# **Accessories**



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# **FUSES/CIRCUIT BREAKERS**

Protection devices are essential to prevent damage to your GS20(X) drive and application equipment. Please use the fuse specification chart below to select fuses that are applicable to your GS20(X) drive. Only use UL-certified fuses which comply with your local regulations.

		Fuse	Specifi	cation Chart	GS20()	() DURAPUIS	F Drives		
	$\overline{}$	450		Power	. 6526(/	Input Fuse		Circ	uit Breaker
Drive Model	HP	Ø	Volts	GS20(X)	Fuse	Fast Acting	Edison	Size	Note
GS21-10P2	1/4	1	120	Input Amps 6.8	<b>Amps</b> 10	Class T TJN10	Class J* JHL10	20	G3P-020
GS21-10F2 GS21-10P5	1/4	1	120	10.1	10	TJN10	JHL10	25	G3P-025
GS21-11P0	1/2	1	120	20.6	25	TJN25	JHL25	50	G3P-050
GS21-11P0 GS21-20P2	1/4	1	230	5.8	10	TJN10	JHL10	15	G3P-030
GS21-20P5	1/4	1	230	8.3	15	TJN15	JHL15	20	G3P-015 G3P-020
	1/2	1				TJN20			G3P-020 G3P-030
GS21-21P0 GS21-22P0		1	230	11.3	20	TJN35	JHL20	30	
	2	<u> </u>	230	18.5	35		JHL35	45	G3P-040
GS21-23P0	3	1	230	27.5	50	TJN50	JHL50	70	G3P-070
GS23-20P2	1/4	3	230	2.2	10	TJN10	JHL10	15	G3P-015
GS23-20P5	1/2	3	230	3.8	15	TJN15	JHL15	15	G3P-015
GS23-21P0	1	3	230	6	20	TJN20	JHL20	15	G3P-015
GS23-22P0	2	3	230	9.6	35	TJN35	JHL35	25	G3P-025
GS23-23P0	3	3	230	15	50	TJN50	JHL50	40	G3P-040
GS23-25P0	5	3	230	23.4	80	TJN80	JHL80	60	G3P-060
GS23-27P5	7 1/2	3	230	32.4	60	TJN60	JHL60	63	G3P-060
GS23-2010	10	3	230	43.2	80	TJN80	JHL80	90	G3P-090
GS23-2015	15	3	230	61.2	110	TJN110	JHL110	125	F3P-125
GS23-2020	20	3	230	82.8	150	TJN150	JHL150	160	BW250JAGU- 3P160SB
GS23-40P5	1/2	3	460	2	10	TJS10	JHL10	15	G3P-015
GS23-41P0	1	3	460	3.3	15	TJS15	JHL15	15	G3P-015
GS23-42P0	2	3	460	5.1	20	TJS20	JHL20	15	G3P-015
GS23-43P0	3	3	460	7.2	25	TJS25	JHL25	20	G3P-020
GS23-45P0	5	3	460	11.6	45	TJS45	JHL45	30	G3P-030
GS23-47P5	7 1/2	3	460	17.3	35	TJS35	JHL35	32	G3P-030
GS23-4010	10	3	460	22.6	45	TJS45	JHL45	45	G3P-040
GS23-4015	15	3	460	30.8	60	TJS60	JHL60	60	G3P-060
GS23-4020	20	3	460	39.6	80	TJS80	JHL80	80	G3P-080
GS23-4025	25	3	460	45.7	90	TJS90	JHL90	90	G3P-090
GS23-4030	30	3	460	53.9	110	TJS110	JHL110	100	G3P-100
GS23-51P0	1	3	575	2.4	6	TJS6	JHL6	6	n/a
GS23-52P0	2	3	575	4.2	10	TJS10	JHL10	10	n/a
GS23-53P0	3	3	575	5.8	10	TJS10	JHL10	15	BW125JAGU- 3P015SB
GS23-55P0	5	3	575	9.3	20	TJS20	JHL20	30	BW125JAGU- 3P030SB
GS23-57P5	7 1/2	3	575	13.4	25	TJS25	JHL25	30	BW125JAGU- 3P030SB
GS23-5010	10	3	575	17.5	30	TJS30	JHL30	30	BW125JAGU- 3P030SB
GS21X-20P5	1/2	1	230	8.3	15	TJN15	JHL15	16	G3P-015
GS21X-21P0	1	1	230	11.3	20	TJN20	JHL20	25	G3P-025
GS21X-22P0	2	1	230	18.5	35	TJN35	JHL35	45	G3P-040
GS21X-23P0	3	1	230	27.5	50	TJN50	JHL50	63	G3P-060
GS23X-20P5	1/2	3	230	3.8	15	TJN15	JHL15	10	FAZ-C10-3-NA
GS23X-21P0	1	3	230	6	20	TJN20	JHL20	15	G3P-015
GS23X-22P0	2	3	230	9.6	35	TJN35	JHL35	25	G3P-025
GS23X-23P0	3	3	230	15	50	TJN50	JHL50	40	G3P-040
GS23X-25P0	5	3	230	23.4	80	TJN80	JHL80	60	G3P-060
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		( )		raca rient p	-9-/				1



	Fuse Specification Chart GS20(X) DURAPULSE Drives - continued										
			Input	Power		Input Fuse		Circuit Breaker			
Drive Model	HP	HP	HP	ø	Volts	GS20(X)	Fuse	Fast Acting	Edison	Size	Note
			Votts	Input Amps	Amps	Class T	Class J*	3120	74010		
GS23X-27P5	7 1/2	3	230	32.4	60	TJN60	JHL60	63	G3P-060		
GS23X-40P5	1/2	3	460	2.5	10	TJS10	JHL10	6	FAZ-C5-3-NA		
GS23X-41P0	1	3	460	4.2	15	TJS15	JHL15	10	FAZ-C10-3-NA		
GS23X-42P0	2	3	460	6.4	20	TJS20	JHL20	16	G3P-015		
GS23X-43P0	3	3	460	7.2	25	TJS25	JHL25	16	G3P-015		
GS23X-45P0	5	3	460	11.6	35	TJS35	JHL35	30	G3P-030		
GS23X-47P5	7 1/2	3	460	17.3	35	TJS35	JHL35	30	G3P-030		
GS23X-4010	10	3	460	22.6	45	TJS45	JHL45	45	G3P-040		

<sup>\*</sup> High-speed Class J.

Note: JHL fuses can be used with GS and DURAPULSE drives in non-UL applications. Fuse the drive according to NEC guidelines (NEC Article 430). For UL applications, GS, and DURAPULSE drives require Class T fuses (refer to the drive's user manual for details).



#### RECOMMENDED FUSE SPECIFICATIONS FOR THE DC-SIDE OF COMMON DC-BUS

These fuses are applicable only when connecting input power directly to the DC bus with terminals DC+ and DC-.

- The fuse current specifications in table below are based on overloading. If there is no possibility of overloading during use then fuses with a lower rating than the table below are allowed. The DC-side current calculation method described below can be used to calculate a suitable fuse rating for drive with DC current. Special cases such as overload or emergency stop must be considered however.
- For the DC-side fuse, please select a DC fuse or refer to the DC voltage specifications from the fuse parameters. The DC voltage rating must be higher than the operating voltage.
- Fuse selection should take into account operating class (e.g. High-speed or general purpose) and overloading.
  - a) If the drive is subject to overloading and high-speed fuse is used: Due to the speed of response the chosen fuse should be rated double that of the calculated maximum instantaneous DC current.
  - b) If the drive is subject to overloading and normal fuse is used: Fuse selection should be based on the calculated maximum instantaneous current during overloading.
  - c) If drive is not subject to overloading: Select a fuse with a current rating close to that of the calculated DC current.
- UL-listed fuse suitable for short-circuit protection of inputs. "In the United States, branch circuits must comply with the US National Electrical Code (NEC) and its local directives." Please select a UL-listed fuse to comply with local regulations.
- "In Canada, branch circuits must comply with the Canadian Electrical Code and its local directives." Please select a UL-listed fuse to comply with local regulations.

	GS20(X) - DC Bus Fusing								
Requirement	Drive Model	230V Drives	460V Drives	575V Drives					
DC Bus Voltage Level	all models	350	700	875					
DC Bus Fuse Voltage Rating	all models	690	1250	1250					
	1P2 (1/4HP)	10	-	-					
	1P5 (1/2HP)	10	10	-					
	1P0 (1HP)	16	10	6					
	2P0 (2HP)	25	16	10					
	3P0 (3HP)	40	20	16					
DC P F ( )	5P0 (5HP)	63	30	20					
DC Bus Fuse (amps)	7P5 (7.5HP)	80	40	30					
	010 (10HP)	100	55	40					
	015 (15HP)	160	80	-					
	020 (20HP)	200	100	-					
	025 (25HP)	-	125	-					
	030 (30HP)	-	160	-					

#### DC SIDE CURRENT CALCULATION

Different motors and loads will produce different DC current values. When the motor power and efficiency parameters are known, use the following formula to calculate the DC current:

$$I_{dc} = P_{motor} / (1.35*V_{Line}*n_{motor})$$

Where  $V_{Line}$ = Output voltage,  $n_{motor}$ = motor efficiency,  $P_{motor}$ =Motor power.



If the input DC voltage, output load, and output power factor are known then the following formulation can be used as well:

$$I_{dc} = V_{line}^* \sqrt{3} lo^* cos \theta / 0.95 / VDC$$

#### For example:

 $V_{line}$ =220V, motor power factor  $cos \theta$ =0.8, drive efficiency 0.95 (generally 0.94~0.98), output current  $I_{o}$ =11A, VDC=360V

$$I_{dc}$$
= (220V\* $\sqrt{3}$ \*11\*0.8 / 0.95) / 360  
 $I_{dc}$ = 9.8A



#### STANDARD FOOTPRINT EMC FILTER AND ZERO PHASE REACTOR

Use EMC filters to enhance the EMC performance for the environment and machines and to comply with EMC regulations, further reducing EMC problems. If you purchase a motor drive without a built-in EMC filter, we recommend that you select an EMC filter as shown below. GS20 drives will mount on top of these footprint filters for Frames A–D. GS20X drives can use the filters, but the filter must be mounted remotely in a panel. For some motor drive models, you need to work with zero phase reactors to be compliant with EMC regulations. Refer to the table and figure below for the recommended model, setting method, and maximum motor cable length of the EMC filter and zero phase reactor.

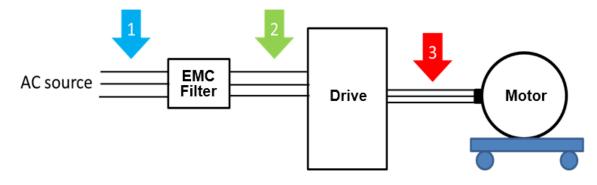
		GS	20(X) EMC Filter a	and Zero Phase	e Rea	ctor						
					Co	nduc	ted En	nission		idiate nissio		
Frame	Drive Model	Drive Model	Input Current (A) Footprint Filter Model #	Footprint Filter Model #	Recommended Zero Phase Reactor	C1-motor cable length-30m  Position to Install a				C2-motor cable length- 100m		gth-
								Reactor				
					1	2	3	n/a	1	2	3	
	GS21-10P2	6.8	EMF11AM21A					N/A				
	GS21-20P2	3.8	EMF11AM21A			✓	✓	N/A		✓	✓	
	GS21-20P5	6.7	EMF11AM21A			✓	✓	N/A		✓	✓	
	GS23-20P2	2.2	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23-20P5	3.8	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23-21P0	6	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23-40P5	2.5	EMF6A0M43A				✓	N/A			✓	
٨	GS23-41P0	4.2	EMF6A0M43A	Delta P/N			✓	N/A			✓	
	GS23-51P0	2.4	EMF6A0M63B	RF008X00A				N/A*				
	GS21-10P5	10.1	EMF11AM21A	Note: Not available from				N/A				
A	GS21X-20P5	8.3	EMF11AM21A			✓	✓	N/A		✓	✓	
A	GS21X-21P0	11.3	EMF11AM21A	Automation		✓	✓	N/A		✓	✓	
	GS21X-22P0	18.5	EMF27AM21B	Direct			✓	N/A			✓	
	GS23X-20P5	3.8	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23X-21P0	6	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23X-22P0	9.6	EMF10AM23A			✓	✓	N/A		✓	✓	
	GS23X-40P5	2.5	EMF6A0M43A				✓	N/A			✓	
	GS23X-41P0	4.2	EMF6A0M43A				✓	N/A			✓	
	GS23X-42P0	6.4	EMF6A0M43A				✓	N/A			✓	
	GS23X-43P0	7.2	EMF12AM43B					N/A				
	GS21-21P0	10.5	EMF11AM21A			✓	✓	N/A		✓	✓	
GS21X-22P0 18.5 GS23X-20P5 3.8 GS23X-21P0 6 GS23X-22P0 9.6 GS23X-40P5 2.5 GS23X-41P0 4.2 GS23X-42P0 6.4 GS23X-43P0 7.2 GS21-21P0 10.5 GS23-22P0 9.6 GS23-52P0 4.2 GS23-42P0 6.4	EMF10AM23A	Delta P/N		✓	✓	N/A		✓	✓			
	GS23-52P0	4.2	EMF6A0M63B	RF008X00A				N/A*				
D D	GS23-42P0	6.4	EMF6A0M43A	Note: Not			✓	N/A			✓	
В	GS21X-23P0	27.5	EMF27AM21B	Note: Not available from			✓	N/A			✓	
	GS23X-23P0	15	EMF24AM23B	Automation		✓	✓	N/A		✓	✓	
	GS23X-25P0	23.4	EMF24AM23B	Direct		✓	✓	N/A		✓	✓	
	GS23X-45P0	11.6	EMF12AM43B			✓	✓	N/A		✓	✓	



		GS20(X)	EMC Filter and Ze	ro Phase React	tor (	onti	nue	1)				
					Conducted Emission			Radiated Emission				
Frame	Drive Model	Input Drive Model Current (A)	urrent Footprint Filter Ze	Recommended Zero Phase Reactor				motor cable length-	C2-motor cable length- 100m		gth-	
					F	Positi		Install a		Phas	е	
					1	1 2 3		Reactor** n/a	1	2	2 3	
	GS21-11P0	20.6	EMF27AM21B		-	_		N/A	-	_		
	GS21-22P0	17.9	EMF27AM21B	Delta P/N RF008X00A			<b>√</b>	N/A			<b>√</b>	
	GS21-23P0	26.3	EMF27AM21B				<b>√</b>	N/A			<b>√</b>	
С	GS23-23P0	15	EMF24AM23B			<b>✓</b>	✓	N/A		<b>✓</b>	<b>✓</b>	
	GS23-25P0	23.4	EMF24AM23B			<b>√</b>	✓	N/A		<b>√</b>	✓	
	GS23-43P0	7.2	EMF12AM43B	Note: Not available from				N/A				
	GS23-53P0	5.8	EMF16AM63B	Automation Direct				N/A*				
	GS23-55P0	9.3	EMF16AM63B					N/A				
	GS23-45P0	11.6	EMF12AM43B			✓	✓	N/A		✓	✓	
	GS23X-27P5	32.4	EMF33AM23B		✓	✓		N/A	✓	✓		
С	GS23X-47P5	17.3	EMF23AM43B		✓	✓	✓	N/A	✓	✓	✓	
	GS23X-4010	22.6	EMF23AM43B		✓	✓	✓	N/A	✓	✓	<b>✓</b>	
	GS23-27P5	32.4	EMF33AM23B		✓	✓		N/A	✓	✓		
	GS23-47P5	17.3	EMF23AM43B		✓	✓	✓	N/A	✓	✓	<b>✓</b>	
D	GS23-57P5	13.4	EMF16AM63B	Delta P/N				N/A				
	GS23-5010	17.5	EMF16AM63B	RF008X00A				N/A				
	GS23-4010	22.6	EMF23AM43B	Note: Not	✓	✓	✓	N/A	✓	✓	✓	
	GS23-2010	43.2	n/a	available from		✓	✓	N/A		✓	✓	
E	GS23-2015	61.2	n/a	Automation		✓	✓	N/A		✓	✓	
-	GS23-4015	30.8	n/a	Direct				N/A				
	GS23-4020	39.6	n/a			✓	✓	N/A		✓	✓	
	GS23-2020	82.8	n/a			✓	✓	N/A		✓	✓	
F	GS23-4025	45.7	n/a			✓	✓	N/A		✓	✓	
	GS23-4030	53.9	n/a			✓	✓	N/A		✓	✓	

Note: It is not necessary to add a zero phase reactor for passing the C2 conducted emission test.

#### Zero phase reactor installation position diagram:



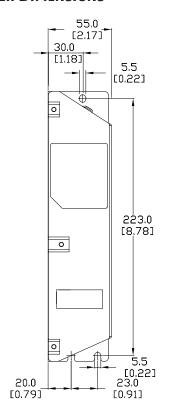
- 1: Install at the cable between the power supply and the EMC filter.
- 2: Install at the cable between the EMC filter and the drive.
- 3: Install at the cable between the drive and the motor.

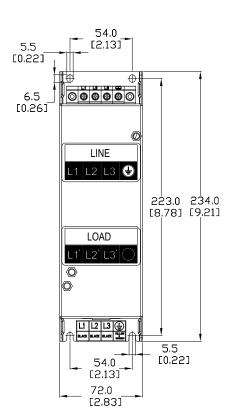
<sup>\*</sup> The maximum motor cable length of the conducted emission C2 class for GS23-51P0, GS23-52P0, and GS23-53P0 is 75 meters. All others are 100 meters.

<sup>\*\*</sup> See diagram below for installation positions.



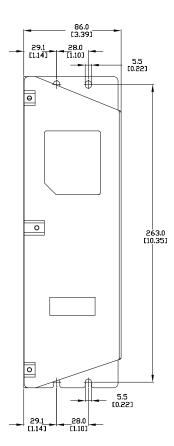
#### FILTER DIMENSIONS

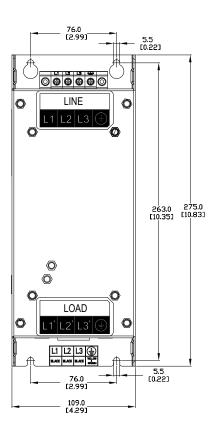




#### EMF11AM21A EMF10AM23A EMF6A0M43A

Screw	Torque
M5 x 2	16–20 kg <b>-</b> cm / 13.9–17.3 lb-in / 1.56–1.96 N•m
M4 x 2	14–16 kg-cm / 12.2–13.8 lb-in. / 1.38–1.56 N•m





EMF27AM21B; EMF24AM23B EMF33AM23B; EMF12AM43B EMF23AM43B; EMF6A0M63B; EMF16AM63B

Screw	Torque
M5 x 4	16–20 kg-cm / 13.9–17.3 lb-in. / 1.56–1.96 N•m



# **HIGH PERFORMANCE EMI INPUT FILTERS**

The optional accessories listed in this chapter are available for use with the GS20(X) drive. Selection of these accessories is application specific and may improve drive performance. Additional information regarding filter installation and operation is available in the AutomationDirect white paper, "Applied EMI/RFI Techniques Overview."

		EMI Filters Selection				
Model	Description	EMI Filter*				
	-	Roxburgh Filters Chassis 1ph	Roxburgh Filters C2 Rated			
GS21-10P2	120V 1ph 0.25 hp	RES90F10	MIF10			
GS21-10P5	120V 1ph 0.5 hp	RES90F16	MIF16			
GS21-11P0	120V 1ph 1.0 hp	RES90S30	MIF23			
GS21-20P2	230V 1ph 0.25 hp	RES90F06	MIF06			
GS21-20P5	230V 1ph 0.5 hp	RES90F10	MIF10			
GS21-21P0	230V 1ph 1.0 hp	RES90F16	MIF16			
GS21-22P0	230V 1ph 2.0 hp	RES90S20	MIF23			
GS21-23P0	230V 1ph 3.0 hp	RES90S30	MIF330B			
GS23-20P2	230V 3ph 0.25 hp	-	KMF306A			
GS23-20P5	230V 3ph 0.5 hp	-	KMF306A			
GS23-21P0	230V 3ph 1.0 hp	-	KMF306A			
GS23-22P0	230V 3ph 2.0 hp	-	KMF318A			
GS23-23P0	230V 3ph 3.0 hp	-	KMF318A			
GS23-25P0	230V 3ph 5.0 hp	-	KMF325A			
GS23-27P5	230V 3ph 7.5 hp	-	KMF336A			
GS23-2010	230V 3ph 10hp	-	KMF350A			
GS23-2015	230V 3ph 15hp	-	KMF370A			
GS23-2020	230V 3ph 20hp	-	KMF3100A			
GS23-40P5	460V 3ph 0.5 hp	-	KMF306A			
GS23-41P0	460V 3ph 1.0 hp	-	KMF306A			
GS23-42P0	460V 3ph 2.0 hp	-	KMF306A			
GS23-43P0	460V 3ph 3.0 hp	-	KMF310A			
GS23-45P0	460V 3ph 5.0 hp	-	KMF318A			
GS23-47P5	460V 3ph 7.5 hp	-	KMF318A			
GS23-4010	460V 3ph 10hp	-	KMF325A			
GS23-4015	460V 3ph 15hp	-	KMF336A			
GS23-4020	460V 3ph 20hp	-	KMF350A			
GS23-4025	460V 3ph 25hp	-	KMF350A			
GS23-4030	460V 3ph 30hp	-	KMF370A			
GS23-51P0	575V 3ph 1.0 hp	-	KMF306V			
GS23-52P0	575V 3ph 2.0 hp	-	KMF306V			
GS23-53P0	575V 3ph 3.0 hp	-	KMF306V			
GS23-55P0	575V 3ph 5.0 hp	-	KMF310V			
GS23-57P5	575V 3ph 7.5 hp	-	KMF318V			
GS23-5010	575V 3ph 10hp	-	KMF318V			
GS21X-20P5	230V 1ph 0.5 hp	RES90F10	MIF10			
GS21X-21P0	230V 1ph 1.0 hp	RES90F16	MIF16			
GS21X-22P0	230V 1ph 2.0 hp	RES90S20	MIF23			
GS21X-23P0	230V 1ph 3.0 hp	RES90S30	MIF330B			
GS23X-20P5	230V 3ph 0.5 hp	-	KMF306A			
GS23X-21P0	230V 3ph 1.0 hp	-	KMF306A			
GS23X-22P0	230V 3ph 2.0 hp	-	KMF310A			
GS23X-23P0	230V 3ph 3.0 hp	-	KMF318A			
GS23X-25P0	230V 3ph 5.0 hp	-	KMF325A			
GS23X-27P5	230V 3ph 7.5 hp	-	KMF336A			
GS23X-40P5	460V 3ph 0.5 hp	-	KMF306A			
GS23X-41P0	460V 3ph 1.0 hp	-	KMF306A			
GS23X-42P0	460V 3ph 2.0 hp	-	KMF306A			
GS23X-43P0	460V 3ph 3.0 hp	-	KMF310A			

	EMI Filters Selection (continued)								
Model	Description	EMI Filter							
моаец	Description	Roxburgh Filters Chassis 1ph	Roxburgh Filters C2 Rated						
GS23X-45P0	460V 3ph 5.0 hp	-	KMF318A						
GS23X-47P5	460V 3ph 7.5 hp	-	KMF318A						
GS23X-4010	460V 3ph 10hp	-	KMF325A						

\* All specs for the EMI filters can be found at www.automationdirect.com or by clicking the following links: -KMF Series Filters

-MIF Series Filters -RES90 Series Filters

#### **EMI FILTER INSTALLATION**

Electrical equipment like the GS20(X) drive, will generate electrical noise when in operation and may interfere with the normal operation of peripheral equipment. The use of an EMI filter will mitigate this type of power supply interference. Other measures may be required for reduction or mitigation of radiated emissions. Roxburgh EMI filters have been tested with the GS20(X) family of drives and are recommended for the mitigation of interference and the highest performance When the GS20(X) drive and Roxburgh EMI filter are installed and wired according to the user manual, the installation will conform to the following rules:

- EN61000-6-4
- EN61800-3: 1996
- EN55011 (1991) Class A Group 1 (1st Environment, restricted distribution)

#### **GENERAL PRECAUTION**

- 1) Install the EMI filter and GS20(X) drive on the same subpanel or metal plate.
- 2) Install the EMI filter as close as possible to the GS20(X) drive.
- 3) Keep wiring between the EMI filter and GS20(X) drive as short as possible.
- 4) The subpanel or metal plate used to support the EMI filter and GS20(X) drive should be well grounded (minimal resistance to ground is typically less then  $1\Omega$ ).
- 5) To insure that the EMI filter and GS20(X) drive are adequately grounded, insure that both are securely attached to the subpanel or plate.

#### **CHOOSE SUITABLE MOTOR CABLE AND PRECAUTIONS**

Proper installation and the choice of good motor cable will positively affect the performance of the filter. When selecting motor cable, please observe the following precautions.

- 1) Cable shielding (double shielding is best).
- 2) Ground the shield on both ends of the motor cable. Maintain minimum length and employ strong mechanical connection to ground.
- Remove paint on the metal saddle, subpanel or plate to insure good contact to ground.

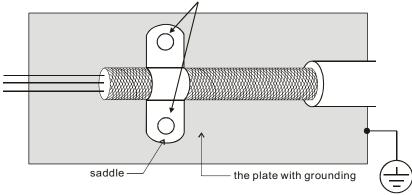


Figure 1



#### EMI FILTER INSTALLATION (CONTINUED)

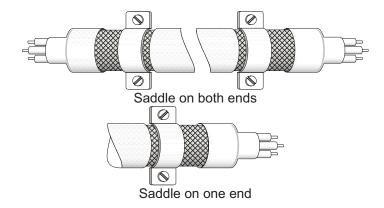


Figure 2

#### REFLECTIVE WAVE PHENOMENON

The inverter section of a PWM drive like the GS20(X) does not produce sinusoidal output voltage wave forms. Rather, the output voltage produced is a continuous train of width modulated pulses, sent to the motor terminals via the motor cable.

Peak pulse voltage at the GS20(X) drive is equal to the drive DC bus voltage and contains steep rise and fall times, the result of the IGBT switching device used in the drive inverter section.

Peak pulse voltage at the motor terminals may exceed the drive DC bus voltage and is dependent on the dynamics of the drive output voltage rise time, cable transmission line characteristics, cable length and motor impedance.

The voltage pulse train at the motor terminals experiences momentary transient over voltage as the IGBT transistors switch. The result being voltage levels at the motor terminals double that of the drive bus voltage.

Over voltage of this type has the potential to stress the motor insulation, damaging the motor.

#### RECOMMENDED MOTOR CABLE LENGTH

- 1) Never connect phase lead capacitors or surge absorbers to the output terminals of the drive.
- 2) As cable length increases, capacitance between cables will increase and may result in leakage current and over current faults with the possibility of damage to the GS20(X) drive.
- 3) If more than one motor is connected to the drive, the total cable length is the sum of the cable lengths from the GS20(X) drive to each motor.
- 4) Should an overload relay malfunction occur, lower the GS20(X) drive carrier frequency (P2.10) or install an output reactor.
- 5) When operating an AC motor with a PWM drive like the GS20(X), the motor may experience reflective wave as described above. To prevent this situation, please observe the recommendations below:
  - a) Use a motor with enhanced insulation. (1000V, 1200V, 1600V, higher is better)
  - b) Connect an output reactor (optional) to the output terminals of the drive.
  - c) Keep motor cable length as short as possible. (65ft, 20m, or less)
  - d) Where motor cable lengths will exceed 65ft (20m), refer to "Maximum Recommended Cable Length GS20(X)" on page A–18.

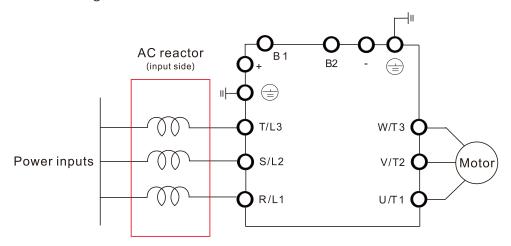


#### **LINE REACTORS / VOLTAGE TIME FILTERS**

#### LINE REACTOR

Installing an AC reactor on the input side of an AC motor drive can increase line impedance, improve the power factor, reduce input current, increase system capacity, and reduce interference generated from the motor drive. It also reduces momentary voltage surges or abnormal current spikes from the mains power, further protecting the drive. For example, when the main power capacity is higher than 500 kVA, or when using a phase-compensation capacitor, momentary voltage and current spikes may damage the AC motor drive's internal circuit. An AC reactor on the input side of the AC motor drive protects it by suppressing surges.

Install an AC input reactor in series between the main power and the three input phases R S T, as shown in the figure below:

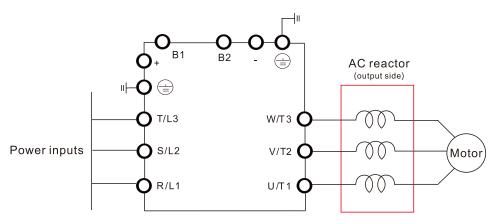


#### LOAD REACTOR/VOLTAGE TIME FILTER

When using drives in long wiring output application, ground fault (GFF), over-current (OC) and motor over-voltage (OV) often occur. GFF and OC cause errors due to the drive's self-protective mechanism; over-voltage damages motor insulation.

The excessive length of the output wires makes the grounded stray capacitance too large, increases the three-phase output common mode current, and the reflected wave of the long wires makes the motor dv / dt and the motor terminal voltage too high. Thus, installing a reactor on the drive's output side can increase the high-frequency impedance to reduce the dv / dt and terminal voltage to protect the motor. For distances greater than 100 feet, a dV/dT filter (VTF Series) is recommended for best performance.

Install an AC output reactor or voltage time filter in series between the three output phases U V W and the motor, as shown in the figure below:





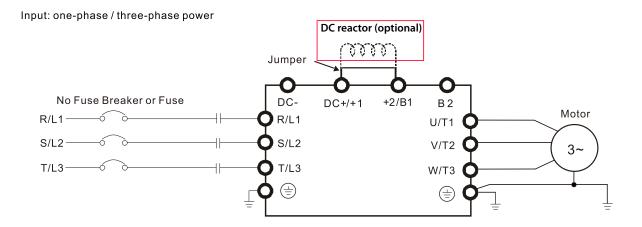
#### DC REACTOR

A DC reactor can also increase line impedance, improve the power factor, reduce input current, increase system power, and reduce interference generated from the motor drive. A DC reactor stabilizes the DC bus voltage. Compared with an AC input reactor, a DC reactor is in smaller size, lower price, and lower voltage drop (lower power dissipation).

Install a DC reactor between terminals +1 and +2. Remove the jumper, as shown in the figure below, before installing a DC reactor.



Note: 120V models have no DC reactor/choke terminals.



When the GS20(X) drive is connected directly to a large-capacity power transformer (600kVA or above) or when a power correction capacitor is switched on, excessive peak currents may occur in the input power circuit resulting in damage to the GS20(X) drive.

To avoid this, install a line reactor in series with the GS20(X) drive on the <u>input</u> side. The installation of a line reactor will reduce input current peaks and improve the output power efficiency.

Line (load) reactors installed on the <u>output</u> side protect the motor insulation against AC drive short circuits and IGBT reflective wave damage, and also allow the motor to run cooler by "smoothing" the motor current waveform. They are recommended for operating "non-inverter-duty" motors, and for any motors where the length of wiring between the AC drive and motor is less than or equal to 100 feet. For AC drive-to-motor wiring distances over 100 feet, use of the VTF series output filter is recommended.



#### **LINE/LOAD REACTORS SELECTION CHARTS**

GS20(X) Line/Load Reactor, AC Output Filter, & DC Reactor Se	elections	
GS20(X) Model Amps (rms) Amps (rms) Motor HP (LR2)** (LR2)**	C Output Filter (VTF)**	DC Reactor Delta P/N*
<b>GS21-10P2</b> 1.6 3.2 1/4 LR2-10P2-1PH LR2-20P2	VTF-46-DE	DR008D0366
<b>GS21-10P5</b> 2.5 5 1/2 LR2-10P5-1PH LR2-20P5	VTF-246-CFG	DR011D0266
<b>GS21-11P0</b> 5 9.6 1 LR2-11P5-1PH LR2-21P0	VTF-24-FH	DR025D0117
<b>GS21-20P2</b> 1.6 3.2 1/4 LR2-20P5-1PH LR2-20P2	VTF-46-DE	DR005D0585
<b>GS21-20P5</b> 2.8 5.6 1/2 LR2-20P5-1PH LR2-20P5	VTF-246-CFG	DR008D0366
<b>GS21-21P0</b> 4.8 9.6 1 LR-23P0 LR2-21P0	VTF-24-FH	DR011D0266
<b>GS21-22P0</b> 7.5 15 2 LR2-22P0-1PH LR-22P0	VTF-246-HKL	DR017D0172
<b>GS21-23P0</b> 11 22 3 LR-27P5 LR-25P0	VTF-24-JL	DR025D0117
<b>GS23-20P2</b> 1.6 3.2 1/4 LR2-20P2 LR2-20P2	VTF-46-DE	DR005D0585
<b>GS23-20P5</b> 2.8 5.6 1/2 LR2-20P5 LR2-20P5	VTF-246-DGH	DR005D0585
<b>GS23-21P0</b> 4.8 9.6 1 LR2-20P7 LR2-20P7	VTF-24-FH	DR005D0585
<b>GS23-22P0</b> 7.5 15 2 LR-22P0 LR-22P0	VTF-246-HKL	DR008D0366
<b>GS23-23P0</b> 11 22 3 LR-25P0 LR-25P0	VTF-24-JL	DR011D0266
<b>GS23-25P0</b> 17 34 5 LR-27P5 LR-25P0	VTF-46-LM	DR017D0172
<b>GS23-27P5</b> 25 50 7 1/2 LR-2010 LR-2010	VTF-46-NP	DR025D0117
<b>GS23-2010</b> 33 66 10 LR-2015 LR-2010	VTF-246-LPQ	DR033DP851
<b>GS23-2015</b> 46 92 15 LR-2020 LR-2020	VTF-246-NRS	DR049DP574
<b>GS23-2020</b> 65 130 20 LR-2025 LR-2025	VTF-246-PSU	DR065DP432
<b>GS23-40P5</b> 1.5 3 1/2 LR2-40P5 LR2-40P5	VTF-46-DE	DR003D1870
<b>GS23-41P0</b> 2.7 5.4 1 LR2-41P0 LR2-41P0	VTF-246-CFG	DR003D1870
<b>GS23-42P0</b> 4.2 8.4 2 LR2-43P0 LR2-42P0	VTF-24-FH	DR004D1403
<b>GS23-43P0</b> 5.5 11 3 LR2-45P0 LR2-43P0	VTF-24-FH	DR006D0935
<b>GS23-45P0</b> 9 18 5 LR2-47P5 LR2-45P0	VTF-246-HKL	DR009D0623
<b>GS23-47P5</b> 13 26 7 1/2 LR-4010 LR2-47P5	VTF-24-JL	DR012D0467
<b>GS23-4010</b> 17 34 10 LR-4015 LR-4010	VTF-24-JL	DR018D0311
<b>GS23-4015</b> 25 50 15 LR-4015 LR-4015	VTF-246-LPQ	DR024D0233
<b>GS23-4020</b> 32 64 20 LR-4020 LR-4020	VTF-246-LPQ	DR032D0175
<b>GS23-4025</b> 38 76 25 LR-4025 LR-4025	VTF-246-MQR	DR038D0147
<b>GS23-4030</b> 45 90 30 LR-4030 LR-4030	VTF-246-NRS	DR045D0124
<b>GS23-51P0</b> 1.7 3.4 1 LR2-51P0 LR2-51P0	VTF-46-DE	n/a
<b>GS23-52P0</b> 3 6 2 LR2-52P0 LR2-52P0	VTF-246-CFG	n/a
<b>GS23-53P0</b> 4.2 8.4 3 LR2-53P0 LR2-53P0	VTF-246-DGH	n/a
<b>GS23-55P0</b> 6.6 13.2 5 LR2-55P0 LR2-55P0	VTF-246-GJJ	n/a
<b>GS23-57P5</b> 9.9 19.8 7 1/2 LR-5010 LR2-57P5	VTF-246-HKL	n/a
<b>GS23-5010</b> 12.2 24.4 10 LR-4010 LR-5010	VTF-246-HKL	n/a
<b>GS21X-20P5</b> 2.8 5.6 1/2 LR2-20P5-1PH LR2-20P2	VTF-246-DGH	DR005D0585
<b>GS21X-21P0</b> 4.8 9.6 1 LR2-21P0-1PH LR2-20P7	VTF-24-FH	DR008D0366
<b>GS21X-22P0</b> 7.5 15.0 2 LR2-22P0-1PH LR2-22P0	VTF-246-HKL	DR011D0266
<b>GS21X-23P0</b> 11.0 22.0 3 LR-27P5 LR-25P0	VTF-24-JL	DR017D0172
<b>GS23X-20P5</b> 2.8 5.6 1/2 LR2-20P2 LR2-20P2	VTF-246-DGH	DR005D0585
<b>GS23X-21P0</b> 4.8 9.6 1 LR2-21P5 LR2-21P0	VTF-24-FH	DR005D0585
<b>GS23X-22P0</b> 7.5 15.0 2 LR2-22P0 LR2-22P0	VTF-246-GJJ	DR008D0366
<b>GS23X-23P0</b> 11.0 22.0 3 LR-25P0 LR-25P0	VTF-24-JL	DR011D0266
<b>GS23X-25P0</b> 17.0 34.0 5 LR-27P5 LR-27P5	VTF-4-M	DR017D0172
<b>GS23X-27P5</b> 25.0 50.0 7 1/2 LR-2010 LR-2010	VTF-246-KMN	DR025D0117
<b>GS23X-40P5</b> 1.5 3.0 1/2 LR2-40P5 LR2-40P5	VTF-46-DE	DR003D1870
<b>GS23X-41P0</b> 2.7 5.4 1 LR2-41P5 LR2-41P0	VTF-246-CFG	DR003D1870
<b>GS23X-42P0</b> 4.2 8.4 2 LR2-43P0 LR2-42P0	VTF-24-FH	DR004D1403
<b>GS23X-43P0</b> 5.5 11.0 3 LR2-44P0 LR2-43P0	VTF-24-FH	DR006D0935
<b>GS23X-45P0</b> 9.0 18.0 5 LR2-47P5 LR2-45P0		
3.0 10.0 5 LNZ-4/F3 LRZ-43P0	VTF-246-HKL	DR009D0623
<b>GS23X-47P5</b> 13.0 26.0 7 1/2 LR-4010 LR2-47P5	VTF-246-HKL VTF-24-JL	DR009D0623 DR012D0467

<sup>\*</sup> Not available at AutomationDirect.com

<sup>\*\*</sup> Reactor sizing is based on rated HP NEMA motor load, not drive output amp load. Size the reactor based on the motor nameplate current. All specs for the LR2 and VTF can be found at www.automationdirect.com or by clicking the following links::

<sup>-</sup>LR2 Line Reactors

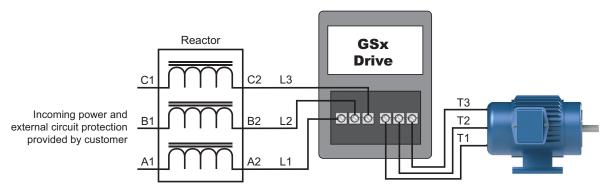
<sup>-</sup>VTF Output Filters



#### LINE REACTOR APPLICATIONS AND WIRING CONNECTIONS

#### INPUT SIDE OF AC DRIVE

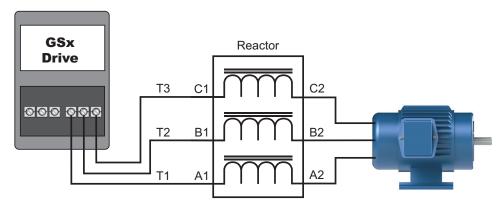
When installed on the input side of the GS20(X) drive, a line reactor will reduce line notching, current peaks, voltage spikes and surges from the incoming line, as well as reduce the available short circuit current. A line reactor will also reduce harmonic distortion from the GS20(X) drive onto the line. The line reactor is installed in front of the GS20(X) drive as shown.



Please refer to "Chapter 2: Installation and Wiring" for detailed wiring information for the GS20(X) drive.

#### **OUTPUT SIDE OF AC DRIVE**

When installed on the output side of the GS20(X) drive, line (load) reactors help to protect the GS20(X) drive from short circuits at the load. Voltage and current waveforms from the GS20(X) drive are enhanced, reducing motor overheating and noise emissions.



Please refer to "Chapter 2: Installation and Wiring" for detailed wiring information for the GS20(X) drive.

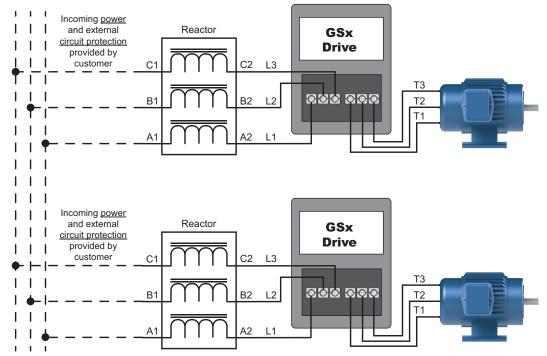


Single phase line reactors should NOT be installed on the output side of an AC Drive. Use only three-phase reactors on drive outputs, and only for three-phase motors.



#### MULTIPLE AC DRIVES

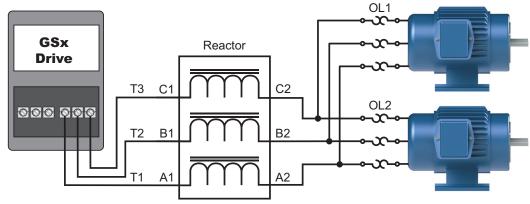
Individual line reactors are recommended when installing multiple GS20(X) drives on the same power line. Individual line reactors eliminate cross-talk between multiple GS20(X) drives and provide isolated protection for each GS20(X) drive for its own specific load.



Please refer to "Chapter 2: Installation and Wiring" for detailed wiring information for the GS20(X) drive.

#### **MULTIPLE MOTORS**

A single output (load) reactor can be used with multiple motors on the same GS20(X) drive, but only if the motors operate simultaneously. Size the reactor based upon the total horsepower of all the motors, and select a reactor with a current rating greater than the sum of the motor full-load currents. Overload relays are required for use in multi-motor applications.



Please refer to "Chapter 2: Installation and Wiring" for detailed wiring information for the GS20(X) drive.

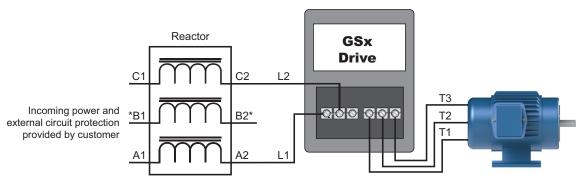


A single reactor should be used with multiple motors ONLY when the motors will operate simultaneously from a single AC drive. OVERLOAD RELAYS are required for use in multiple motor applications.



#### SINGLE-PHASE APPLICATIONS

Some three-phase line reactors are listed for use with single-phase input power. Follow the connection diagram shown below. Make sure that terminals B1 and B2, if present, are properly insulated before any connections are made. If a 3-phase reactor is used on the line side of a single-phase input drive application, ensure that the actual single-phase current does not exceed the Line Reactor's current rating (example: a 3-phase, 5hp Line Reactor and 3-phase 5hp drive will not handle enough current to power a 5hp motor on a single-phase supply - both the drive and the Line Reactor will have to be upsized).



\*LR series 1-phase reactors do not include a B-phase winding.

Please refer to "Chapter 2: Installation and Wiring" for detailed wiring information for the GS20(X) drive.



Ensure that you properly insulate terminals B1 and B2 before making any connections to single-phase power.

#### RECOMMENDED CABLE LENGTH

#### **Motor Leakage Current**

If the cable length is too long, the stray capacitance between cables increases and may cause leakage current. This activates over-current protection, increases leakage current, or may affect the current display. In the worst case, it may damage the AC motor drive. If more than one motor is connected to one AC motor drive, the total wiring length should be the sum of the wiring length from AC motor drive to each motor.

For the 460V series AC motor drive, when you install an overload thermal relay between the drive and the motor to protect the motor from overheating, the connecting cable must be shorter than 50m; however, an overload thermal relay malfunction may still occur. To prevent the malfunction, install an output reactor (optional) to the drive or lower the carrier frequency setting (see P00.17 Carrier Frequency).

#### **Motor Surge Voltage**

When a motor is driven by a PWM-type AC drive, the motor terminals experience surge voltages (dv/dt) due to power transistor conversion of the drive. For very long motor cable (especially for the 460V series), surge voltages (dv/dt) may damage the motor insulation and bearing. To prevent this, follow these rules:

- A) Use a motor with enhanced insulation.
- B) Reduce the cable length between the AC drive and motor to suggested values.
- C) Connect an output reactor (optional) to the output terminals of the AC drive.

Refer to the following tables for the suggested motor shielded cable length. For drive models < 480V, use a motor with a rated voltage ≤ 500 VAC and an insulation level ≥ 1.35 kVp-p in accordance with IEC 60034-17. For the 575V drive model, use a motor with a rated voltage ≤ 600 VAC and an insulation level ≥ 1.79 kVp-p in accordance with IEC 60034-25.

			Maximun	n Recommende	d Cable Length - G	S20(X)	
GS20(X)	Input	Power	VT Rated Current		tput AC Reactor eters)	With Output A	C Reactor (meters)
Model	Ø	Volts	(Arms)	Shielded Cable	Unshielded Cable	Shielded Cable	Unshielded Cable
GS21-10P2			1.8				
GS21-10P5		120	2.7				
GS21-11P0			5.5				
GS21-20P2	1		1.8				
GS21-20P5	'		3.2				
GS21-21P0			5				
GS21-22P0			8.5				
GS21-23P0			12.5	50	75	75	115
GS23-20P2			1.8				
GS23-20P5			3.2				
GS23-21P0		230	5				
GS23-22P0			8				
GS23-23P0			12.5				
GS23-25P0			19.5				225
GS23-27P5			27				
GS23-2010			36			150	
GS23-2015			51	100	150		
GS23-2020			69				
GS23-40P5		3 460	1.8	25	50 75	50	
GS23-41P0			3	35			90
GS23-42P0	2		4.6	50			
GS23-43P0	3		6.5			75	115
GS23-45P0 GS23-47P5			10.5 15.7			75	
GS23-47F3			20.5				
GS23-4010							
GS23-4020	-		28 36 100	150	150	225	
GS23-4025			41.5	100	150	150	223
GS23-4030			49				
GS23-51P0			2.1	15	55		
GS23-52P0			3.6	50	80		
GS23-53P0			5		120	N/A	
GS23-55P0		575	8.5	65	295		N/A
GS23-57P5			11.5	4.5			
GS23-5010			15	145	320		
GS21X-20P5			3.2				
GS21X-21P0	1		5				
GS21X-22P0	1		8.5				
GS21X-23P0			12.5				
GS23X-20P5		230	3.2	50	75	75	115
GS23X-21P0		230	5	50	13	13	113
GS23X-22P0			8				
GS23X-23P0			12.5				
GS23X-25P0			19.5				
GS23X-27P5	3		27				
GS23X-40P5			1.8				
GS23X-41P0			3	35	50	50	90
GS23X-42P0		460	4.6				
GS23X-43P0			6.5	50	75	75	15
GS23X-45P0			10.5		.5		



#### **DYNAMIC BRAKING**

Dynamic braking resistors dissipate the regeneration energy of AC motors when they are being controlled to a stop faster than a coasting stop. All GS20(X) drives have the braking function circuitry built-in and do not require a separate dynamic braking unit.

To utilize dynamic braking:

- 1) Wire the appropriate braking resistor to terminals B1/B2 (refer to page 2–21).
- 2) Set parameter <u>P07.00 Software Brake Chopper Action Level</u> for the application. When the DC bus voltage rises above this setpoint, the dynamic braking circuit will activate.



TO AVOID POSSIBLE INJURY, PLEASE REFER TO CHAPTER 2 OF THIS MANUAL FOR CORRECT WIRING OF THE RESISTORS.

#### **DRIVE UNIT DYNAMIC BRAKING SPECIFICATIONS**

	GS20(X) AC Drive Dynamic Braking Specifications						
, e	Motor	or Power		Drive	Braking Circuit B1	/B2	Compatible Brake
Drive Voltage	Voltae (dd)	(kW)	Drive Model	Min Resistor Value (Ω)	Max Total Brake Current (A)	Peak Power (kW)	Resistors* (125% Torque, 10% Duty Cycle)
>	1/4	0.2	GS21-10P2	190.0	2	0.8	
120V	1/2	0.4	GS21-10P5	95.0	4	1.5	
1	1	0.75	GS21-11P0	63.3	6	2.3	
	1/4	0.2	GS21-20P2	190.0	2	8.0	
	1/2	0.4	GS21-20P5	95.0	4	1.5	
	1	0.75	GS21-21P0	63.3	6	2.3	
	2	1.5	GS21-22P0	47.5	8	3.0	
	3	2.2	GS21-23P0	38.0	10	3.8	
	1/4	0.2	GS23-20P2	190.0	2	8.0	
>	1/2	0.4	GS23-20P5	95.0	4	1.5	
230V	1	0.75	GS23-21P0	63.3	6	2.3	
(1)	2	1.5	GS23-22P0	47.5	8	3.0	
	3	2.2	GS23-23P0	38.0	10	3.8	
	5	3.7	GS23-25P0	19.0	20	7.6	
	7 1/2	5.5	GS23-27P5	16.5	23	8.7	
	10	7.5	GS23-2010	14.6	26	9.9	
	15	11	GS23-2015	12.6	29	11.0	Click
	20	15	GS23-2020	8.3	46	17.5	<u>here</u>
	1/2	0.4	GS23-40P5	380.0	2	1.5	<u>riore</u>
	1	0.75	GS23-41P0	190.0	4	3.0	
	2	1.5	GS23-42P0	126.7	6	4.6	
	3	2.2	GS23-43P0	108.6	7	5.3	
>	5	3.7	GS23-45P0	84.4	9	6.8	
460V	7 1/2	5.5	GS23-47P5	50.7	15	11.4	
4	10	7.5	GS23-4010	40.0	19	14.4	
	15	11	GS23-4015	33.0	23	17.5	
	20	15	GS23-4020	26.2	29	22.0	
	25	18	GS23-4025	26.2	29	22.0	
	30	22	GS23-4030	23.0	33	25.1	
	1	0.75	GS23-51P0	280.0	4	4.5	
	2	1.5	GS23-52P0	186.7	6	6.7	
575V	3	2.2	GS23-53P0	160.0	7	7.8	
57	5	3.7	GS23-55P0	93.3	12	13.4	
	7 1/2	5.5	GS23-57P5	80.0	14	15.7	
	10	7.5	GS23-5010	70.0	16	17.9	



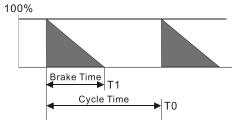
	GS20(X) AC Drive Braking Component Selection (continued)						
36	ည္ Motor Power			Drive Braking Circuit B1/B2			Compatible Brake
Drive Voltage	(hp)	(kW)	Drive Model	Min Resistor Value (Ω)	Max Total Brake Current (A)	Peak Power (kW)	Resistors* (125% Torque, 10% Duty Cycle)
	1/2	0.4	GS21X-20P5	95.0	4	1.5	
	1	0.75	GS21X-21P0	63.3	6	2.3	
	2	1.5	GS21X-22P0	47.5	8	3.0	
	3	2.2	GS21X-23P0	38.0	10	3.8	
301	1/2	0.2	GS23X-20P5	190.0	2	0.8	
23	1	0.4	GS23X-21P0	95.0	4	1.5	
	2	0.75	GS23X-22P0	63.3	6	2.3	
	3	1.5	GS23X-23P0	47.5	8	3.0	Cl: -l.
	5	2.2	GS23X-25P0	38.0	10	3.8	Click <u>here</u>
	7 1/2	3.7	GS23X-27P5	19.0	20	7.6	<u>nere</u>
	1/2	0.4	GS23X-40P5	380.0	2	1.5	
	1	0.75	GS23X-41P0	190.0	4	3.0	
_	2	1.5	GS23X-42P0	126.7	6	4.6	
460V	3	2.2	GS23X-43P0	108.6	7	5.3	
4	5	3.7	GS23X-45P0	84.4	9	6.8	
	7 1/2	5.5	GS23X-47P5	50.7	15	11.4	
	10	7.5	GS23X-4010	40.0	19	14.4	
* 10%	Duty	Cycle v	vith maximum	ON (braking)	time for 10 secon	ds.	



For a full list of all brake resistors compatible with GS20(X) drives, please see the GS20(X) series braking technical specfiication: <a href="https://cdn.automationdirect.com/static/specs/gs20braking.pdf">https://cdn.automationdirect.com/static/specs/gs20braking.pdf</a>

#### CHOOSING AND INSTALLING A BRAKING RESISTOR

Select the resistance value, power and brake usage (ED %).
 Definition for Brake Usage ED%:



 $ED\% = T1 / T0 \times 100(\%)$ 

#### Explanation:

Brake usage ED (%) is the amount of time needed for the brake unit and brake resistor to dissipate heat generated by braking. When the brake resistor heats up, the resistance increases with temperature, and braking torque decreases accordingly.

For safety, install a thermal overload relay (O.L) between the brake unit and the brake resistor in conjunction with the magnetic contactor (MC) supplying the drive's input power for additional protection. The thermal overload relay protects the brake resistor from damage due to frequent or continuous braking. Under such circumstances, disconnect the drive's AC supply to prevent damage to the brake resistor and drive.



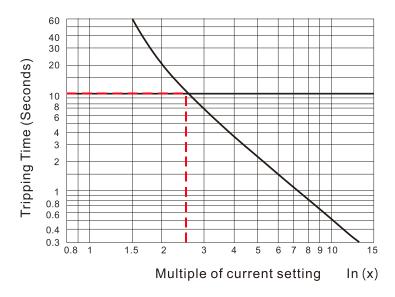
Note: Never use the thermal overload relay to disconnect the brake resistor.

- 2) Any damage to the drive or other equipment caused by using brake resistors and brake modules that are not provided by AutomationDirect voids the warranty.
- 3) Consider environmental safety factors when installing the brake resistors. If you use the minimum resistance value, consult AutomationDirect for the power calculation.
- 4) Refer to the ADC Dynamic Braking unit User Manual for more detail on braking resistors here.
- 5) The selection tables are for 10% duty cycle. If the AC motor drive requires frequent braking, increase the Watts by two to three times.



#### 6) Thermal Overload Relay (TOR):

Thermal overload relay selection is based on its overload capacity. A standard braking capacity of the GS20(X) is 10% ED (Tripping time=10 s). As shown in the figure below, a 460V, 1kw GS20(X) required the thermal relay to take 260% overload capacity for 10 seconds (hot starting) and the braking current is 24A. In this case, select a thermal overload relay rated at 10A (10 \* 260% = 26 A > 24 A). The property of each thermal relay may vary among different manufacturers. Carefully read the specification before using it.



#### **EMC Shield & Earthing Plates**

#### **GS20 EMC SHIELD PLATES**

EMC shield plates are available for use with shielded cable and your GS20 drive. Find the frame type from the specification tables of your GS20 and reference the table below:

		GS20 EMC Shield Plate Selection	
Frame	EMC Shield Plate Model	Reference Drawing	
А	GS20A-ESP-A		
В	GS20A-ESP-B		
С	GS20A-ESP-C		
D	GS20A-ESP-D		
E	GS20A-ESP-E		
F	GS20A-ESP-F		

# EMC Shield Plate Installation

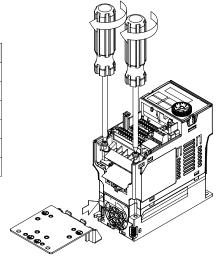
The steps below show how to install the EMC shield plate on a GS20 drive. The diagram examples use an A frame model.



1) Attach the shield plate to the GS20 drive as shown in the diagram to the right.

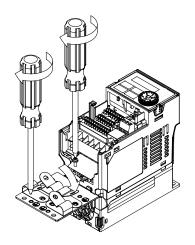
Torque the screws per the table below:

Frame	Screw	Torque
А	M3.5	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]
В	M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]
С	M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]
D	M3	4–6 kg-cm (3.5–5.2 lb-in.) [0.39–0.59 N•m]
E	M3	4–6 kg-cm (3.5–5.2 lb-in.) [0.39–0.59 N•m]
F	M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]



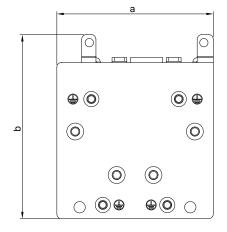
2) Select an R-clip suitable for the wire gauge used and then fix the R-clip to the shield plate as shown in the diagram to the right. Torque the R-clip screws per the table below:

Screw	Torque	
M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]	



#### **EMC Shield Plate Dimensions**

EMC Shield Plate Dimensions				
Model	Dimensions mm [inch]			
riouet	а	ь		
GS20-ESP-A	69.3 [2.73]	80.0 [3.15]		
GS20-ESP-B	67.7 [2.67]	79.7 [3.14]		
GS20-ESP-C	78.0 [3.07]	91.0 [3.58]		
GS20-ESP-D	103.4 [4.07]	97.0 [3.82]		
GS20-ESP-E	124.3 [4.89]	77.4 [3.05]		
GS20-ESP-F	168.0 [6.61]	80.0 [3.15]		



#### RECOMMENDED WIRING METHOD

The diagrams below show the recommended R-clip configuration for wiring shielded cable to each frame type/EMC shield plate model.

	EMC Shield Plate Wiring Methods				
Frame	EMC Shield Plate Model	Reference Drawing			
А	GS20A-ESP-A				
В	GS20A-ESP-B				
С	GS20A-ESP-C				
D	GS20A-ESP-D				
E	GS20A-ESP-E				
F	GS20A-ESP-F				



#### **GS20X EARTHING PLATES**

Earthing plates are available for use with shielded cable and your GS20X drive. Find the frame type of your GS20X from the specification tables and reference the table below:

Frame	Earthing Plate Model	Reference Drawing	
А	GS20XA-EPA		
В	GS20XA-EPB		
С	GS20XA-EPC		

#### **EARTHING PLATE INSTALLATION**

The steps below show how to install the earthing plate to your GS20X drive. The steps are fundamentally the same for each frame type, except Frame B has a different grounding screw configuration.

Torque all screws per the table below regardless of frame type.

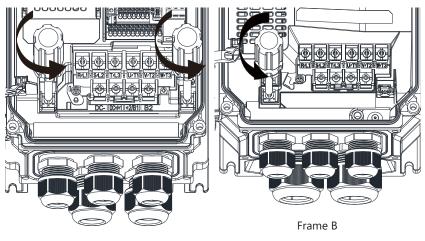
Screw	Torque
M4	6-8 kg-cm (5.2-6.9 lb-in.) [0.59-0.78 N•m]

#### 1) Frame A and C: Loosen the ground screws on

the right and left.

#### Frame B:

Loosen the ground screw on the left.



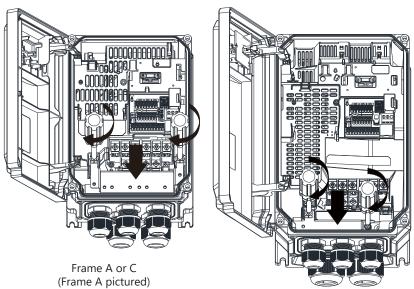
Frame A or C (Frame A pictured)

#### 2) Frame A and C:

Put the first earthing plate into the drive, then tighten the ground screws on the right and left again.

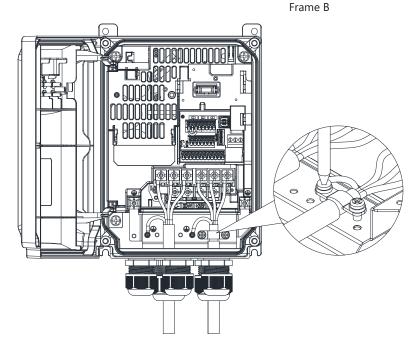
#### Frame B:

Put the first earthing palte into the drive, then tighten the ground screw on the left and the fixing screw on the right.

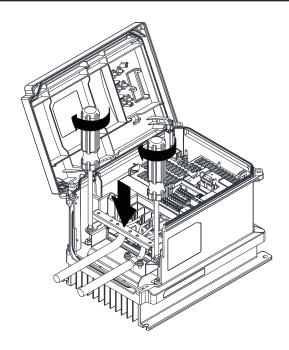


'

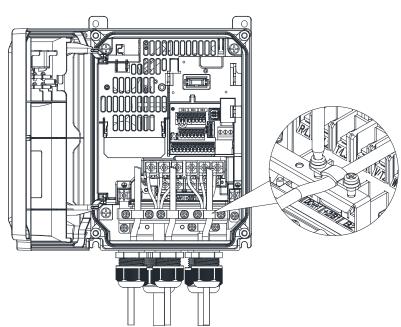
3) Before doing any wiring, strip part of the wire wraps, and then tighten the wires for the output terminals on the earthing plate (clamps must be fixed on the shielding).



4) Install the second earthing plate on top of the first one.



5) Tighten and fix the control wire with clamps.





# **CAPACITIVE FILTER (GS20A-CAPF)**

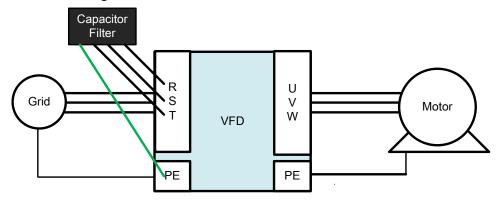
The GS20A-CAPF capacitive filter supports basic filtering and noise interference reduction for models 460V and below.

GS20A-CAPF Specifications				
Model	Applicable Voltage	Temperature Range	Capacitance	
GS20A-CAPF	110-480 VAC	-40-85°C	Cx: 1uF ± 20% Cy: 0.1uF ± 20%	

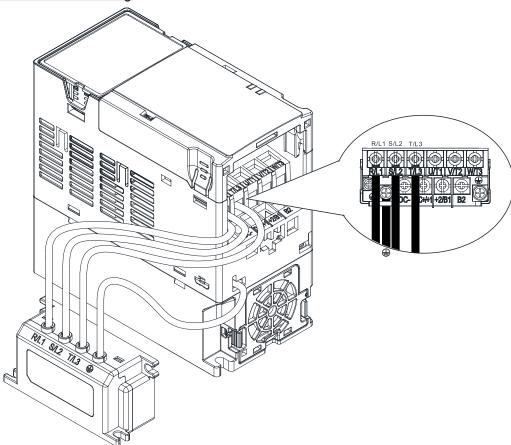


Note: GS20A-CAPF cannot be used with 575V GS20 models.

# **Installation diagram:**

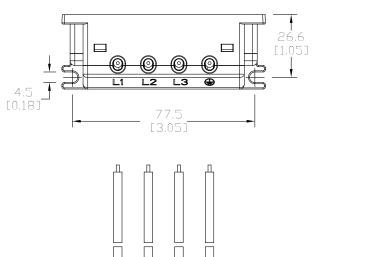


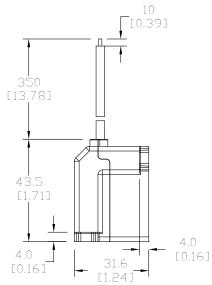
#### Filter and Drive Wiring

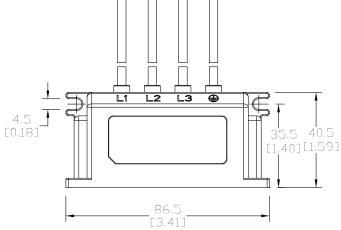




# GS20A-CAPF DIMENSIONS Units = mm [inch]







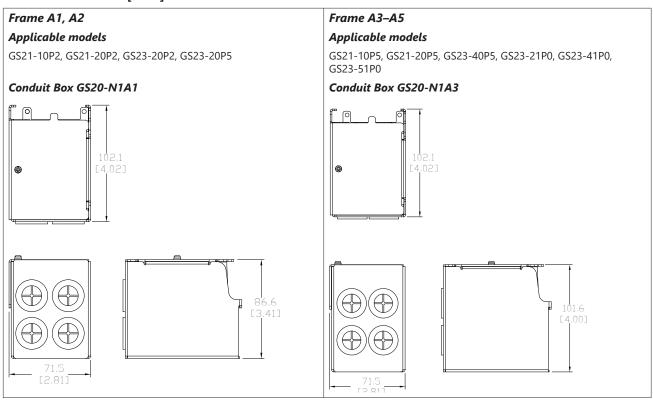


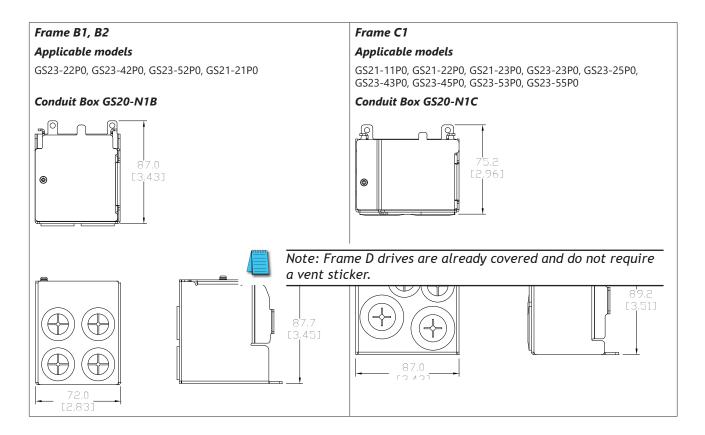
# **CONDUIT BOX**

NEMA 1 / UL Type 1 compliant conduit boxes are available for all frame sizes (A–F).

#### **CONDUIT BOX DIMENSIONS**

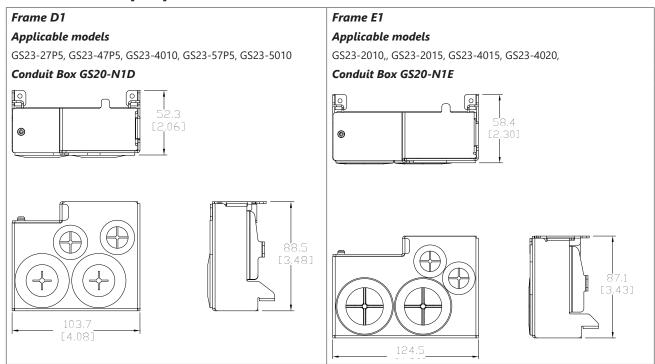
Units = mm [inch]

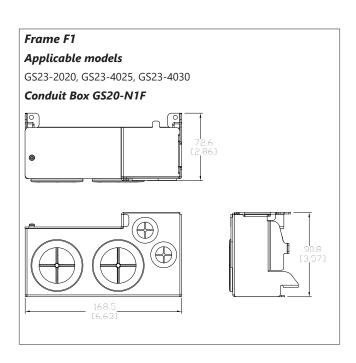






#### Units = mm [inch]







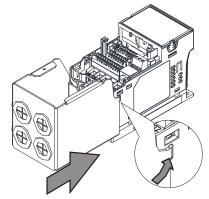
#### **CONDUIT BOX INSTALLATION**

Follow the steps below to install a conduit box to your GS20 drive. The first set of instructions are for Frame A drives, the second set of instructions is for Frame B–F drives.

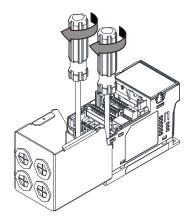
Recommended Screw Size and Torque Value				
Screw	Torque			
M3	4–6 kg-cm (3.5–5.2 lb-in.) [0.39–0.59 N•m]			
M3.5	4–6 kg-cm (3.5–5.2 lb-in.) [0.39–0.59 N•m]			
M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]			

### Frame A Conduit Box Installation:

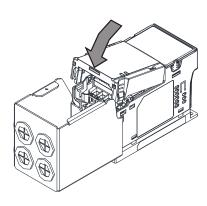
1)



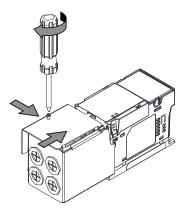
2)



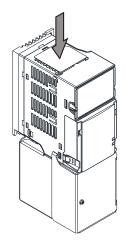
3)



4)

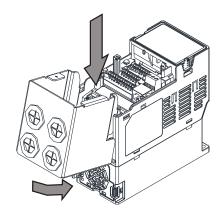


5)

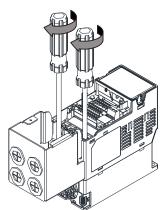


# Frame B-F Conduit Box Installation:

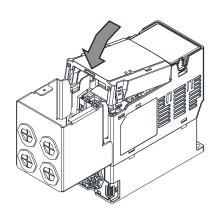
1)



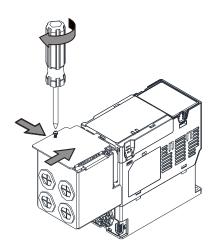




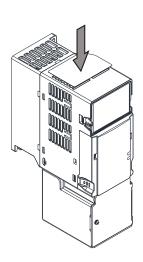
3)







5)





#### **DISCONNECT SWITCH**

The GS20XA-DSx series accessory provides a local on/off disconnect switch that is easily mounted to the GS20X drive. This accessory provides an easy, quick, single hasp lockout point to isolate power to the drive.



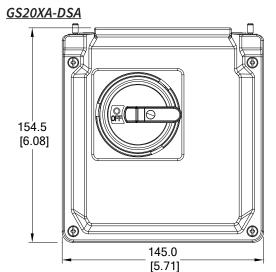
Note: DSC series disconnect switches are for use with GS20X NEMA4X drives only.

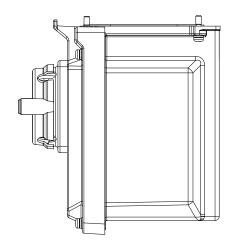
#### **DISCONNECT SWITCH COMPATIBILITY**

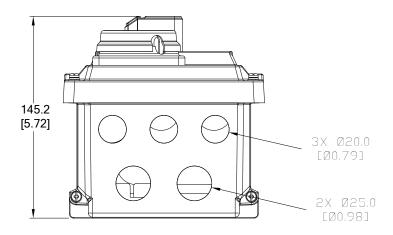
GS20X Disconnect Switch Selection	
Frame	Disconnect Switch
А	GS20XA-DSA
В	GS20XA-DSB
С	GS20XA-DSC

#### **DSC Series Dimensions**

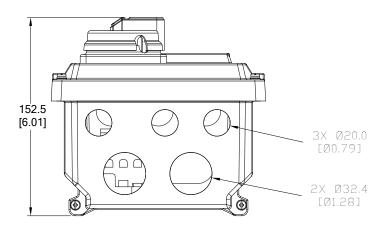
#### Units = MM [INCH]





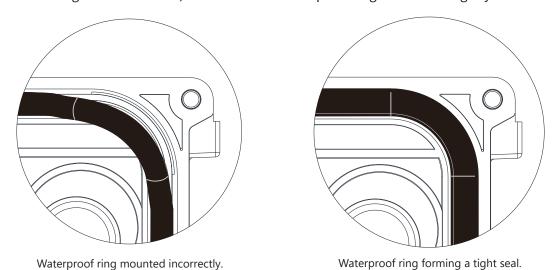


# 164.5 [6.48]



#### **INSTALLING THE DISCONNECT SWITCH**

Before installing the main switch, ensure that the waterproof ring is mounted tightly.

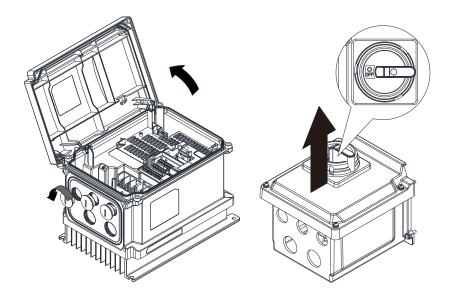




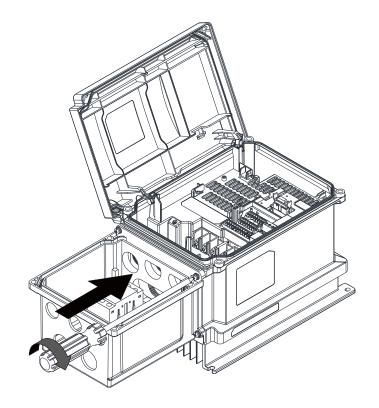
# **Torque for all screws:**

Screw	Torque
M4	6–8 kg-cm (5.2–6.9 lb-in.) [0.59–0.78 N•m]

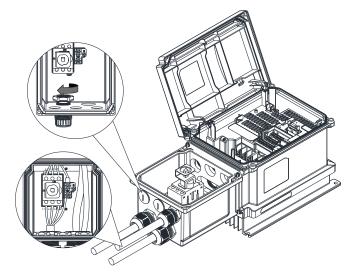
 Open the front cover of the drive and remove all waterproof plugs. Then open the front cover of the main switch (keep the switch at OFF position).



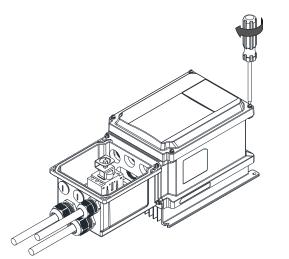
2) Mount the main switch to the drive.



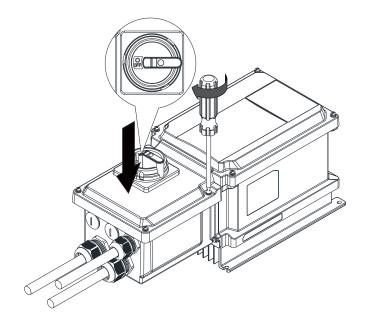
 Tighten the waterproof connector and waterproof plugs before doing any wiring.



4) Close the front cover of the drive and tighten it.



 Close the front cover of the main switch and tighten it (keep the switch at OFF position).





# REPLACEMENT FAN KIT

Most GS20(X) drives come equipped with a fan that can be replaced if needed. Use the table below to select the right fan for your drive, then remove and replace the existing fan.

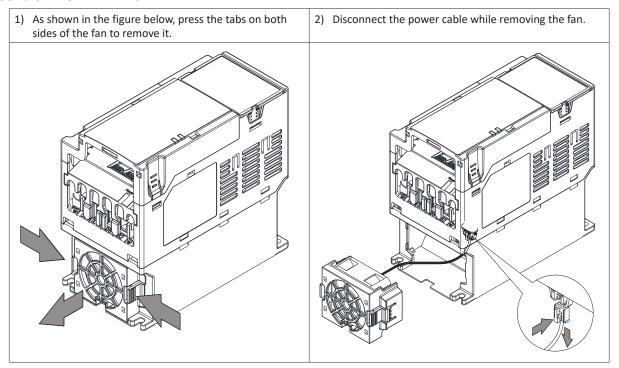
	GS20(X) Fan Kit Selector			
Frame	Drive Series	Fan Kit Model	Reference Drawing (units	s = mm [inch])
А	GS20	n/a	20.0 [0.79]	
В	GS20	GS20A-FAN-B	54.2 [2.13] 43.6 [1.72]	23.0
В	GS20X	GS20XA-FAN-B	35.9	
С	GS20X	GS20XA-FAN-C	84.6	60.0
С	GS20	GS20A-FAN-C	70.0 (2.76)	50.2



GS20 Fan Kit Selector (continued)				
Frame		Fan Kit Model	Reference Drawing (units	= mm [inch])
			35.9 (1.41)	
D	GS20	GS20A-FAN-D	34.6 (3.33)	60.0
E	GS20	GS20A-FAN-E		92.2 (3.6.3)
F	GS20	GS20A-FAN-F	114.0 14.491	92.0



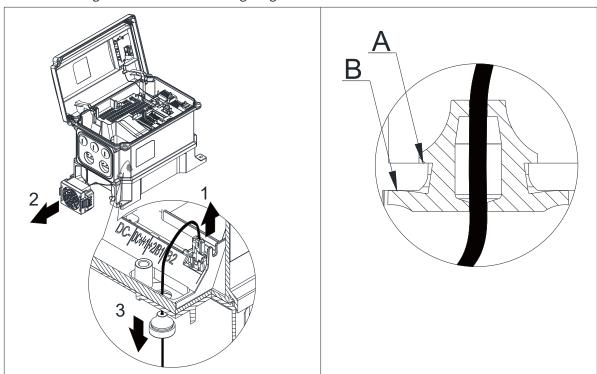
# GS20 SERIES FAN REMOVAL



### **GS20X SERIES FAN REMOVAL**

Follow the steps below to remove the existing fan from your GS20X drive.

- 1) Unplug the fan connector.
- 2) Remove the fan cover from the drive.
- 3) Remove the rubber bushing from the hole of the casing.
- 4) To install the new fan, perform steps 1 to 3 in reverse order. Verify that end A is correctly mounted and the petticoat of end B is turned outward after inserting the rubber bushing into the hole of the casing as shown in the lower right figure.

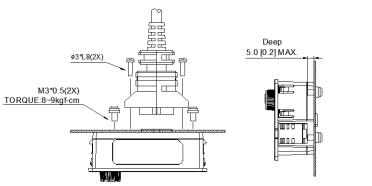


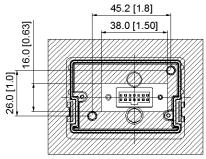


# **REMOTE KEYPAD MOUNTING**

The GS20 keypad can detach from the drive and be mounted remotely. Use an extension cable and screws to create a remote access keypad for the drive.. The keypad can be mounted either directly on a plate, or embedded in a plate. Use the reference material below to mount and connect your GS20 keypad.

### **DIRECT MOUNTING ON A PLATE**

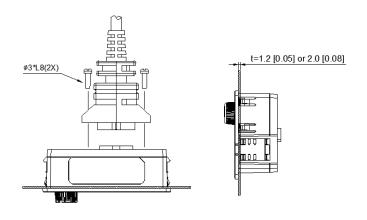


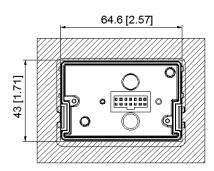


Screw	Torque
M3	8–9 kg-cm (6.94–7.81 lb-in.) [0.78–0.88 N•m]

### EMBEDDED MOUNTING IN A PLATE

Plate Thickness (mm[inch]) = 1.2 [0.05] or 2.0 [0.08]





### **AVAILABLE EXTENSION CABLES**

GS20 Keypad Compatible Extension Cables			
Cable	Length (units = m [ft])		
GS-CBL2-1L	1 [3.28]		
GS-CBL2-3L	3 [9.84]		
GS-CBL2-5L	5 [16.4]		



# **DIN RAIL MOUNTING**

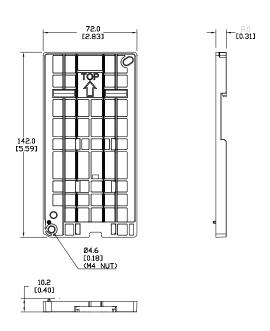
Frame A, B, and C GS20 drives can be DIN rail mounted using a DIN rail mounting kit. One kit is used for A and B frame drives, while a second kit is used for C frame drives.

GS20 DIN Rail Mounting Compatibility			
Drive Model	Frame	Mounting Plate	
GS21-10P2	A1		
GS21-20P2	A1		
GS23-20P2	A1		
GS23-20P5	A2		
GS21-10P5	A3		
GS21-20P5	A3		
GS23-40P5	A4	GS20A-DR-AB	
GS23-21P0	A5	GSZUA-DR-AB	
GS23-41P0	A5		
GS23-51P0	A5		
GS23-22P0	B1		
GS23-42P0	B1		
GS23-52P0	B1		
GS21-21P0	B2		
GS21-11P0	C1		
GS21-22P0	C1		
GS21-23P0	C1		
GS23-23P0	C1		
GS23-25P0	C1	GS20A-DR-C	
GS23-43P0	C1		
GS23-45P0	C1		
GS23-53P0	C1		
GS23-55P0	C1		

## GS20A-DR-AB

Used with Frame A and B GS20 drives.

Screw	Torque
M4 x 2	8–10 kg-cm (6.9–8.7 lb-in.) [0.78–0.98 N•m]

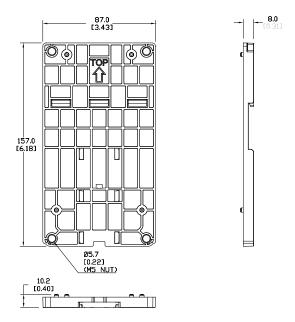




GS20A-DR-C

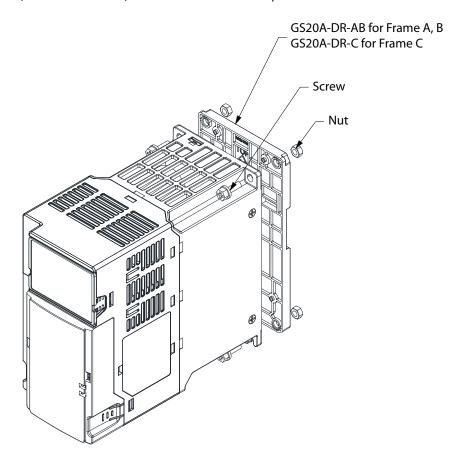
Used with Frame C GS20 drives.

Screw	Torque
M5 x 4	10–12 kg-cm (8.7–10.4 lb-in.)
	[0.98–1.18 N•m]



# **GS20 DIN RAIL INSTALLATION**

Attach the GS20 drive to the DIN rail kit mounting bracket as shown below. The diagram is for a Frame C drive, for Frame A or B, use one screw at the top and one at the bottom.





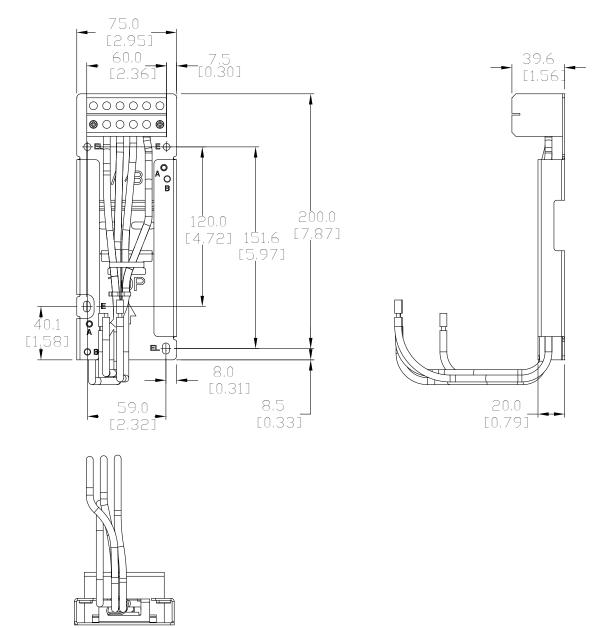
# MOUNTING ADAPTER PLATE

The mounting adapter plate can be used to change the wiring method for the GS20 series and provides flexibility for installation. This accessory changes the wiring method from the "bottom-mains input/ bottom-motor output" to the "top-mains input/bottom-motor output" for GS20. Use the table below to select the correct mounting plate for your drive.

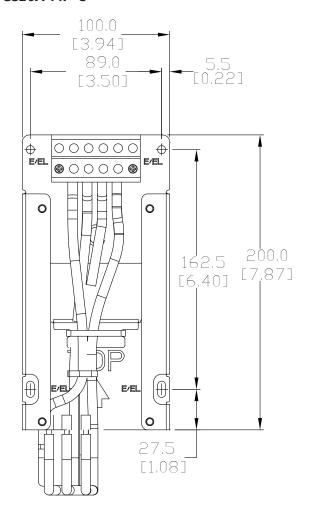
GS20 Mounting Adapter Compatibility			
Drive Model	Frame	Mounting Plate	
GS21-10P2	A1		
GS21-20P2	A1		
GS23-20P2	A1		
GS23-20P5	A2		
GS21-10P5	A3		
GS21-20P5	A3		
GS23-40P5	A4	GS20A-MP-AB	
GS23-21P0	A5	GSZUA-IMP-AB	
GS23-41P0	A5		
GS23-51P0	A5		
GS23-22P0	B1		
GS23-42P0	B1		
GS23-52P0	B1		
GS21-21P0	B2		
GS21-11P0	C1		
GS21-22P0	C1		
GS21-23P0	C1		
GS23-23P0	C1		
GS23-25P0	C1	GS20A-MP-C	
GS23-43P0	C1		
GS23-45P0	C1		
GS23-53P0	C1		
GS23-55P0	C1		

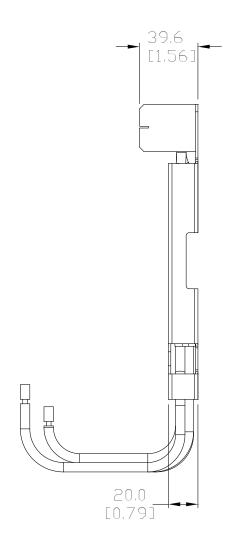


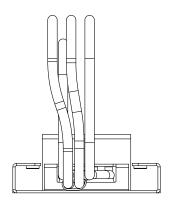
# MOUNTING ADAPTER PLATE DIMENSIONS GS20A-MP-AB



# GS20A-MP-C







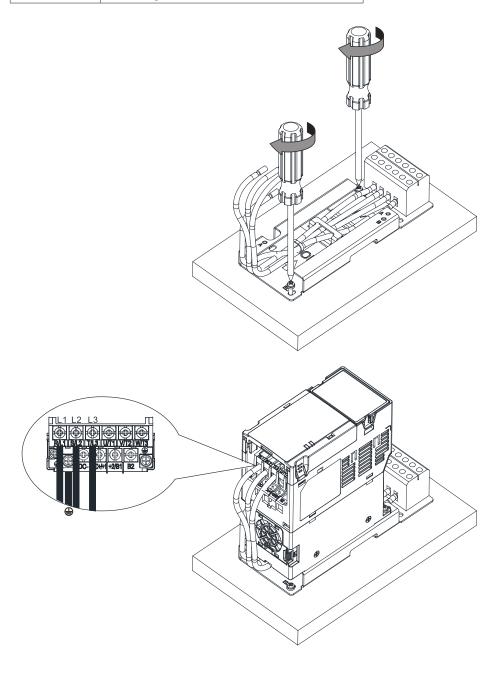


# MOUNTING ADAPTER PLATE INSTALLATION

Use the diagrams below and on the following page to install the mounting adapter plate and reroute the wiring.

# GS20A-MP-AB

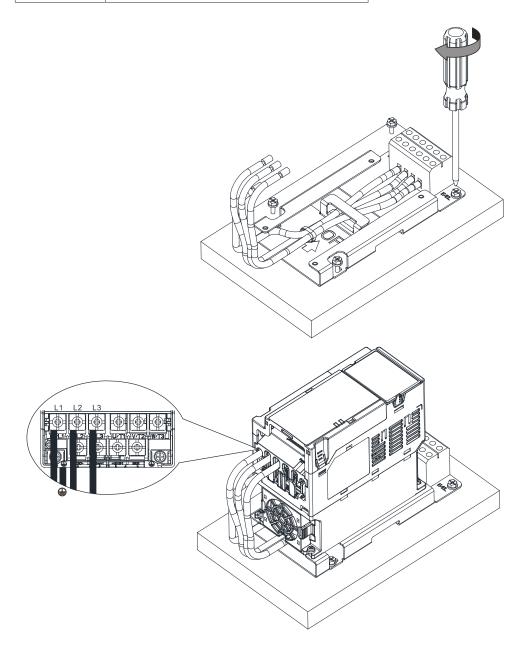
GS20A-MP-AB Screw Size and Torque Value		
Screw Torque		
M4	14–16 kg-cm (12.4–13.9 lb-in.) [1.37–1.57 N•m]	
M5	16–20 kg-cm (13.9–17.4 lb-in.) [1.57–1.96 N•m]	





# GS20A-MP-C

GS20A-MP-C Screw Size and Torque Value		
Screw Torque		
M4	14–16 kg-cm (12.4–13.9 lb-in.) [1.37–1.57 N•m]	
M5	16–20 kg-cm (13.9–17.4 lb-in.) [1.57–1.96 N•m]	





## **OPTIONAL ADVANCED KEYPAD**

### GS4-KPD

The GS4-KPD can be used with GS20(X) drives and offers a more advanced interface with additional features. The keypad can be installed flat on the surface any control panel (with or without bezel GS4-BZL). The front cover is IP56 rated.

The maximum RJ45 extension lead is 5m (16ft). The keypad communication connection to the drive when mounted remotely can be accomplished by using a standard RJ45 CAT5e straight through patch cable. No other wiring is required. The small RJ45 plastic connector that comes standard with each GS4-KPD kit is not used with GS20.

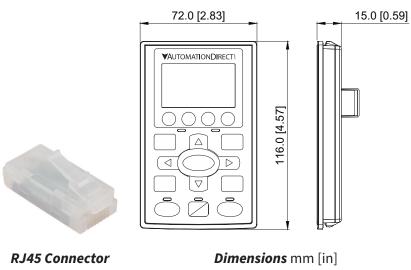
The communication protocol for GS4-KPD is RTU 19200, 8, N, 2. Therefore, you must set GS20(X) communication parameters so as to connect with the digital keypad GS4-KPD. The setting steps are as follows:

- 1) Set P09.00 communication address = 1
- 2) Set P09.01 COM1 transmission speed (Baud rate) = 19.2 Kbps
- 3) Set P09.04 COM1 communication protocol = 13: 8N2 (RTU)

To control the GS20(X) drive motion and speed with the keypad, the setting steps are as follows:

- 1) Frequency control Parameter P00.20 and/or P00.30 to 1:RS-485 input
- 2) Operation control- Parameter P00.21 and/or P00.31 to 2: RS-485 input.





RJ45 Connector (included, not used)

### **Descriptions of Keypad Functions**

### **RUN Key**



- 1) It is only valid when the source of operation command is from the advanced keypad via RS-485.
- 2) It can operate the AC motor drive by the function setting and the RUN LED will be ON.
- 3) RUN can be pressed even when drive is in process of stopping.
- 4) When enabling "LOCAL" mode, it is only valid when the source of operation command is from the advanced keypad via RS-485.

### STOP/RESET Kev



This key has the highest processing priority in any situation.

- 1) When it receives STOP command, whether or not the AC drive is in operation or stop status, the AC motor drive will execute a "STOP" command.
- 2) The RESET key can be used to reset the drive after the fault occurs. For those faults that can't be reset by the RESET key, see the fault records after pressing MENU key for details.

Continued on next page.



# Descriptions of Keypad Functions (continued)

# **FWD REV**

### **Operation Direction Key**

- 1) This key only controls the operation direction and does NOT activate the drive. FWD: forward. REV: reverse.
- 2) Refer to the LED descriptions for more details.



### **ENTER Key**

Press ENTER and go to the next menu level. If it is the last level, then press ENTER to execute the command.



### ESC Key

The ESC key function serves to leave the current menu and return to the last menu. It also functions as a return key while in the sub-menu.

# **MENU**

#### MENU Kev

Press MENU to return to the main menu.

Menu Content:

- - 1) Param Setup
  - 2) Quick Start
  - 3) Keypad Lock
  - 4) Fault Record
- 5) PLC
- 6) Copy Param
- 7) Copy PLC
- 8) Displ Setup
- 9) Time Setup
- 10) Language
- 11) Start-up





### Direction: Left/Right/Up/Down

- 1) In the numeric value setting mode, it is used to move the cursor and change the numeric value.
  - 2) In the menu/text selection mode, it is used for item selection.





### **Function Keys**



- 1) F1 is JOG function
- 2) The F2, F3, F4 keys are reserved for future use.



### **LOCAL Key**

- 1) This key is executed by the parameter settings of the source of Local frequency and Local operation. The factory settings of both source of Local frequency and Local operation are the digital keypad.
- 2) Pressing the LOCAL key with the drive stopped will switch the operation and frequency to the LOCAL source. Pressing the LOCAL key with the drive running will stop the drive, with "AHSP" warning displayed and when stopped, will switch the operation and frequency source to the LOCAL source.
- 3) The selected mode, LOCAL or REMOTE, will be displayed on the GS4-KPD.
- 4) When P00.29=0 then LOCAL correlates to HAND mode. The Digital Input Definition must not be set to 56 (LOC/REM Switch).

Refer to P00.29 for more detail and other options on how the drive behaves when switching between LOCAL and REMOTE.

### **REMOTE Key**

1) This key is executed by the parameter settings of the source of Remote frequency and Remote operation. The digital keypad is the the factory default source for both Remote frequency and Remote operation.



- 2) Pressing the REMOTE key with the drive stopped will switch the operation and frequency to the REMOTE source. Pressing the REMOTE key with the drive running will stop the drive, with "AHSP" warning displayed and when stopped, will switch the operation and frequency source to the REMOTE source.
- 3) The selected mode, LOCAL or REMOTE, will be displayed on the GS4-KPD.
- 4) When P00.29=0 then LOCAL correlates to HAND mode. The Digital Input definition must not be set to 56 (LOC/REM Switch).

Refer to P00.29 for more detail and other options on how the drive behaves when switching between LOCAL and REMOTE.



	Descriptions of LED Functions		
RUN	Steady ON: Operation indicator of the AC motor drive, including DC brake, zero speed, standby, restart after fault and speed search.  Blinking: Drive is decelerating to stop or in the status of base block.  Steady OFF: Drive is not currently executing an operational (RUN) command.		
STOP RESET	Steady ON: Stop indicator of the AC motor drive. Blinking: Drive is in the standby status. Steady OFF: Drive is not currently executing an operational (STOP) command.		
FWD REV	Operation Direction LED  1) Green light is on, the drive is running forward or will run forward when given a run command.  2) Red light is on, the drive is running backwards or will run backwards when given a run command.  3) Alternating green/red light: the drive is changing direction.		
	ERR_COMM_RUN Descriptions reserved for future use.		



# GS20(X) DISPLAY SCREENS FOR GS4-KPD

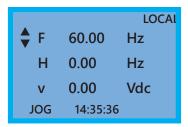
### START-UP DISPLAY



At power up, the Start-up Page displays the *DURAPULSE*, GS20 logo. This page is replaced by the Status Page in 3 seconds.

Pressing the UP Arrow while the Start-up Page is displayed will show the current keypad firmware.

### STATUS PAGE



Drive status:

Press the LOCAL key to allow local control of the drive.

Press the REMOTE key to allow remote control of the drive.

Pressing the Up and Down Direction keys allow the user to see

Pressing the Up and Down Direction keys allow the user to scroll through the Status Page items.

F X.xx Hz (actual GS20 command frequency)

H X.xx Hz (actual GS20 output frequency)

U XXX.x User defined value (in this example P00.04 = 3 DC bus voltage\*

A X.xx Amp (output amperage)

JOG and time:

JOG appears above the F1 key and is the function assigned to that key.

The internal clock is displayed, center bottom.



NOTE: When Power is applied, the keypad will display the startup Page followed by the Status Page. The Status Page displays the GS20(X) default settings F/H/U/A. While the order F/H/U/A is always fixed, P00.03 can be used to set which value appears on the top row at power-up. The UP and DOWN Arrows will scroll through the display options.



NOTE: If an "Err" appears on the keypad after pressing <Enter> in any menu or parameter, then the action did not take affect. The keypad will report back "End" if the action was performed correctly. Ex: writing a value out of range to a parameter will cause a "Err" message.



\* NOTE: Refer to Parameter P00.04 in Chapter 4, AC Drive Parameters for a complete list of the values that can be displayed on line 3 of the keypad display. The value in P00.04 is the value that will be shown when the drive powers up. By scrolling to the User Defined row, the Left and Right Direction keys can be used to display any of the other selections available.



NOTE: The GS4-KPD is connected to the GS20(X) by the RJ45 communications port with a standard ethernet cable. The following communications settings must be used: P09.01=19.2 (kBps) and P09.04=13 (8N2 RTU).



### MENU PAGE

Menu

1: Param Setup

3:Keypad Lock

2: Quick Start

Press the Menu button from any page to access the Menu Page. Use the Up and Down Direction keys to scroll through the Menu content. Press the Enter key to open the selected Menu content item.

- 1: Param Setup Parameter Setup Set up the individual drive parameters.
- 2: Quick Start This function not available for GS20(X).
- 3: Keypad Lock Lock the Keypad.
- 4: Fault Record Display fault information for the drive.
- Run the current PLC program.
  6: Copy Param Copy Parameters
- Save drive parameters to the keypad or drive.
- Copy a previously saved PLC program to the keypad or drive.
  8: Displ Setup
- Adjust contrast and backlight settings for the display.
  9: Time Setup
- Set the time. 10: Language
  - Set the display language.
- 11: Start-up Set the Start-up Page display.

### PARAM SETUP - PARAMETER SETUP PAGE

See the individual parameter summary tables in *Chapter 4 - AC Drive Parameters* for specific parameter explanations and settings.

00: DRIVE

01: BASIC

02: DIGITAL

03: ANALOG

04: SPEED

05: MOTOR

06: PROTECT

07: SPECIAL

08: PID

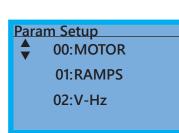
09: COMMUNICATION

10: FEEDBACK

11: ADVANCED

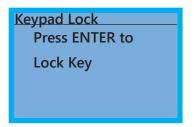
13: USER

14: PROTECT(2)





### KEYPAD LOCK - KEYPAD LOCK PAGE



Keypad Lock is used to lock the keypad from unintentional activation during operation.



Press the Enter key to lock the keypad.



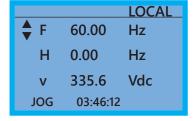
The Status Page will again display.



Keypad Lock
Press ESC 3sec
to UnLock Key

Pressing ANY key will display the message Press ESC to UnLock Key.





Press and hold the ESC key for 3 seconds to unlock the keypad. The display will return to the Status Page.



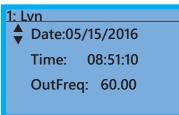
### FAULT RECORD - FAULT RECORD PAGE

GS20 drive faults are stored from 1: to 20:. Refer to *Chapter 6: Maintenance and Troubleshooting* for a complete list of fault messages that may appear. Use the Up and Down Direction keys to scroll through the list.

- 1:
- 2:
- 3:
- **▲** ▼
- 18:
- 19:
- 20:



Press the Enter key to display information about the drive status when the fault occurred.



Date: 00/00/0000 Time: 00:00:00 OutFreq: 0.00 OutAmp: 0.00 OutVolt 0.0 DCBus: 0.0



### **PLC - PLC FUNCTION PAGE**



PLC Function is used to Enable/Disable and Run/Stop the internal PLC. The active selection is marked by a smiley face character on the far right of the display.



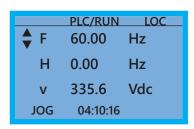
WARNING: ON A POWER CYCLE THE PLC RUN/STOP STATE WILL BE DETERMINED BY THE LAST STATE THE KEYPAD WAS PLACED IN, OR BY THE CONFIGURED DIGITAL INPUTS. IF THE STATE WAS CHANGED VIA GSLOGIC, THAT RUN/STOP STATE MAY NOT BE TRUE ON A POWER CYCLE.



Use the Up and Down Direction keys to select Disable, PLC Run or PLC Stop.



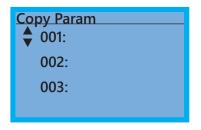
Press the Enter key to confirm the selection.



Selecting PLC Run will activate the GS20 internal PLC. The keypad status Page will display PLC/RUN at the top, center of the display. If PLC Stop is selected, the PLC program will stop and the Status Page will display PLC/STOP at the top center of the page. Selecting Disable will disable the GS20 internal PLC and return control to the drive. Selecting PLC Run or PLC Stop also can determine whether the physical I/O are controlled by the Drive or are controlled by the PLC. See Chapter 8 for more information on the integrated PLC and GSLogic software.



### COPY PARAM - COPY PARAMETERS PAGE (KEYPAD COPY)



Copy Parameters is used to save up to four drive configurations into the keypad. The keypad can then download any of these configurations into the drive, or it can be moved to a different drive and download the parameter settings of the original drive. Use the Up and Down Direction keys to scroll through the four available copy parameter locations. If a field is blank, then no copy has been made to that location.

001: ExhaustFan 002: IntakeFan1 003: Filename02 004:

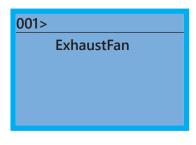


Press the Enter key to select the desired location for writing the current parameter settings.



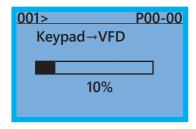
Use the Up and Down Direction keys to select Keypad→VFD to copy the current parameter settings from the keypad to the drive or VFD→Keypad to write the current parameter settings from the drive to the keypad. Press the Enter key.

VFD→ KEYPAD



After VFD→Keypad is selected, the keypad will prompt you for a filename to save the existing configuration into. Use the Left/Right Arrows to scroll from character to character and the Up/Down Arrows to change the alphanumeric character. Pressing Enter will begin the transfer of parameters from the drive into the keypad.

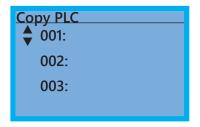
**KEYPAD** → **VFD** 



When Keypad→VFD is selected, the keypad will begin the transfer of the preselected file parameters from the keypad into the drive. As shown in the example to the left, "001" is the file to be transferred. Pressing F4 while in the Copy Param menu will prompt you to Delete All 4 saved programs ("Press ENTER to clear").



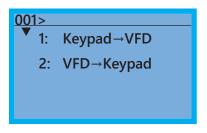
### COPY PLC - COPY PLC PAGE



Copy PLC is used to copy previously saved PLC program from the keypad to the drive or from the drive to the keypad. Use the Up and Down Direction keys to scroll through the four available Copy PLC locations. If the field is blank, then no copies have been made. The keypad can store both the parameters and the PLC program at the same time.

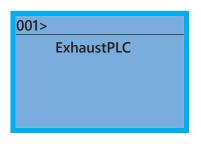


Press the Enter key to select the desired location for writing the current program.



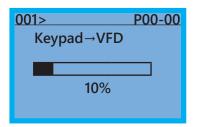
Use the Up and Down Direction keys to select Keypad→VFD to copy the previously saved PLC settings from the keypad to the drive or VFD→Keypad to write the current PLC program from the drive to the keypad.

VFD→ KEYPAD



When VFD→Keypad is selected, the keypad will prompt you for a filename to save the existing configuration into. Use the Left/Right arrows to scroll from character to character and the Up/Down arrows to change the alphanumeric character. Pressing Enter will begin the transfer of PLC program from the drive into the keypad.

KEYPAD → VFD



When Keypad→VFD is selected, the keypad will begin the transfer of PLC program from the keypad into the drive.

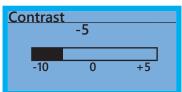


### DISPL SETUP - DISPLAY SETUP PAGE



The Display Setup Page allows the user to adjust the Contrast, Backlight time and Text Color of the display.

- 1: Contrast
- 2: Timeout
- 3: Text Color

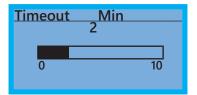


Use the Up and Down direction arrows to adjust the Contrast to the desired setting.

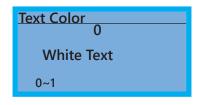
The range of adjustment is from -20 to +20.

The default value is 0.

Entering a value of 0 will keep the backlight ON all the time.



Use the Up and Down direction arrows to adjust the time when the display backlight turns off. The range of adjustment is from 0 to 10 minutes. The default value is 5 minutes.



Use the Up and Down direction arrows to select from white text or blue text for the display.

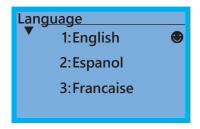
### TIME SETUP - TIME SETUP PAGE



The Time Setup Page allows the user to change the date and time. The date format is Year/Month/Day. Time is displayed in 24-hour clock format and is displayed as Hours:Minutes:Seconds. Use the Right and Left Arrow keys to move the cursor to the desired location and use the Up and Down Arrow keys to adjust the setting. After adjusting the time, move the cursor to the Seconds entry before pressing the Enter Key.

The real time clock (RTC) is maintained in the keypad. A capacitor is used to provide power for the RTC during power loss. The capacitor can maintain power for the RTC for 7 days with no drive power applied.

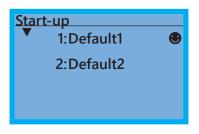
### LANGUAGE - LANGUAGE PAGE



The Language Page sets the language shown on the display. Select from English, Spanish or French. The translation applies to the keypad menu structure only. The Detailed parameter settings will remain in English.



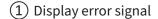
### START-UP - START-UP PAGE



The Start-up Page allows the user to select from two different screens that display during initial start-up. Default1 setting displays the GS20 logo screen, Default2 setting displays "Initializing, Please Wait."

### KEYPAD FAULT CODES

Following are the fault codes and descriptions for the GS4-KPD. To reset the fault codes press the Enter and Reset buttons simultaneously. These faults indicate either a communication error between the keypad and the drive or a keypad failure. To correct: 1) Inspect and clean the RJ45 connectors on the back of the keypad and the RJ45 connector leading into the drive. 2) Replace the cable and/or RJ45 M-M adapter with a standard Ethernet patch cable. 3) If the RJ45 connections are OK, replace the keypad.





- ② Abbreviated error code
  The code is displayed as shown on GS4-KPD
- 3 Display error description

ID No.	Description	Corrective Actions
Fault FrEr  kpdFlash Read Er	Keypad flash memory read error.	<ul> <li>An error has occurred on keypad's flash memory.</li> <li>1. Press RESET on the keypad to clear the error.</li> <li>2. Verify what kind of error has occurred on keypad's flash memory.</li> <li>3. Shut down the system, wait 10 minutes and power up the system.</li> <li>If the error remains contact technical support.</li> </ul>
Fault FSEr kpdFlash Save Er	Keypad flash memory save error.	<ul> <li>An error has occurred on keypad's flash memory.</li> <li>1. Press RESET on the keypad to clear the error.</li> <li>2. Verify what kind of error has occurred on keypad's flash memory.</li> <li>3. Shut down the system, wait 10 minutes and power up the system.</li> <li>If the error remains contact technical support.</li> </ul>
Fault FPEr kpdFlash Pr Er	Keypad flash memory parameter error.	Errors occurred on factory setting parameters possibly caused by firmware update.  1. Press RESET on the keypad to clear the error.  2. Verify if there is a problem on the FLASH IC.  3. Shut down the system, wait 10 minutes and power up the system.  If the error remains contact technical support.
Fault VFDr Read VFD Info Er	Keypad flash memory when read AC data error.	Keypad can't read data from drive.  1. Verify if the keypad is properly connected to the drive with the RJ45 connector.  2. Press RESET on the keypad to clear the error.  3. Shut down the system, wait 10 minutes and power up the system.  If the error remains contact technical support.
Fault ERR88  Type Mismatch	Keypad/Drive parameter file mismatch.	There has been an attempt to copy an incorrect file between the keypad and the drive. Ensure that there is a valid file in the keypad (if attempting Keypad → VFD transfer).



# **KEYPAD PANEL MOUNTING KIT GS4-BZL**

This panel mounting kit can be used for wall mounting or embedded mounting of the GS4-KPD.

