameter Set Up

*DURA*PULSE GS20X AC Drives offer parameter setup from the keypad for some of the most common drives applications. Choose parameters from the table below, then set the applicable parameters for that application as shown.

To Configure Parameters:

From the power up screen:

1) *Press* **MENU** *until you see* **H 0.00** *(this is the parameter group) and press* **ENTER**.
2) *Use the* **UP/DWN** *arrows to select the parameter group you want and press* **ENTER**.
3) *Use the* **UP/DWN** *arrows to select the parameter number you want within that group and press* **ENTER**.
4) *Change the value of the parameter using the* **UP/DWN** *arrows and press* **ENTER**.
5) *Press* **MENU** *to exit back to the main menu.*
6) *Repeat as needed until all required parameters are configured.*

Please refer to the user manual if you need more detailed information about the parameters.

DURA*PULSE GS20X Parameter Settings – Quick Configuration

Parameter Group	Parameter #	Description	Range	Default	User
00	00	GS20X Model ID	Read Only	n/a	
00	01	Displays AC drive rated current	Displays value based on model	n/a	
00	02	Restore to default**	0=No function 1=Parameter write protect 5=Reset kWH display to 0 6=Reset PLC 7=Reserved 8=Keypad doesn't respond 9=Reset 50Hz defaults 10=Reset 60Hz defaults 11=Reset 50Hz defaults (keep user config) 12=Reset 60Hz defaults (keep user config)	0	
00	06	Firmware Version	Read Only	n/a	
00	10	Control Mode	0=Speed mode 2=Torque mode	0	
00	11	Speed Control Mode	0=VF (IM V/F control) 1=VFPG (IM V/F control + Encoder) 2=SVC (Parameter 05.33 set as IM or PM) 5=FOC (Field Oriented Control)	0	
00	16	Load Selection	0=VT 1=CT	1	
00	20	Frequency Command Source (Auto)	0=Digital keypad 1=Communication RS-485 input 2=External analog input (refer to parm 03.00) 3=External UP/DOWN terminal 4=Pulse input without direction command (refer to parm 10.16 without direction)	0	
00	21	Operation Command Source (Auto)	0=Digital keypad 1=External terminals 2=Communication RS-485 input 5=Communication card	0	
00	22	Stop Method	0=Ramp to stop 1=Coast to stop	0	
00	23	Motor Direction Control	0=Enable forward/reverse 1=Disable reverse 2=Disable forward	0	
01	00	Motor 1 Max Frequency	0.00-599.00 Hz	60	
01	01	Motor 1 Base Frequency	0.00-599.00 Hz	60	
01	02	Motor 1 Rated Voltage	110V/230V: 0.0~255.0 460V: 0.0~510.0V	220.0 440.0	
01	09	Startup Frequency	0.00-599.0 Hz	0.5	
01	10	Output Frequency Upper Limit	0.00-599.0 Hz	599.0	
01	11	Output Frequency Lower Limit	0.00-5.99.0 Hz	0.00	
01	12	Acceleration Time 1	P01.45=0: 0.00-600.00 sec P01.45=1: 0.00-6000.00 sec	10.00 10.00	
01	13	Deceleration Time 1	P01.45=0: 0.00-600.00 sec P01.45=1: 0.00-6000.00 sec	10.00 10.00	
01	20	Jog Acceleration Time	P01.45=0: 0.00-600.00 sec P01.45=1: 0.00-6000.00 sec	10.00 10.00	
01	21	Jog Deceleration Time	P01.45=0: 0.00-600.00 sec P01.45=1: 0.00-6000.00 sec	10.00 10.00	
01	22	Jog Frequency	0.00-599.0 Hz	0.5	

* Assumes default V/Hz mode with no feedback. To change control modes see complete parameter listing in User manual.
** Reboot drive after resetting defaults.

***Note:** Drive default is Auto mode and cannot be changed from the keypad. For Local/Hand, use Discrete input configuration settings (P02.00–P02.07) and P00.29–P00.31.*

(table continued next column)

***DURA*PULSE GS20X Parameter Settings – Quick Configuration (continued)**

Parameter Group	Parameter #	Description	Range	Default	User
02	00	2-wire / 3-wire Control	0=No function 1=2-wire mode 1, power on for operation control (M1: FWD/STOP, M2: REV/STOP) 2=2-wire mode 2, power on for operation control (M1: RUN/STOP, M2 REV/FWD) 3=3-wire, power on for operation control (M1: RUN, M2: REV/FWD, M3: STOP) 4=2-wire mode 1, fast start up (M1: FWD/STOP, M2: REV/STOP) 5=2-wire mode 2, fast start up (M1: RUN/STOP, M2: REV/FWD) 6=3-wire, fast start up (M1: RUN, M2: REV/FWD, M3: STOP) Note: In fast start up mode, the drive skips detecting IGBT signal and will run immediately. When using fast start up mode: • Terminal output stays in ready status and drive responds to commands immediately. • The output terminal will have higher voltage • If the drive is short circuited an OC error will display when running up	1	
02	01	Multi-function Input Command 1 (FWD/DI1)	See "Multi-function Input Selections" on page 5	0	
02	02	Multi-function Input Command 2 (REV/DI2)		0	
02	03	Multi-function Input Command 3 (DI3)		1	
02	04	Multi-function Input Command 4 (DI4)		2	
02	05	Multi-function Input Command 5 (DI5)		3	
02	06	Multi-function Input Command 6 (DI6)		4	
02	07	Multi-function Input Command 7 (DI7)		0	
02	13	Multi-function Output 1 (R1)	See "Multi-function Output Selections" on page 5	11	
02	16	Multi-function Output 2 (DO1)		0	
02	17	Multi-function Output 3 (DO2		0	
02	35	Auto-run on Power-up (includes after a Fault reset)	0: Disable 1: Drive Runs if Cmd ON after Flt Reset or Pwr up	0	
03	00	Analog Input Selection (AI1)	See "AI Multi-function Input Selections" on page 5	1	
03	01	Analog Input Selection (AI2)		0	
03	20	Multi-function Output (AO1)	See "AO1 Multi-function Output Selections" on page 5	0	
03	29	AI2 terminal input selection	0=4-20 mA 1=0-10 V 2=0-20 mA	0	
04	00 to 14	Multi-step Speed Frequency 1–15	0.00-599.00 Hz	0.00	
05	00	Motor Parameter Auto-tuning	0=No function 1=Dynamic test for induction motor (IM) 2=Static test for induction motor (IM) 5=Rolling auto-tuning for PM (IPM /SPM) 6=Simple rolling auto-tuning for induction motor (IM) 12=FOC sensorless inertia estimation (IM) 13=High frequency stall test for PM	0	
05	01	Motor 1 Full Load Amps (FLA)	10-120% of drive rated current	#.##	
05	03	Motor 1 Rated RPM	0-65535	1710	
05	04	Motor 1 Number of poles	2-20	4	
06	07	Over-torque Detection Level (Motor 1)	10–250% (100% corresponds to the rated current of the drive)	120	
06	08	Over-torque Detection Time (Motor 1)	0.1–60.0 seconds	0.1	
06	13	Motor 1 Electronic Thermal Overload Relay	0=Inverter motor (with external forced cooling) 1=Standard motor (motor with fan on the shaft) 2=Disabled **Note:** A value of 0 or 1 is recommended to protect the motor in most applications.	2	
06	14	Motor 1 Electronic Thermal Relay Time	30.0-600.0	60	
06	55	Drive Derating Method	0=Constant rated current and limit carrier wave by load current and temperature 1=Constant carrier frequency and limit load current by setting carrier wave 2=Constant rated current (same as setting 0) but close current limit	0	
07	10	Restart after fault action	0=Stop operation 1=Speed tracking by current speed 2=Speed tracking by minimum output frequency	0	
07	11	Number of times of restart after fault	0–10	0	

(table continued next page)

DURAPULSE GS20X Parameter Settings – Quick Configuration (continued)					
Parameter Group	Parameter #	Description	Range	Default	User
07	19	Fan cooling control	0=Fan is always ON 1=Fan is OFF after the AC motor drive stops for one minute 2=Fan is ON when the AC motor drive runs, fan is OFF when the AC motor drive stops 3=Fan turns ON when temperature (IGBT) reaches approximately 600℃	3	
08	00	Terminal selection of PID feedback	0=No function 1=Negative PID feedback: by analog input (P03.00, P03.01) 2=Negative PID feedback: by single- phase input (DI7), without direction (P10.16=5) 4=Positive PID feedback: by analog input (P03.00, P03.01) 5=Positive PID feedback: by single- phase input (DI7), without direction (P10.16=5) 7=Negative PID feedback: by communication protocols 8=Positive PID feedback: by communication protocols	0	
08	01	Proportional gain (P)	0.0–1000.0 (When P08.23 bit 1=0) 0.00–100.00 (When P08.23 bit 1=1)	1.00	
08	02	Integral time (I)	0.00–100.00 sec.	1.00	
08	03	Differential time (D)	0.00–1.00 sec.	0.00	
08	04	Upper limit of integral control	0.0–100.0%	100.0	
08	05	PID output command limit (positive limit)	0.0–110.0%	100.0	
08	06	PID feedback value by communication protocol	-200.00–200.00%	0.00	
08	07	PID delay time	0.0–2.5 sec.	0.0	
08	08	Feedback signal detection time	0.0–3600.0 sec.	0.0	
08	09	Feedback signal fault treatment	0=Warn and continue operation 1=Fault and ramp to stop 2=Fault and coast to stop 3=Warn and operate at last frequency	0	
08	65	PID target value source	0=Frequency command (P00.20, P00.30) 1=P08.66 setting 2=RS-485 communication input 3=External analog input (refer to P03.00, P03.01) 6=Communication card 7=Digital keypad potentiometer dial (GS20 only)	0	
13	00	Application Selection	00=Disabled 01=User parameter 02=Compressor 03=Fan 04=Pump 05=Conveyor 06=Machine tool 07=Packing 08=Textiles	0	

Multi-function Input Selections		
0=No function 1=Multi-step speed command 1 / multi-step position command 1 2=Multi-step speed command 2 / multi-step position command 2 3=Multi-step speed command 3 / multi-step position command 3 4=Multi-step speed command 4 / multi-step position command 4 5=Reset 6=JOG [by external control or GS4-KPD (optional)] 7=Acceleration / deceleration speed inhibit 8=1st and 2nd acceleration / deceleration time selection 9=3rd and 4th acceleration / deceleration time selection 10=External Fault (EF) Input (P07.20) 11=Base Block (B.B.) input from external source 12=Output stop 13=Cancel the setting of auto-acceleration / auto-deceleration time	15=Rotating speed command from AI1 16=Rotating speed command from AI2 18=Force to stop (P07.20) 19=Digital up command 20=Digital down command 21=PID function disabled 22=Clear the counter 23=Input the counter value (DI6) 24=FWD JOG command 25=REV JOG command 26=TQC / Field Oriented Control (FOC) mode selection 27=ASR1 / ASR2 selection 28=Emergency stop (EF1) 29=Signal confirmation for Y-connection 30=Signal confirmation for Δ-connection 31=High torque bias (P11.30) 32=Middle torque bias (P11.31) 33=Low torque bias (P11.32) 38=Disable writing EEPROM function 39=Torque command direction 40=Force coasting to stop 41=HAND switch	42=AUTO switch 48=Mechanical gear ratio switch 49=Enable drive 50=Slave dEb action to execute 51=Selection for PLC mode bit 0 52=Selection for PLC mode bit 1 56=Local / Remote selection 58=Enable fire mode (with RUN command) 59=Enable fire mode (without RUN command) 70=Force auxiliary frequency return to 0 71=Disable PID function, force PID output return to 0 72=Disable PID function, retain the output value before disabled 73=Force PID integral gain return to 0, disable integral 74=Reverse PID feedback 81=Simple positioning zero point position signal input 82=OOB loading balance detection 83=Multi-motor (IM) selection bit 0 84=Multi-motor (IM) selection bit 1

Multi-function Output Selections		
0=No function 1=Indication during RUN 2=Operation speed reached 3=Desired frequency reached 1 (P02.22) 4=Desired frequency reached 2 (P02.24) 5=Zero speed (Frequency command) 6=Zero speed including STOP (Frequency command) 7=Over-torque 1 (P06.06–06.08) 8=Over-torque 2 (P06.09–06.11) 9=Drive is ready 10=Low voltage warning (Lv) (P06.00) 11=Malfunction indication 13=Overheat warning (P06.15) 14=Software brake signal indicator (P07.00) 15=PID feedback error (P08.13, P08.14) 16=Slip error (oSL) 17=Count value reached, does not return to 0 (P02.20) 18=Count value reached, return to 0 (P02.19)	19=External interrupt B.B. input (Base Block) 20=Warning output 21=Over-voltage 22=Over-current stall prevention 23=Over-voltage stall prevention 24=Operation mode 25=Forward command 26=Reverse command 29=Output when frequency ≥ P02.34 30=Output when frequency < P02.34 31=Y-connection for the motor coil 32=Δ-connection for the motor coil 33=Zero speed (actual output frequency) 34=Zero speed including STOP (actual output frequency) 35=Error output selection 1 (P06.23) 36=Error output selection 2 (P06.24) 37=Error output selection 3 (P06.25) 38=Error output selection 4 (P06.26)	40=Speed reached (including STOP) 42=Crane function 43=Motor speed detection 44=Low current output (use with P06.71–06.73) 45=UVW output electromagnetic valve switch 46=Master dEb output 51=Analog output control for RS-485 interface 52=Output control for communication cards 53=Fire mode indication 66=SO output logic A 67=Analog input level reached 68=SO output logic B 73=Over-torque 3 74=Over-torque 4 75=Forward RUN status 76=Reverse RUN status

AI Multi-function Input Selections		
0=No function 1=Frequency command 2=Torque command (torque limit under speed mode) 3=Torque compensation command	4=PID target value 5=PID feedback signal 6=Thermistor (PTC) input value 7=Positive torque limit 8=Negative torque limit	9=Regenerative torque limit 10=Positive / negative torque limit 11=PT100 thermistor input value 12=Auxiliary frequency input 13=PID compensation value

AO1 Multi-function Output Selections		
0=Output frequency (Hz) 1=Frequency command (Hz) 2=Motor speed (Hz) 3=Output current (rms) 4=Output voltage 5=DC bus voltage 6=Power factor 7=Power	8=Output torque 9=AI1 10=AI2 12=Iq current command 13=Iq feedback value 14=Id current command 15=Id feedback value	16=Vq-axis voltage command 17=Vd-axis voltage command 18=Torque command 19=PG2 (DI7) frequency command 21=RS-485 analog output 22=Communication card analog output 23=Constant voltage output

Cooling and Heat Dissipation

Airflow Rate for Cooling			Power Dissipation (Watts)		
Model Number	Flow Rate (cfm)	Flow Rate (m^3/hr)	Loss External (Heat sink)	Internal	Total
GS21X-20P5	0.0	0.0	16.3	14.5	30.8
GS21X-21P0			29.1	20.1	49.2
GS23X-20P5			16.5	12.6	29.1
GS23X-21P0			29.1	20.1	49.2
GS23X-40P5			17.6	11.1	28.7
GS23X-41P0			30.5	17.8	48.3
GS21X-22P0			46.5	31	77.5
GS23X-22P0			50.1	24.2	74.3
GS23X-42P0			45.9	21.7	67.6
GS23X-43P0			60.6	22.8	83.4
GS21X-23P0	27.3	46.4	70.0	35.0	105.0
GS23X-23P0			76.0	30.7	106.7
GS23X-25P0			108.2	40.1	148.3
GS23X-45P0			93.1	42.0	135.1
GS23X-27P5	33.5	56.6	192.8	53.3	246.1
GS23X-47P5			132.8	39.5	172.3
GS23X-4010			164.7	53.3	246.1

- External Flow Rate is across the heat sink.
- Internal Flow Rate is through the chassis.
- Published flow rates are the result of active cooling using fans, factory installed in the drive.
- Unpublished flow rates (-) are the result of passive cooling in drives without factory installed fans.
- The required airflow shown in the chart is for installing a single GS20X drive in a confined space.
- When installing multiple GS20X drives, the required air volume would be the required air volume for a single GS20X drive multiplied by the number of GS20X drives.
- When calculating power dissipation (Watt Loss), use the Total value. Heat dissipation shown in the chart is for installing a single GS20X drive in a confined space.
- When installing multiple drives, the volume of heat/power dissipation should be the heat/power dissipated by a single GS20X drive multiplied by the number of GS20X drives.
- Heat dissipation for each model is calculated by rated voltage, current and default carrier frequency.

Environment for Operation, Storage, and Transportation

Do not place the GS20X drive in a critical environment, such as direct contact with chemical substance and solvent, or exposure to direct sunlight.

Environment	Installation Location	PCB design is compliant with IEC60364-1/IEC60664-1 Pollution degree 2. The outer case meets IP66 standard for indoor use. If the drive is for outdoor application, avoid direct sunlight.		
	Surrounding Temperature	Operation: -20°C to +40°C, -20°C to +50°C with derating		
		Storage: -40°C to +85°C	Transportation: -20°C to +70°C	
		No condensation, non-freezing		
	Rated Humidity	Operation: 0~100%	Storage/Transportation: Max. 95%	
		No condensed water		
	Air Pressure	Operation: 86 to 106 kPa	Storage/Transportation: 70 to 106 kPa	
	Pollution Level	IEC60721-3		
		Operation: Class 3C2; Class 3S2	Storage: Class 2C2; Class 2S2	Transportation: Class 1C2; Class 1S2
		No concentrate		
	Altitude	Operation	If the GS20X drive is installed at altitudes of 0~1000m, follow normal operation restriction. If installed at altitudes of 1000~2000m, decrease 1% of rated current or lower 0.5°C of temperature for every 100m increase in altitude. Maximum altitude for Corner Grounded is 2000m. Contact ADC for more information if you need to use this motor drive at an altitude of 2000m or higher.	
Package Drop	Storage	ISTA procedure 1A (according to weight) IEC60068-2-31		
	Transportation			
Vibration	Operating	1.0mm, peak-to-peak value range from 2Hz to 13.2 Hz; 0.7G~1.0G range from 13.2Hz to 55Hz; 2.0G range from 55Hz to 512 Hz. Complies with IEC 60068-2-6.		
	Non-operating	2.5 G peak, 5Hz~2kHz: 0.015" maximum displacement.		
Impact	Operating	IEC/EN60068-2-27: 15G, 11ms		
	Non-operating	30G		
Protection Level		IP66 / NEMA4X		

To prevent personal injury, please make sure that the case and wiring are installed according to these instructions. The figures in these instructions are only for reference. They may be slightly different from the one you have, but it will not affect your customer rights.

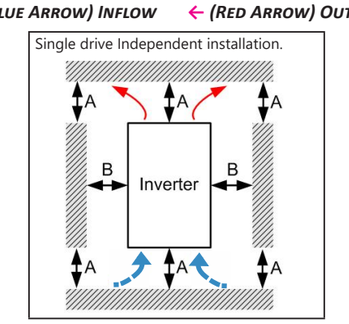
These installation instructions may be revised without prior notice. The most recent edition can be downloaded from the AutomationDirect web site at any time: http://www.automationdirect.com/static/manuals/index.html.

Minimum Mounting Clearances

When installing your GS20X drive, please keep the following in mind:

- *Prevent fiber particles, scraps of paper, shredded wood, saw dust, metal particles, etc., from adhering to the heat sink.*
- *Install the AC motor drive in an incombustible (non-flammable) indoor environment to prevent the risk of accidental fire.*
- *Install the AC motor drive in Pollution Degree 2 environments only: normally only nonconductive pollution occurs and temporary conductivity caused by condensation is expected.*

← (Blue Arrow) Inflow ← (Red Arrow) Outflow

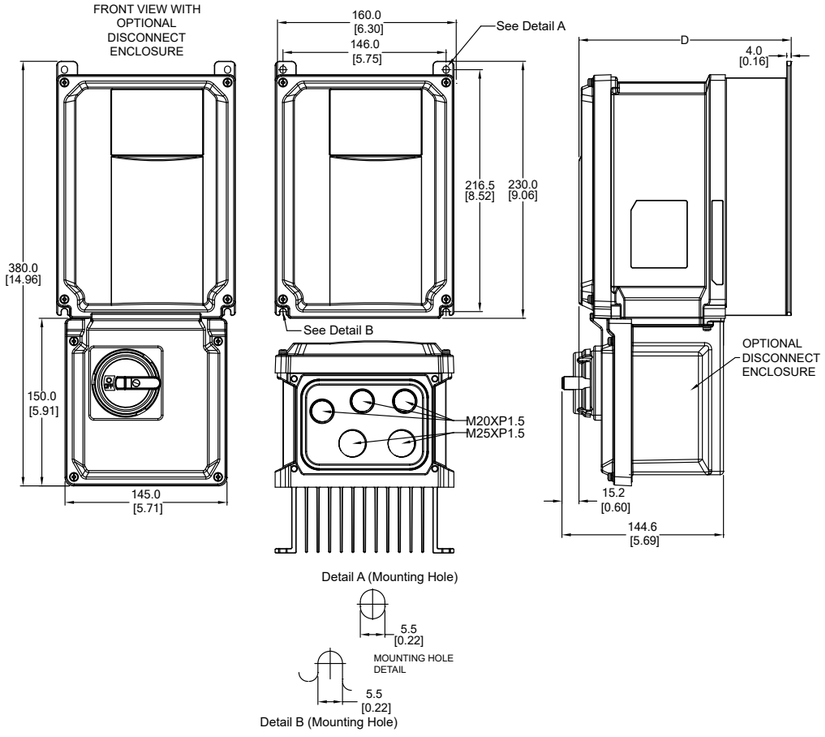


Installation Method	A (mm)	B (mm)	Ambient Temperature	
			Max (w/out derating)	Max (Derating)
Single drive installation	50	30	40	50

DIMENSION DIAGRAMS

GS20X FRAME A

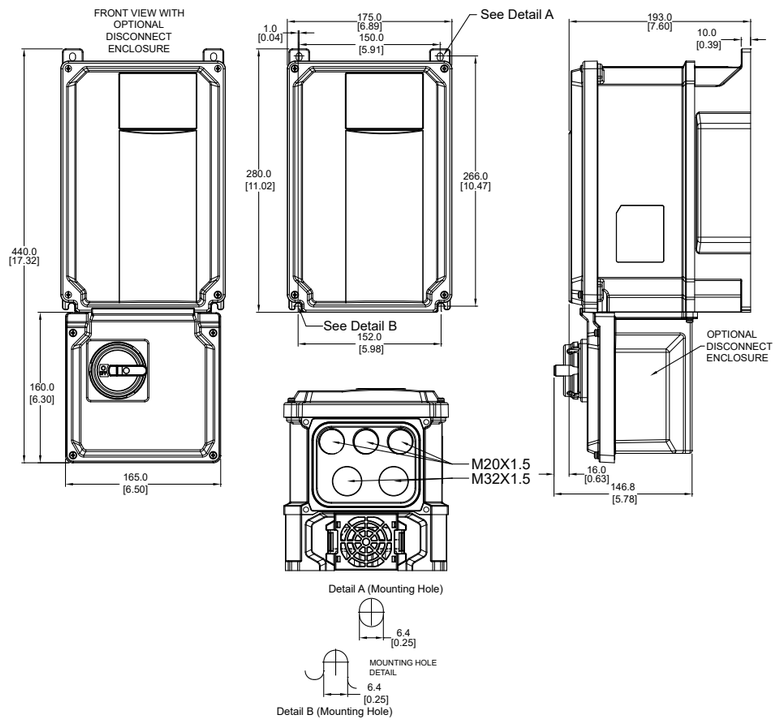
Units = mm [in]



Models by Frame Size		
Model	Frame	D mm [in]
GS21X-20P5 GS21X-21P0 GS23X-20P5 GS23X-21P0 GS23X-40P5 GS23X-41P0	A1	151.0 [5.94]
GS21X-22P0 GS23X-22P0 GS23X-42P0	A2	167.0 [6.57]
GS23X-43P0	A3	190.0 [7.48]

GS20X FRAME B

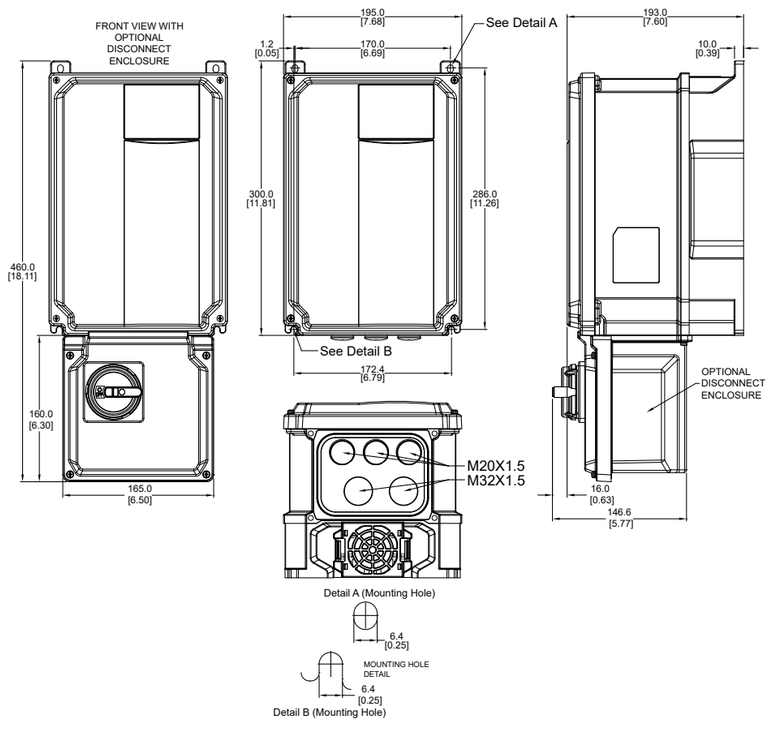
Units = mm [in]



Models by Frame Size	
Model	Frame
GS21X-23P0 GS23X-23P0 GS23X-25P0 GS23X-45P0	B

GS20X FRAME C

Units = mm [in]



Models by Frame Size	
Model	Frame
GS23X-27P5 GS23X-47P5 GS23X-4010	C